Package 'implant'

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throughput Phenotyping Pipeline for Image Processing and Functional Growth Curve Analysis

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Description The package `implant" includes functionality for image processing and functional data analysis, which is able to provide statistical growth curve analysis for plant traits extracted from the input images. For image processing, the package provides methods including thresholding, hidden Markov random field model, etc. For the growth curve analysis, this package can produce nonparametric curve fitting with its confidence region. A functional ANOVA model to test for the treatment and genotype effects on the growth curve dynamics is also provided.					
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CI					
CI_contrast					
Color2Gray					
ColorB					
ColorG					
Color_Exchange					
dilation					
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erosion					
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CI

Description

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This function is used for estimating a linear combination of treatment effects and its confidence regions in functional data analysis. It can be used for testing for the significance of the linear comination of effects.

Usage

CI(fit, L, alpha)

Arguments

fit	an object of output obtained by function "fanova".
L	a numeric contrast vector corresponding to the design matrix in "fanova", which specifies the linear combination of the parameters of interest. Users can use the design matrix output from the function fanova(), to idenfity the value of L. See the example part for details.
alpha	a positive small number between 0 and 1. 1-alpha gives the confidence level. In default, alpha = 0.05 .

Details

We can estimate a linear combination of treatment effects and its confidence regions with the function " $CI(fit,L\dots)$ ", where fit is the output from " $fanova(\dots)$ ", and L is a contrast vector under the Fanova model specifying the linear combination of the parameters of interest. The parameter estimation $\hat{\beta}$ (see the detail part in the help documentation for function "fanova()") is implemented by the function " $fanova(\dots)$ " in our package. By specifying the linear vector L, the estimated linear combination of effects at time t is:

$$\hat{\tau}(t) = L \otimes B'(t)\hat{\beta},$$

where " \otimes " is the Kronecker product, and $B(t) = (B_{d,1}(t), B_{d,2}(t), \dots, B_{d,K}(t))'$. Here d is the order of the B-spline basis function and K is the rank of the B-spline basis function. More details can be found in the help documentation for function "fanova".

In the example part, we study the relationship between the plant sizes and treatments using functional data models. Let $y_i(t)$ be the size of the ith plant measured at time t, where $i=1,\ldots,9$. We treat genotype and block as fixed effects. There are 3 different genotypes (1,2,3) and 3 blocks (1,2,3) in this study. We can use $G_i=(G_{ik})_{k=2}^3$ as the categorical indicator of the ith plant genotype. Specifically, G_{ik} is set to one if the plant has the kth genotype; otherwise, $G_{ik}=0$, and the genotype 1 is set as the baseline.

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Similarly, $P_i = (P_{ik})_{k=2}^3$ is defined to represent the block that the ith plant belongs to, and the first block is set as the baseline. The model can be written as:

$$y_i(t_{ij}) = \mu(t_{ij}) + \sum_{k=2}^{3} G_{ik} g_k(t_{ij}) + \sum_{k=2}^{3} P_{ik} p_k(t_{ij}) + \epsilon_i(t_{ij}),$$

where $\mu(t)$ is the growth function of the plant with the 1st genotype (Genotype 1) from the 1st block, $g_k(t)$ s are the genotype effect functions, $p_k(t)$ s are the fixed block effect functions, and the residuals $\epsilon_i(t)$ s are modeled by independent random processes with mean zeros. To be more specific, $\mu(t) = \sum_{v=1}^K \beta_{\mu,v} B_{d,v}(t)$, where $\{B_{d,v}(t)\}_{v=1}^K$ are order d B-spline basis functions, and $\{\beta_{\mu,v}\}_{v=1}^K$ are the corresponding coefficients. $g_k(t) = \sum_{v=1}^K \beta_{g_k,v} B_{d,v}(t)$, and $\{\beta_{g_k,v}\}_{v=1}^K$ are the corresponding coefficients. Similarly, $p_k(t) = \sum_{v=1}^K \beta_{p_k,v} B_{d,v}(t)$, where $\{\beta_{p_k,v}\}_{v=1}^K$ are the corresponding coefficients.

Using the function CI(...), we can estimate a linear combination of treatment effects, including estimating the average growth curve of a particular genotype over all the blocks. In the example part, we use this function to estimate the average growth curve of Genotype 1 over three blocks.

Value

trt	a t by 1 vector giving the estimated linear combination of coefficients at t observation time points.
ub	A t by 1 vector which indicates the upper bound of the (1-alpha) confidence band at different time points.
1b	A t by 1 vector which indicates the lower bound of the (1-alpha) confidence band at different time points.

See Also

fanova

```
#load the data
data_new = read.csv(system.file("extdata","data.csv",
                                  package = "implant", mustWork = TRUE))
#The first three columns of data_new refer to the original position of the observations from the
#original dataset, genotype and block, respectively
Y = data_new[,-c(1:3)]
#This step is to factorize each factor
Genotype = as.factor(data_new$Genotype)
Block = as.factor(data_new$Block)
X = data.frame(Genotype,Block)
formula = "~ Genotype + Block"
tt = seq(from = 0, to = 44, by = 2)
#fit the model
fit = fanova(Y.na.mat = Y, X = X, tt = tt, formula, K.int = 6, order = 4, lower = -10, upper = 15)
fit$design_mat
> fit$design_mat
       (Intercept) Genotype2 Genotype Block2 Block3
1
                                   1
2
```

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```
6
             1
                         0
                                       0
7
                         0
                                               0
             1
                                       1
                                                       1
8
                         1
                                       0
                                               0
             1
                                                       1
9
                         0
                                       0
                                               0
```

#We want to estimate the growth curve of genotype 1 averaging over three blocks, #that is, we are interested in the 1st, the 4th and the 5th column of the design matrix. #Therefore, we can define:

```
L1 = c(1, 0, 0, 1/3, 1/3)
ci1 = CI(fit = fit, L = L1, alpha = 0.05)
plot(tt,ci1$trt,type = "1")
lines(tt,ci1$lb, col = "blue")
lines(tt,ci1$ub, col = "blue")
```

CI_contrast

Constructing confidence regions for specific treatment effect in functional data analysis

Description

This is a special case of the function "CI" in this package. This function is easier to use when studying the difference between two specific treatments/genotype, without specifying the linear combination needed in "CI".

Usage

```
CI_contrast(fit, j1, j2, alpha)
```

Arguments

fit	An object of output obtained by function "fanova".
j1	A positive integer, specifying the columns of the design matrix corresponding to one treatment of interest. Users can use the design matrix output from the function fanova(), to idenfity the value of j1. See the example part for details.
j2	A positive integer, specifying the columns of the design matrix corresponding to the other treatment of interest. Users can use the design matrix output from the function fanova(), to idenfity the value of j2. See the example part for details. Note that, if we want to test the difference between the baseline level and other level, we should always use j2 to specify the baseline level,i.e., let $j2 = 1$.
alpha	A positive small number between 0 and 1. 1-alpha gives the confidence level. In default, alpha = 0.05 .

Details

We can test the significance of the treatment effects of interest by constructing the corresponding confidence regions with the function " $CI_contrast(fit, j1, j2, \ldots)$ ", where fit is the output from "fanova()", and j1 and j2 specify the columns of the design matrix corresponding to the treatments of interest. This is the simplified version of " $CI_contrast$ " by setting the j1th and j2th elements of L being 1 and -1, and all other elements beign 0.

CI_contrast 5

Value

at by 1 vector, which refers to the estimated treatment effect, where t is the number of observation time points specified in the argument tt in the function fanova().

1b at by 1 vector, which refers to the lower bound of the (1-alpha) confidence band, where t is the number of observation time points specified in the argument tt in the function fanova().

ub at by 1 vector, which refers to the upper bound of the (1-alpha) confidence band, where t is the number of observation time points specified in the argument tt in the function fanova().

See Also

fanova

```
#load the data
data_new = read.csv(system.file("extdata","data.csv",
                                 package = "implant", mustWork = TRUE))
#The first three columns of data_new refer to the original position of the observations from the
#original dataset, genotype and block, respectively
Y = data_new[,-c(1:3)]
#This step is to factorize each factor
Genotype = as.factor(data_new$Genotype)
Block = as.factor(data_new$Block)
X = data.frame(Genotype,Block)
formula = "~ Genotype + Block"
tt = seq(from = 0, to = 44, by = 2)
fit = fanova(Y.na.mat = Y, X = X, tt = tt, formula, K.int = 6, order = 4, lower = -10, upper = 15)
fit$design_mat
> fit$design_mat
       (Intercept) Genotype2 Genotype Block2 Block3
1
                       0
                                  1
                                          0
2
            1
                       0
                                   0
                                          0
                                                  0
3
                                          0
            1
                       1
                                   0
                                                  0
                                   0
4
            1
                       1
                                          1
5
            1
                       0
                                   1
                                          1
6
            1
                       0
                                   0
                                                 0
                                          1
7
            1
                       0
                                   1
                                          0
                                                 1
8
            1
                       1
                                   0
                                          0
                                                 1
                       0
            1
                                   0
                                          0
#We want to test the significance between genotype 2 and genotype 3,
#that is, we are interested in the 2nd, the 3rd column of the design matrix.
#Therefore, we can define:
ci_diff = CI_contrast(fit = fit,j1 = 2, j2 = 3, alpha = 0.05)
plot(tt,ci_diff$trt,type = "1")
lines(tt,ci_diff$lb, col = "blue")
lines(tt,ci_diff$ub, col = "blue")
```

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Color2Gray

Converting an RGB image to a grayscale image

Description

This function is used to convert an RGB image to Grayscale.

Usage

```
Color2Gray(image, weight = c(0.299, 0.587, 0.114))
```

Arguments

image an array of an RGB image file for processing.

weight a numeric vector, giving weights for the Red, the Green and the Blue channels

of the image, respectively.

Value

image A matrix of pixels of the image converted from RGB to Grayscale.

Examples

ColorB

Identifying the region of interest (left and right boundaries) for a plant image

Description

This function is specifically designed for processing the plant images taken in the University of Nebraska-Lincoln (UNL) greenhouse Innovation Center. It identifies the left and right boundaries of the black bars of the background and help users identify the region of interest for the plants. See image1.png in the example data.

Usage

```
ColorB(image, colThreshold = 0.5)
```

Arguments

image an RGB image of plant.

colThreshold a positive real number, which is the used to identify the black bars appear in the

columns of the image.

ColorG 7

Value

1b	left bound for the region of interest.
rb	right bound for the region of the interest.
С	A modified image replacing all the area outside the region of interest by white
	color.

Examples

ColorG

Identifying the region of interest (lower bound) for a plant image

Description

This function is specifically designed for processing the plant images taken in the University of Nebraska-Lincoln (UNL) greenhouse Innovation Center. It helps identify the lower boundary of the plant by using images of empty pot with a plastic green bar. See the sample image: image_pot.png.

Usage

```
ColorG (imagefile, rowThreshold = 0.007, Bthreshold = 60 / 255, EGThreshold = 0.1, weight = c(-1, 2, -1))
```

Arguments

imagefile	an input RGB image of the empty pot
rowThreshold	a positive real number, used to identify the position of the green strip in the empty pot.
Bthreshold	a value between 0 and 1. It is applied to the sum of the RGB intensities.
EGThreshold	a value between 0 and 1. It is applied to the contrast intensity by the specified weight in the function.
weight	a 3 by 1 numeric vector. The three elements indicate the weight of the pixel intensities of R, G, B, respectively. In default, it takes weight c(-1,2,-1), for contrast intensity.

Details

In the example part, this function identifies the green strip in an empty pot, which can be considered as the lower boundary of a plant, and change the color of the green strip from green to white.

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Value

lowb lower bound of the region of interest.c output image with changed color on the green strip.

Examples

Color_Exchange

Exchanging the color of the background and the foreground.

Description

This function exchanges the color of the background and the foreground for a binary image.

Usage

```
color_exchange(image1)
```

Arguments

image1

A binary matrix of a segmented image

Details

Exchange 0 and 1 in the input binary matrix.

Value

A binary matrix with exchanged background and the foreground.

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dilation

Morphological Dilation

Description

This function is used to perform morphological dilation of an image.

Usage

```
dilation(imagefile, mask = matrix(1, 3, 3))
```

Arguments

imagefile a binary matrix of the segmented image.mask a matrix constructed by structuring elements.

Value

a binary matrix of the dilated image.

References

Image Analysis and Mathematical Morphology by Jean Serra, ISBN 0-12-637240-3 (1982)

Examples

downsize

Reducing the size of an RGB image

Description

This function reduces the size of each matrix of an RGB image (3-D array) by picking one component from every k1 components in each row and one component from every k2 components in each column of the input image, and use the selected elements to construct a reduced image, where k1 and k2 are specified by "RowSample" and "ColSample", respectively.

Usage

```
downsize(image, RowSample = 1, ColSample = 1)
```

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Arguments

image an input RGB image array

RowSample a positive integer for the rows. Select one component from every RowSample

components. For example, RowSample = 2 means you select the 1st, 3rd, ... element from each row of the original image to construct your new image.

ColSample a positive integer for the columns. Select one component from every ColSample

components. For example, ColSample = 2 means you select the 1st, 3rd, ... element from each column of the original image to construct your new image.

Details

This function can be used to reduce the size of an image by picking sample elements of the original image as the elements of the reduced image. For example, "RowSample = 2", and "ColSample = 2" reduce the original size of an image to a quarter.

Value

array of pixels of the reduced image.

Note

This function is different from another function in this package called "downsize_matrix()". That function is used to reduce the size of matrices while this function, downsize(), is used to reduce the size of 3-D arrays.

Examples

downsize_avg

Reducing size of an image using the method of averaging in blocks.

Description

This function is used for reducing size of an image by averaging its pixels in blocks.

Usage

```
downsize_avg(image, block_nrow = 2, block_ncol = 2)
```

downsize_matrix 11

Arguments

image a pixel matrix or an array of the image for processing.

block_nrow an integer number, which is the number of rows from a block. The reduced

matrix is the average value within each block.

For example, if block_nrow = 2 means you select every two rows of the input image as a block. Note that this number needed to be divisible by number of

rows of the array of the input image.

block_ncol an integer number, which is the number of columns from a block. The reduced

matrix is the average value within each block.

For example, if block_ncol = 2 means you select every two columns of the input image as a block. Note that this number needed to be divisible by number of

columns of the array of the input image.

Details

This function is used to reduce the size of an image by dividing the original array into several blocks and calculate the average values within each block.

Value

a pixel array of the reduced image.

Note

block_nrow and block_ncol must be divisible by number of rows and columns of the pixel-arrary of the image, respectively. Otherwise, Errors will be reported as: "block_nrow(block_ncol) must be divisible by number of rows(columns) of the pixel-arrary of the image."

Examples

downsize_matrix

Reducing the Size of a Matrix

Description

This function reduces the size of a matrix by picking one component from every k1 components in each row and one component from every k2 components in each column of the input matrix, and use the selected elements to construct a reduced matrix, where k1 and k2 are specified by "RowSample" and "ColSample", respectively.

Usage

```
downsize_matrix(M, RowSample = 1, ColSample = 1)
```

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Arguments

M the original input matrix.

RowSample a positive integer for the rows. Select one component from every RowSample

components.

For example, RowSample = 2 means you select the 1st, 3rd, ... element from

each row of the original matrix to construct your new matrix.

ColSample a positive integer for the columns. Select one component from every ColSample

components.

For example, ColSample = 2 means you select the 1st, 3rd, ... element from

each column of the original matrix to construct your new matrix.

Details

This function can be used to reduce the size of a matrix by picking sample elements of the original matrix as the elements of the reduced matrix. For example, "RowSample = 2", and "ColSample = 2" reduce the original size of a matrix to a quarter.

Value

the reduced matrix.

Note

This function is different from another function in this package called "downsize()". That function is used to reduce the size of 3-D arrays while this function, downsize_matrix(), is used to reduce the size of matrices.

Examples

erosion

Morphological Erosion

Description

This function is used to perform morphological erosion of an image.

Usage

```
erosion(imagefile, mask = matrix(1, 3, 3))
```

Arguments

imagefile a binary matrix of the segmented image.mask a matrix constructed by structuring elements.

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Value

a binary matrix of the eroded image.

References

Image Analysis and Mathematical Morphology by Jean Serra, ISBN 0-12-637240-3 (1982)

Examples

extract_pheno

Extract phenotypical features from segmented images

Description

This function extracts phenotypical features from segmented images.

Usage

```
extract_pheno(processed_image, Xsize = 1, Ysize = 1, a = 1, b = 1)
```

Arguments

processed_image

a binary matrix contains only 0 and 1, giving the segmented image of a plant.

Xsize, Ysize

Xsize and Ysize are the actual horizontal and vertical lengths of one pixel, respectively. The default set is Xsize = 1, Ysize = 1 for the non-adjustment for the

pixel size.

a,b

positive integers, the same as the values of RowSample and ColSample in the function: "downsize", respectively. This is only used if the function "downsize"

was used to reduce the size of the image in image segmentation.

Value

pixelCount The total number of pixels of the segmented plant of interest.

plantheight The height of the segmented plant.

plantwidth The width of the segmented plant.

plantSize The size of the segmented plant based on the total number of pixels of the seg-

mented plant of interest. i.e. Size = pixelCount * Xsize * Ysize.

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See Also

downsize for reducing size of an image.

Examples

fanova

Fitting Functional ANOVA Models

Description

This function is to fit Fanova models by B-Spline basis expansion with a penalty term on the second derivative of of the estimated functions for the smoothness of the curves. The penalty parameter, λ , is chosen by generalized cross validation (GCV).

Usage

```
fanova(Y.na.mat, X, tt, formula, K.int = 6, order = 4, d1 = 2, lower = -10, upper = 15)
```

Arguments

Y.na.mat	an n by t matrix of response variable (the extracted features), where each row contains the time series data of an observation, and each column contains all the observations at a given time. Here n is the number of biological units of the study (for example, in the study of plant growth curve, n is the number of plants and t is the number of observation time points. Any missing observation is filled by "NA" in the matrix. For example, if a measurement of plant is missing for plant i on date j, the (i, j) component in Y.na.mat should be filled by "NA".
X	an n by r dataframe or matrix of explanatory variables, where n is the number of observations and r is the number of explanatory variables.
tt	a t by 1 vector, with the same length as the rows in Y.na.mat. Each element implies the observation date.
formula	an object of class "formula", which specifies the model to use.
K.int	a positive integer, which refers to the number of interior knots of the B-spline.
order	a positive integer, which refers to the order of the B-spline. In default, order = 4, which implies that we use a cubic polynomial to connect each two adjacent knots.

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d1 a non-negative integer, giving the order of the derivatives of the basis expansion function in the penalty matrix, Ω . See the "detail"" part. In default, d1 = 2. Note that d1 should be smaller than the order of the basis function.

lower bound for the possible values of log (smoothing parameter), i.e., $log(\lambda)$,

used in GCV.

upper upper bound for the possible values of log (smoothing parameter), i.e., $log(\lambda)$,

used in GCV.

Details

Suppose the trait is potentially affected by q factors. Denote by l_j the number of levels of the jth factor. We define $X_{ij}=(x_{ij2},\ldots,x_{ijl_j})'$ as the categorical indicators of the jth factor of the ith plant. Specifically, x_{ijk} is set to one if the jth factor of the ith plant has level "k"; otherwise, $x_{ijk}=0$. In convenience, let q=2 in the help documentation.

Denote by \otimes the Kronecker product of matrices. A functional ANOVA model with interactions can be written in the following form:

$$y_i(t) = \mu(t) + X'_{i1}a_1(t) + X'_{i2}a_2(t) + (X'_{i1} \otimes X'_{i2})a_{1,2}(t) + \epsilon_i(t),$$

where $a_j(t) = (a_{j2}(t), \ldots, a_{jl_j}(t))'$ are the treatment effect functions of the jth factor with dimension $l_j - 1$, $a_{1,2}(t)$ are the pairwise interaction effect functions between the two factors with dimension $(l_1 - 1)(l_2 - 1)$, and $\epsilon_i(t)$ s are temporal dependent random processes with zero means. We have implemented this multi-factor model $(q \ge 2)$ in our package such that researchers can specify the main and interactions effects as needed.

Under the model, we can estimate the temporally varying coefficient functions. First, we approximate all of the coefficient functions with rank K splines expansions. For example, $a_{1k}(t) = \sum_{v=1}^K \beta_{1k,v} B_{d,v}(t)$, where $\{B_{d,v}(t)\}_{v=1}^K$ are order d B-spline basis functions, and $\{\beta_{1k,v}\}_{v=1}^K$ are the corresponding coefficients. Let β_{μ} , β_{1k} , β_{2k} and $\beta_{intk1,k2}$ denote the k-dimensional vector of the B-spline coefficients for the intercept, the two main factor effects (kth level), and their interaction terms $(k_1$ th and k_2 th level), respectively. Let $\beta = (\beta'_{\mu}, \beta'_{12}, \ldots, \beta'_{1l_1}, \beta'_{21}, \ldots, \beta'_{2l_2}, \ldots)'$ be the vector containing all these coefficients.

To estimate all those coefficients β in front of basis functions, we apply the least squares estimation with penalizations on the d1th derivatives of the rank K spline expansion functions to attain smooth estimators. Denoting $y_i(t_{i,z})$ as the measurement for the ith (i=1,...,n) plant observed at the zth (z=1,...,m) time point, we minimize the penalized error sum of squares:

$$\sum_{i=1}^{n} \sum_{z=1}^{m} \{y_{i}(t_{i,z}) - B(t_{i,z})'\beta_{\mu} - \sum_{k=2}^{l_{1}} X_{i1k}B(t_{i,z})'\beta_{1k} - \sum_{k=2}^{l_{2}} X_{i2k}B(t_{i,z})'\beta_{2k} - \sum_{k=2}^{l_{1}} \sum_{k_{2}=2}^{l_{2}} X_{i1k_{1}}X_{i2k_{2}}B(t_{i,z})'\beta_{intk_{1},k_{2}} + \lambda \beta'_{\mu}\Omega\beta_{\mu} + \sum_{k=2}^{l_{1}} \lambda \beta'_{1k}\Omega\beta_{1k} + \lambda \sum_{k=2}^{l_{2}} \beta'_{2k}\Omega\beta_{2k} + \lambda \sum_{k_{1}=2}^{l_{1}} \sum_{k_{2}=2}^{l_{2}} \beta'_{intk_{1},k_{2}}\Omega\beta_{intk_{1},k_{2}}$$

where λ is the smoothing parameter, $\Omega = \int B^{(d1)}(t) \{B^{(d1)}(t)\}' dt$ is a penalty matrix, $B(t) = (B_{d,1}(t), \ldots, B_{d,K}(t))'$, and d1 is the order of the derivitives in the penalty term. We obtain the estimated B-spline coefficient β by minimizing the above quantity. The smoothing parameter λ is estimated by generalized cross validation (GCV). By plugging $\hat{\beta}$ back to the rank K splines expansions, we get the estimated varying coefficient functions in the model, $\hat{\beta}_{\mu}(t) = B(t)'\hat{\beta}_{\mu}, \hat{a}_{1}(t) = B(t)'\hat{\beta}_{1}, \ldots$

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Value

est_fun

a t by u matrix of the estimated function of coefficients, where t is the number of observation time points, and u is the number of columns of the design matrix. For example, if the model includes two categorical variables without interaction terms, each categorical variable contains two levels, the model can be expressed as

$$y(t) = \beta_0(t) + \beta_1(t)X_1 + \beta_2(t)X_2 + \epsilon(t).$$

In this case, u=3. This means your output "est_fun" contains 3 columns, and the columns repesent $\hat{\beta}_0(t)$, $\hat{\beta}_1(t)$ and $\hat{\beta}_2(t)$, respectively.

bhat a $(u \times K) \times 1$ numeric vector, containing all the estimated coefficients, $\hat{\beta}$ for

the B-spline expansion, where \boldsymbol{u} is the number of columns of the design matrix,

and K is the rank of the spline expansion.

design_mat The design matrix under the model specified in the function. It can be used as

reference to help users identify the contrast vector \boldsymbol{L} in the function $\boldsymbol{CI}(\),$ and

the values of j1 and j2 in the function CI_contrast().

lambda The penalty parameter, obatined by GCV.

K The rank of the B-spline basis function. K = number of interior knots + order of

the B-spline basis function.

... Other ouputs are for writing other functions. Users can ignore them.

Note

The rank of the B-spline basis functions, K, is equal to the order (degree+1) of the spline plus the number of interior knots. To avoid over-fitting, we choose the rank less than half of the number of observation time points, m.

References

Ramsay, James O., and Silverman, Bernard W. (2005), Functional Data Analysis, 2nd ed., Springer, New York.

Ramsay, James O., Hooker, Giles, and Graves, Spencer (2009) Functional Data Analysis in R and Matlab, Springer, New York.

HMRF

HMRF	Image Segmentation using Hidden Markov Random Field with EM Algorithm

Description

This function can be used to obtain the segmented image using HMRF-EM Algorithm.

Usage

Arguments

X	an m by n binary matrix of the inital labels for an image, which can be obtained using initital segmentation methods, such as K-means or thresholding methods. Note that X could be any binary matrix, for example, its element could be 0 & 1, or 1 & 2, or 2 & 3,, etc.
Υ	an m by n matrix of pixel intensity. For plant segmentation, we recommend to use relative green.
Z	an m by n binary matrix, giving an estimate for the object edges in Y. We can obtain Z using the Canny edge detector: $Z = t(cannEdges\ (Y)\ [\ ,\ ,\ 1,\ 1])$ from the package: imager. See the example for details.
em_iter	a positive integer, which is the number of iteration steps of the EM Algorithm.
map_iter	a positive integer, which is the number of iteration steps of calculating MAP (the maximum a posterior estimation).
beta	The clique potential parameter for neighbourhood dependence. In default, beta = 2. See details in the supplementary file on the HMRF Model. This beta is equivalent to the Psi in the supplentary file (see page 20, 21).
epsilon_em	a small positive number, which is the convergence criterion of the EM Algorithm.
epsilon_map	a small positive number, which is the convergence criterion of MAP (maximum a posterior estimation).

Details

- 1. More detailed explanation about this method can be found in the supplymentary file: https://github.com/rwang14/implant/blob/master/vignettes/HMRF_EM.pdf
- 2. The arguement Z can be obatined by CannyEdge detector using function cannEdges() from the package: imager. However, since this package needs to involve Rcpp and other dependent packages which may increase installation complexity of our package, we recommend the users to install the package "imager" by themselves if needed.

Value

image_matrix A matrix giving labels for the segmented image.

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Note

This function is modified based on the matlab code written by Quan Wang (see reference).

References

Wang, Quan (2012), "Hmrf-em-image: implementation of the hidden markov random field model and its expectation-maximization algorithm." arXivpreprintarXiv:1207.3510

See Also

```
image_kmeans
```

Examples

```
library(implant)
library(png)
orig = readPNG(system.file("extdata", "reduced.png", package = "implant", mustWork = TRUE))
#Define the response as relative green.
Y = orig[ , , 2]/(orig[ , , 1] + orig[ , , 2] + orig[ , , 3])
#Z is a matrix obtained by CannyEdge detector
Z = readPNG(system.file("extdata", "Z.png",
                         package = "implant", mustWork = TRUE))
##Note: Users can obtain Z using the package "imager" and the function
#CannyEdges( ) for different images
\#Z = t(cannyEdges(orig)[, , 1, 1])
#Take the initial label of EM algorithm using K-means
X = image\_kmeans(Y, k = 2)$X
#Obtain the image produced by kmeans clustering
output = matrix(as.numeric(X), nrow = nrow(X), ncol = ncol(X)) - 1
writePNG(output,"~/kmeans.png")
\# Run \ the \ HMRF \ Model. Note that it may take a lot of time ...
img = HMRF(X, Y, Z, em_iter = 20, map_iter = 20, beta = 2,
              epsilon_em = 0.00001, epsilon_map = 0.00001)
#Obtain the matrix of the segmented image
image = img$image_matrix
#Morphological Operations
imageD = dilation(image)
imageDE = erosion(imageD)
imageDEE = erosion(imageDE)
imageDEED = dilation(imageDEE)
writePNG("~/HMRF.png")
```

imageBinary

Segmentation and Binarization

Description

This function uses the Double-Criterion Thresholding method (DCT) to segment the object of study from the background of an image, and tranform the image to a binary image, i.e., a black and white image.

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Usage

```
imageBinary(image, weight = c(-1, 2, -1), threshold1 = 30 / 255, threshold2 = 0.075)
```

Arguments

image an array of pixels of the image for processing.

weight a 3 by 1 vector. The three elements indicate the weight of the pixel intensities

of R,G,B, respectively. In default, it takes the value of c(-1, 2, -1), which helps

to construct a relative green ratio.

 $threshold 1\,, threshold 2\,$

Values between 0 and 1. threshold1 is applied to the sum of the RGB intensities. threshold2 is applied on the contrast intensity by the specified weight in the function.

Details

The plant pixels are classified as the intersection of sum of RGB intensities larger than threshold 1 and green intensities larger than threshold 2.

Value

A matrix of the processed image.

Examples

image_kmeans

Obtain the Matrix of the Segmented Image using K-means Clustering.

Description

This function is to obtain a segmented plant image using K-means Clustering Method, together with the means and standard deviations of the pixel intensities for different classes.

Usage

```
image_kmeans(Y, k)
```

Arguments

Y an input matrix. For plant segmentation, we recommend to use the relative green intensity of the image.

k a positive integer, which refers to the cluster number. In default, k = 2 to separate the plant from the background.

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Value

X a matrix of the class label of the segmented image.

mu a k by 1 matrix. Each row represents the sample mean of each cluster.

sigma a k by 1 matrix. Each row represents the sample standard deviation of each

cluster.

```
library(png)
orig = readPNG(system.file("extdata", "reduced.png", package = "implant", mustWork = TRUE))
#Define the response as relative green.
Y = orig[ , , 2]/(orig[ , , 1]+orig[ , , 2]+orig[ , , 3])
#Take the initial label of EM algorithm using K-means
X = image_kmeans(Y, k = 2)$X
#Obtain the image produced by kmeans clustering
output = matrix(as.numeric(X), nrow = nrow(X), ncol = ncol(X)) - 1
writePNG(output,"~/kmeans.png")
```

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