

PyLith v3.0 Tutorial

Quasi-static Poroelasticity with No Fault

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Matthew Knepley
Brad Aagaard

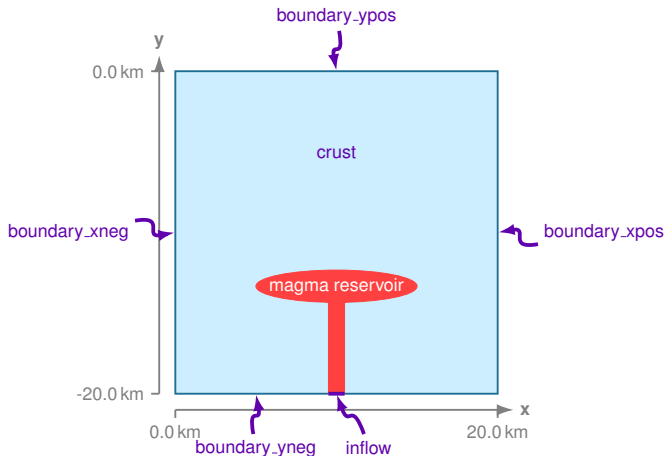


COMPUTATIONAL
INFRASTRUCTURE
for GEODYNAMICS



June 21, 2022

2D Magma Reservoir Using Poroelasticity: `examples/magma-2d`



Model flow and deformation for a magma reservoir with poroelastic properties that differ from the surrounding domain.

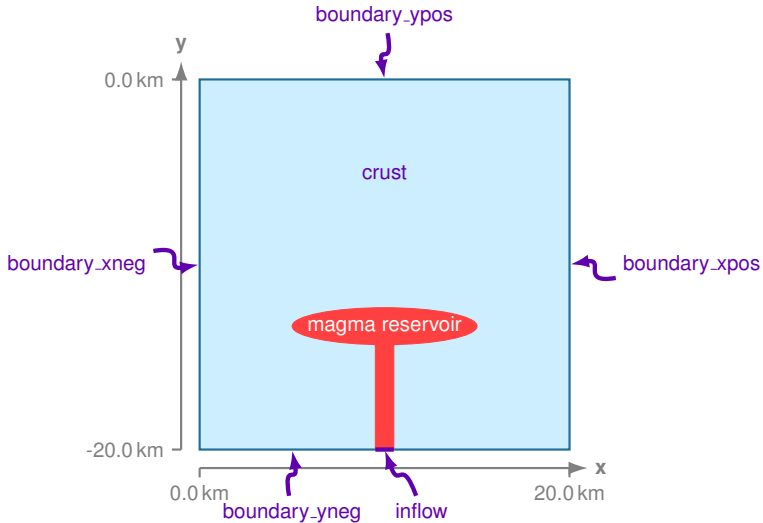
Steps in example

- Step 1 **Magma influx with displacement and pressure boundary conditions**
- Step 2 **Magma influx with updating porosity, displacement and pressure boundary conditions**

Concepts covered

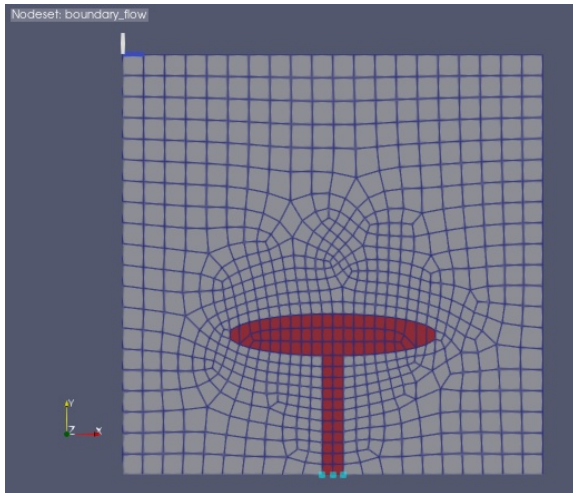
- Generation of mesh using Cubit
- Variable mesh size with distance from the magma reservoir
- Quasistatic simulations for poroelasticity
- Elastic bulk rheology
- Dirichlet fluid pressure boundary condition
- Initial condition for fluid pressure

Cubit: Geometry



Cubit: Creating the finite-element mesh

We create the mesh using geometric primitives



Files used in simulations

Files are in directory `examples/magma-2d`

README.md Brief description of the various examples

- *.cfg** PyLith parameter files

- *.jou** Cubit Journal scripts used to generate the mesh

- *.exo** Finite-element mesh files generated by Cubit

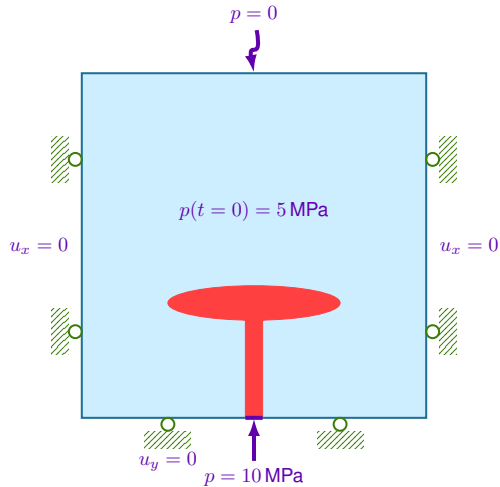
- *.spatialdb** Spatial database files

- viz** Directory containing ParaView Python scripts

- output** Directory containing simulation output; created automatically when running the simulations

Step 1: Overview

Inflation of the magma reservoir



Step 1: Physics

$$\vec{s} = (\vec{u} \quad p \quad \epsilon_v)^T$$

$$\nabla \cdot \boldsymbol{\sigma}(\vec{u}, p) = \vec{0}$$

$$\frac{\partial \zeta(\vec{u}, p)}{\partial t} + \nabla \cdot \vec{q}(p) = 0$$

$$\nabla \cdot \vec{u} - \epsilon_v = 0$$

$$u_x = 0 \text{ on boundary_xneg}$$

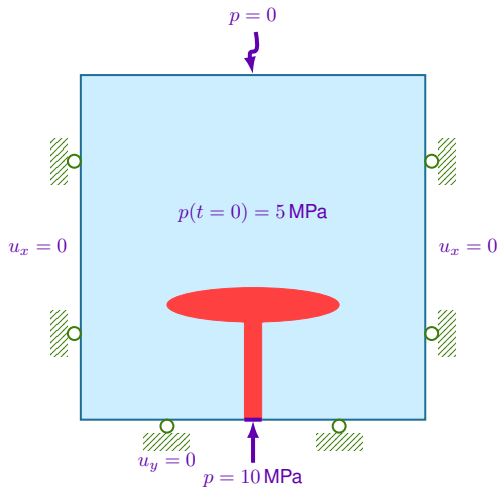
$$u_x = 0 \text{ on boundary_xpos}$$

$$u_y = 0 \text{ on boundary_yneg}$$

$$p = 0 \text{ on boundary_ypos}$$

$$p = 10 \text{ MPa on boundary_flow}$$

$$p(t = 0) = 5 \text{ MPa in domain}$$



Auxiliary Fields

for Quasistatic Linear Isotropic Poroelasticity

Origin	Variable	Description	Position	Notes
Material	ρ_b	Rock Density	0	
	ρ_f	Fluid Density	1	
	μ_f	Fluid Viscosity	2	
	ϕ	Porosity	3	
	\vec{f}_b	Body Force	+1	
	\vec{g}	Gravity	+1	
	γ	Fluid Source	+1	
Rheology	σ_R	Reference Stress	NumAux - 7	
	ϵ_R	Reference Strain	NumAux - 6	
	G	Shear Modulus	NumAux - 5	
	K_d	Drained Bulk Modulus	NumAux - 4	
	α	Biot Coefficient	NumAux - 3	
	M	Biot Modulus	NumAux - 2	$\frac{K_f}{\phi} + \frac{K_s}{\alpha - \phi}$
	k	Permeability	NumAux - 1	
Input	K_s	Solid Grain Bulk Modulus	-	
	K_f	Fluid Bulk Modulus	-	

Step 1: Physics to simulation parameters

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$$p(t = 0) = 5 \text{ MPa in domain}$$

```
[pylithapp.problem]
```

```
solution = pylith.problems.SolnDispPresTracStrain
```

```
[pylithapp.problem.solution.subfields]
```

```
displacement.basis_order = 2
```

```
pressure.basis_order = 1
```

```
trace_strain.basis_order = 1
```

```
[pylithapp.problem]
```

```
normalizer = spatialdata.units.NondimElasticQuasistatic
```

```
normalizer.length_scale = 100.0*m
```

```
normalizer.relaxation_time = 0.2*year
```

```
normalizer.shear_modulus = 10.0*GPa
```



Step 1: Physics to simulation parameters

$$\vec{s} = (\vec{u} \quad p \quad \epsilon_v)^T$$

$$\nabla \cdot \boldsymbol{\sigma}(\vec{u}, p) = \vec{0}$$

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```
[pylithapp.problem]
```

```
materials = [crust, intrusion]
```

```
materials.crust = pylith.materials.Poroelasticity
```

```
materials.intrusion = pylith.materials.Poroelasticity
```

```
[pylithapp.problem.materials]
```

```
crust.bulk_rheology = pylith.materials.IsotropicLinearPoroelasticity
```

```
intrusion.bulk_rheology = pylith.materials.IsotropicLinearPoroelasticity
```

```
[pylithapp.problem.materials.crust]
```

```
description = crust
```

```
label_value = 1
```

```
db_auxiliary_field = spatialdata.spatialdb.UniformDB
```

```
db_auxiliary_field.description = Poroelastic properties for the crust
```

```
db_auxiliary_field.values = [solid_density, fluid_density, fluid_viscosity]
```

```
db_auxiliary_field.data = [ 2500*kg/m**3, 1000*kg/m**3, 0.001*kg/m**s]
```

```
...
```

Step 1: Physics to simulation parameters

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```
[pylithapp.problem]
```

```
bc = [bc_xneg, bc_xpos, bc_yneg, bc_ypos, bc_flow]
```

```
bc.bc_xneg = pylith.bc.DirichletTimeDependent
```

```
bc.bc_xpos = pylith.bc.DirichletTimeDependent
```

```
bc.bc_yneg = pylith.bc.DirichletTimeDependent
```

```
bc.bc_ypos = pylith.bc.DirichletTimeDependent
```

```
bc.bc_flow = pylith.bc.DirichletTimeDependent
```

```
...
```

```
[pylithapp.problem.bc.bc_flow]
```

```
constrained_dof = [0]
```

```
label = boundary_flow
```

```
field = pressure
```

```
db_auxiliary_field = spatialdata.spatialdb.UniformDB
```

```
db_auxiliary_field.description = Flow into external boundary of condu
```

```
db_auxiliary_field.values = [initial_amplitude]
```

```
db_auxiliary_field.data = [10.0*MPa]
```

Step 1: Physics to simulation parameters

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$$p(t = 0) = 5 \text{ MPa in domain}$$

```
[pylithapp.problem]
ic = [domain]
ic.domain = pylith.problems.InitialConditionDomain

[pylithapp.problem.ic.domain]
db = spatialdata.spatialdb.UniformDB
db.description = Initial conditions for domain
db.values = [displacement_x, displacement_y, pressure, trace_strain]
db.data = [0.0*m, 0.0*m, 5.0*MPa, 0.0]
```



Step 1: Input files

`mesh_quad.exo` Finite-element mesh generated using Cubit

`pylithapp.cfg` PyLith parameter file common to all steps

`step01_inflation.cfg` PyLith parameter file

Step 1: Run the simulation

```
pylith step01_inflation.cfg
```

Output

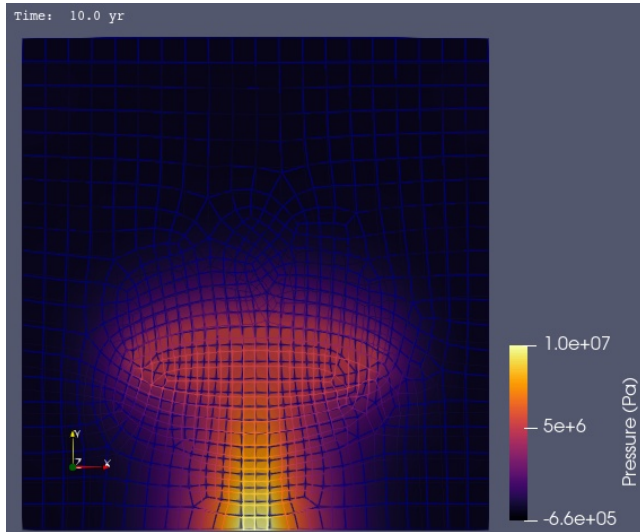
```
>> /Users/baagaard/software/unix/py39-venv/pylith-debug/lib/python3.9/site-packages/pylith/meshio/MeshIOObj.py:44:read
-- meshiocubit(info)
-- Reading finite-element mesh
>> /Users/baagaard/src/cig/pylith/libsrc/pylith/meshio/MeshIOCubit.cc:157:void pylith::meshio::MeshIOCubit::_readVertices(pylith::mesh
-- meshiocubit(info)
-- Component 'reader': Reading 747 vertices.
>> /Users/baagaard/src/cig/pylith/libsrc/pylith/meshio/MeshIOCubit.cc:217:void pylith::meshio::MeshIOCubit::_readCells(pylith::meshio:
-- meshiocubit(info)
-- Component 'reader': Reading 705 cells in 2 blocks.

# -- many lines omitted --

50 TS dt 1. time 49.
   0 SNES Function norm 3.049429649018e-03
   Linear solve converged due to CONVERGED_ATOL iterations 1
   1 SNES Function norm 5.567219918314e-16
   Nonlinear solve converged due to CONVERGED_FNORM_ABS iterations 1
51 TS dt 1. time 50.
>> /Users/baagaard/software/unix/py39-venv/pylith-debug/lib/python3.9/site-packages/pylith/problems/Problem.py:201:finalize
-- timedependent(info)
-- Finalizing problem.
```

Step 1: Visualize results

Run the `viz/plot_dispwrap.py` Python script from within ParaView



Step 2: Physics

$$\vec{s} = (\vec{u} \quad p \quad \epsilon_v \quad \vec{v} \quad P_{dot} \quad E_{dot})^T$$

$$\nabla \cdot \boldsymbol{\sigma}(\vec{u}, p) = \vec{0}$$

$$\frac{\partial \zeta(\vec{u}, p)}{\partial t} + \nabla \cdot \vec{q}(p) = 0$$

$$\nabla \cdot \vec{u} - \epsilon_v = 0$$

$$\dot{\vec{u}} - \vec{0} = \vec{0}$$

$$\dot{p} - P_{dot} = 0$$

$$\dot{\epsilon}_v - E_{dot} = 0$$

$$u_x = 0 \text{ on boundary_xneg}$$

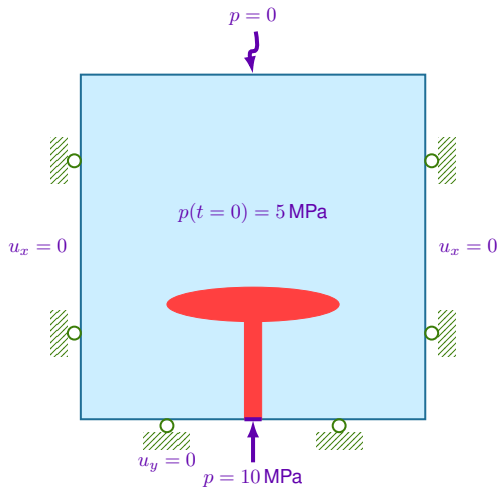
$$u_x = 0 \text{ on boundary_xpos}$$

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Step 1: Physics to simulation parameters

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$$\dot{\vec{u}} - \vec{0} = \vec{0}$$

$$\dot{p} - P_{dot} = 0$$

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$$\frac{\partial \phi}{\partial t} = (\alpha - \phi) \dot{\epsilon}_v + \frac{(1 - \alpha)(\alpha - \phi)}{K_{dr}} \dot{p}$$

$$\phi^{n+1} = \phi^n + \left[(\alpha - \phi^n) \dot{\epsilon}_v^n + \frac{(1 - \alpha)(\alpha - \phi^n)}{K_{dr}} \dot{p}^n \right] \Delta t$$

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```
[pylithapp.problem]
```

```
solution = pylith.problems.SolnDispPresTracStrainVelPdotTdot
```

```
[pylithapp.problem.solution.subfields]
```

```
displacement.basis_order = 2
```

```
pressure.basis_order = 1
```

```
trace_strain.basis_order = 1
```

```
velocity.basis_order = 2
```

```
pressure_t.basis_order = 1
```

```
trace_strain_t.basis_order = 1
```

```
[pylithapp.problem]
```

```
normalizer = spatialdata.units.NondimElasticQuasistatic
```

```
normalizer.length_scale = 100.0*m
```

```
normalizer.relaxation_time = 0.2*year
```

```
normalizer.shear_modulus = 10.0*GPa
```

Step 1: Physics to simulation parameters

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crust.bulk_rheology = pylith.materials.IsotropicLinearPoroelasticity
```

```
intrusion.bulk_rheology = pylith.materials.IsotropicLinearPoroelasticity
```

```
crust.use_state_variables = True
```

```
intrusion.use_state_variables = True
```

```
[pylithapp.problem.materials.crust]
```

```
description = crust
```

```
label_value = 1
```

```
db_auxiliary_field = spatialdata.spatialdb.UniformDB
```

```
db_auxiliary_field.description = Poroelastic properties for the crust
```

```
db_auxiliary_field.values = [solid_density, fluid_density, fluid_viscosity]
```

```
db_auxiliary_field.data = [ 2500*kg/m**3, 1000*kg/m**3, 0.001*kg/m*s]
```

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bc.bc_yneg = pylith.bc.DirichletTimeDependent
```

```
bc.bc_ypos = pylith.bc.DirichletTimeDependent
```

```
bc.bc_flow = pylith.bc.DirichletTimeDependent
```

```
...
```

```
[pylithapp.problem.bc.bc_flow]
```

```
constrained_dof = [0]
```

```
label = boundary_flow
```

```
field = pressure
```

```
db_auxiliary_field = spatialdata.spatialdb.UniformDB
```

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ic.domain = pylith.problems.InitialConditionDomain

[pylithapp.problem.ic.domain]
db = spatialdata.spatialdb.UniformDB
db.description = Initial conditions for domain
db.values = [displacement_x, displacement_y, pressure, trace_strain]
db.data = [0.0*m, 0.0*m, 5.0*MPa, 0.0]
```