Robert L. Whitney

rw429@cornell.edu || Portfolio

Education:

<u>Cornell University</u>

Master of Engineering in Mechanical & Aerospace Engineering - GPA : 3.98

Bachelor of Science in Mechanical & Aerospace Engineering - GPA : 3.37

2016-2020

Skills:

Matlab · Simulink · Arduino · <u>Analysis and Design of RC Quadcopters</u> · Multirotor Piloting · Mechatronics Motors, Sensors, and Actuators · XFLR5 · Fusion 360 · Autodesk · Java · Machine Shop Training (Lathe, Milling, GD&T) · Python · C/C++ · Data Structures

Specialized Courses:

Fast Robots · Intelligent Sensor Planning and Control · Design Failure Mode Analysis · Autonomous Mobile Robots · Multivariable Control Theory · Feedback & Control Systems · Automotive Engineering · Experimental Applications of Mechanical Structures · Intermediate Dynamics · Mechatronics

Engineering Experience:

Cornell University: SIOS Laboratory

Ithaca, NY

CCAT-p Research Team: Controls Subteam Engineer

Summer 2019-2020

- Implemented mechatronics hardware and software for a high precision metrology robot
- Programmed in Arduino IDE, Python, and Matlab for localizing, actuating, and wireless communication
- Collaborated with 3 other subteams (16 engineers total) to develop the chassis and meet performance specifications

Independent Senior Design Project

Ithaca, NY

Simulation, Analysis, and Design of an RC Aircraft Autopilot

Spring 2020-Present

- Designed and modeled an airframe in Fusion 360
- Performed an airfoil and control surface simulation in XFLR5 fluid simulation
- Developed a 6DoF simulation of the aircraft and feedback control systems in Matlab and Simulink
- Implementing the autopilot system in hardware with Arduino for navigation and control

MAE 5180: Autonomous Mobile Robots

Ithaca, NY

Spring 2020

- A graduate course on autonomous localization, mapping, SLAM, path planning, and navigation
- Programmed in Matlab to test algorithms on hardware with iRobot Roombas

Accomplishments:

Cornell Division I Cross Country/Winter/Spring Track • B.S.A. Eagle Scout