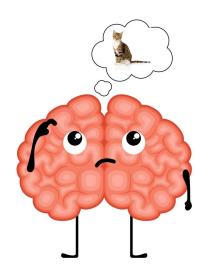
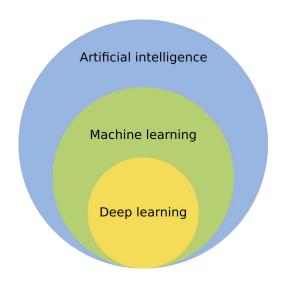


Wat is deep learning?

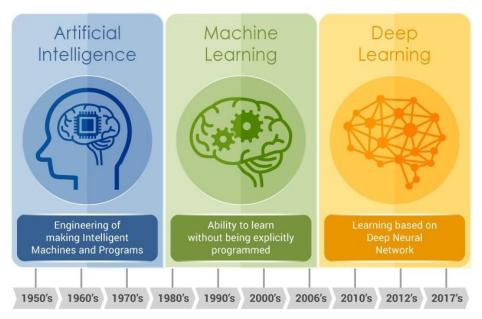
Deep learning is een machine learning methode waarbij kunstmatige neurale netwerken leren van grote hoeveelheden data.





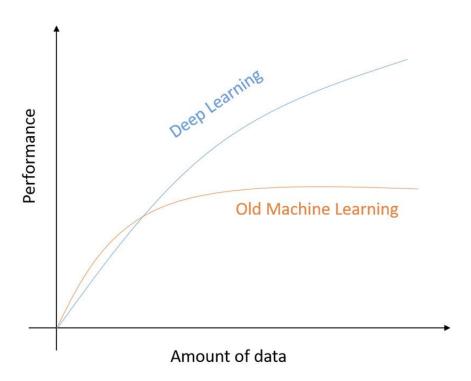
Het ontstaan van deep learning

Neurale netwerken and deep learning bestaan al een tijd, maar computers hadden niet voldoende rekenkracht om deep learning te faciliteren.



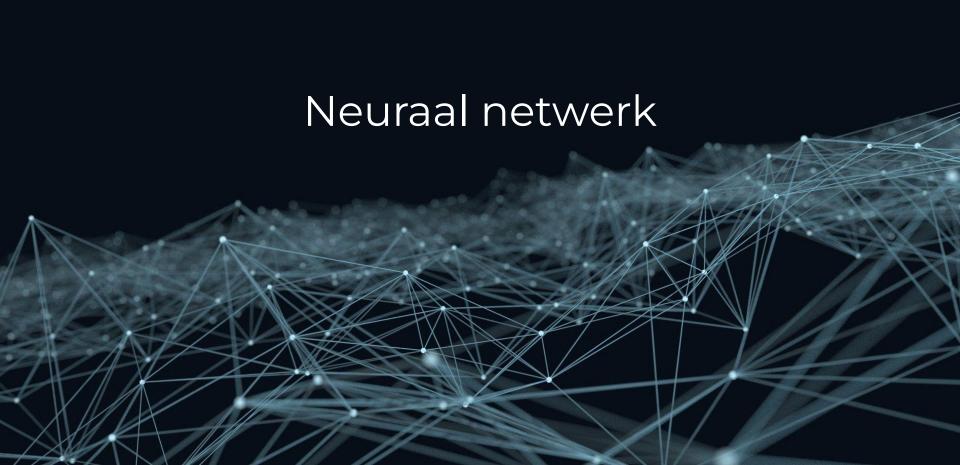
Waarom deep learning?

Prestatie van deep learning modellen t.o.v. hoeveelheid data blijft toenemen

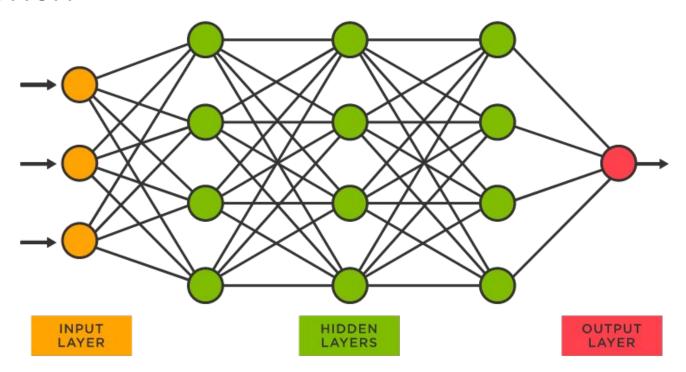


Machine learning vs. Deep learning

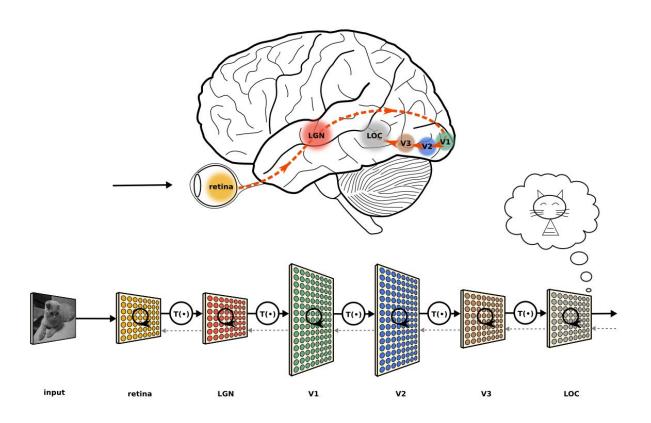
Machine Learning Car Not Car Output Input Feature extraction Classification Deep Learning Not Car Input Feature extraction + Classification Output

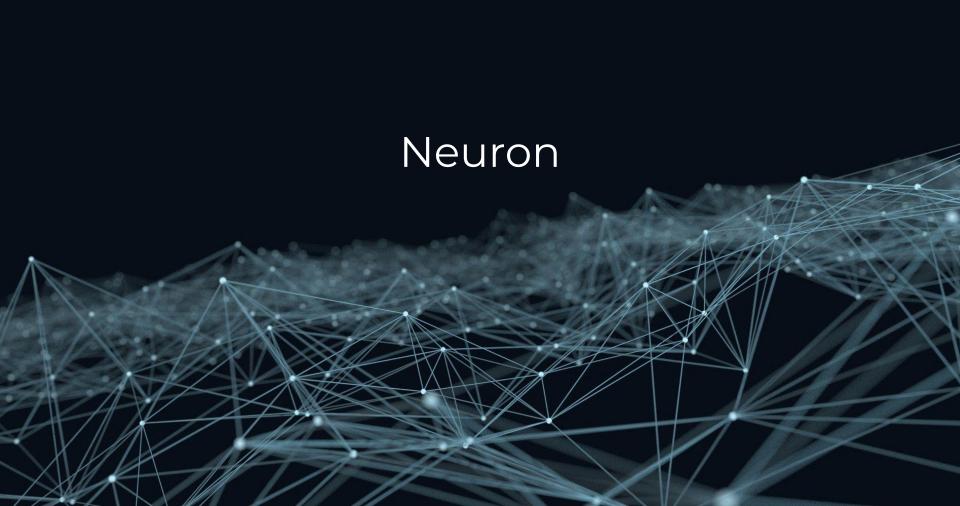


Een neuraal netwerk is een groep verbonden neuronen

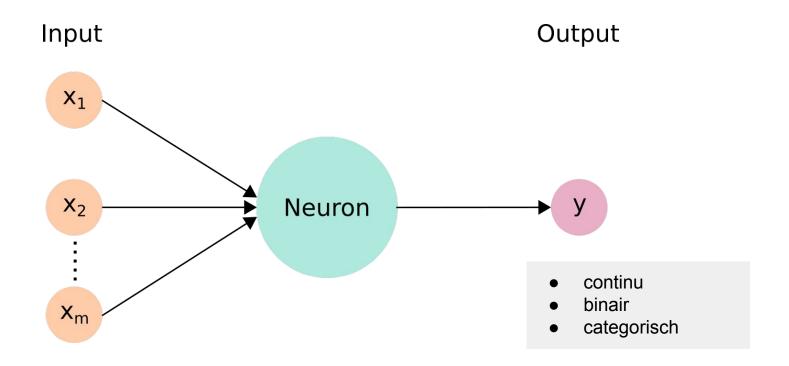


Geïnspireerd op de werking van het menselijk brein

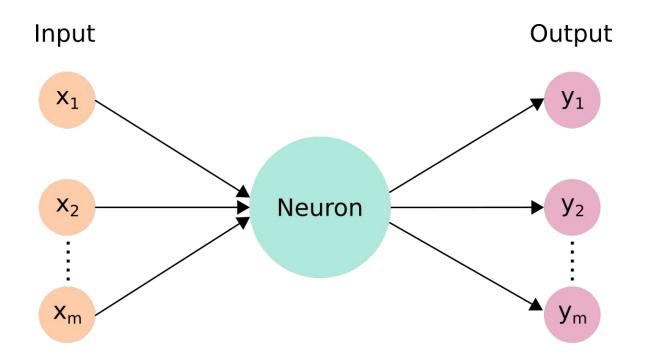




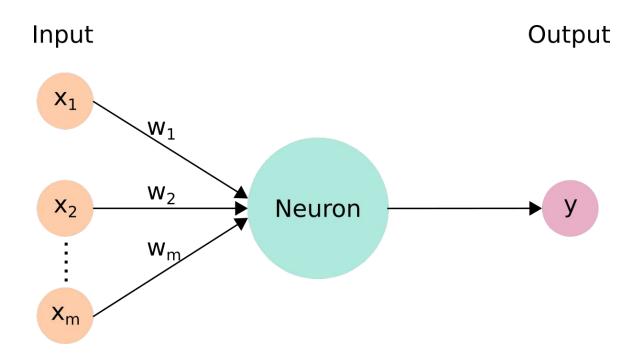
De werking van een neuron



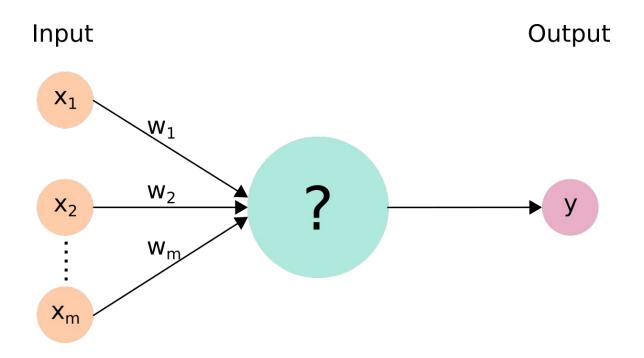
De werking van een neuron



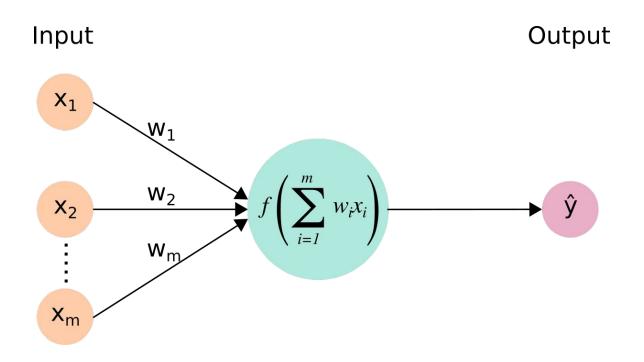
De gewichten



Wat gebeurt er in de neuron?

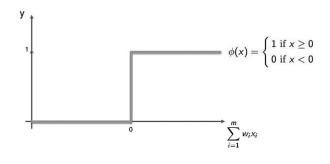


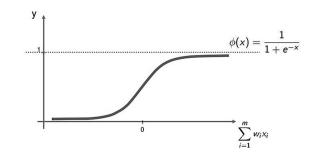
Activatiefunctie over gewogen som

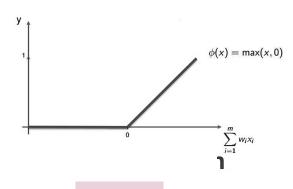




Activatiefuncties bepalen de output





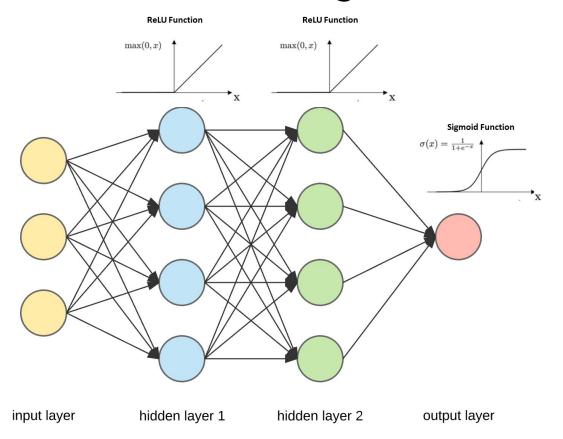


Threshold

Sigmoid

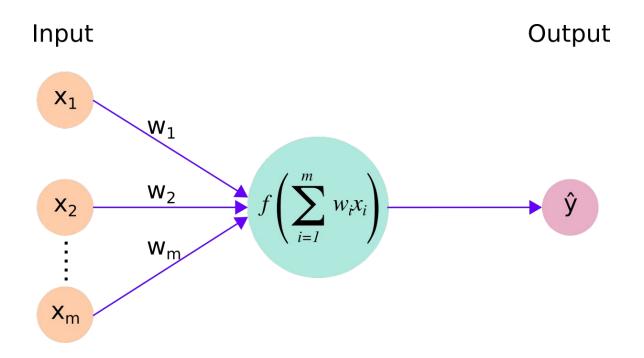
ReLU

Activatiefunctie voor elke laag

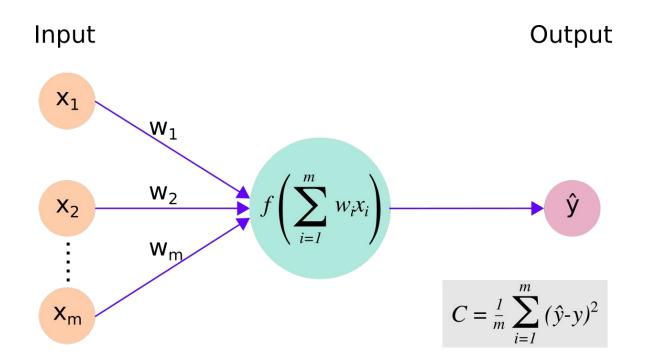




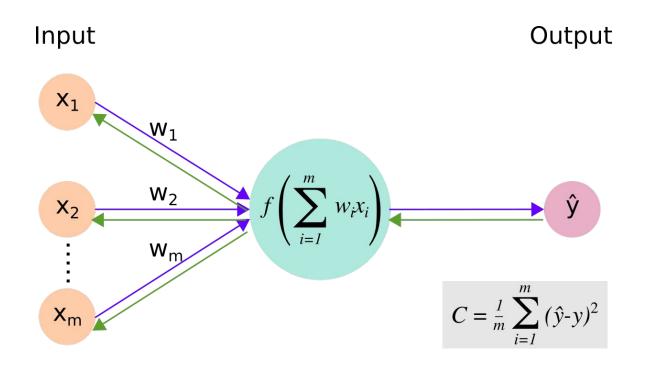
Een neurale netwerk trainen



Kostfunctie om error te meten

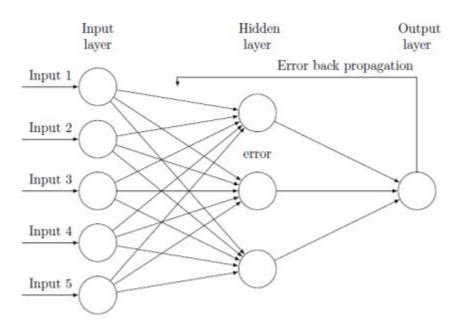


Gewichten updaten





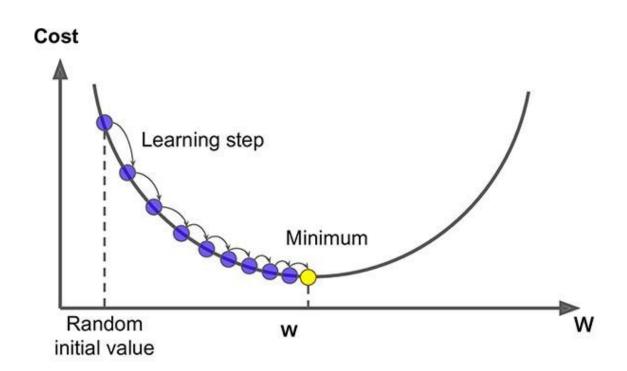
Back propagation



Gradient descent

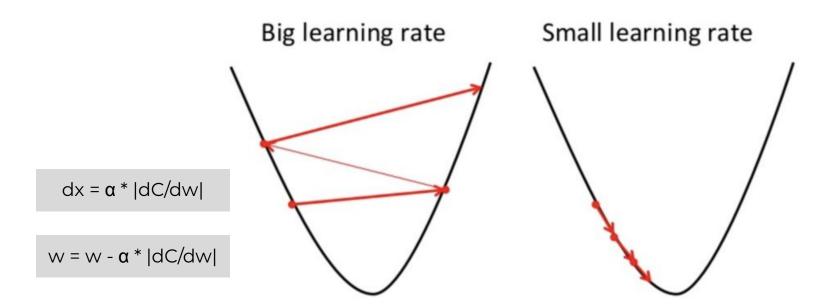
Stap voor stap kosten minimaliseren

Gradient = dC/dw



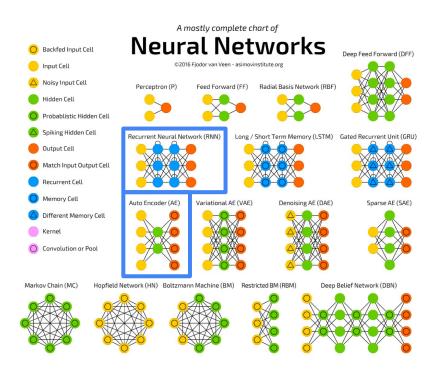
Learning rate

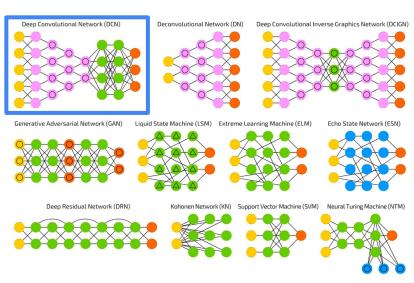
Learning rate mag niet te hoog en niet te laag zijn





Verschillende soorten NNs





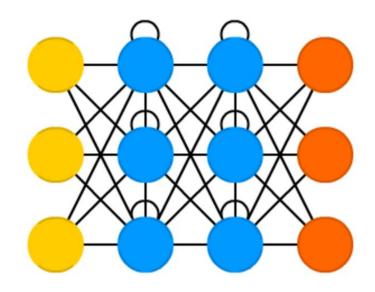
Recurrent Neural Network (RNN)

Sequentiële data (tijdsgebonden)

text data

audio data

Reinforcement learning



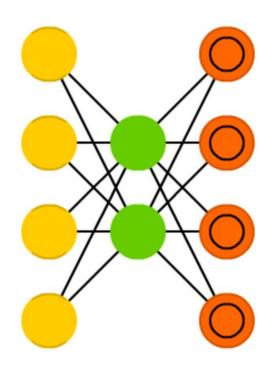
Auto Encoder (AE)

Model traint de output om gelijkenissen te vinden met de input

Representation/feature learning

audioverwerking

ruisonderdrukking

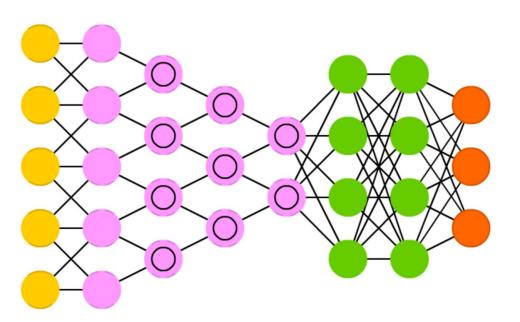


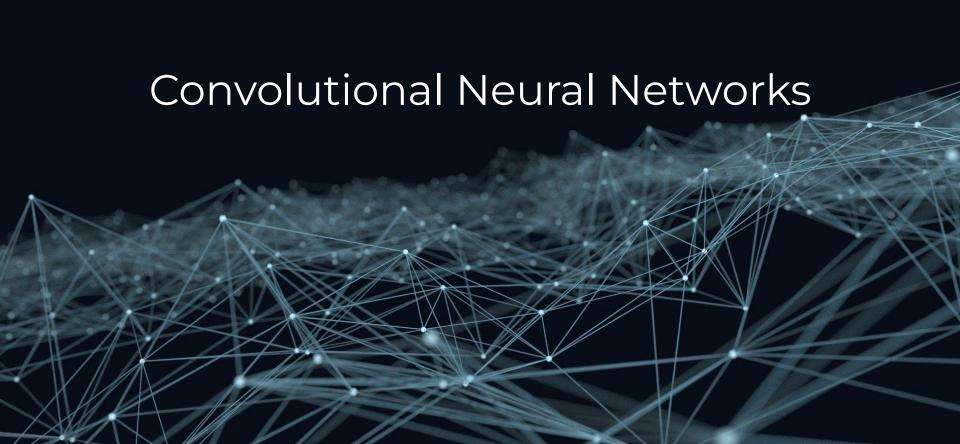
Deep Convolutional Neural Network (CNN)

Ruimte en tijdsgebonden data

Video

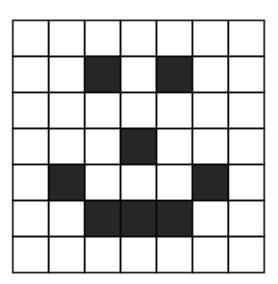
Audio





Beelddata



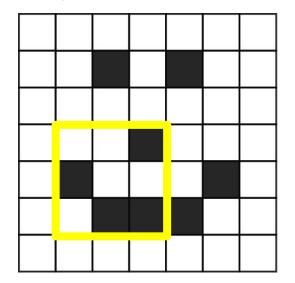


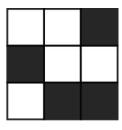
| 0 | 0 | 0 | 0 | 0 | 0 | 0 |
|---|---|---|---|---|---|---|
| 0 | 0 | 1 | 0 | 1 | 0 | 0 |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| 0 | 0 | 0 | 1 | 0 | 0 | 0 |
| 0 | 1 | 0 | 0 | 0 | 1 | 0 |
| 0 | 0 | 1 | 1 | 1 | 0 | 0 |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Convolutional layer

Feature map: Een filter/kernel die eigenschappen herkent

Feature map scant de hele afbeelding en geeft hoge scores als deze dezelfde eigenschap vindt.

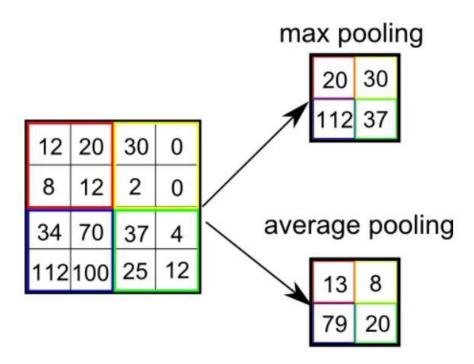




| 0 | 0 | 1 |
|---|---|---|
| 1 | 0 | 0 |
| 0 | 1 | 1 |

Pooling layer

Dimensie reductie d.m.v. poolen



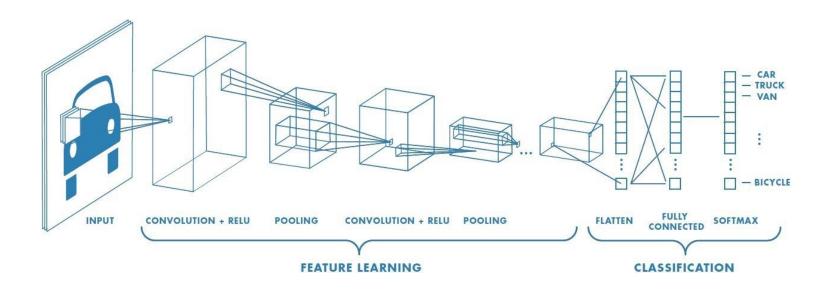
Flattening

Van tabel naar vector

| 1 | 1 | 0 | |
|---|---|---|--|
| 1 | 2 | 1 | |
|) | 2 | 1 | |
| | | | |
| | | | |

0

Structuur van een CNN





Gradient descent algoritmes

- Stochastic Gradient Descent Het model wordt geoptimaliseerd volgens de error na elke sample.
- Batch Gradient Descent Het model wordt geoptimaliseerd gebaseerd op de gemiddelde error van de hele trainingsset.
- Mini-Batch Gradient Descent —Splitst de trainingset op in batches en past het model aan na elke batch.

