```
PRIVATE void init clock()
132
133
       /* First of all init the clock system.
134
        * Here the (a) clock is set to produce a interrupt at
135
136
        * every 1/60 second (ea. 60Hz).
137
138
        * Running right away.
        * /
139
140
                           /* architecture-dependent initialization. */
       arch_init_clock();
141
142
       /* Initialize the CLOCK's interrupt hook. */
143
       clock_hook.proc_nr_e = CLOCK;
144
       put_irq_handler(&clock_hook, CLOCK_IRQ, clock_handler);
145
146
       enable_irq(&clock_hook);
                                           /* ready for clock interrupts */
147
       /* Set a watchdog timer to periodically balance the scheduling queues. */
148
                                           /* side-effect sets new timer */
149
       balance queues(NULL);
150
     }
151
152
     /*-----*
153
                             clock_handler
154
      155
     PRIVATE int clock handler(hook)
156
     irq_hook_t *hook;
157
158
     /* This executes on each clock tick (i.e., every time the timer chip generates
      * an interrupt). It does a little bit of work so the clock task does not have
159
160
      * to be called on every tick. The clock task is called when:
161
162
             (1) the scheduling quantum of the running process has expired, or
163
             (2) a timer has expired and the watchdog function should be run.
164
165
      * Many global global and static variables are accessed here. The safety of
166
      * this must be justified. All scheduling and message passing code acquires a
167
      * lock by temporarily disabling interrupts, so no conflicts with calls from
168
      * the task level can occur. Furthermore, interrupts are not reentrant, the
169
      * interrupt handler cannot be bothered by other interrupts.
170
171
      * Variables that are updated in the clock's interrupt handler:
172
             lost_ticks:
                     Clock ticks counted outside the clock task. This for example
173
174
                     is used when the boot monitor processes a real mode interrupt.
175
            realtime:
176
                    The current uptime is incremented with all outstanding ticks.
177
             proc_ptr, bill_ptr:
178
                     These are used for accounting. It does not matter if proc.c
179
                     is changing them, provided they are always valid pointers,
180
                     since at worst the previous process would be billed.
181
182
       register unsigned ticks;
183
       /* Get number of ticks and update realtime. */
184
185
       ticks = lost_ticks + 1;
186
       lost_ticks = 0;
187
       realtime += ticks;
188
189
       /* Update user and system accounting times. Charge the current process for
190
        * user time. If the current process is not billable, that is, if a non-user
191
        * process is running, charge the billable process for system time as well.
192
        * Thus the unbillable process' user time is the billable user's system time.
193
        * /
194
195
       proc_ptr->p_user_time += ticks;
```

```
196
      proc ptr->p recent time += ticks;
197
      if (priv(proc_ptr)->s_flags & PREEMPTIBLE) {
198
         proc_ptr->p_ticks_left -= ticks;
199
200
      if (! (priv(proc_ptr)->s_flags & BILLABLE)) {
201
         bill_ptr->p_sys_time += ticks;
         bill_ptr->p_ticks_left -= ticks;
202
203
      }
204
205
      /* Update load average. */
206
      load_update();
207
208
      /* Check if do_clocktick() must be called. Done for alarms and scheduling.
      * Some processes, such as the kernel tasks, cannot be preempted.
209
      * /
210
      if ((next_timeout <= realtime) || (proc_ptr->p_ticks_left <= 0)) {</pre>
211
212
                                         /* store running process */
         prev_ptr = proc_ptr;
                                          /* send notification */
213
         lock notify(HARDWARE, CLOCK);
214
215
                                          /* reenable interrupts */
      return(1);
216
    }
217
218
    219
                             get_uptime
220
     2.2.1
    PUBLIC clock_t get_uptime(void)
222
223
      /* Get and return the current clock uptime in ticks. */
224
      return(realtime);
225
226
    /*----*
227
228
                             set timer
229
     230
    PUBLIC void set_timer(tp, exp_time, watchdog)
                            /* pointer to timer structure */
231
    struct timer *tp;
232
                             /* expiration realtime */
    clock_t exp_time;
                             /* watchdog to be called */
233
    tmr_func_t watchdog;
234
235
    /* Insert the new timer in the active timers list. Always update the
236
     * next timeout time by setting it to the front of the active list.
237
238
     tmrs_settimer(&clock_timers, tp, exp_time, watchdog, NULL);
239
     next_timeout = clock_timers->tmr_exp_time;
240
241
242
    /*=============*
243
                             reset timer
244
     *=======*/
245
    PUBLIC void reset_timer(tp)
                             /* pointer to timer structure */
246
    struct timer *tp;
247
     /* The timer pointed to by 'tp' is no longer needed. Remove it from both the
248
     * active and expired lists. Always update the next timeout time by setting
249
250
     * it to the front of the active list.
     * /
251
252
     tmrs clrtimer(&clock timers, tp, NULL);
253
     next_timeout = (clock_timers == NULL) ?
254
           TMR_NEVER : clock_timers->tmr_exp_time;
255
256
257
    /*----*
258
                             load_update
259
     260
    PRIVATE void load_update(void)
```