

Package ‘implant’

November 20, 2019

Type Package

Title A High-throughput Phenotyping Pipeline for Image Processing and Functional Growth Curve Analysis

Version 0.1.0

Author Ronghao Wang, Yumou Qiu, Yuzhen Zhou, Yuhang Xu, James Schnable

Maintainer Ronghao Wang <rhwang64@gmail.com>

Description The package ``implant" is used for both image processing and functional data analysis, which is able to provide statistical inference for the plant traits directly from the input images. For image processing, the package provides methods including thresholding, hidden Markov random field model, etc. For the growth curve analysis, this package can produce nonparametric curve fitting with its confidence region for plant growth. A functional ANOVA model to test for the treatment and genotype effects of the growth curve dynamics is also provided.

Depends fda,
imager,
dplyr,
spatstat,
png,
matrixcalc,
MASS,
matlab,
SDMTools,

Suggests R.rsp

VignetteBuilder R.rsp

License What license is it under?

Encoding UTF-8

LazyData true

R topics documented:

| | |
|----------------------------|---|
| average_reducing | 2 |
| CI.trt | 3 |
| CI.trt.diff | 4 |
| Color2Gray | 4 |
| ColorB | 5 |
| ColorG | 6 |

| | |
|------------------------------|-----------|
| Color_Exchange | 7 |
| dilation | 7 |
| erosion | 8 |
| extract_pheno | 8 |
| fanova_mean | 9 |
| HMRF_EM | 10 |
| imageBinary | 12 |
| imkmeans | 12 |
| Largest_Connection | 13 |
| sample | 14 |
| Index | 15 |

| | |
|------------------|---|
| average_reducing | <i>Reducing size of an image using the method of averaging in blocks.</i> |
|------------------|---|

Description

This function is used for reducing size of an image by averaging its pixels in blocks.

Usage

```
average_reducing(image, block_nrow = 2, block_ncol = 2)
```

Arguments

- image a pixel matrix or an array of the image for processing.
- block_nrow an integer number, needed to be divisible by number of rows of the pixel-array of the image.
- block_ncol an integer number, needed to be divisible by number of columns of the pixel-array of the image.

Details

This function is used to reduce the size of an image by dividing the original array into several blocks and calculate the average values within each block.

Value

pixel array of the reduced image.

Note

block_nrow and block_ncol must be divisible by number of rows and columns of the pixel-array of the image, respectively. Otherwise, Errors will be reported as: "block_nrow(block_ncol) must be divisible by number of rows(columns) of the pixel-array of the image."

Examples

```
image1 = average_reducing(image1,2,2)
writePNG(image1,"~/Desktop/Visible/imagereduce.png")
```

| | |
|--------|--|
| CI.trt | <i>Estimating a linear combination of treatment effects and obtaining its confidence regions</i> |
|--------|--|

Description

This function is used for estimating a linear combination of treatment effects and its confidence regions. Moreover, it can be used to test the coefficient of the difference between two treatments.

Usage

```
CI.trt(fit,L,alpha)
```

Arguments

| | |
|-------|---|
| fit | An object of output obtained by function "fanova_mean". |
| L | A numeric contrast vector which specifies the linear combination of the parameters of interest. |
| alpha | A positive small number, which is the probability of making type I error. e.g., if you want to calculate the 0.95 confidence band, take alpha = 0.05. |

Value

| | |
|-----|---|
| trt | A t by 1 vector which includes the estimated mean of the treatment mean at different observation time points. |
| ub | A t by 1 vector which indicates the upper bound of the (1-alpha) confidence band at different time points. |
| lb | A t by 1 vector which indicates the lower bound of the (1-alpha) confidence band at different time points. |

Examples

```
fit = fanova_mean(Y.na.mat = Y.na.mat, X = X,
                  tt = seq(from = 0, to = 44, by = 2),
                  formula = toString("~ X[,1]+X[,2]"),
                  K.int = 6, order = 4,
                  d0 = 0, d1 = 2, d2 = 2, lower = -10, upper = 15)
L1 = c(1,0,0,1/3,1/3)
ci1 = CI.trt(fit = fit, L = L1, alpha = 0.05)
plot(tt,ci1$trt,type = "l")
lines(tt,ci1$lb, col = "blue")
lines(tt,ci1$ub, col = "blue")
```

| | |
|-------------|--|
| CI.trt.diff | <i>Testing the significance of the treatment effects of interest by constructing the corresponding confidence regions.</i> |
|-------------|--|

Description

This function can be used for testing the significance of the treatment effects of interest by constructing the corresponding confidence regions. In fact, it is a special case of the function "CI.trt" in this package. This function is more efficient and more easy to use when testing the difference between two treatments.

Usage

```
CI.trt.diff(fit, j1, j2, alpha)
```

Arguments

| | |
|-------|---|
| fit | An object of output obtained by function "fanova_mean". |
| j1 | A positive integer, which indicates the columns of the design matrix corresponding to the treatment of interest. |
| j2 | A positive integer, which indicates the columns of the design matrix corresponding to the treatment of interest. |
| alpha | A positive small number, which is the probability of making type I error. e.g., if you want to calculate the 0.95 confidence band, take alpha = 0.05. |

Examples

```
fit = fanova_mean(Y.na.mat = Y, X = X,
                  tt = seq(from = 0, to = 44, by = 2),
                  formula = toString("~ X[,1]+X[,2]"),
                  K.int = 6, order = 4,
                  d0 = 0, d1 = 2, d2 = 2, lower = -10, upper = 15)

ci_diff = CI.trt(fit = fit, j1 = 5, j2 = 4, alpha = 0.05)
plot(tt, ci_diff$trt, type = "l")
lines(tt, ci_diff$lb, col = "blue")
lines(tt, ci_diff$sub, col = "blue")
```

| | |
|------------|-------------------------------------|
| Color2Gray | <i>Converting RGB to Grayscale.</i> |
|------------|-------------------------------------|

Description

This function is used to convert an RGB image to Grayscale.

Usage

```
Color2Gray(image, weight = c(0.299, 0.587, 0.114))
```

Arguments

| | |
|--------|--|
| image | array of an RGB image file for processing. |
| weight | numeric vector, in which elements are weights for the Red channel of the image, Green channel of the image, and the Blue channel of the image, respectively. |

Value

| | |
|-------|--|
| image | A matrix of pixels of the image converted from RGB to Grayscale. |
|-------|--|

Examples

```
imageGray = Color2Gray(image)
```

| | |
|--------|---|
| ColorB | <i>Identifying the region of interest</i> |
|--------|---|

Description

This function is used to identify the region of interest of an image. Specifically, this function is designed to identify the region of interest of the plant image taken from the UNL greenhouse system, by removing the parts of the image that contains the black bars, but keep the black part of the pot.

Usage

```
ColorB(image, colThreshold = 0.5, colTol = c(5, 5), changefromub = rep(0.1, 3),
changeto = c(1, 1, 1))
```

Arguments

| | |
|--------------|--|
| image | matrix of pixels of the image file for processing. |
| colThreshold | positive real number, which is the threshold level of the signals of the black bars appear in each column. |
| colTol | A 2 by 1 numeric vector, in which elements are some small numbers. Essentially, this argument to add the tolerance when identifying the boundaries of the region of interest. |
| changefromub | A 3 by 1 numeric vector, in which elements refer to the threshold levels of the black bars of the image for the Red Channel, the Green Channel and the Blue Channel, respectively. |
| changeto | A 3 by 1 numeric vector, in which elements refer to the pixel intensities of the colors you want each channel of the eliminated part changed to, respectively. |

Value

| | |
|----|---|
| lb | left bound of the part of the region of interest. |
| rb | right bound of the part of the region of the interest. |
| c | matrix of pixels of the obtained image by applying this function. |

Examples

```
resultColor = ColorB(image)
bound = c(resultColor$lb, resultColor$rb)
imageColor = resultColor$c
```

| | |
|--------|---|
| ColorG | <i>Identifying the region of interest & changing color of particular part of an image</i> |
|--------|---|

Description

This function is used to identify the region of interest, and change the color of particular part of an image. Specifically, this function is designed for the plant images taken by the UNL greenhouse system. It helps identify the lower boundary of the region of interest and change the color of the green strip of an empty pot from green to white. See example image:

Usage

```
ColorG (image, rowThreshold = 0.007, block = 5, Tol = 2, Bthreshold = 60 / 255,
EGThreshold = 0.1, weight = c(-1, 2, -1), changeto = c(1, 1, 1))
```

Arguments

| | |
|--------------|---|
| image | matrix of pixels of the image for processing. |
| rowThreshold | positive real number, which is the threshold value of each row. |
| block | positive integer, which is the moving average of average pixels of each row of the matrix of the matrix. |
| Tol | small number. Essentially, this argument to add the tolerance when identifying the lower boundary of the region of interest. |
| Bthreshold | Value between 0 and 1. It is applied to the sum of the RGB intensities. |
| EGThreshold | Value between 0 and 1. It is applied to the contrast intensity by the specified weight in the function. |
| weight | 3 by 1 numeric vector. The three elements indicate the weight of the pixel intensities of R,G,B, respectively. In default, it takes the value of c(-1,2,-1), which helps to construct a relative green ratio. |
| changeto | numeric vector, in which elements refer to the pixel intensities of the colors you want each channel of the eliminated part changed to, respectively. |

Details

In the example part, this function helps identify the lower boundary of the region of interest, and eliminate the green strip of an empty pot by changing its color from green to white.

Value

| | |
|---------|---|
| uppb | upper bound of the region of interest. |
| lowb | lower bound of the region of interest. |
| rowmean | proportion of the signals of the green strip appear in each row of pixel matrix of the image. |
| c | matrix of pixels of the processed image. |

Examples

```
ColorG (image, rowThreshold = 0.007, block = 5, Tol = 2, Bthreshold = 60 / 255,
EGThreshold = 0.1, weight = c(-1, 2, -1), changeto = c(1, 1, 1))
writePNG(image, "~/Desktop/Visible/imageColorG.png")
```

Color_Exchange

*Exchanging the color of the background and the foreground.***Description**

This function exchanges the color of the background and the subject for a binary image.

Usage

```
color_exchange(image1)
```

Arguments

image1 A pixel matrix of a binary image

Details

The input matrix should be a matrix of 0 and 1 only.

Value

A pixel matrix with exchanging the color of the background and subject.

Examples

```
image = color_exchange(image1)
```

dilation

*Morphological Dilation***Description**

This function is used to perform morphological dilation of an image.

Usage

```
dilation(image, mask = matrix(1, 3, 3))
```

Arguments

image array or matrix of pixels of the original image.
mask matrix constructed by structuring elements.

Value

matrix of pixels of the dilated image.

Examples

```
imageBD = dilation(imageB, mask = matrix(1, 5, 5))
```

| | |
|---------|------------------------------|
| erosion | <i>Morphological Erosion</i> |
|---------|------------------------------|

Description

This function is used to perform morphological erosion of an image.

Usage

```
erosion(image, mask = matrix(1, 3, 3))
```

Arguments

| | |
|-------|---|
| image | matrix of pixels of the original image. |
| mask | matrix constructed by structuring elements. |

Value

matrix of pixels of the eroded image.

Examples

```
imageBDE = erosion( imageBD, mask = matrix(1, 5, 5) )
```

| | |
|---------------|--|
| extract_pheno | <i>Extract phenotypical features from segmented images</i> |
|---------------|--|

Description

This function extract phenotypical features from segmented images.

Usage

```
extract_pheno(processed_image, Xsize = 1, Ysize = 1, a = 1, b = 1)
```

Arguments

| | |
|-----------------|---|
| processed_image | a binary matrix contains only 0 and 1. i.e., the segmented image of a plant. |
| Xsize, Ysize | Xsize and Ysize are the actual horizontal and vertical lengths of one pixel, respectively. If users prefer to calculate in pixel level rather than actual units, use the default set, i.e. Xsize = 1, Ysize = 1. |
| a, b | positive integers. To be more specific, a and b are respectively the same as the values of RowSample and ColSample in function: "sample". This is only used when you have used function "sample" to reduce the size of the image in image segmentation. |

Value

| | |
|-------------|--|
| plantheight | The height of the segmented plant by taking the 2.5th% quantile and 97.56th% quantile of the segmented pixels of interest. |
| plantwidth | The width of the segmented plant by taking the 2.5th% quantile and 97.56th% quantile of the segmented pixels of interest. |
| plantSize | The size of the segmented plant based on the total number of pixels of the segmented plant of interest. |
| pixelCount | The total number of pixels of the segmented plant of interest. |

See Also

[reducingsize](#) for reducing size of an image.

Examples

```
#reduce the size of an image
image_reduced = sample(original_image, RowSample = 2, ColSample = 2)
#segment the reduced image
imageBD = imageBinary(image_reduced, weight = c(-1, 2, -1), threshold1 = 30 / 255, threshold2 = 0.05)
#obtain the size of the segmented image
extract_pheno(processed_image = imageBD, Xsize = 1.5, Ysize = 1.5, a = 2, b = 2)$size
```

fanova_mean

*Fitting functional anova models***Description**

This function is used for fitting fanova models using B-Spline basis expansion.

Usage

```
fanova_mean(Y.na.mat, X, tt, formula,
            K.int = 6, order = 4,
            d0 = 0, d1 = 2, d2 = 2, lower = -10, upper = 15)
```

Arguments

| | |
|----------|--|
| Y.na.mat | A n by t matrix of response variable (the extracted features), where n is the number of observations (in general, plant ids), and t is the number of observation time points. If a measurement of an observed object is missing on a particular date, the value is filled by “NA” in the matrix. |
| X | A n by r matrix, where n is the number of observations and r is the number of explanatory variables. |
| tt | A t by 1 vector, in which elements implicate the observation days. |
| formula | An object of class "formula", which specifies the model to use. |
| K.int | A positive integer, which refers to the number of interior knots. |
| order | A positive integer, which refers to the order of the polynomial. |
| d0 | A non-negative integer. 0 if you want to evaluate the original basis function, 1 for the first derivative and 2 for the second derivatives of the basis function. |

| | |
|-------|--|
| d1 | A non-negative integer. For the original function, use 2. For the second derivatives, use 4. |
| d2 | A non-negative integer. For the original function, use 2. For the second derivatives, use 4. |
| lower | Lower bound of the possible values of the smoothing parameter, lambda. |
| upper | Upper bound of the possible values of the smoothing parameter, lambda. |

Value

| | |
|---------|---|
| est_fun | A t by q matrix of the estimates, where t is the number of observation time points, and q is the number of columns of the design matrix. The ijth element represents the estimate of the jth variable of the design matrix at the ith observation time point.(i.e. beta.hat_j(t_i)) |
| bhat | A q by K numeric vector, in which contains all the estimated parameters (i.e., betahat), where q is the number of columns of the design matrix, and K is the rank of the spline expansion. |
| lambda | The estimated smoothing parameter. |

Examples

```
fit = fanova_mean(Y.na.mat = Y, X = X,
                  tt = seq(from = 0, to = 44, by = 2),
                  formula = toString("~ X[,1]+X[,2]"),
                  K.int = 6, order = 4,
                  d0 = 0, d1 = 2, d2 = 2, lower = -10, upper = 15)
para = fit$est_fun
mu.hat.t = para[,1]
```

HMRF_EM

Image Segmentation using Hidden Markov Random Field and EM Algorithm Framework

Description

This function can be used to obtain the segmented image using HMRF-EM.

Usage

```
HMRF_EM(X,Y,Z,mu,sigma,k,em_iter,map_iter, beta = 2,
        epsilon_em = 0.00001, epsilon_map = 0.00001)
```

Arguments

| | |
|---|--|
| X | A matrix of the initial labelled image, which can be obtained using other segmentation methods, such as K-means. |
| Y | A m by n matrix of the response variable. Note that the dimension of the original image is n by m. Recommended to use load.imageimager to load the original image. |
| Z | A m by n matrix. This is to have a brief edge detection of the response variable. e.g., We can use Canny edge detector: Z = cannyEdges(Y,...) |

| | |
|-------------|--|
| mu | A k by 1 matrix. The two rows represent the mean of the pixel intensities of the response variable under k different classes, respectively. This can be obtained using the function "imkmeans" in this package. |
| sigma | A k by 1 matrix. The two rows represent the sigma of the pixel intensities of the response variable under k different classes, respectively. This can be obtained using the function "imkmeans" in this package. |
| k | A positive integer, which infers the nubmer of classes that you want to classify the image into. In default, k = 2. |
| em_iter | A positive integer, which is the number of iteration steps of EM Algorithm. |
| map_iter | A positive integer, which is the number of iteration steps of MAP. |
| beta | The clique potential parameter, in default, beta = 2. See more in |
| epsilon_em | A small positive number, which is the convergence criterion of EM Alogrithm. |
| epsilon_map | A small positive number, which is the convergence criterion of MAP. |

Value

| | |
|--------------|----------------------------------|
| image_matrix | A matrix of the segmented image. |
| mu | Updated mu. |
| sigma | Updated sigma. |

References

Wang, Quan (2012), "Hmrf-em-image: implementation of the hidden markov random field model and its expectation-maximization algorithm."arXivpreprintarXiv:1207.3510

Examples

```
orig1 = load.image("~/Desktop/Visible/image_original.png")
orig = resize(orig1, size_x = 500, size_y = 500, size_z = 1, size_c = 3)
#Define the response as relative green.
I = orig[, ,1,2]/(orig[, ,1,1]+orig[, ,1,2]+orig[, ,1,3])
Y = t(I)
k = 2
map_iter = 20
em_iter = 20
Z = cannyEdges(orig)
Z = Z[, ,1,1]
Z = t(Z)
X = imkmeans(Y,k)$X
mu = imkmeans(Y,k)$mu
sigma = imkmeans(Y,k)$sigma
output = matrix(as.numeric(X),nrow = nrow(X), ncol = ncol(X))-1
img = HMRF_EM(X,Y,Z,mu,sigma,k,em_iter,map_iter,beta = 2,
              epsilon_em = 0.00001, epsilon_map = 0.00001)
image = img$image_matrix
```

 imageBinary

Segmentation and Binarization

Description

This function uses the Double-Criterion Thresholding method (DCT) to segment the object of study from the background of an image, and transform the image to a binary image, i.e., a black and white image.

Usage

```
imageBinary(image, weight = c(-1, 2, -1), threshold1 = 30 / 255,
threshold2 = 0.075)
```

Arguments

| | |
|------------------------|---|
| image | an array of pixels of the image for processing. |
| weight | a 3 by 1 vector. The three elements indicate the weight of the pixel intensities of R,G,B, respectively. In default, it takes the value of c(-1,2,-1), which helps to construct a relative green ratio. |
| threshold1, threshold2 | Values between 0 and 1. threshold1 is applied to the sum of the RGB intensities. threshold2 is applied on the contrast intensity by the specified weight in the function. |

Details

In processing the green plants images taken in the greenhouse system, the two thresholds are to delete the black pixels and to segment the plant green pixels, respectively.

Value

A matrix of pixels of the processed image.

Examples

```
imageB = imageBinary(imageColor, weight = c(-1, 2, -1),
threshold1 = 30 / 255, threshold2 = 0.05)
```

 imkmeans

Obtain the Matrix of the Segmented Image using K-means Method.

Description

This function is to obtain the Matrix of the Segmented Image using K-means Method, together with the means and variances of the pixel intensities within different classes.

Usage

```
imkmeans(Y, k)
```

Arguments

Y
k

Value

| | |
|-------|---|
| X | A matrix of the segmented image, using the K-means method. |
| mu | A k by 1 matrix. The k rows represent the mean of the pixel intensities of the response variable under k different classes, respectively. |
| sigma | A k by 1 matrix. The k rows represent the mean of the pixel intensities of the response variable under k different classes, respectively. |

Examples

```
orig1 = load.image("~/Desktop/Visible/image_original.png")
orig = resize(orig1, size_x = 500, size_y = 500, size_z = 1, size_c = 3)
I = orig[, , 1, 2] / (orig[, , 1, 1] + orig[, , 1, 2] + orig[, , 1, 3])
Y = t(I)
k = 2
X = imkmeans(Y, k)$X
mu = imkmeans(Y, k)$mu
sigma = imkmeans(Y, k)$sigma
output = matrix(as.numeric(X), nrow = nrow(X), ncol = ncol(X)) - 1
```

Largest_Connection

Finding the Largest Connection

Description

This function is used to identify the components of a binary image. By doing this, you can find the component which has the largest connection. Also one can plot the image by using different colors to represent different components. Moreover, one can improve the segmentation result by inputting the threshold value.

Usage

```
Largest_Connection(A, thred)
```

Arguments

| | |
|-------|--|
| A | a binary matrix in which elements are 0 and 1. |
| thred | thresholding value to filter the unwanted noise of the image. To be more specific, this function divides the image into several components. Each component has its own number of pixels. We use the number of pixels as the threshold level to filter out the unwanted components. |

Value

| | |
|-----------------|--|
| plot | the plot of the matrix with different components |
| matrix | the original outcome of the matrix (without filtering) in which pixel elements are represented by different integers. Each number represent a component. |
| filtered_matrix | the outcome of the matrix (after filtering) in which pixel elements are represented by different integers. Each number represent a component. |

See Also

[ConnCompLabel](#)

Examples

```
img11 = Largest_Connection(A = image,thred = 10)
img11$filtered_matrix
```

| | |
|--------|----------------------------------|
| sample | <i>Reducing size of an image</i> |
|--------|----------------------------------|

Description

This function reduces the size of an image by picking sample pixels from each row and each column of the original image, and use the selected pixels to construct a reduced image.

Usage

```
sample(image, RowSample = 1, ColSample = 1)
```

Arguments

| | |
|-----------|--|
| image | array of pixels of the image file to reduce. |
| RowSample | a positive integer. It means you select every "RowSample" pixels of each row of the original image as a pixel of the reduced image. |
| ColSample | a positive integer. It means you select every "RowSample" pixels of each column of the original image as a pixel of the reduced image. |

Details

This function can be used to reduce the size by picking sample pixels of the original image as the pixels of the reduced image. For example, RowSample = 2, and ColSample = 2 mean that we pick the 1st, the 3rd, the 5th,..., pixel of each row and each column of the original image as the pixels of the reduced image.

Value

array of pixels of the reduced image.

Examples

```
sample(image, RowSample = 2, ColSample = 2)
```

Index

Average Reducing (average_reducing), [2](#)
average_reducing, [2](#)

Background Exchange (Color_Exchange), [7](#)
Binarization (imageBinary), [12](#)

CI.trt, [3](#)
CI.trt.diff, [4](#)
Color2Gray, [4](#)
Color_Exchange, [7](#)
ColorB, [5](#)
ColorG, [6](#)
ConnCompLabel, [14](#)

Dilation (dilation), [7](#)
dilation, [7](#)

Erosion (erosion), [8](#)
erosion, [8](#)
extract_pheno, [8](#)

fanova_mean, [9](#)

HMRF_EM, [10](#)

imageBinary, [12](#)
imkmeans, [12](#)

Largest Connection
(Largest_Connection), [13](#)
Largest_Connection, [13](#)

reducingsize, [9](#)

sample, [14](#)