

camera_rgb_frame

Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz

Most recent transform: 0.000 (3074.532 sec old)

Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz

Most recent transform: 0.000 (3074.532 sec old)
Buffer length: 0.000 sec

camera_depth_frame

camera_depth_optical_frame