# Probability and Statistics Based on lectures by Dr. Angshuman Bhattacharya

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These notes are not endorsed by the lecturers, and I have modified them (often significantly) after lectures. They are nowhere near accurate representations of what was actually lectured, and in particular, all errors are almost surely mine.  $^1$ 

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 $<sup>^{1}</sup>$ This is how Dexter Chua describes his lecture notes from Cambridge. I could not have described mine in any better way.

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# 1 Probability Space

# 1.1 Event space

**Definition 1** ( $\sigma$ -field). Let  $\mathscr{A}$  be a collection of subsets of  $\Omega(A \in \mathscr{A} \Rightarrow A \subset \Omega)$ .  $\mathscr{A}$  is called a  $\sigma$ -algebra(or,  $\sigma$ -field) of subsets of  $\Omega$  if

- 1.  $\mathscr{A}$  is non-empty.
- 2.  $A \in \mathcal{A} \Rightarrow A^C \in \mathcal{A}$
- 3. If  $A, B \in \mathcal{A}$ ,  $A \cup B \in \mathcal{A}$  and  $A \cap B \in \mathcal{A}$ .

**Theorem 1.** A  $\sigma$ -algebra  $\mathscr{A}$  of subsets of  $\Omega$  contains  $\Omega$  and  $\varnothing$ .

**Theorem 2.** The power set of  $\Omega(\Omega \neq \emptyset)$  forms a  $\sigma$ -algebra of subsets of  $\Omega$ .

This will be assumed to be the event space, unless mentioned otherwise.

**Definition 2** (Event space, sample space). An event space  $\mathscr{A}$  of  $\Omega$  is a  $\sigma$ -algebra of subsets of  $\Omega$ . The elements of  $\mathscr{A}$  are called events.  $\Omega$  is called the sample space.

# 1.2 Probability measure

**Definition 3.** Let  $\mathscr{A}$  be an event space of  $\Omega$ .  $P:\mathscr{A}\to\mathbb{R}$  is called a probability measure of  $\mathscr{A}$  if

- 1.  $P(A) \ge 0, \ \forall A \in \mathscr{A}$
- 2.  $P(\Omega) = 1$
- 3. Let  $A, B \in \mathcal{A}$ . If  $A \cap B = \emptyset$ ,

$$P(A \cup B) = P(A) + P(B)$$

**Theorem 3.**  $P(A) \leq 1$ ,  $\forall A \in \mathcal{A}$ . Hence, range of P is [0,1].

**Theorem 4.**  $P(A^C) = 1 - P(A)$ 

Corollary 4.1.

$$\underbrace{P\left(\bigcup_{i=1}^{\infty} A_i\right)} = 1 - \underbrace{P\left(\bigcap_{i=1}^{\infty} A_i^C\right)}$$

at least one of the events occurs

none of the events occur

**Theorem 5.**  $A \subset B \implies P(A) \leq P(B)$ 

**Theorem 6.**  $P(A \cup B) \leq P(A) + P(B)$ 

Theorem 7.

1. If 
$$A_1 \subset A_2 \subset A_3 \subset \cdots$$
 and  $A = \bigcup_{n \geq 1} A_n$ ,

$$P(A) = \lim_{n \to \infty} P(A_n)$$

2. If 
$$A_1 \supset A_2 \supset A_3 \supset \cdots$$
 and  $A = \bigcap_{n \geq 1} A_n$ ,

$$P(A) = \lim_{n \to \infty} P(A_n)$$

**Definition 4** (Probability space). If  $\Omega$  is a sample space,  $\mathscr{A}$  is an event space of  $\Omega$  and P is a probability measure of  $\mathscr{A}$ ,  $(\Omega, \mathscr{A}, P)$  is called a probability space.

# 2 Uniform Probability Spaces

**Definition 5** (Symmetric probability space).  $(\Omega, \mathcal{A}, P)$  (where  $\Omega$  is a finite set) is called a symmetric probability space if P(A) = P(B) for all singleton sets  $A, B \in \mathcal{A}$ .

**Theorem 8.** 
$$P(\{x\}) = \frac{1}{|\Omega|}, \ \forall x \in \Omega. \ \text{Also,} \ P(A) = \frac{|A|}{|\Omega|}, \ \forall A \subset \Omega.$$

**Definition 6** (Cardinality of uncountable set). If  $A \subset \mathbb{R}^n$ , |A| denotes the *n*-dimensional volume of the region A.

**Definition 7** (Uniform probability space). Let  $\Omega \subset \mathbb{R}^n$  where  $|\Omega|$  is finite.  $(\Omega, \mathcal{P}(\Omega), P)$  is called an uniform probability space if  $P(A) = \frac{|A|}{|\Omega|}$ ,  $\forall A \subset \Omega$ .

# 3 Conditional Probability

**Definition 8** (Conditional probability). Let A, B be two events such that  $P(A) \neq 0$ . The conditional probability of B given A denoted by P(B|A) is

$$P(B|A) = \frac{P(B \cap A)}{P(A)}$$

**Theorem 9** (Principle of total probability). Let  $A_k, 1 \leq k \leq n$  be mutually disjoint events in  $\Omega$  such that  $\bigcup_{k=1}^n A_k = \Omega$  and  $P(A_k) \neq 0, \forall 1 \leq k \leq n$ .

$$P(B) = \sum_{k=1}^{n} P(A_k)P(B|A_k), \ \forall B \in \mathscr{A}$$

#### 3.1 Baye's Rule

**Theorem 10** (Baye's rule). Let  $A_k, 1 \le k \le n$  be mutually disjoint events in  $\Omega$  such that  $\bigcup_{k=1}^n A_k = \Omega$  and  $P(A_k) \ne 0, \forall 1 \le k \le n$ . If  $B \in \mathscr{A}$  such that  $P(B) \ne 0$ ,

$$P(A_i|B) = \frac{P(A_i)P(B|A_i)}{\sum_{k=1}^{n} P(A_k)P(B|A_k)}$$

# 3.2 Independence

**Definition 9.** Two events A and B are independent iff  $P(A \cap B) = P(A)P(B)$ .

**Theorem 11.** If P(A) > 0, A, B are independent iff P(B|A) = P(B).

# 4 Combinatorial Analysis

**Definition 10.** (Ordered sample) A random sample of size r from population S is the r-tuple  $(x_1, x_2, \dots, x_r), x_i \in S$ 

It is called a random sample without replacement if  $x_i = x_j \Rightarrow i = j(r \leq |S|)$ . Otherwise, it is a random sampling with replacement.

**Theorem 12.** The number of possible random samples with replacement of size r from a population of size n is  $n^r$ .

It is the number of ways in which r balls can be picked from n distinct balls, with replacement, where the order of picking matters.

#### 4.1 Permutations

**Theorem 13** (Permutation). The number of possible random samples without replacement of size r from a population of size n is

$${}^{n}P_{r} = \frac{n!}{(n-r)!}$$

It is the number of ways in which r balls can be picked from n distinct balls, where the order of picking matters.

#### 4.2 Combinations

**Theorem 14** (Combinations). The number of ways in which r balls can be picked from n distinct balls, where the order of picking does not matter is

$${}^{n}C_{r} = \frac{n!}{(n-r)! \ r!}$$

**Theorem 15.** The number of r-tuples  $(x_1, x_2, \dots, x_r), x_i \in \mathbb{N} \cup \{0\}$  that satisfy  $(n \in \mathbb{N})$ 

$$x_1 + x_2 + \dots + x_r = n$$

is  $\binom{n+r-1}{r-1}$ . If  $x_i \in \mathbb{N}$ , we have  $\binom{n-1}{r-1}$  solutions.

#### 5 Discrete Random Variable

**Definition 11** (Discrete random variable). A discrete real-valued random variable X on a probability space  $(\Omega, \mathscr{A}, P)$  is a function X with domain  $\Omega$  and range a finite or countably infinite subset  $\{x_1, x_2, \dots\}$  of  $\mathbb{R}$  such that  $\{\omega : X(\omega) = x_i\}$  is an event for all i.

# 5.1 Discrete Density

**Definition 12** (Discrete density).  $f_X : \mathbb{R} \to [0, 1]$ ,

$$f_X(x) = P(X = x)$$

is the discrete density of random variable X.

# 5.2 Joint Density

**Definition 13** (Discrete random vector). A discrete real-valued random vector  $\mathbf{X}$  on a probability space  $(\Omega, \mathcal{A}, P)$  is a function  $\mathbf{X}$  with domain  $\Omega$  and range a finite or countably infinite subset  $\{\mathbf{x}_1, \mathbf{x}_2, \cdots\}$  of  $\mathbb{R}^r$  such that  $\{\omega : \mathbf{X}(\omega) = \mathbf{x}_i\}$  is an event for all i.

The density is the function  $f(\mathbf{x}) = P(\mathbf{X} = \mathbf{x})$  or

$$f_{X_1,X_2,\cdots X_r}(x_1,x_2,\cdots,x_r) = P(X_1 = x_1,X_2 = x_2,\cdots,X_r = x_r)$$

where  $X_i$  are components of **X**.  $f_{X_1,X_2,\cdots X_r}$  is called the **joint density** of the random variables  $X_1,X_2,\cdots X_r$ .

# 5.3 Independence

**Definition 14** (Independent random variables). Two random variables X, Y are independent iff

$$f_{X,Y}(x,y) = f_X(x)f_Y(y), \forall x, y \in \mathbb{R}$$

#### 5.4 Sum

Theorem 16 (Sum of random variables).

$$f_{X+Y}(z) = P(X = x, Y = z - x) = \sum_{x} f_{X,Y}(x, z - x)$$

# 5.5 Conditional Density

**Definition 15** (Conditional density).  $P(Y = y|X = x) = \frac{P(X = x, Y = y)}{P(X = x)} = \frac{f_{X,Y}(x,y)}{f_{X}(x)}$ 

$$f_{Y|X}(y|x) := \begin{cases} \frac{f_{X,Y}(x,y)}{f_X(x)}, & f_X(x) \neq 0\\ 0, & f_X(x) = 0 \end{cases}$$

is called the conditional density of Y given X.

# 5.6 Probability Generating Function

**Definition 16** (Probability generating function).  $\Phi_X : [-1, 1] \to \mathbb{R}$ ,

$$\Phi_X(t) = \sum_{x=0}^{\infty} f_X(x)t^x$$

#### 5.7 Expectation

**Definition 17** (Expectation of discrete random variable). Let the range of X be  $\{x_1, x_2, \dots\}$ . The expectation of X is

$$E(X) = \sum_{i=1}^{\infty} x_i f_X(x_i)$$

**Theorem 17.** Let  $\varphi$  be defined on the range of X and  $Z = \varphi(X)$ .

$$E(Z) = \sum_{i} \varphi(x_i) f_X(x_i)$$

**Definition 18** (Conditional expectation). The conditional expectation of Y, given X is

$$E(Y|X=x) = \sum_{i} y_i f(y|x)$$

Theorem 18 (Linearity of expectation).

$$E(cX) = cE(X)$$
$$E(X + Y) = E(X) + E(Y)$$

**Theorem 19.**  $P(X \ge Y) = 1 \implies E(X) \ge E(Y)$ . Moreover,  $E(X) = E(Y) \iff P(X = Y) = 1$ .

**Theorem 20.**  $|E(X)| \le E(|X|)$ 

Lemma 20.1.  $P(|X| \le M) = 1 \implies |E(X)| \le M$ 

**Lemma 20.2.**  $P(|X - Y| \le M) = 1 \implies |E(X) - E(Y)| \le M$ 

**Theorem 21.** If X, Y are independent, E(XY) = E(X)E(Y)

#### 5.8 Variance

**Definition 19** (Moment). Let X be a random variable with expectation  $\mu$ . The  $r^{th}$  moment of X is  $E(X^r)$  and the  $r^{th}$  central moment is  $E((X - \mu)^r)$ 

**Definition 20** (Variance). The  $2^{nd}$  central moment.

$$V(X) = E((X - \mu)^2) = E(X^2) - \mu^2$$

V(X) is denoted by  $\sigma^2$ , where  $\sigma \geq 0$  is called the **standard deviation** of the X.

Theorem 22.

$$V(X + b) = V(x)$$
$$V(aX) = a^{2}V(X)$$

Theorem 23.

$$\mu = \Phi_X'(1)$$
 
$$E(X^2) = \Phi_X''(1) + \Phi_X'(1)$$

#### 5.9 Covariance and Correlation

Theorem 24 (Variance of sum).

$$V(X + Y) = V(X) + V(Y) + 2E[(X - E(X))(Y - E(Y))]$$

**Definition 21** (Covariance). The covariance of X, Y is given by

$$Cov(X, Y) = E[(X - E(X))(Y - E(Y))] = E(XY) - E(X)E(Y)$$

**Theorem 25.** X, Y are independent  $\implies Cov(X, Y) = 0$ 

**Definition 22** (Correlation coefficient). The correlation coefficient of X, Y is

$$\rho(X,Y) = \frac{Cov(X,Y)}{\sqrt{V(X)V(Y)}}$$

# 5.10 Schwartz and Chebyshev's Inequalities

**Theorem 26** (Schwartz inequality).  $[E(XY)]^2 \le E(X^2)E(Y^2)$ 

Corollary 26.1.  $[Cov(X,Y)]^2 \leq V(X)V(Y)$ . This means  $|\rho(X,Y)| \leq 1$ .

Theorem 27 (Chebyshev's inequality).

$$P(|X - \mu| \ge t) \le \frac{\sigma^2}{t^2}, \forall t > 0$$

# 6 Important Discrete Densities

#### 6.1 Uniform

Discrete  
Unif
$$(a,b) \sim f(x) = \begin{cases} \frac{1}{b-a+1}, & a \leq x \in \mathbb{Z} \leq b \\ 0, & \text{otherwise} \end{cases}$$
 
$$\mu = \frac{a+b}{2}$$
 
$$\sigma^2 = \frac{(a+b-1)^2-1}{12}$$

# 6.2 Bernoulli

$$Ber(p) \sim f(x) = \begin{cases} p, & x = 1\\ 1 - p, & x = 0\\ 0, & \text{otherwise} \end{cases}$$

$$\mu = p$$

$$\sigma^2 = p - p^2$$

#### 6.3 Binomial

$$\mbox{Binom}(n;p) \sim f(x) = \begin{cases} \binom{n}{x} p^x (1-p)^{n-x}, & x=0,1,\cdots,n\\ 0, & \mbox{otherwise} \end{cases}$$
 
$$\mu = np$$
 
$$\sigma^2 = np(p-1)$$

#### 6.4 Geometric

$$\mathrm{Geom}(p) \sim f(x) = \begin{cases} p(1-p)^x, & x=0,1,\cdots,n\\ 0, & \text{otherwise} \end{cases}$$
 
$$\mu = \frac{1-p}{p}$$
 
$$\sigma^2 = \frac{1-p}{p^2}$$

#### 6.5 Negative binomial

NegBinom
$$(\alpha; p) \sim f(x) = \begin{cases} \binom{\alpha+x-1}{x} p^{\alpha} (1-p)^x, & x=0,1,\cdots,n \\ 0, & \text{otherwise} \end{cases}$$

$$\mu = \frac{p\alpha}{1-p}$$

$$\sigma^2 = \frac{p\alpha}{(1-p)^2}$$

## 6.6 Hypergeometric

HyperGeom
$$(r, r_1; n) \sim f(x) = \begin{cases} \frac{\binom{r_1}{x}\binom{r_{-r_1}}{n-x}}{\binom{r}{n}}, & x = 0, 1, \dots, n \\ 0, & \text{otherwise} \end{cases}$$

$$\mu = \frac{nr_1}{r}$$

$$\sigma^2 = \frac{nr_1(r - r_1)(r - n)}{r^2(r - 1)}$$

Consider a population of r objects, of which  $r_1$  are of one type and  $r_2 = r - r_1$  are of a second type. Suppose a random sample of size n is drawn from the pouplation. Let X be the number of objects of the first type in the sample.

# 6.7 Poisson

$$\operatorname{Poisson}(\lambda) \sim f(x) = \begin{cases} \frac{\lambda^x e^{-\lambda}}{x!}, & x = 0, 1, \cdots, n \\ 0, & \text{otherwise} \end{cases}$$
 
$$\mu = \lambda$$
 
$$\sigma^2 = \lambda$$
 
$$\Phi(z) = e^{\lambda(z-1)}$$

#### 6.8 Multinomial

$$\text{Multinom}(n; p_1, p_2, \cdots, p_n) \sim f(x_1, x_2, \cdots, x_n) \begin{cases} \frac{n!}{x_1!} p_1^{x_1} p_2^{x_2} \cdots p_n^{x_n}, & x_i \in \mathbb{N} \cup \{0\}, \ x_1 + x_2 + \cdots + x_r = n \\ 0, & \text{otherwise} \end{cases}$$

We have,  $X_i \sim \text{Binom}(n; p_i)$ .

**Theorem 28.** Let  $X_1, X_2, \dots, X_r$  be pair-wise independent. Let  $Y = X_1 + X_2 + \dots + X_r$ .

- $X_i \sim \text{Binom}(n_i; p) \implies Y \sim \text{Binom}(\sum_i n_i; p)$
- $X_i \sim \text{NegBinom}(\alpha_i; p) \implies Y \sim \text{NegBinom}(\sum_i \alpha_i; p)$
- $X_i \sim \text{Poisson}(\lambda) \implies Y \sim \text{Poisson}(\sum_i \lambda_i)$
- $X_i \sim \text{Geom}(p) \implies Y \sim \text{NegBinom}(r; p)$ .

# 7 Continuous Random Variable

**Definition 23** (Continuous random variable). A continuous random variable X on a probability space  $(\Omega, \mathcal{A}, P)$  is a real-valued function  $X : \Omega \to \mathbb{R}$  such that for  $x \in \mathbb{R}$ ,  $\{\omega | X(\omega) \le x\}$  is an event.

$$P(X=x) = 0, \forall x$$

# 7.1 Continuous Distribution

**Definition 24** (Continuous distribution).  $F_X : \mathbb{R} \to [0,1]$ 

$$F_X(x) = P(X \le x)$$

is called the distribution of continuous random varibale X.

Theorem 29. A continuous distribution is right-continuous and non-decreasing.

Corollary 29.1. If F is a continuous distribution,

$$\lim_{x \to -\infty} F(x) = 0$$

$$\lim_{x \to +\infty} F(x) = 1$$

## 7.2 Continuous Density

**Definition 25** (Continuous density function).  $f_X : \mathbb{R} \to \mathbb{R}$ 

$$\int_{-\infty}^{\infty} f_X(x) \ dx = 1$$

$$F(x) = \int_{-\infty}^{x} f(t) \ dt, \ \forall x \in \mathbb{R}$$

If such a density  $f_X$  exists, X and  $F_X$  are called absolutely continuous.

**Theorem 30.** If  $F_X$  is continuously differentiable (or, f is continuous) at  $x_0$ ,

$$f(x_0) = F'(x_0)$$

# 7.3 Change of Variable

**Theorem 31** (Change of variable). Let  $Y = \varphi(X)$ , where  $\varphi$  is differentiable and strictly increasing or decreasing in an interval I. Let  $f_X(x) = 0, \forall x \notin I$ .

$$f_Y(y) = \begin{cases} f\left(\varphi^{-1}(y)\right) \left| \frac{d}{dy} \left(\varphi^{-1}(y)\right) \right|, & \forall y \in \varphi(I) \\ 0, & \text{otherwise} \end{cases}$$

#### 7.4 Joint distribution

**Definition 26** (Joint distribution).  $F: \mathbb{R}^2 \to [0, 1]$ 

$$F_{X,Y}(x,y) = P(X \le x, Y \le y)$$

**Theorem 32.** Probability in a rectangular region is given by

$$P(a < X \le b, c < Y \le d) = F(b, d) - F(a, d) - F(b, c) + F(a, c)$$

# 7.5 Joint Density

**Definition 27** (Joint density).  $f: \mathbb{R}^2 \to \mathbb{R}$ 

$$\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(x, y) \ dx \ dy = 1$$

$$F(x,y) = \int_{-\infty}^{x} \int_{-\infty}^{y} f(u,v) \ dv \ du$$

**Theorem 33.** If f is continuous at  $(x_0, y_0)$ ,

$$f(x_0, y_0) = F_{xy}(x_0, y_0)$$

# 7.6 Independence

**Definition 28** (Independence). X, Y are independent iff

$$F(x,y) = F_X(x)F_y(y), \forall x, y \in \mathbb{R}$$

or,

$$f(x,y) = f_X(x)f_Y(y), \forall x, y \in \mathbb{R}$$

**Theorem 34.** Let  $X_1, X_2, \dots, X_n$  be pair-wise independent. Suppose,  $Y = \varphi(X_1, X_2, \dots, X_n)$  and  $Z = \psi(X_{m+1}, X_{m+2}, \dots, X_n)$  where  $1 \le m < n$ . Y, Z are independent.

## 7.7 Sum

Theorem 35 (Sum of continuous random variables).

$$F_{X+Y}(z) = \int_{-\infty}^{z} \int_{-\infty}^{\infty} f_{X,Y}(x, v - x) dx dv$$

$$f_{X+Y}(z) = \int_{-\infty}^{\infty} f_{X,Y}(x, z - x) \ dx = f_X(z) * f_Y(z)$$

# 7.8 Conditional Density

**Definition 29** (Conditional density). The conditional density of Y given X is defined as

$$f_{Y|X}(y|x) := \begin{cases} \frac{f_{X,Y}(x,y)}{f_X(x)}, & 0 < f_X(x) < \infty \\ 0, & \text{otherwise} \end{cases}$$

$$P(a \le Y \le b|X = x) = \int_a^b f_{Y|X}(y|x) \ dy$$

Theorem 36 (Baye's rule).

$$f_{X|Y}(x|y) = \frac{f_X(x)f_{Y|X}(y|x)}{\int_{-\infty}^{\infty} f_X(x)f_{Y|X}(y|x) \ dx}$$

# 7.9 Expectation

Definition 30 (Expectation of continuous random variable).

$$E(X) = \int_{-\infty}^{\infty} x f(x) \ dx$$

**Theorem 37.** Let  $X_1, X_2, \dots, X_n$  have joint density f and  $Z = \varphi(X_1, \dots, X_n)$ .

$$E(Z) = \int \varphi(x_1, \dots, x_n) f(x_1, \dots, x_n) d\mathbf{x}$$

Definition 31 (Conditional expectation).

$$E[Y|X=x] = \int_{-\infty}^{\infty} y f(y|x) \ dy = \frac{\int_{-\infty}^{\infty} y f(x,y) \ dy}{f_X(x)}$$

is called the conditional expectation of Y given X or the regression function of Y on X.

#### 7.10 Moments

Moments, variance, covariance, correlation are defined like the discrete case.

# 8 Important Continuous Densities

# 8.1 Symmetric

f is symmetric if  $f(-x) = f(x), \forall x$ . If X and -X have the same distribution, X is called a symmetric random variable.

#### 8.2 Standard Normal

$$\Phi(x) = \frac{1}{\sqrt{2\pi}}e^{-\frac{x^2}{2}}$$

$$\mu = 0$$

$$\sigma^2 = 1$$

 $\Phi$  is symmetric. The density and distribution have the same function.

#### 8.3 Normal

For  $\sigma > 0$ ,

$$n(\mu, \sigma^2) \sim f(x) = \frac{1}{\sigma\sqrt{2\pi}} \exp\left(-\frac{(x-\mu)^2}{2\sigma^2}\right)$$
  
$$F(x) = \Phi\left(\frac{y-\mu}{\sigma}\right)$$

 $X \sim \Phi \implies \mu + \sigma X \sim n(\mu, \sigma^2)$ 

#### 8.4 Exponential

$$\operatorname{Exp}(\lambda) \sim f(x) = \begin{cases} \lambda e^{-\lambda x}, & x \ge 0 \\ 0, & x < 0 \end{cases}$$
$$F(x) = \begin{cases} 1 - e^{-\lambda x}, & x \ge 0 \\ 0, & x < 0 \end{cases}$$
$$\mu = \frac{1}{\lambda}$$
$$\sigma^2 = \frac{1}{\lambda^2}$$

#### 8.5 Gamma

$$\Gamma(\alpha, \lambda) \sim f(x) = \begin{cases} \frac{\lambda^{\alpha}}{\Gamma(\alpha)} x^{\alpha - 1} e^{-\lambda x}, & x > 0 \\ 0, & x \le 0 \end{cases}$$

where  $\Gamma(x) = \int_0^\infty t^{x-1} e^{-t} dt, x > 0.$ 

$$\mu = \frac{\alpha}{\lambda}$$
$$\sigma^2 = \frac{\alpha}{\gamma^2}$$

 $\text{Exp}(\lambda) \sim \gamma(1, \lambda)$ 

# 8.6 Cauchy

Cauchy
$$(\alpha, \gamma) \sim f(x) = \frac{1}{\pi \gamma \left[1 + \left(\frac{x - \alpha}{\gamma}\right)^2\right]}$$
$$F(x) = \frac{1}{\pi} \tan^{-1} \left(\frac{x - \alpha}{\gamma}\right) + \frac{1}{2}$$

## 8.7 Standard Bivariate Normal

$$f(x,y) = \frac{1}{2\pi} e^{-\frac{x^2 + y^2}{2}}$$

**Theorem 38.** Let  $X \sim \text{Exp}(\lambda)$  and  $a, b \geq 0$ .

1. 
$$P(X > a + b) = P(X > a)P(X > b)$$

2. 
$$P(X > a + b|X > a) = P(x > b)$$

Both these statements are equivalent. If they hold for some X, X is either exponentially distributed or P(X > 0) = 0.

Theorem 39.  $X \sim n(0, \sigma^2) \implies X^2 \sim \Gamma\left(\frac{1}{2}, \frac{1}{2\sigma^2}\right)$ 

Theorem 40.  $X_i \sim \Gamma(\alpha_i, \lambda) \implies \sum_i X_i \sim \Gamma(\sum_i \alpha_i, \lambda)$ 

Theorem 41.  $X_i \sim n(\mu_i, \sigma_i^2) \implies \sum_i X_i \sim n(\sum_i \mu_i, \sum_i \sigma_i^2)$ 

**Theorem 42.** Here are some important results that may be useful in computations:

$$\bullet \int_{-\infty}^{\infty} e^{-\frac{x^2}{2}} dx = \sqrt{2\pi}$$

• 
$$\int_0^\infty x^{\alpha-1} e^{-\lambda x} dx = \frac{\Gamma(\alpha)}{\lambda^{\alpha}}$$

• 
$$\Gamma(x+1) = x\Gamma(x)$$

• 
$$\Gamma(1) = 1$$
,  $\Gamma\left(\frac{1}{2}\right) = \sqrt{\pi}$ 

• 
$$\Gamma(n) = (n-1)!, \ \forall n \in \mathbb{N}$$

• 
$$\Gamma\left(\frac{n}{2}\right) = \frac{\sqrt{\pi}(n-1)!}{2^{n-1}\left(\frac{n-1}{2}\right)!}, \forall \text{ odd natural number } n$$

# 9 Central Limit Theorem

**Theorem 43** (Central limit theorem). Let  $X_1, X_2, \cdots$  be independent, identically distributed random variables with mean  $\mu$  and variance  $\sigma^2$ . Let  $S_n = \sum_i X_i$ .

$$\lim_{n \to \infty} P\left(\frac{S_n - n\mu}{\sigma\sqrt{n}} \le x\right) = \Phi(x), \ \forall x \in \mathbb{R}$$

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Corollary 43.1. For very large n,  $\frac{S_n - n\mu}{\sigma\sqrt{n}} \sim \Phi$ .