

 rvizarreta hw3 added

Latest commit 5bd1499 9 minutes ago

History

1 contributor

PROBLEM 01 -----

```
In [119]: # IMPORTING REQUIRED PACKAGES AND CONSTANTS
import numpy as np
from scipy.constants import pi

In [120]: # DEFINING AREA FUNCTION (There's a reason for using an array input of parameters, it's in exercise 2)
surface_area = lambda parameters : 4*pi*parameters[0]**2

# DEFINING INITIAL PARAMETERS
r_val, r_uncert = 0.310, 0.001
```

Error propagation method

The uncertainty in the measurement of the surface area S is determined by:

$$\delta S = \left| \frac{\partial S}{\partial r} \delta r \right| = 8\pi r \delta r$$

```
In [121]: # DETERMININIG THE VALUE OF THE SURFACE AREA WITH UNCERTAINTY
S = surface_area([r_val])
delta_S = 8*pi*r_val*r_uncert
print('S = ', S, ' m2 , ΔS = ', delta_S, ' m2')

S =  1.2076282160399165  m2 , ΔS =  0.007791149780902688  m2

Finally:

S = (1000 ± 8) × 10-3 m2
```

Variational method

```
In [122]: delta_up = abs(surface_area([r_val+r_uncert]) - surface_area([r_val]))
delta_down = abs(surface_area([r_val-r_uncert]) - surface_area([r_val]))
delta_S = 0.5*(delta_up + delta_down)
print('S = ', S, ' m2 , ΔS = ', delta_S, ' m2')

S =  1.2076282160399165  m2 , ΔS =  0.007791149780902673  m2

Finally:

S = (1000 ± 8) × 10-3 m2
```

As we can see, the values for the uncertainty in the measurement of S varies slightly within each method. However, for our reporting purposes it remains intact.

PROBLEM 02 -----

```
In [123]: # DEFINING A FUNCTION THAT RETURNS THE UNCERTAINTY USING VARIATIONAL METHOD (Each function must receive a parameters array)
def uncertainty_var(values, deltas, function):
    values, deltas = np.array(values), np.array(deltas)
    delta_matrix = deltas*np.identity(values.shape[0])
    sum = 0
    for delta in delta_matrix:
        #sum += (0.5*(abs(function(val+delta) - function(val)) + abs(function(val-delta) - function(val))))**2
        sum += (0.5*(abs(function(values + delta) - function(values)) + abs(function(values-delta) - function(values))))**2
    return np.sqrt(sum)

In [124]: # TESTING THE FUNCTION ABOVE WITH PROBLEM 1 DATA
print(uncertainty_var([r_val],[r_uncert],surface_area))
print('Works!')

0.007791149780902673
Works!

In [125]: # DEFINING q FUNCTION
q = lambda parameters : parameters[0]*parameters[1]**2 + parameters[0]**2

# DEFINING INITIAL PARAMETERS
x, x_uncert = 8.0, 0.2
y, y_uncert = 4.0, 0.1
```

Error propagation method

The uncertainty in the measurement of q is determined by:

$$\delta q = \sqrt{\left(\frac{\partial q}{\partial x} \delta x\right)^2 + \left(\frac{\partial q}{\partial y} \delta y\right)^2} = \sqrt{[(y^2 + 2x)\delta x]^2 + (2xy\delta y)^2}$$

```
In [126]: # DETERMININIG THE VALUE OF q WITH UNCERTAINTY
q_val = q([x,y])
delta_q = np.sqrt(((y**2 + 2*x)*x_uncert)**2 + (2*x*y*y_uncert)**2)
print('q = ', q_val, ' , Δq = ', delta_q)

q =  192.0  , Δq =  9.05096679918781

Finally

q = 200 ± 9
```

Variational method

```
In [127]: delta_q = uncertainty_var([x,y], [x_uncert,y_uncert], q)
print('q = ', q_val, ' , Δq = ', delta_q)

q =  192.0  , Δq =  9.050966799187806

Finally

q = 200 ± 9
```

As we can see, the values for the uncertainty in the measurement of q varies slightly within each method. However, for our reporting purposes it remains intact.

```
In [ ]:
```