

# **Robert L. Whitney**

[rw429@cornell.edu](mailto:rw429@cornell.edu) || [Portfolio](#)

## **Education:**

### **Cornell University**

Ithaca, NY

*Master of Engineering in Mechanical & Aerospace Engineering - GPA : 3.98*

2020

*Bachelor of Science in Mechanical & Aerospace Engineering - GPA : 3.37*

2016-2020

## **Skills:**

Matlab • Simulink • Arduino • [Analysis and Design of RC Quadcopters](#) • Multirotor Piloting •  
Mechatronics Motors, Sensors, and Actuators • XFLR5 • Fusion 360 • Autodesk • Java • Machine Shop  
Training (Lathe, Milling, GD&T) • Python • C/C++ • Data Structures

## **Specialized Courses:**

Fast Robots • Intelligent Sensor Planning and Control • Design Failure Mode Analysis • Autonomous  
Mobile Robots • Multivariable Control Theory • Feedback & Control Systems • Automotive  
Engineering • Experimental Applications of Mechanical Structures • Intermediate Dynamics •  
Mechatronics

## **Engineering Experience:**

### **Cornell University: SIOS Laboratory**

Ithaca, NY

*CCAT-p Research Team: Controls Subteam Engineer*

Summer 2019-2020

- Implemented mechatronics hardware and software for a high precision metrology robot
- Programmed in Arduino IDE, Python, and Matlab for localizing, actuating, and wireless communication
- Collaborated with 3 other subteams (16 engineers total) to develop the chassis and meet performance specifications

### **Independent Senior Design Project**

Ithaca, NY

[Simulation, Analysis, and Design of an RC Aircraft Autopilot](#)

Spring 2020-Present

- Designed and modeled an airframe in Fusion 360
- Performed an airfoil and control surface simulation in XFLR5 fluid simulation
- Developed a 6DoF simulation of the aircraft and feedback control systems in Matlab and Simulink
- Implementing the autopilot system in hardware with Arduino for navigation and control

### **MAE 5180 : Autonomous Mobile Robots**

Ithaca, NY

Spring 2020

- A graduate course on autonomous localization, mapping, SLAM, path planning, and navigation
- Programmed in Matlab to test algorithms on hardware with iRobot Roombas

## **Accomplishments:**

Cornell Division I Cross Country/Winter/Spring Track • B.S.A. Eagle Scout