02132 Assignment 2 report

Hardware implementation in Chisel of a small CPU running the image erosion

Group: 22

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github.com/rwiuff/02132Assignment2

November 12th

1 Work distribution

Table 1 shows the work distribution in the group for this project.

Table 1: Work distribution on the project

Name	Development tasks	Report tasks
Mikkel Arn Andersen		
Niclas Juul Schæffer		
Rasmus Wiuff	ISA	Section 2.1

2 Design

2.1. ISA and encoding

The ISA instructions are inspired from Appendix A in the assignment description. Chosen instructions are listed in Table 2.

Table 2: Instruction-set architecture used in the assignment

Instruction	**Syntax**	**Meaning**
	Arithmetic instructions	
Addition	`ADD Rx, Ry, Rz;`	`Rx = Ry + Rz`
Subtraction	`SUB Rx, Ry, Rz;`	`Rx = Ry - Rz`
Immediate addition	`ADDI Rx, Ry, z;`	`Rx = Ry + z`
Immediate subtraction	`SUBI Rx, Ry, z;`	`Rx = Ry - z`
Immediate multiplication	`MULT Rx, Ry, z;`	`Rx = Ry · z`
Increment	`INC, Rx`	`Rx = Rx + 1`
	Logic instructions	
Bitwise OR	`OR Rx, Ry, Rz;`	`Rx = Ry | Rz`
Bitwise AND	`AND Rx, Ry, Rz;`	`Rx = Ry & Rz`
	Memory instructions	
Load immediate	`LOADI Rx, y;`	`Rx = y`
Load data	`LOAD Rx, Ry;`	`Rx = memory(Ry)`
Store data	`STORE Rx, Ry;`	`memory(Ry) = Rx`
	Control and flow instructions	
Jump	`JMP x`	`GOTO INST x`
Jump if equal	`JEQ Rx, Ry, z;`	`if(Rx > Ry) GOTO INST z`
END	`END;`	`Terminate`

To design the instructions, first the bit sizes are considered. Some are given in the assignment. If there are 16 registers, these can be reached with $\log_2 16 = 4$ bits. Values for the logic and arithmetic operations are 16 bit as well as addresses in the memory. The opcodes fit within 4 bits.
The instruction layout is laid out in Fig. 1.

Figure 1: *Instruction layout. R1 and 2 are operands, Rd is the destination register. Remaining bits are used for either memory address or immediate value.*

OPCODE (4 bits)	Rd (4 bits)	R1 (4 bits)	R2 (4 bits)	Value/address (16 bit)
31···28	27···24	23···20	19···16	15···0

2.1.1. Opcodes As seen in Fig. 1 there are 4 bits allocated to opcodes. Table 2 accounts for seven register type operations, four jump types, three immediate types and two runtime operations.

Table 3: *OPCODE instruction bits.*

OPCODE bits	Instruction	OPCODE bits	Instruction
0001	`ADD`	1000	`LOADI`
0010	`SUB`	1001	`LOAD`
0011	`ADDI`	1010	`STORE`
0100	`SUBI`	1011	`INC`
0101	`MULT`	1100	`JMP`
0110	`OR`	1101	`JEQ`
0111	`AND`	1111	`END`

2.2. Compile and encode

2.2.1. Compiled to assember Listing 1 shows the erosion algorithm compiled to assebler using the ISA provided in Table 2.

2.2.2. Encoding the program The program in Listing 1 is encoding using the opcodes in Table 3 and instruction scheme in Fig. 1 to the machine code in Listing 2.

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Listing 1: *The program compiled to assembly*

```
    # Initial values
00. LOADI R0, 0;      # x counter
01. LOADI R1, 0;      # y counter
02. LOADI R2, 19;     # Pixel limit
03. LOADI R3, 0;      # Zero value
04. LOADI R4, 255;    # 255 value
    # For loop conditions
05. JEQ R0, R2, 47;   # Check x, GOTO END
06. JEQ R1, R2, 44;   # Check y, GOTO INC X
    # Output image adress
07. MULT R5, R1, 20;  # y * 20
08. ADD R6, R0, R5;   # x + y * 20
09. ADDI R5, R6, 400; # Out image address
    # Process border pixel
10. JEQ R0, R3, 40;   # If x or y = 0
11. JEQ R1, R3, 40;   #
12. JEQ R0, R4, 40;   # If x or y = 19
13. JEQ R1, R4, 40;   # GOTO erosion
    # Process inner pixel
14. MULT R6, R1, 20;  # y * 20
15. ADD R7, R0, R6;   # x + y * 20
16. LOAD R8, R7;      # Get input pixel
17. JEQ R8, R3, 40;   # If 0, GOTO erosion
    # Process outer pixels
18. SUBI R12, R0, 1;  # x - 1
19. ADDI R13, R0, 1;  # x + 1
20. SUBI R14, R1, 1;  # y - 1
21. ADDI R15, R1, 1;  # y + 1
22. MULT R6, R1, 20;  # y * 20
23. ADD R7, R6, R12;  # (x - 1) + y * 20
24. LOAD R8, R7;      # Save pixel in R8
25. MULT R6, R1, 20;  # y * 20
26. ADD R7, R6, R13;  # (x + 1) + y * 20
27. LOAD R9, R7;      # Save pixel in R9
28. AND R10, R8, R9;  # AND R8 and R9, save to R10
29. MULT R6, R14, 20; # (y - 1) * 20
30. ADD R7, R6, R0;   # x + (y - 1) * 20
31. LOAD R8, R7;      # Save pixel in R8
32. AND R9, R8, R10;  # AND R8 and R10, save to R9
33. MULT R6, R15, 20; # (y + 1) * 20
34. ADD R7, R6, R0;   # x + (y + 1) * 20
35. LOAD R10, R7;     # Save pixel in R10
36. AND R8, R9, R10;  # AND R9 and R10, save to R8
37. JEQ R8, R3, 40;   # If = 0 GOTO Erosion
    # No erosion
38. STORE R4, R5;     # Set pixel to 255
39. JMP 42;           # GOTO increment y
    # Erosion
40. STORE R3, R5;     # Set Pixel to zero
41. JMP 42;           # GOTO increment y
    # Increment y
42. INC R1;           # Increment y
43. JMP 6;            # Continue nested loop
    # Increment x
44. INC R0;           # Increment x
45. LOADI R1, 0;      # Zerorise y
46. JMP 5;            # Continue main loop
    # Terminate program
47. END;              # Terminate program
```

Listing 2: *The encoded program*

	OP	Rd	R1	R2	Value/adress
00.	1000	0000	0000	0000	0000000000000000
01.	1000	0001	0000	0000	0000000000000000
02.	1000	0010	0000	0000	0000000000010011
03.	1000	0011	0000	0000	0000000000000000
04.	1000	0100	0000	0000	0000000011111111
05.	1101	0000	0000	0010	0000000000101111
06.	1101	0000	0001	0010	0000000000101100
07.	0101	0101	0001	0000	0000000000010100
08.	0001	0110	0000	0101	0000000000000000
09.	0011	0101	0110	0000	0000000110010000
10.	1101	0000	0000	0011	0000000000101000
11.	1101	0000	0001	0011	0000000000101000
12.	1101	0000	0000	0100	0000000000101000
13.	1101	0000	0001	0100	0000000000101000
14.	0101	0110	0001	0000	0000000000010100
15.	0001	0111	0000	0110	0000000000000000
16.	1001	1000	0000	0111	0000000000000000
17.	1101	0000	1000	0011	0000000000101000
18.	0100	1100	0000	0000	0000000000000001
19.	0011	1101	0000	0000	0000000000000001
20.	0100	1110	0001	0000	0000000000000001
21.	0011	1111	0001	0000	0000000000000001
22.	0101	0110	0001	0000	0000000000010100
23.	0001	0111	0110	1100	0000000000000000
24.	1001	1000	0000	0111	0000000000000000
25.	0101	0110	0001	0000	0000000000010100
26.	0001	0111	0110	1101	0000000000000000
27.	1001	1001	0000	0111	0000000000000000
28.	0111	1010	1000	1001	0000000000000000
29.	0101	0110	1110	0000	0000000000010100
30.	0001	0111	0110	0000	0000000000000000
31.	1001	1000	0000	0111	0000000000000000
32.	0111	1001	1000	1010	0000000000000000
33.	0101	0110	1111	0000	0000000000010100
34.	0001	0111	0110	0000	0000000000000000
35.	1001	1010	0000	0111	0000000000000000
36.	0111	1000	1001	1010	0000000000000000
37.	1101	0000	1000	0011	0000000000101000
38.	1010	0000	0100	0101	0000000000000000
39.	1100	0000	0000	0000	0000000000101010
40.	1010	0000	0011	0101	0000000000000000
41.	1100	0000	0000	0000	0000000000101010
42.	1011	0001	0001	0000	0000000000000000
43.	1100	0000	0000	0000	0000000000000110
44.	1011	0000	0000	0000	0000000000000000
45.	1000	0001	0000	0000	0000000000000000
46.	1100	0000	0000	0000	0000000000000101
47.	1111	0000	0000	0000	0000000000000000

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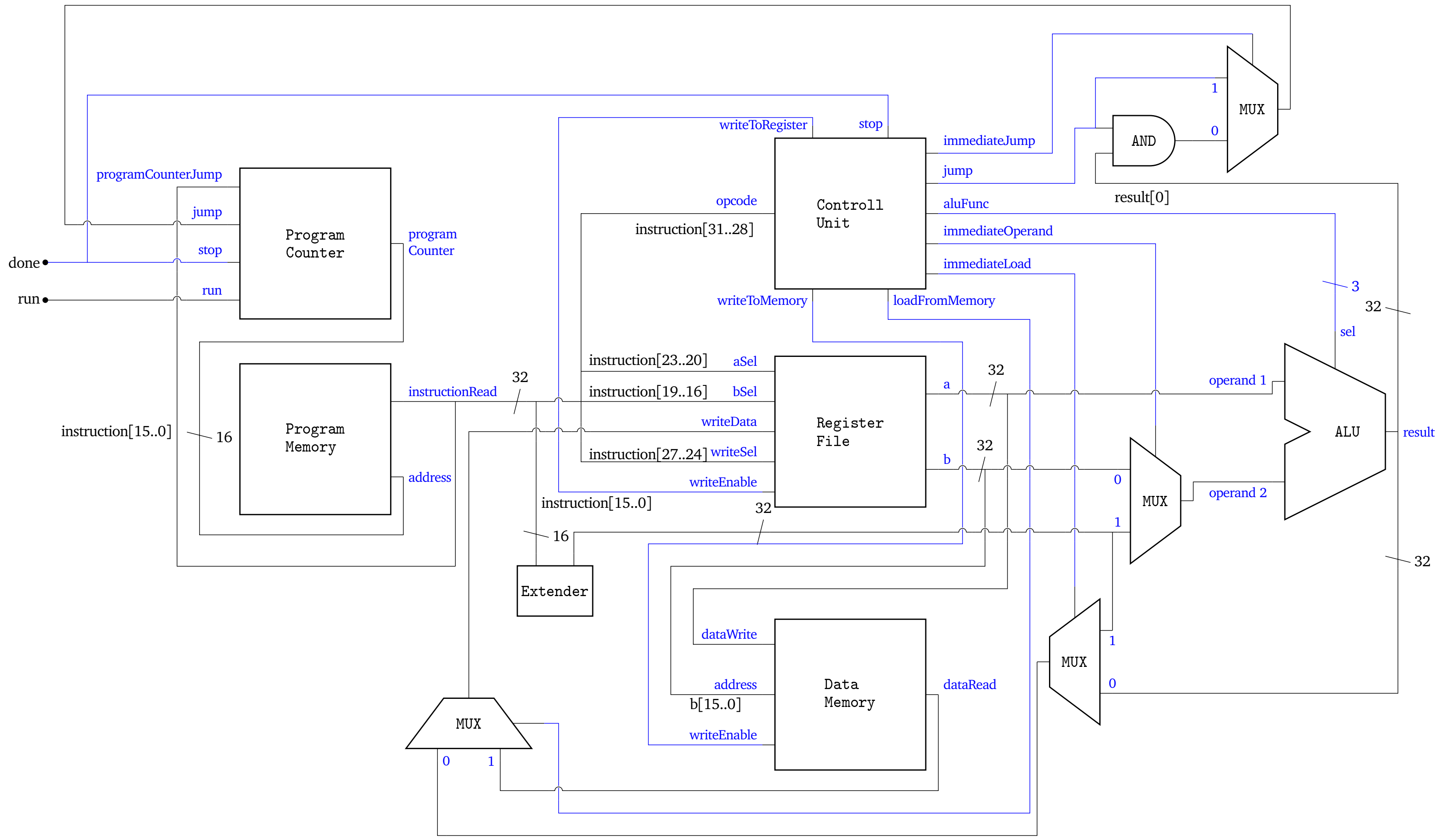
Figure 2: *Block diagram of the CPU architecture. Blue lines are control signals.*



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3 Implementation

Briefly discuss the implementation in Chisel of your design. You can include some code snippets if these are relevant to explain certain aspects of the implementation. In other words, try to answer the question "What does a reader need to know about your Chisel implementation?"

4 Test and analysis

Report here the results from the test you have carried out. Present the test you have developed (if any). Remember to discuss the results and the test you have carried out, do not just present them, but explain and argue their meaning. Address the design evaluation questions listed in Task 11 in the Assignment 2 document.

References

[1] Arduino, José Bagur, Taddy Chung *Arduino Memory Guide (19/09/2023)* *https://docs.arduino.cc/learn/programming/memory-guide*