

4/10

$$Ax = dx$$

$$(d-\mu)x = dx - \mu x = Ax - \mu x$$

$$= (A-\mu I)x$$

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v. good

$$\therefore (A-\mu I)x = (d-\mu)x$$

$\Rightarrow d-\mu$ is an ew of $A-\mu I$.

True |

$$Ax = dx$$

$$A = \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} \Rightarrow \begin{vmatrix} 2-d & 0 \\ 0 & 2-d \end{vmatrix} = 0$$

$$(2-d)^2 = 0$$

False |

$$(2-d)(2-d) = 0$$

$$d = 2, 2$$

$d=2$ is eigen value of A but $-d=-2$
is not B .

$$Ax = dx$$

$$= 9/10$$

all the eigen values of A are zero,

$$\Rightarrow \det(A) = 0, \operatorname{tr}(A) = 0$$

Let, $A = \begin{bmatrix} 2 & 4 \\ -1 & -2 \end{bmatrix}$ with $\operatorname{tr}(A) = 0$
and $\det(A) = 0$

$$d_1 + d_2 = 0$$

$$d_1 d_2 = 0$$

$$2) (2-d)^2 - 4 = d_1^2 + d_2^2 = 0$$

$$\begin{vmatrix} (2-d)^2 & 4 \\ -1 & -2-d \end{vmatrix} = 0$$

$$= -(2-d)^2(2+d) + 4 = 0$$

$$-(4-d^2) + 4 = 0$$

$$-4 + d^2 + 4 = 0$$

$$d^2 = 0$$

$$d_1 = d_2 = 0 \text{ but } A \neq 0$$

\therefore not true

2.

A is hermitian means $A = A^*$ and its all eigen values are real

Singular values of A are square roots of eigen values of $A^* A$

$$A = Q \Lambda Q^* = Q |\Lambda| \operatorname{sign}(\Lambda) Q^* \quad \text{--- (1)}$$

where $|\Lambda|$ is diagonal matrix whose entries are $|d_i|$ and

$\operatorname{sign}(\Lambda)$ is a diagonal matrix with entries $\operatorname{sign}(d_i)$

A is diagonalizable

$\Rightarrow A = X \Lambda X^{-1}$ and all evs are equal

$A = X \Lambda X^{-1}$ (\because all evs are equal)

$$A = dXX^{-1} = dI$$

$$\underline{A = dI}$$

$\Rightarrow A$ is diagonal.

$$A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix}, B = \begin{bmatrix} 0 & \epsilon & \epsilon \\ \epsilon & 0 & \epsilon \\ \epsilon & \epsilon & 0 \end{bmatrix}, \epsilon \leq 10^{-3}$$

$$A + B$$

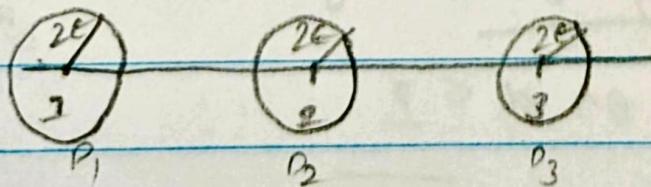
$$= \begin{bmatrix} 1 & \epsilon & \epsilon \\ \epsilon & 2 & \epsilon \\ \epsilon & \epsilon & 3 \end{bmatrix}$$

eigen values:

$$D_1 = |z - 1| \leq 2\epsilon$$

$$D_2 = |z - 2| \leq 2\epsilon$$

$$D_3 = |z - 3| \leq 2\epsilon$$



$$D = \begin{bmatrix} 1 & 0 & 0 \\ 0 & d & 0 \\ 0 & 0 & d \end{bmatrix}, d > 0$$

$$D^{-1}AD$$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1/d & 0 \\ 0 & 0 & 1/d \end{bmatrix} \left[\begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix} + \begin{bmatrix} \epsilon & \epsilon & \epsilon \\ \epsilon & \epsilon & \epsilon \\ \epsilon & \epsilon & 0 \end{bmatrix} \right] \begin{bmatrix} 1 & 0 & 0 \\ 0 & d & 0 \\ 0 & 0 & d \end{bmatrix}$$

$$\left[\begin{bmatrix} 1 & 0 & 0 \\ 0 & 2/d & 0 \\ 0 & 0 & 3/d \end{bmatrix} + \begin{bmatrix} 0 & \epsilon & \epsilon \\ \epsilon/d & 0 & \epsilon/d \\ \epsilon/d & \epsilon/d & 0 \end{bmatrix} \right] \begin{bmatrix} 1 & 0 & 0 \\ 0 & d & 0 \\ 0 & 0 & d \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix} + \epsilon \begin{bmatrix} 0 & d & d \\ 1/d & 0 & 1 \\ 2/d & 1 & 0 \end{bmatrix}$$

$$D_1(\epsilon) = |2-1| \leq 2\epsilon d$$

$$D_2(\epsilon) = |2-2| \leq \frac{\epsilon}{d} + \epsilon = \epsilon \left(1 + \frac{1}{d}\right)$$

$$D_3(\epsilon) = |2-3| \leq \epsilon \left(1 + \frac{1}{d}\right)$$

The estimate for $d, \tilde{d} \approx 1$ can be improved by choosing $d \approx \frac{\epsilon}{2}$

$$\text{or } d < 1$$

What is the best we can do?

To prove:-

$$(a) \quad |\tilde{d}_j - d_j| \leq K(v) \|SA\|_2$$

Proof:-

using (i) & (iv) conditions of Q6.1.

$$\|SA\|_2 \leq \epsilon \Rightarrow \|\tilde{d}_j I - A\|_2 \geq \epsilon^{-1}$$
$$\Rightarrow \epsilon \|\tilde{d}_j I - A\|_2 \geq 1$$

$$\text{from (i)} \Rightarrow \|SA\|_2 \|\tilde{d}_j I - A\|_2 \leq \epsilon \|\tilde{d}_j I - A\|_2$$
$$= \|SA\|_2 \|\tilde{d}_j I - A\|_2 \geq 1$$

$$\text{Now, } A = V \Lambda V^{-1}$$

$$\Rightarrow \|SA\|_2 \|\tilde{d}_j I - V \Lambda V^{-1}\|_2 \geq 1$$

$$= \|SA\|_2 \|\tilde{d}_j VV^{-1} - V \Lambda V^{-1}\|_2 \geq 1$$

$$= \|SA\|_2 \|\tilde{d}_j V(\tilde{d}_j I - \Lambda)V^{-1}\|_2 \geq 1$$

$$= \|SA\|_2 \|V(\tilde{d}_j^2 \Lambda) V^{-1}\|_2 \geq 1$$

$$= \|SA\|_2 \|V\|_2 \|\tilde{d}_j I - \Lambda\|_2 \|V^{-1}\|_2 \geq 1$$

$$= \|SA\|_2 \|V\|_2 \|\tilde{d}_j I - \Lambda\|_2 \geq 1$$

$$= \|SA\|_2 K(v) \|\tilde{d}_j I - \Lambda\|_2 \geq 1$$

$$\|\tilde{d}_j I - \Lambda\|_2 = \max \frac{\|\tilde{d}_j I - \Lambda\|_2}{\|x\|_2}$$
$$= \max_{d_j \in \Lambda(A)} \frac{1}{|\tilde{d}_j - d_j|} = \min_{d_j \in \Lambda(A)} |\tilde{d}_j - d_j|$$

$$\|SA\|_2 K(v) \geq 1$$

In case of normal matrices,

V is unitary matrix)

$$\therefore \|V\|_2 = \|V^{-1}\|_2 = 1$$

$$\Rightarrow \kappa(V) = 1$$

$$\therefore \underbrace{|d_j - d_i| \leq \|dA\|_2}_{\text{Proved}} \quad \text{Proved}$$

(7)

```
%===== Q(4) =====
%it provides [A] matrix
%then it calls function hessenberg to get [W,H] and then, that W is
%used for calling function formQ that provides Q
%finally, it provides error norm
%=====
clc
clear all
m=5;
for i=1:m
    for j=1:m
        if (i==j)
            A(i,j)=9;
        else
            A(i,j)= 1/(i+j);
        end
    end
end
[W,H]= hessenberg(A);
[Q]= formQ(W);
% A matrix
A1= Q*H*Q';
disp('A1 = QHQ* is')
A1
% Hessenberg matrix
H
% W
W
%Q
Q
%=====Error=====
disp('*****Error*****')
fprintf('||Q*Q-I|| = %8.2e\n',norm(Q'*Q-eye(m),2));
fprintf('||A-QHQ*||=%8.2e \n',norm(A-A1,2));
%
```

A1 = QHQ* is

A1 =

9.0000	0.3333	0.2500	0.2000	0.1667
0.3333	9.0000	0.2000	0.1667	0.1429
0.2500	0.2000	9.0000	0.1429	0.1250
0.2000	0.1667	0.1429	9.0000	0.1111
0.1667	0.1429	0.1250	0.1111	9.0000

H =

9.0000	-0.4913	0	0	0
-0.4913	9.4289	0.1080	-0.0000	0.0000
0	0.1080	8.8463	0.0400	-0.0000
0	0	0.0400	8.8507	-0.0208

0 -0.0000 0 -0.0208 8.8741

W =

0	0	0
0.9161	0	0
0.2777	-0.8281	0
0.2222	-0.3721	-0.7992
0.1851	-0.4194	-0.6010

Q =

1.0000	0	0	0	0
0	-0.6785	0.6754	-0.2850	-0.0479
0	-0.5088	-0.1666	0.7519	0.3847
0	-0.4071	-0.4524	0.0300	-0.7929
0	-0.3392	-0.5580	-0.5938	0.4701

*****Error*****

$\|Q^*Q - I\| = 3.52e-16$

$\|A - QHQ^*\| = 6.64e-15$

```
[m,n]=size(W);  
x=eye(m);  
for k=n:-1:1  
    x(k:m,:)=x(k:m,:)-2*W(k:m,k)*(W(k:m,k) '*x(k:m,:));  
end  
Q=x;  
end  
%
```

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```
function [W,H]= hessenberg(A)
%
%this function transforms A to upper hessenberg form
%Input:
%      m by m [A] matrix
%Output:
%      W- matrix of householder vectors (v(k))
%      H- upper hessenberg matrix
%
m=size(A,1);
for k=1:m-2
    x=A(k+1:m,k);
    v=sign(x(1))* (norm(x,2)*eye(m-k,1))+x;
    v=v/norm(v,2);
    A(k+1:m,k:m)= A(k+1:m,k:m)-2*v*(v'*A(k+1:m,k:m));
    A(1:m,k+1:m)= A(1:m,k+1:m)-2*(A(1:m,k+1:m)*v)*v';
    W(k+1:m,k)=v;
end
H=A ;
end
```