

1) Assume  $x$  is an  $m$ -dimensional vector, prove  $\|x\|_\infty \leq \|x\|_2$  and  $\|x\|_2 \leq \sqrt{m}\|x\|_\infty$ .

Recall that

$$\|x\|_2 = \sqrt{\sum_{i=1}^m |x_i|^2} \quad (1)$$

$$\|x\|_\infty = \max\{|x_1|, |x_2|, \dots, |x_m|\}. \quad (2)$$

Thus, for the first inequality we have the following. Suppose that  $|x_k| = \|x\|_\infty$ , then

$$\|x\|_2 = \sqrt{\|x\|_\infty^2 + \sum_{i \neq k} |x_i|^2} \leq \sqrt{\|x\|_\infty^2} \leq \|x\|_\infty, \quad (3)$$

since  $|x_i| \geq 0$  for all  $i$ .

For the second inequality, we know that  $|x_i| \leq \|x\|_\infty$  for all  $i$ . Hence,

$$\|x\|_2 \leq \sqrt{\sum_{i=1}^m \|x\|_\infty^2} = \sqrt{m}\|x\|_\infty. \quad (4)$$

2) Show that if a matrix  $A$  is both triangular and unitary, then it is diagonal.

Suppose that  $A = (a_{ij}) \in \mathbb{C}^{n \times n}$  is an upper triangular matrix we know that  $a_{ij} = 0$  if  $i > j$ . First, we will show that  $A^{-1}$ , assuming that  $A$  is non-singular, is upper triangular. Let  $A^{-1} = [b_1 b_2 \dots b_n]$ , then  $A^{-1}A = \mathbf{1}$  and

$$\begin{cases} b_1 a_{11} = e_1 \\ b_2 a_{12} + b_2 a_{22} = e_2 \\ \vdots \\ b_1 a_{1n} + b_2 a_{2n} + \dots + b_n a_{nn} = e_n, \end{cases} \quad (5)$$

where  $(e_i)_j = \delta_{ij} = \begin{cases} 1 & i = j \\ 0 & i \neq j \end{cases}$  is the standard basis. From lectures, we know that we can solve this system using forward substitution as follows:

$$\begin{cases} b_1 = e_1/a_{11} \\ b_i = (e_i - \sum_{k=1}^{i-1} b_k a_{ki})/a_{ii}. \end{cases} \quad (6)$$

Observe that

$$(b_1)_j = \frac{1}{a_{11}} \delta_{1j} \quad (7)$$

$$(b_i)_j = \frac{1}{a_{ii}} \delta_{ij} - \sum_{k=1}^{i-1} (b_k)_j \frac{a_{ki}}{a_{ii}}. \quad (8)$$

Using induction, it is easy to see that  $b_{ij} = 0$  if  $i > j$ .

Next, we will show that  $A^T$  must be lower triangular, which implies that  $A^\dagger = A^{*\text{T}}$  is lower triangular. From the definition  $(A^T)_{ij} = a_{ji}$ . Since  $a_{ji} = 0$  if  $j > i$ , then it follows that  $(A^T)_{ij} = 0$  if  $j > i$ , which proves that  $A^T$  is lower triangular.

Now, let  $A$  be a unitary. Then,  $A^\dagger = A^{-1}$ . Hence,

$$(A^\dagger)_{ij} = a_{ji}^* = (A^{-1})_{ij}. \quad (9)$$

Recall that the inverse of  $A$  is upper triangular, so

$$a_{ji}^* = 0 \quad (10)$$

if  $i > j$ . That is,  $a_{ji} = 0$  if  $j < i$ , meaning that  $A$  has no off-diagonal entries and that  $A$  is diagonal. Furthermore, it is clear now that  $|a_{ii}|^2 = 1$  or  $|a_{ii}| = 1$ , which gives a constraint for the diagonal values of  $A$ .

The proof for a lower triangular matrix is simple. Let  $A$  be a lower triangular unitary matrix. Then  $A^\dagger$  is upper triangular and unitary since  $A^\dagger A = \mathbb{1}$ , which we showed above must imply that  $A^\dagger$  is diagonal. Hence,  $A$  must be diagonal as well.

**3)** Prove that matrix  $\infty$ -norm is

$$\|A\|_\infty = \max_i \sum_{j=1}^n |a_{ij}|. \quad (11)$$

Let  $A = \begin{pmatrix} a_{11} & \dots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{m1} & \dots & a_{mn} \end{pmatrix}$  Let  $v \in \mathbb{C}^n$ , then

$$Av = \begin{pmatrix} \sum_{k=1}^n a_{1k} v_k \\ \vdots \\ \sum_{k=1}^n a_{mk} v_k \end{pmatrix}, \quad (12)$$

and

$$\|Av\|_\infty = \max_i \left| \sum_{k=1}^n a_{ik} v_k \right| \leq \max_i \sum_{k=1}^n |a_{ik}| |v_k|. \quad (13)$$

Furthermore,

$$\frac{\|Av\|_\infty}{\|v\|_\infty} \leq \max_i \sum_{k=1}^n |a_{ik}| \frac{|v_k|}{\|v\|_\infty} \leq \max_i \sum_{k=1}^n |a_{ik}|, \quad (14)$$

Now, we will show that  $\|A\|_\infty$  attains this maximum for some choice of  $v$ . Consider  $v$  such that  $v_k = \frac{|a_{ik}|}{a_{ik}}$  for some  $i = 1, \dots, n$  (unless  $a_{ik} = 0$ , in which case we choose  $v_k = 0$ ). Then,

$$(Av)_i = \sum_{k=1}^n |a_{ik}|. \quad (15)$$

Obviously, we can choose  $i$  such that it attains the maximum from Eq. (14). Now, this is just one component of the vector  $Av$ , so  $\|Av\|_\infty \geq (Av)_i$ . Hence, we have proven our claim that  $\|A\|_\infty$  is the maximum absolute row sum of  $A$ .

**4)** Let  $\|\cdot\|$  denote any norm on  $\mathbb{C}$  and also the induced matrix norm on  $\mathbb{C}^{m \times m}$ . Show that  $\rho(A) \leq \|A\|$ , where  $\rho$  is the spectral radius of  $A$ , which is the largest absolute value of an eigenvalue of  $A$ .

Suppose  $x$  is an eigenvector of  $A$  with a corresponding eigenvalue  $\lambda$ . That is,  $Ax = \lambda x$ . Further, suppose that  $\|x\| = 1$ , which is a valid choice since if  $x$  is an eigenvector of  $A$  then  $x/\|x\|$  is also an eigenvector of  $A$  with the same eigenvalue. Then  $\|A\| \geq \|Ax\| = \|\lambda x\| = |\lambda|$ , which is true for all eigenvalues  $\lambda$  of  $A$ .

**5)** Find  $l_1$ ,  $l_2$ , and  $l_\infty$  norms of the following vectors and matrices, also, please verify your results by MATLAB.

(a)  $x = (3, -4, 0, \frac{3}{2})^T$

The hand calculations are as follows:

$$\begin{aligned} \|x\|_1 &= |3| + |-4| + |0| + \left|\frac{3}{2}\right| = \frac{17}{2} \\ \|x\|_2 &= \sqrt{|3|^2 + |-4|^2 + |0|^2 + \left|\frac{3}{2}\right|^2} = \frac{\sqrt{109}}{2} \\ \|x\|_\infty &= \max\{|3|, |-4|, |0|, \left|\frac{3}{2}\right|\} = 4. \end{aligned} \quad (16)$$

The computer calculations are shown below as a screenshot of the code and the output:

(b)  $\begin{pmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{pmatrix}$

Let the matrix above be denoted by  $A$ .

The hand calculations are as follows:

$$\begin{aligned} \|A\|_1 &= \max\{|2| + |-1| + |0|, |-1| + |2| + |-1|, |0| + |-1| + |2|\} = 4 \\ \|A\|_2 &= \sqrt{A^T A} = \sqrt{4\sqrt{2} + 6} \\ \|A\|_\infty &= 4. \end{aligned} \tag{17}$$

Note that  $A$  is symmetric, so its 1 and  $\infty$  norms are the same.

The work for the 2-norm of  $A$  is as follows. First, we obtain

$$A^T A = \begin{pmatrix} 5 & -4 & 1 \\ -4 & 6 & -4 \\ 1 & -4 & 5 \end{pmatrix}. \tag{18}$$

Then we find the eigenvalues by solving the characteristic equation

$$\det(A^T A - \lambda \mathbf{1}) = -\lambda^3 + 16\lambda^2 - 52\lambda + 16 = 0, \tag{19}$$

which has solutions

$$\lambda \in \{4, 6 \pm 4\sqrt{2}\}. \tag{20}$$

The code for parts (a) and (b) of this problem is shown below along with a screenshot of the output:

```
#!/usr/bin/env python3

import numpy as np

####—Part (a)—###
print( '\nPart (a) \n' )

x = np.array([3, -4, 0, 3/2])
print( '1-norm:    %.2f'%np.linalg.norm(x, ord=1) )
print( '2-norm:    %.2f'%np.linalg.norm(x, ord=2) )
print( 'inf-norm:   %.2f'%np.linalg.norm(x, ord=np.inf) )

####—Part (b)—###
print( '\n\nPart (b) \n' )

A = np.array([[2, -1, 0], [-1, 2, -1], [0, -1, 2]])
print( '1-norm:    %.2f'%np.linalg.norm(A, ord=1) )
print( '2-norm:    %.2f'%np.linalg.norm(A, ord=2) )
print( 'inf-norm:   %.2f'%np.linalg.norm(A, ord=np.inf) )

print()
```

**Part (a)**

1-norm: 8.50  
 2-norm: 5.22  
 inf-norm: 4.00

**Part (b)**

1-norm: 4.00  
 2-norm: 3.41  
 inf-norm: 4.00

6) Determine SVDs of the following matrices by hand calculation and MATLAB.

(a)  $\begin{pmatrix} 3 & 0 \\ 0 & -2 \end{pmatrix}$

First, we solve the eigenproblem for  $A^T A$ , where we denote the matrix above as  $A$ .

$$A^T A = \begin{pmatrix} 9 & 0 \\ 0 & 4 \end{pmatrix}. \quad (21)$$

Then the characteristic equation is

$$\lambda^2 - 13\lambda + 36 = 0 \Rightarrow \lambda \in \{4, 9\}. \quad (22)$$

Now, we find the eigenvectors of  $A^T A$  for each eigenvalue  $x$ , which are trivial to read off since  $A^T A$  is diagonal:

$$\lambda = 9: \quad x = \begin{pmatrix} 1 & 0 \end{pmatrix}^T \quad (23)$$

$$\lambda = 4: \quad x = \begin{pmatrix} 0 & 1 \end{pmatrix}^T. \quad (24)$$

Hence

$$\Sigma = \begin{pmatrix} 3 & 0 \\ 0 & 2 \end{pmatrix} \quad V = \mathbb{1}_{2 \times 2}. \quad (25)$$

Finally, we find the columns of  $U$  by solving  $u_j = Av_j/\sigma_j$  for  $j = 1, 2$ :

$$u_1 = \frac{1}{3} \begin{pmatrix} 3 & 0 \\ 0 & -2 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = 1 \quad (26)$$

$$u_2 = \frac{1}{2} \begin{pmatrix} 3 & 0 \\ 0 & -2 \end{pmatrix} \begin{pmatrix} 0 & -1 \end{pmatrix} = -1, \quad (27)$$

which means

$$U = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}. \quad (28)$$

$$(b) \begin{pmatrix} 0 & 2 \\ 0 & 0 \\ 0 & 0 \\ 0 & 0 \end{pmatrix}$$

We perform the SVD in the same way as above. First, we diagonalize  $A^T A = \begin{pmatrix} 0 & 0 \\ 0 & 4 \end{pmatrix}$ . Incidentally,  $A^T A$  is already diagonal, so we can read off its eigenvalues and eigenvectors directly:  $\lambda \in \{0, 4\}$  with corresponding eigenvectors  $\begin{pmatrix} 1 & 0 \end{pmatrix}^T$  and  $\begin{pmatrix} 0 & 1 \end{pmatrix}^T$ . Now we can write down our matrices for the SVD as follows

$$U = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \quad \Sigma = \begin{pmatrix} 2 & 0 \\ 0 & 0 \\ 0 & 0 \\ 0 & 0 \end{pmatrix} \quad V = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}. \quad (29)$$

The code for parts (a) and (b) of this problem is shown below along with a screenshot of the output:

```
#!/usr/bin/env python3

import numpy as np

####—Part (a)—####
print( '\nPart (a) \n' )

A = np.array([[3,0],[0,-2]])
U,Sig,Vt = np.linalg.svd(A,full_matrices=True)
print( 'U=\n{}\n'.format(U) )
print( 'Sigma=\n{}\n'.format(Sig) )
print( 'V*=\n{}\n'.format(Vt) )

####—Part (b)—####
print( '\n\nPart (b) \n' )

A = np.array([[0,2],[0,0],[0,0],[0,0]])
U,Sig,Vt = np.linalg.svd(A,full_matrices=True)
print( 'U=\n{}\n'.format(U) )
print( 'Sigma=\n{}\n'.format(Sig) )
print( 'V*=\n{}\n'.format(Vt) )

print()
```

Part (a)

U=  
 $\begin{bmatrix} 1. & 0. \\ 0. & 1. \end{bmatrix}$

Sigma=  
 $\begin{bmatrix} 3. & 2. \end{bmatrix}$

V\*=  
 $\begin{bmatrix} 1. & 0. \\ -0. & -1. \end{bmatrix}$

Part (b)

U=  
 $\begin{bmatrix} 1. & 0. & 0. & 0. \\ 0. & 1. & 0. & 0. \\ 0. & 0. & 1. & 0. \\ 0. & 0. & 0. & 1. \end{bmatrix}$

Sigma=  
 $\begin{bmatrix} 2. & 0. \end{bmatrix}$

V\*=  
 $\begin{bmatrix} 0. & 1. \\ -1. & 0. \end{bmatrix}$