

view_frames Result

Recorded at time: 260.583

map

Broadcaster: /rtabmap/rtabmap
Average rate: 20.392 Hz
Most recent transform: 260.665 (-0.082 sec old)
Buffer length: 2.550 sec

odom

Broadcaster: /gazebo
Average rate: 10.400 Hz
Most recent transform: 260.501 (0.082 sec old)
Buffer length: 2.500 sec

robot_footprint

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (260.583 sec old)
Buffer length: 0.000 sec

chassis

Broadcaster: /robot_state_publisher
Average rate: 10.404 Hz
Most recent transform: 260.500 (0.083 sec old)
Buffer length: 2.499 sec

left_wheel

Broadcaster: /robot_state_publisher
Average rate: 10.404 Hz
Most recent transform: 260.500 (0.083 sec old)
Buffer length: 2.499 sec

right_wheel

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (260.583 sec old)
Buffer length: 0.000 sec

kinect

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (260.583 sec old)
Buffer length: 0.000 sec

hokuyo