

Step	Algorithm: $y := \alpha x + y$
1a	$\{y = \hat{y}\}$
4	$x \rightarrow \begin{pmatrix} x_T \\ x_B \end{pmatrix}, y \rightarrow \begin{pmatrix} y_T \\ y_B \end{pmatrix}$ <p>where x_T has 0 rows, y_T has 0 rows</p>
2	$\left\{ \begin{pmatrix} y_T \\ y_B \end{pmatrix} = \begin{pmatrix} \alpha x_T + \hat{y}_T \\ \hat{y}_B \end{pmatrix} \right\}$
3	while $m(x_T) < m(x)$ do
2,3	$\left\{ \begin{pmatrix} y_T \\ y_B \end{pmatrix} = \begin{pmatrix} \alpha x_T + \hat{y}_T \\ \hat{y}_B \end{pmatrix} \wedge m(x_T) < m(x) \right\}$
5a	$\begin{pmatrix} x_T \\ x_B \end{pmatrix} \rightarrow \begin{pmatrix} x_0 \\ \chi_1 \\ x_2 \end{pmatrix}, \begin{pmatrix} y_T \\ y_B \end{pmatrix} \rightarrow \begin{pmatrix} y_0 \\ \psi_1 \\ y_2 \end{pmatrix}$ <p>where χ_1 has 1 row, ψ_1 has 1 row</p>
6	$\left\{ \begin{pmatrix} y_0 \\ \psi_1 \\ y_2 \end{pmatrix} = \begin{pmatrix} \alpha x_0 + \hat{y}_0 \\ \hat{\psi}_1 \\ \hat{y}_2 \end{pmatrix} \right\}$
8	$\psi_1 := \alpha \chi_1 + \psi_1$
7	$\left\{ \begin{pmatrix} y_0 \\ \psi_1 \\ y_2 \end{pmatrix} = \begin{pmatrix} \alpha x_0 + \hat{y}_0 \\ \alpha \chi_1 + \hat{\psi}_1 \\ \hat{y}_2 \end{pmatrix} \right\}$
5b	$\begin{pmatrix} x_T \\ x_B \end{pmatrix} \leftarrow \begin{pmatrix} x_0 \\ \chi_1 \\ x_2 \end{pmatrix}, \begin{pmatrix} y_T \\ y_B \end{pmatrix} \leftarrow \begin{pmatrix} y_0 \\ \psi_1 \\ y_2 \end{pmatrix}$
2	$\left\{ \begin{pmatrix} y_T \\ y_B \end{pmatrix} = \begin{pmatrix} \alpha x_T + \hat{y}_T \\ \hat{y}_B \end{pmatrix} \right\}$
	endwhile
2,3	$\left\{ \begin{pmatrix} y_T \\ y_B \end{pmatrix} = \begin{pmatrix} \alpha x_T + \hat{y}_T \\ \hat{y}_B \end{pmatrix} \wedge \neg(m(x_T) < m(x)) \right\}$
1b	$\{y = \alpha x + \hat{y}\}$

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1a	{
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	where
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8	
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2	$\left\{ \left(\frac{y_T}{y_B} \right) = \left(\frac{\alpha x_T + \widehat{y}_T}{\widehat{y}_B} \right) \right\}$
3	while do
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	endwhile

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$$x \rightarrow \begin{pmatrix} x_T \\ x_B \end{pmatrix}, y \rightarrow \begin{pmatrix} y_T \\ y_B \end{pmatrix}$$

where x_T has 0 rows, y_T has 0 rows

while $m(x_T) < m(x)$ **do**

$$\begin{pmatrix} x_T \\ x_B \end{pmatrix} \rightarrow \begin{pmatrix} x_0 \\ \chi_1 \\ x_2 \end{pmatrix}, \begin{pmatrix} y_T \\ y_B \end{pmatrix} \rightarrow \begin{pmatrix} y_0 \\ \psi_1 \\ y_2 \end{pmatrix}$$

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endwhile