**CONTENTS**

|  |  |  |
| --- | --- | --- |
| **CHAPTER**  **NO** | **PARTICULARS** | **PAGE NO.** |
|  | ACKNOWLEDGEMENT  ABSTRACT  LIST OF FIGURES | i  ii  iii |
| 1 | INTRODUCTION | 1 |
|  | Objectives | 2 |
| 2 | LITERATURE SURVEY | 3-5 |
|  | Summary of literature review | 6 |
| 3 | THEORITICAL BACKGROUND | 7-20 |
|  | 3.1 Software | 7 |
|  | 3.1.1 Python | 7 |
|  | 3.1.2 OpenCV | 7 |
|  | 3.1.3 pySerial | 7 |
|  | 3.1.4 NumPy | 7 |
|  | 3.1.5 Canny Edge Detection | 7 |
|  | 3.1.6 Gaussian Blur | 8 |
|  | 3.1.7 Houghline Transform  3.1.8 TensorFlow  3.1.9 TensorFlow Object Detection API  3.1.10 CUDA**®**  3.1.11 AlexNet  3.2 Hardware  3.2.1 Arduino  3.2.2 The NRF24L01  3.2.3 DC Motor  3.2.4 Relay Module  3.2.5 Server Computer | 9  11  11  12  12  14  14  15  17  18  20 |
| 4 | PROPOSED WORK | 21-26 |
|  | 4.1 Lane detection using Houghline Transform | 21 |
|  | 4.2 Training a Neural Network to make driving predictions  4.3 Block diagram of project | 23  26 |
| 5 | RESULTS AND CONCLUSION | 28 |
|  | 5.1 Results | 28 |
|  | 5.2 Conclusion  5.3 Future Scope | 28  28 |
| REFERENCES |  | 29-30 |