

Due: Monday February 14, 2022

Problem Set 4

NPDE is the textbook *Numerical Partial Differential Equations*. Submissions are due in the LMS, and must be typeset (e.g. L^AT_EX).

1. (0 pts.) **Rework PS 3, number 4 using the backward Euler time integrator**

$$D_{+t}v_j^n = \nu D_{+x}D_{-x}v_j^{n+1} + f_j^{n+1}$$

Notice now that you can take a large time step (e.g. $\nu\Delta t/\Delta x$ fixed), but in doing so the observed temporal accuracy is only $O(\Delta t)$. For reference refer to Section 2.6 in the text.

The following discretization scheme is expanded and written as

$$v_j^{n+1} = v_j^n + r \left(v_{j+1}^{n+1} - 2v_j^{n+1} + v_{j-1}^{n+1} \right) + \Delta t f_j^{n+1}$$

This can be re-written in the form,

$$-rv_{j-1}^{n+1} + (1+2r)v_j^{n+1} - rv_{j+1}^{n+1} = v_j^n + \Delta t f_j^{n+1}$$

Now, to deal with the boundary conditions, I chose to use Implicit compatibility condition for the Dirichlet BC specified on the left boundary and an Implicit Neumann for the BC specified on the right boundary.

$$\begin{aligned} v_{-1}^{n+1} - 2v_0^{n+1} + v_1^{n+1} &= \Delta x^2 \frac{\gamma_L'(t_n)}{\nu} \\ v_{N+1}^{n+1} - v_{N-1}^{n+1} &= 2\Delta x \gamma_R(t_n) \end{aligned}$$

Listing 1: Heat Equation - Order 4 (Q.3b)

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1 function [err_norm , x , uhat , u_ex , A] = HeatEqn_ImplicitForcing(N,r,xlim1,xlim2,...
2                                     tlim1,tlim2)
3 % $Author: Vignesh Ramakrishnan$
4 % $RIN: 662028006$
5 %  $u_t - \nu u_{xx} = f(x,t)$ 
6 % s.t  $u(x,0) = u_0(x)$ 
7 %  $u(0,t) = \gamma_L(t)$ 
8 %  $u_x(1,t) = \gamma_R(t)$ 
9 %  $u_{ex} = 2\cos(x)\cos(t)$ 
10 % This function is a method to prove that the Difference methods work and
11 % will be a good approximate to the exact solution. The task is to find
12 % functions  $f(x,t)$ ,  $u_0(x)$ ,  $\gamma_L(t)$  and  $\gamma_R(t)$ , plug it in
13 % and solve using the scheme:  $D_{+t} v^{n+1}_j = \nu D_{+x} D_{-x} v^{n+1}_j + f^{n+1}_j$ 
14 % Inputs: N          - Number of elements
15 %              r      - CFL number

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16 %      xlim1      - left end of the spatial boundary
17 %      xlim2      - right end of the spatial boundary
18 %      tlim1      - start time of simulation
19 %      tmin2      - end time of simulation
20 % Output: err_norm - L2 norm of the error between the exact solution and
21 %                  numerical solution
22
23 nu  = 1;          % Co-efficient of heat conduction
24
25 u0  = @(x) 2*cos(x);          % Initial condition
26 gL  = @(t) 2*cos(t);          % Drichlet BC on Left Boundary
27 gR  = @(t) -2*sin(1)*cos(t);  % Neumann BC on Right Boundary
28 u0t = @(t) -2*sin(t);          % u_t @ x=0
29 f   = @(x,t) 2*cos(x)*(cos(t)-sin(t)); % Forcing function f
30
31 dx  = (xlim2-xlim1)/N;        % dx - spatial discretization
32
33 dt   = r*dx^2;                % r = CFL number
34
35 ng   = 1 ;                    % number of ghost points at BC
36 NP   = N+1+2*ng;              % Total number of spatial points
37 ja   = ng+1;                  % xlim1 's index number
38 jb   = NP-ng;                 % xlim2 's index number
39
40 x    = (xlim1:dx:xlim2);       % Spatial locations x
41 t    = (tlim1:dt:tlim2);       % Temporal locations t
42
43 u_prev = zeros(NP,1);          % Solution at previous timestep
44 u_curr = zeros(NP,1);          % Solution at current timestep
45
46 % set initial conditions for the spatial grid
47 u_prev(ja:jb) = u0(x);
48 u_prev(ja)    = gL(tlim1);
49
50 % Set Compatability boundary condition
51 u_prev(ng)     = (u0t(tlim1) - f(xlim1,tlim1))*dx^2 ...
52                + 2*u_prev(ja) - u_prev(ja+1);
53 % Set Neumann boundary condition
54 u_prev(NP)     = u_prev(jb-1) + 2*gR(tlim1)*dx;
55
56 % create Matrix A
57 A = zeros(NP);
58
59 for j = ng:NP
60     if (j==ng)
61         A(j,ng) = 1;
62         A(j,ja) = -2;
63         A(j,ja+1) = 1;

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64     elseif (j==NP)
65         A(j,jb-1) = -1;
66         A(j,NP)   = 1;
67     else
68         A(j,j-1)   = -r;
69         A(j,j)     = 1+2*r;
70         A(j,j+1)   = -r;
71     end
72 end
73
74 RHS = zeros(NP,1);
75
76 % find implicit solution each time step
77 for i=2:length(t)
78     for j=ng:NP
79         if j==ng
80             RHS(j) = dx^2*u0t(t(i))/nu;
81         elseif j==NP
82             RHS(j) = 2*dx*gR(t(i));
83         else
84             RHS(j) = u_prev(j) + f(x(j-1),t(i))*dt;
85         end
86     end
87     u_curr = A\RHS;
88 end
89
90 u_ex = 2*cos(x)*cos(tlim2);
91 uhat = u_curr(ja:jb);
92 err   = u_ex - u_prev(ja:jb);
93 err_norm = norm(err);
94
95 end

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In Fig 1, $r = 0.6$ which should be unstable in the previous discretization scheme, but it produces results in this Implicit scheme but the error varies linearly with time step.

2. (10 pts.) **Prove that the Lax-Friedrichs scheme**

$$v_j^{n+1} = \frac{1}{2}(v_{j+1}^n + v_{j-1}^n) - \frac{R}{2}(v_{j+1}^n - v_{j-1}^n)$$

is convergent in the max-norm to the solution of the PDE $u_t + au_x = 0$ for $|R| \leq 1$ with $R = a\Delta t/\Delta x$.

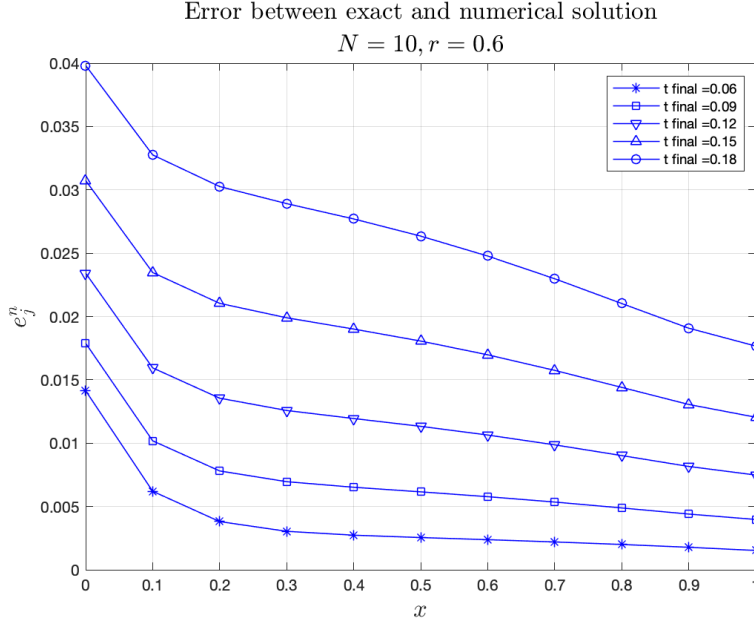


Figure 1: Error between exact and numerical solution

$$v_j^{n+1} = \left(\frac{1-R}{2} \right) v_{j+1}^n + \left(\frac{1+R}{2} \right) v_{j-1}^n$$

Let, $e_j^n = v_j^n + u_j^n$

(Assume u is smooth and u_j^n is a discrete value of u in the spatial grid.)

$$e_j^{n+1} = \left(\frac{1-R}{2} \right) e_{j+1}^n + \left(\frac{1+R}{2} \right) e_{j-1}^n - \left\{ u_j^{n+1} - \left(\frac{1-R}{2} \right) u_{j+1}^n - \left(\frac{1+R}{2} \right) u_{j-1}^n \right\}$$

We can compute the truncation error as follows,

$$\begin{aligned} u_j^{n+1} &= \left[u + \Delta t u_t + \frac{\Delta t^2}{2!} u_{tt} + \frac{\Delta t^3}{3!} u_{ttt} + \mathcal{O}(\Delta t^4) \right]_j^n \\ u_{j+1}^n &= \left[u + \Delta x u_x + \frac{\Delta x^2}{2!} u_{xx} + \frac{\Delta x^3}{3!} u_{xxx} + \mathcal{O}(\Delta x^4) \right]_j^n \\ u_{j-1}^n &= \left[u - \Delta x u_x + \frac{\Delta x^2}{2!} u_{xx} - \frac{\Delta x^3}{3!} u_{xxx} + \mathcal{O}(\Delta x^4) \right]_j^n \end{aligned}$$

$$\begin{aligned}
u_j^{n+1} - \left(\frac{1-R}{2}\right) u_{j+1}^n - \left(\frac{1+R}{2}\right) u_{j-1}^n = \\
[\Delta t u_t + \frac{\Delta t^2}{2!} u_{tt} + \mathcal{O}(\Delta t^3) + \\
R \Delta x u_x + R \frac{\Delta x^3}{3!} u_{xxx} + \dots \dots \\
- \frac{\Delta x^2}{2!} u_{xx} - \frac{\Delta x^4}{4!} u_{xxxx} + \mathcal{O}(\Delta x^6)]_j^n
\end{aligned}$$

Combining the terms in blue, we get,

$$(\Delta t u_t + R \Delta x u_x) = \Delta t (u_t + a u_x) = 0$$

Now, combining this we get the truncation error to be,

$$\begin{aligned}
u_j^{n+1} - \left(\frac{1-R}{2}\right) u_{j+1}^n - \left(\frac{1+R}{2}\right) u_{j-1}^n &= \mathcal{O}(\Delta t^2) + \mathcal{O}(\Delta t \Delta x^2) + \mathcal{O}(\Delta x^2) \approx A (\Delta t^2 + \Delta t \Delta x^2 + \Delta x^2) \\
\tau_j^n &= A (\Delta t^2 + \Delta t \Delta x^2 + \Delta x^2)
\end{aligned}$$

The error equation becomes,

$$\begin{aligned}
e_j^{n+1} &= \left(\frac{1-R}{2}\right) e_{j+1}^n + \left(\frac{1+R}{2}\right) e_{j-1}^n + \tau_j^n \\
e_j^{n+1} &= \left(\frac{1-R}{2}\right) e_{j+1}^n + \left(\frac{1+R}{2}\right) e_{j-1}^n + A (\Delta t^2 + \Delta t \Delta x^2 + \Delta x^2)
\end{aligned}$$

Take the max norm of the above equation (absolute value) and set $E^n = \max_j e_j^n$

$$\text{If, } k = 1 - R = 1 + (-R) \text{ and, } 0 \leq (|R| = m^2) \leq 1$$

$$0 \leq \left| \frac{1-R}{2} \right| \leq \frac{1}{2} (|1| + |-R|) \leq 1$$

$$\text{Similarly, } 0 \leq \left| \frac{1+R}{2} \right| \leq \frac{1}{2} (|1| + |R|) \leq 1$$

$$\left| e_j^{n+1} \right| \leq \left(\frac{1-R}{2}\right) |e_{j+1}^n| + \left(\frac{1+R}{2}\right) |e_{j-1}^n| + A (\Delta t^2 + \Delta t \Delta x^2 + \Delta x^2)$$

$$\begin{aligned}
E^{n+1} &\leq E^n + A (\Delta t^2 + \Delta t \Delta x^2 + \Delta x^2) \\
&\leq E^{n-1} + 2A (\Delta t^2 + \Delta t \Delta x^2 + \Delta x^2) \\
&\leq E^{n-2} + 3A (\Delta t^2 + \Delta t \Delta x^2 + \Delta x^2) \\
&\vdots \\
&\vdots \\
&\leq E^0 + (n+1) A (\Delta t^2 + \Delta t \Delta x^2 + \Delta x^2) \\
&\leq (n+1) A (\Delta t^2 + \Delta t \Delta x^2 + \Delta x^2), \text{ as } E^0 = 0 \\
&\leq (n+1) A \left(\frac{R^2}{a^2} \Delta x^2 + \frac{R}{a} \Delta x^3 + \Delta x^2 \right) \rightarrow 0, \text{ as, } \Delta x \rightarrow 0
\end{aligned}$$

Hence, it is convergent.

3. (10 pts.) **Prove that the scheme**

$$D_{+t}v_j^n = \nu D_{+x}D_{-x}v_j^n + aD_{0x}v_j^n$$

is convergent in the max-norm to the solution of the PDE $u_t = \nu u_{xx} + au_x$, under certain constraints on Δx and Δt . What are these constraints? Use the notation $r = \nu\Delta t/\Delta x^2$ and $\sigma = a\Delta t/\Delta x$.

$$\begin{aligned}\frac{v_j^{n+1} - v_j^n}{\Delta t} &= \frac{\nu}{\Delta x^2} (v_{j+1}^n - 2v_j^n + v_{j-1}^n) + \frac{a}{2\Delta x} (v_{j+1}^n - v_{j-1}^n) \\ v_{j+1}^n &= v_j^n + r (v_{j+1}^n - 2v_j^n + v_{j-1}^n) + \frac{\sigma}{2} (v_{j+1}^n - v_{j-1}^n) \\ v_{j+1}^n &= \left(r - \frac{\sigma}{2}\right) v_{j-1}^n + (1 - 2r) v_j^n + \left(r + \frac{\sigma}{2}\right) v_{j+1}^n \\ v_{j+1}^n &= (1 - 2r) v_j^n + r [v_{j+1}^n + v_{j-1}^n] + \frac{\sigma}{2} (v_{j+1}^n - v_{j-1}^n)\end{aligned}$$

Performing a DFT,

$$\begin{aligned}\frac{1}{\sqrt{2\pi}} \sum_{j=-\infty}^{\infty} e^{-ij\xi} v_j^{n+1} &= \hat{V}^{n+1} \\ \frac{1}{\sqrt{2\pi}} \sum_{j=-\infty}^{\infty} e^{-ij\xi} v_j^n &= \hat{V}^n \\ \frac{1}{\sqrt{2\pi}} \sum_{j=-\infty}^{\infty} e^{-i(j)\xi} v_{j+1}^n &= \frac{1}{\sqrt{2\pi}} \sum_{j=-\infty}^{\infty} e^{-i(m-1)\xi} v_m^n = e^{i\xi} \hat{V}^n \\ \frac{1}{\sqrt{2\pi}} \sum_{j=-\infty}^{\infty} e^{-ij\xi} v_{j-1}^n &= e^{-i\xi} \hat{V}^n\end{aligned}$$

Substituting it into the equation,

$$\begin{aligned}\hat{V}^{n+1} &= (1 - 2r) \hat{V}^n + r [e^{i\xi} + e^{-i\xi}] \hat{V}^n + \frac{\sigma}{2} [e^{i\xi} - e^{-i\xi}] \hat{V}^n \\ \hat{V}^{n+1} &= (1 - 2r + 2r \cos \xi + i\sigma \sin \xi) \hat{V}^n \\ \hat{V}^{n+1} &= (1 - 2r(1 - \cos \xi) + i\sigma \sin \xi) \hat{V}^n \\ |a(\xi)|^2 &= (1 - 2r(1 - \cos \xi))^2 + (\sigma \sin \xi)^2 \leq 1 \\ \implies |a(\xi)|^2 &= 1 + 4r^2(1 - \cos \xi)^2 - 4r(1 - \cos \xi) + \sigma^2(1 - \cos^2 \xi) \leq 1\end{aligned}$$

Let $z = \cos \xi$

$$4r^2(1 - z) - 4r + \sigma^2(1 + z) \leq 0$$

If $z = -1$, $r \leq \frac{1}{2}$.

If $z = 1$, $\sigma^2 \leq 2r \leq 1$.

Therefore, the 2 constraints are,

$$\Delta x^2 - a^2 \Delta t^2 \geq 0 \tag{1}$$

$$\Delta x^2 - 2\nu \Delta t \geq 0 \tag{2}$$

4. (15 pts.) Determine the formal order of accuracy of the following difference equations (i.e. investigate the truncation error). Throughout, use the definitions $r = \nu\Delta t/\Delta x^2$ and $\sigma = a\Delta t/\Delta x$.

(a) For the PDE $u_t = \nu u_{xx} - au_x$ consider the discretization

$$D_{+t}v_j^n = \nu D_{+x}D_{-x}v_j^n - aD_{0x}v_j^n.$$

Let $e_j^n = v_j^n - u_j^n$,

$$\begin{aligned} D_{+t}(e_j^n + u_j^n) &= \nu D_{+x}D_{-x}(e_j^n + u_j^n) - aD_{0x}(e_j^n + u_j^n) \\ D_{+t}e_j^n &= \nu D_{+x}D_{-x}e_j^n - aD_{0x}e_j^n - (D_{+t}u_j^n - \nu D_{+x}D_{-x}u_j^n + aD_{0x}u_j^n) \end{aligned}$$

$$\begin{aligned} D_{+t}u_j^n &= \left[u_t + \frac{\Delta t}{2}u_{tt} + \mathcal{O}(\Delta t^2) \right]_j^n = [u_t + \mathcal{O}(\Delta t)]_j^n \\ D_{+x}D_{-x}u_j^n &= \left[u_{xx} + \frac{\Delta x^2}{12}u_{xxxx} + \mathcal{O}(\Delta x^4) \right]_j^n = [u_{xx} + \mathcal{O}(\Delta x^2)]_j^n \\ D_{0x}u_j^n &= \left[u_x + \frac{\Delta x^2}{3!}u_{xxx} + \mathcal{O}(\Delta x^4) \right]_j^n = [u_x + \mathcal{O}(\Delta x^2)]_j^n \end{aligned}$$

$$D_{+t}e_j^n = \nu D_{+x}D_{-x}e_j^n - aD_{0x}e_j^n - \left([u_t - \nu u_{xx} + au_x + \mathcal{O}(\Delta t) + \mathcal{O}(\Delta x^2)]_j^n \right)$$

The terms in blue sum up to 0 since it is the actual PDE.

Therefore, truncation error is,

$$\tau_j^n = \mathcal{O}(\Delta t) + \mathcal{O}(\Delta x^2)$$

(b) For the PDE $u_t = \nu u_{xx} - au_x$ consider the discretization

$$D_{+t}v_j^n = \nu D_{+x}D_{-x}v_j^{n+1} - aD_{0x}v_j^{n+1}.$$

Similar to last problem,

$$D_{+t}e_j^n = \nu D_{+x}D_{-x}e_j^{n+1} - aD_{0x}e_j^{n+1} - \left(D_{+t}u_j^n - \nu D_{+x}D_{-x}u_j^{n+1} + aD_{0x}u_j^{n+1} \right)$$

$$\begin{aligned} D_{+t}u_j^n &= \left[u_t + \frac{\Delta t}{2}u_{tt} + \mathcal{O}(\Delta t^2) \right]_j^n = [u_t + \mathcal{O}(\Delta t)]_j^n \\ D_{+x}D_{-x}u_j^{n+1} &= \left[u_{xx} + \frac{\Delta x^2}{12}u_{xxxx} + \mathcal{O}(\Delta x^4) \right]_j^{n+1} \\ &= [u_{xx}]_j^{n+1} + \frac{\Delta x^2}{12}[u_{xxxx}]_j^{n+1} + [\mathcal{O}(\Delta x^4)]_j^{n+1} \\ &= [u_{xx} + \Delta t u_{txx} + \mathcal{O}(\Delta t^2)]_j^n + \frac{\Delta x^2}{12}[u_{xxxx} + \Delta t u_{txxxx} + \mathcal{O}(\Delta t^2)]_j^n + \mathcal{O}(\Delta x^4) \\ D_{0x}u_j^{n+1} &= \left[u_x + \frac{\Delta x^2}{3!}u_{xxx} + \mathcal{O}(\Delta x^4) \right]_j^{n+1} \\ &= [u_x + \Delta t u_{tx} + \mathcal{O}(\Delta t^2)]_j^n + \frac{\Delta x^2}{3!}[u_{xxx} + u_{txxx} + \mathcal{O}(\Delta t^2)]_j^n + \mathcal{O}(\Delta x^4) \end{aligned}$$

$$D_{+t}u_j^n - \nu D_{+x}D_{-x}u_j^{n+1} + aD_{0x}u_j^{n+1} = [u_t - \nu u_{xx} + au_x + \mathcal{O}(\Delta t) + \mathcal{O}(\Delta x^2)]_j^n$$

$$\tau_j^n = \mathcal{O}(\Delta t) + \mathcal{O}(\Delta x^2)$$

(c) For the PDE $u_t = -au_x$ consider the discretization

$$D_{+t}v_j^n = -aD_{-x}v_j^{n+1}.$$

Similar to the previous problem,

$$D_{+t}e_j^n = -aD_{-x}e_j^{n+1} - \left(D_{+t}u_j^n + aD_{-x}u_j^{n+1}\right)$$

$$D_{+t}u_j^n = \left[u_t + \frac{\Delta t}{2}u_{tt} + \mathcal{O}(\Delta t^2)\right]_j^n = [u_t + \mathcal{O}(\Delta t)]_j^n$$

$$D_{-x}u_j^{n+1} = \left[u_x - \frac{\Delta x^2}{2!}u_{xx} + \frac{\Delta x^3}{3!}u_{xxx} + \mathcal{O}(\Delta x^4)\right]_j^{n+1}$$

$$= [u_x + \Delta t u_{tx} + \mathcal{O}(\Delta t^2)]_j^n - \frac{\Delta x^2}{2!} [u_{xx} + \Delta t u_{txx} + \mathcal{O}(\Delta t^2)]_j^n + \mathcal{O}(\Delta x^4)$$

$$\tau_j^n = [u_t + au_x + \mathcal{O}(\Delta t) + \mathcal{O}(\Delta x^2)]_j^n = \mathcal{O}(\Delta t) + \mathcal{O}(\Delta x^2)$$

5. (15 pts.) Investigate the stability of the schemes from number 4 above, and discuss any limitations on parameters that you find are required to guarantee stability. Again use the definitions $r = \nu \Delta t / \Delta x^2$ and $\sigma = a \Delta t / \Delta x$. Hint: using the DFT is probably simplest.

I'm going to assume that the coefficients ν, a are positive in all three cases considered. So if, $\Delta t, \Delta x$ are set to be positive numbers, the parameters r, σ are positive constants.

(a) For the PDE $u_t = \nu u_{xx} - au_x$, consider the discretization

$$D_{+t}v_j^n = \nu D_{+x}D_{-x}v_j^n - aD_{0x}v_j^n$$

$$\frac{v_j^{n+1} - v_j^n}{\Delta t} = \frac{\nu}{\Delta x^2} (v_{j+1}^n - 2v_j^n + v_{j-1}^n) - \frac{a}{2\Delta x} (v_{j+1}^n - v_{j-1}^n)$$

$$v_{j+1}^n = v_j^n + r (v_{j+1}^n - 2v_j^n + v_{j-1}^n) - \frac{\sigma}{2} (v_{j+1}^n - v_{j-1}^n)$$

$$v_{j+1}^n = \left(r + \frac{\sigma}{2}\right) v_{j-1}^n + (1 - 2r) v_j^n + \left(r - \frac{\sigma}{2}\right) v_{j+1}^n$$

$$v_{j+1}^n = (1 - 2r) v_j^n + r [v_{j+1}^n + v_{j-1}^n] - \frac{\sigma}{2} (v_{j+1}^n - v_{j-1}^n)$$

Performing a DFT,

$$\begin{aligned}
\frac{1}{\sqrt{2\pi}} \sum_{j=-\infty}^{\infty} e^{-ij\xi} v_j^{n+1} &= \hat{V}^{n+1} \\
\frac{1}{\sqrt{2\pi}} \sum_{j=-\infty}^{\infty} e^{-ij\xi} v_j^n &= \hat{V}^n \\
\frac{1}{\sqrt{2\pi}} \sum_{j=-\infty}^{\infty} e^{-i(j)\xi} v_{j+1}^n &= \frac{1}{\sqrt{2\pi}} \sum_{j=-\infty}^{\infty} e^{-i(m-1)\xi} v_m^n = e^{i\xi} \hat{V}^n \\
\frac{1}{\sqrt{2\pi}} \sum_{j=-\infty}^{\infty} e^{-ij\xi} v_{j-1}^n &= e^{-i\xi} \hat{V}^n
\end{aligned}$$

Substituting it into the equation,

$$\begin{aligned}
\hat{V}^{n+1} &= (1 - 2r) \hat{V}^n + r \left[e^{i\xi} + e^{-i\xi} \right] \hat{V}^n - \frac{\sigma}{2} \left[e^{i\xi} - e^{-i\xi} \right] \hat{V}^n \\
\hat{V}^{n+1} &= (1 - 2r + 2r \cos \xi - i\sigma \sin \xi) \hat{V}^n \\
\hat{V}^{n+1} &= (1 - 2r(1 - \cos \xi) - i\sigma \sin \xi) \hat{V}^n \\
|a(\xi)|^2 &= (1 - 2r(1 - \cos \xi))^2 + (\sigma \sin \xi)^2 \leq 1 \\
\implies |a(\xi)|^2 &= 1 + 4r^2(1 - \cos \xi)^2 - 4r(1 - \cos \xi) + \sigma^2(1 - \cos^2 \xi) \leq 1
\end{aligned}$$

Let $z = \cos \xi$

$$4r^2(1 - z) - 4r + \sigma^2(1 + z) \leq 0$$

If $z = -1$, $r \leq \frac{1}{2}$.

If $z = 1$, $\sigma^2 \leq 2r \leq 1$.

If these conditions are met, then the scheme is stable.

(b) **For the PDE $u_t = \nu u_{xx} - au_x$, consider the discretization**

$$D_{+t} v_j^n = \nu D_{+x} D_{-x} v_j^{n+1} - a D_{0x} v_j^{n+1}$$

$$v_j^{n+1} - v_j^n = \left(r - \frac{\sigma}{2} \right) v_{j+1}^{n+1} - 2r v_j^{n+1} + \left(r + \frac{\sigma}{2} \right) v_{j-1}^{n+1}$$

Taking a DFT,

$$\begin{aligned}
\frac{1}{\sqrt{2\pi}} \sum_{j=-\infty}^{\infty} e^{-ij\xi} v_{j+1}^{n+1} &= \frac{1}{\sqrt{2\pi}} \sum_{m=-\infty}^{\infty} e^{-i(m-1)\xi} v_m^{n+1} \equiv e^{i\xi} \hat{V}^{n+1} \\
\frac{1}{\sqrt{2\pi}} \sum_{j=-\infty}^{\infty} e^{-ij\xi} v_{j-1}^{n+1} &= \frac{1}{\sqrt{2\pi}} \sum_{m=-\infty}^{\infty} e^{-i(m+1)\xi} v_m^{n+1} \equiv e^{-i\xi} \hat{V}^{n+1} \\
\cos \xi &= \frac{e^{i\xi} + e^{-i\xi}}{2} \\
\sin \xi &= \frac{e^{i\xi} - e^{-i\xi}}{2i}
\end{aligned}$$

$$\begin{aligned}
\hat{V}^{n+1} - \hat{V}^n &= \left(r - \frac{\sigma}{2}\right) e^{i\xi} \hat{V}^{n+1} - 2r \hat{V}^{n+1} + \left(r + \frac{\sigma}{2}\right) e^{-i\xi} \hat{V}^{n+1} \\
\hat{V}^{n+1} &= \frac{1}{[1 + 2r(1 - \cos \xi) + i\sigma \sin \xi]} \hat{V}^n \\
\implies a(\xi) &= \frac{[1 + 2r(1 - \cos \xi) - i\sigma \sin \xi]}{(1 + 2r(1 - \cos \xi))^2 + \sigma^2 \sin^2 \xi} \\
|a(\xi)|^2 &= \frac{1}{(1 + 2r(1 - \cos \xi))^2 + \sigma^2 \sin^2 \xi}
\end{aligned}$$

If $|a(\xi)| \leq 1$, then this is a stable scheme.

$$\begin{aligned}
\text{If, } \cos \xi &= -1, \\
8r^2 + 4r &\geq 0 \\
4r(2r + 1) &\geq 0
\end{aligned}$$

This is always true since we assumed $r \geq 0$

$$\begin{aligned}
\text{If, } \cos \xi &= 1, \\
4r + 2\sigma^2 &\geq 0
\end{aligned}$$

This is also true since $r \geq 0$ and $\sigma \geq 0$. Hence this is a stable scheme as $|a(\xi)| \leq 1$ always.

(c) [For the PDE \$u_t = -au_x\$ consider the discretization](#)

$$D_{+t}v_j^n = -aD_{-x}v_j^{n+1}.$$

$$\begin{aligned}
v_j^{n+1} - v_j^n &= -\sigma v_j^{n+1} + \sigma v_{j-1}^{n+1} \\
\hat{V}^{n+1} &= \frac{1}{1 + \sigma(1 - e^{-i\xi})} \hat{V}^n \\
e^{-i\xi} &= \cos \xi - i \sin \xi \\
\implies |a(\xi)|^2 &= \frac{1}{(1 + \sigma(1 - \cos \xi))^2 + \sigma^2(1 - \cos^2 \xi)}
\end{aligned}$$

The denominator is positive and always greater than 1, this stable is always stable since $|a(\xi)| \leq 1$