Type-based Exception Analysis

for Non-strict Higher-order Functional Languages with Imprecise Exception Semantics

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"Well-typed programs do not go wrong."

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- Except:
 - reciprocal x = 1 / x
 - head (x:xs)=x
 - **.**..
- Practical programming languages allow functions to be partial.

- Requiring all functions to be total may be undesirable.
 - Dependent types are heavy-weight.
 - Running everything in the Maybe monad does not solve the problem, only moves it.
 - ▶ Some partial functions are *benign*.
- We do want to warn the programmer something may go wrong at run-time.

► Currently compilers do a local and syntactic analysis.

head ::
$$[\alpha] \rightarrow \alpha$$

head $xs = \mathbf{case} \ xs \ \mathbf{of} \ \{ (y:ys) \rightarrow y \}$

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▶ "The problem is in *head* and *every* place you call it!"

$$main = head [1, 2, 3]$$

▶ Worse are non-escaping local definitions.

▶ The canonical example by Mitchell & Runciman (2008):

```
risers :: Ord \alpha \Rightarrow [\alpha] \rightarrow [[\alpha]]

risers [] = []

risers [x] = [[x]]

risers (x_1 : x_2 : x_3) =

if x_1 \leqslant x_2 then (x_1 : y) : ys else [x_1] : (y : ys)

where (y : ys) = risers (x_2 : x_3)
```

Computes monotonically increasing subsegments of a list:

risers
$$[1,3,5,1,2] \longrightarrow^* [[1,3,5],[1,2]]$$

► Program invariants can ensure incomplete pattern matches never fail.



► Instead use a semantic approach: "where can exceptions flow to?"

- ► Simultaneously need to track data flow to determine which branches are not taken.
- Using a type-and-effect system, the analysis is still modular.

Basic idea: data flow

▶ We can then assign to each of the three individual branches of *risers* the following types:

```
risers<sub>1</sub> :: \forall \alpha.Ord \ \alpha \Rightarrow [\alpha]^{\mathbf{N}} \rightarrow [[\alpha]^{\mathbf{N} \sqcup \mathbf{C}}]^{\mathbf{N}}
risers<sub>2</sub>, risers<sub>3</sub> :: \forall \alpha.Ord \ \alpha \Rightarrow [\alpha]^{\mathbf{C}} \rightarrow [[\alpha]^{\mathbf{N} \sqcup \mathbf{C}}]^{\mathbf{C}}
```

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$$risers_1$$
 :: $\forall \alpha.Ord \ \alpha \Rightarrow [\alpha]^{\mathbf{N}} \rightarrow [[\alpha]^{\mathbf{N} \sqcup \mathbf{C}}]^{\mathbf{N}}$
 $risers_2, risers_3$:: $\forall \alpha.Ord \ \alpha \Rightarrow [\alpha]^{\mathbf{C}} \rightarrow [[\alpha]^{\mathbf{N} \sqcup \mathbf{C}}]^{\mathbf{C}}$

▶ From the three individual branches we may infer:

risers ::
$$\forall \alpha.Ord \ \alpha \Rightarrow [\alpha]^{\mathbf{N} \sqcup \mathbf{C}} \rightarrow [[\alpha]^{\mathbf{N} \sqcup \mathbf{C}}]^{\mathbf{N} \sqcup \mathbf{C}}$$

▶ Adding *polyvariance* gives us a more precise result:

risers ::
$$\forall \alpha \beta. Ord \ \alpha \Rightarrow [\alpha]^{\beta} \rightarrow [[\alpha]^{\mathbf{N} \sqcup \mathbf{C}}]^{\beta}$$



Basic idea: exception flow

▶ A compiler will translate the partial function *head* into:

which can be assigned the exception type:

$$head:: \forall \tau \alpha \beta. [\tau^{\alpha}]^{\beta} \xrightarrow{\emptyset} \tau^{\alpha \sqcup \beta \sqcup pattern-match-failure}$$

Basic idea: exception flow

► A compiler will translate the partial function *head* into:

head
$$xs = \mathbf{case} \ xs \ \mathbf{of}$$

$$[] \mapsto \mbox{$\frac{1}{2}$ pattern-match-failure}$$

$$(y:ys) \mapsto y$$

which can be assigned the exception type:

$$head :: \forall \tau \alpha \beta. [\tau^{\alpha}]^{\beta} \xrightarrow{\varnothing} \tau^{\alpha \sqcup \beta \sqcup pattern-match-failure}$$

- ► This type tells us that *head* might always raise a **pattern-match-failure** exception!
- Introduce a dependency of the exception flow on the data flow of the program:

head ::
$$\forall \tau \alpha \beta \gamma . [\tau^{\alpha}]^{\beta} \xrightarrow{\emptyset} \tau^{\alpha \sqcup \beta \sqcup \gamma}$$
 with $\{ \mathbf{N} \sqsubseteq \beta \Rightarrow \text{pattern-match-failure} \sqsubseteq \gamma \}$



Imprecise exception semantics

- ▶ Non-strict languages can have an *imprecise exception semantics* (Peyton Jones *et al*, 1999).
 - Can non-deterministically raise one from a set of exceptions.
 - Necessary for the soundness of certain program transformations, e.g. the case-switching transformation:

```
orall e_i. if e_1 then if e_2 then e_3 else e_4 else if e_2 then e_5 else e_6= if e_2 then if e_1 then e_3 else e_5 else if e_1 then e_4 else e_6
```

Imprecise exception semantics

- If an exception can be raised by pattern matching, we need to continue evaluating all branches.
- ▶ Implication for the analysis: cannot separate data and exception flow phases.

Algorithm

- Assumes program is well-typed in underlying type system.
- ▶ Algorithm *W*-like constraint generation phase.
- ▶ Worklist/fixpoint-based constraint solver.

Types and constraints

Annotated types:

$$\tau ::= \alpha \mid \tau_1 \xrightarrow{\alpha} \tau_2 \mid \tau_1 \times^{\alpha} \tau_2 \mid [\tau]^{\alpha}$$

Conditional constraints and indices model dependence between data flow and exception flow:

$$c ::= g \Rightarrow r$$

$$g ::= \Lambda_{\iota} \sqsubseteq_{\iota} \alpha \mid \exists_{\iota} \alpha \mid g_{1} \vee g_{2} \mid \mathbf{true}$$

$$r ::= \Lambda_{\iota} \sqsubseteq_{\iota} \alpha \mid \alpha_{1} \sqsubseteq_{\iota} \alpha_{2} \mid \tau_{1} \leqslant_{\iota} \tau_{2}$$

► Asymmetric to keep solving tractable.



A type rule (case-expressions)

$$C; \Gamma \vdash e_{1} : [\tau_{1}]^{\alpha_{1}} \quad C; \Gamma \vdash e_{2} : \tau_{2}$$

$$C; \Gamma, x_{1} : \tau_{1}, x_{2} : [\tau_{1}]^{\beta} \vdash e_{3} : \tau_{3}$$

$$C \Vdash \mathbf{N} \sqsubseteq_{\delta} \alpha_{1} \vee \exists_{\chi} \alpha_{1} \Rightarrow \tau_{2} \leqslant_{\delta\chi} \tau$$

$$C \Vdash \mathbf{C} \sqsubseteq_{\delta} \alpha_{1} \vee \exists_{\chi} \alpha_{1} \Rightarrow \tau_{3} \leqslant_{\delta\chi} \tau$$

$$C \Vdash \alpha_{1} \sqsubseteq_{\chi} [\tau] \quad C \Vdash \mathbf{N} \sqcup \mathbf{C} \sqsubseteq_{\delta} \beta \quad C \Vdash \alpha_{1} \sqsubseteq_{\chi} \beta$$

$$C; \Gamma \vdash \mathbf{case} \ e_{1} \ \mathbf{of} \{[] \mapsto e_{2}; x_{1} :: x_{2} \mapsto e_{3}\} : \tau$$

$$[T-CASE]$$

Operators

Operators have a constraint set corresponding to their abstract interpretation:

$$\omega_{\div}(\alpha_{1},\alpha_{2},\alpha) \stackrel{\text{def}}{=} \left\{ \begin{array}{l} \mathbf{o} \sqsubseteq_{\delta} \alpha_{2} \Rightarrow \{\mathbf{div\text{-}by\text{-}o}\} \sqsubseteq_{\chi} \alpha \\ -\sqsubseteq_{\delta} \alpha_{1} \land -\sqsubseteq_{\delta} \alpha_{2} \Rightarrow +\sqsubseteq_{\delta} \alpha \\ -\sqsubseteq_{\delta} \alpha_{1} \land +\sqsubseteq_{\delta} \alpha_{2} \Rightarrow -\sqsubseteq_{\delta} \alpha \\ +\sqsubseteq_{\delta} \alpha_{1} \land -\sqsubseteq_{\delta} \alpha_{2} \Rightarrow -\sqsubseteq_{\delta} \alpha \\ +\sqsubseteq_{\delta} \alpha_{1} \land +\sqsubseteq_{\delta} \alpha_{2} \Rightarrow +\sqsubseteq_{\delta} \alpha \\ \mathbf{o} \sqsubseteq_{\delta} \alpha \end{array} \right\}$$

Can make a trade-off between precision and accuracy.

Operators

Definition

An operator constraint set ω_{\oplus} is said to be *consistent* with respect to an operator interpretation $\llbracket \cdot \oplus \cdot \rrbracket$ if, whenever $C; \Gamma \vdash n_1 : \alpha_1, C; \Gamma \vdash n_2 : \alpha_2$, and $C \Vdash \omega_{\oplus}(\alpha_1, \alpha_2, \alpha)$ then $C; \Gamma \vdash \llbracket n_1 \oplus n_2 \rrbracket : \alpha'$ with $C \Vdash \alpha' \leq_{\delta\chi} \alpha$ for some α' .

Definition

An operator constraint set ω_{\oplus} is *monotonic* if, whenever $C \Vdash \omega_{\oplus}(\alpha_1, \alpha_2, \alpha)$ and $C \Vdash \alpha'_1 \sqsubseteq_{\delta\chi} \alpha_1, C \Vdash \alpha'_2 \sqsubseteq_{\delta\chi} \alpha_2, C \Vdash \alpha \sqsubseteq_{\delta\chi} \alpha'$ then $C \Vdash \omega_{\oplus}(\alpha'_1, \alpha'_2, \alpha')$.

Metatheory

Theorem (Conservative extension)

If e is well-typed in the underlying type system, then it can be given a type in the annotated type system.

Theorem (Progress)

If C; $\Gamma \vdash e : \sigma$ then either e is a value or there exist an e', such that for any ρ with $C \vdash \Gamma \bowtie \rho$ we have $\rho \vdash e \longrightarrow e'$.

Theorem (Preservation)

If $C; \Gamma \vdash e : \sigma_1, \rho \vdash e \longrightarrow e'$ and $C \vdash \Gamma \bowtie \rho$ then $C; \Gamma \vdash e' : \sigma_2$ with $C \Vdash \sigma_2 \leqslant_{\delta\chi} \sigma_1$.



Polyvariant recursion

- ▶ To precisely type *risers* (i.e. infer that no exception can be raised if not already present in input) we need *polyvariant recursion* (i.e. polymorphic recursion restricted to annotations).
- ▶ This poses algorithmic difficulties w.r.t. termination.
 - Variable elimination technique by Dussart, Henglein & Mossin (1995) does not work due to conditional constraints.
 - Restricting the number of fresh variables generated makes the analysis fairly unpredictable.
 - ► Terminating before a fixpoint has been reached invalidates the soundness result, but may not be a problem in practice.
- ▶ The *ad hoc* nature of the constraint language comes back to bite us; currently looking at more well-behaved constraint languages (Boolean rings).

Questions?