

p1Exported 2/7/2026, 4:01:14 PM

For full code (e.g., implementation of each numerical integration method), please view my github repository: <https://github.com/rx9933/COE-347/tree/main/HW02>. Thank you!

Question 1

$$\frac{dy(x)}{dx} = y'(x) = -50(y - \cos(x))$$

1.1 & 1.2

In [30]:

```
import numpy as np
import matplotlib.pyplot as plt
import os

from true import *
from solvers.euler_explicit import *
from solvers.euler_implicit import *
from solvers.midpoint import *
from solvers.trapezoidal import *
from solvers.ab_2 import *
from solvers.rk_2 import *
from solvers.rk_4 import *

# Define the ODE
def f(x, y):
    return -50 * (y - np.cos(x))

# Parameters
y0 = 0
x_range = [0, 1]
x_start, x_end = x_range

# Get exact solution
sol_exact = exact_solution(f)
x_exact = np.linspace(x_start, x_end, 1000)
y_exact = sol_exact.sol(x_exact)[0]

# Define method-specific step size ranges
# Higher order methods can handle larger steps
method_step_ranges = {
    'Explicit Euler': {'min_steps': 50, 'max_steps': 8000,
    'num_points': 6},
    'Implicit Euler': {'min_steps': 10, 'max_steps': 1600,
    'num_points': 6},
    'Midpoint': {'min_steps': 30, 'max_steps': 1600, 'num_points': 6},
    # implicit_midpoint
    'Trapezoidal': {'min_steps': 20, 'max_steps': 1600, 'num_points':
    6},
    'Adams-Basforth2': {'min_steps': 60, 'max_steps': 1600,
    'num_points': 6},
    'RK2': {'min_steps': 30, 'max_steps': 1600, 'num_points': 6},
    'RK4': {'min_steps': 19, 'max_steps': 320, 'num_points': 6}
}

# Dictionary of methods
methods = {
    'Explicit Euler': explicit_euler,
```

This document was converted with CodeFormat: <https://code-format.com/>

```
'Implicit Euler': implicit_euler,
'Midpoint': midpoint, # implicit_midpoint,ss
'Trapezoidal': trapezoidal,
'Adams-Bashforth2': adams_bashforth2,
'RK2': rk2,
'RK4': rk4
}
num_values = 4
# Plot each method separately with different step sizes
for method_name, method_func in methods.items():
    plt.figure(figsize=(10, 6))

        # Plot exact solution
    plt.plot(x_exact, y_exact, 'k-', linewidth=2, label='Exact
(MATLAB-like)')

        # Get method-specific step sizes
    config = method_step_ranges[method_name]
    min_steps = config['min_steps']
    max_steps = config['max_steps']
    num_points = config['num_points']

        # Generate geometrically spaced step counts for this method
    num_steps_list = [int(min_steps * 2**i) for i in
range(num_values)]

        # Plot numerical solutions for different step sizes
    for i, num_steps in enumerate(num_steps_list):
        h = (x_end - x_start) / num_steps # Ensure exact step size

            x_num, y_num, n_evals = method_func(f, y0, x_range, h,
return_evals=True)

            # Interpolate exact solution to numerical grid for error
calculation
        y_exact_interp = sol_exact.sol(x_num)[0]
        error = compute_error(y_num, y_exact_interp)

            plt.plot(x_num, y_num, '--', linewidth=1.5,
label=f'n={num_steps}, h={h:.6f}, error={error:.2e}')

            plt.xlabel('x')
            plt.ylabel('y(x)')
            plt.title(f'{method_name} Method - ODE: dy/dx = -50(y - cos(x))')
            plt.legend()
            plt.grid(True, alpha=0.3)
            plt.tight_layout()
os.makedirs('solo_method', exist_ok=True)
```

The document was converted from CodeFormat <https://codeformat.com/>

```

    plt.savefig(f'solo_method/{method_name.replace(" ", "_")}_comparison.png', dpi=150, bbox_inches='tight')
    plt.show()

    # Print errors table
    print(f"\n{method_name} Errors:")
    print("-" * 60)
    print("Num Steps | Step size h | Relative L2 Error")
    print("-" * 60)
    for num_steps in num_steps_list:
        h = (x_end - x_start) / num_steps
        x_num, y_num = method_func(f, y0, x_range, h)
        y_exact_interp = sol_exact.sol(x_num)[0]
        error = compute_error(y_num, y_exact_interp)
        print(f" {num_steps:4d} | {h:8.6f} | {error:.4e}")
    print()

# All methods comparison on a single plot with split view
# Use method-appropriate step sizes for comparison
method_optimal_steps = {
    'Explicit Euler': 5000,    # Need many steps
    'Implicit Euler': 200,
    'Midpoint': 200,
    'Trapezoidal': 200,
    'Adams-Basforth2': 200,
    'RK2': 200,
    'RK4': 40                # Fewer steps needed for RK4
}

plt.figure(figsize=(16, 14)) # Increased from (14, 12) to (16, 14)
fig, (ax1, ax2, ax3) = plt.subplots(3, 1, figsize=(16, 14),
height_ratios=[4, 3, 2]) # Changed from [3, 3, 2] to [4, 3, 2]
plt.subplots_adjust(hspace=0.6)

# Define color cycle for better visibility
colors = plt.cm.tab10(np.linspace(0, 1, len(methods)))
color_dict = {name: color for name, color in zip(methods.keys(), colors)}

# Plot all methods on all axes
for idx, (method_name, method_func) in enumerate(methods.items()):
    style, linewidth = '--', 1.5

    # Use method-specific step count
    static_num_steps = 80
    h_static = (x_end - x_start) / static_num_steps

```

The document was converted with Code-Format: <https://code-format.com/>

```

x_num, y_num = method_func(f, y0, x_range, h_static)
y_exact_interp = sol_exact.sol(x_num)[0]
error = compute_error(y_num, y_exact_interp)

if method_name == 'Midpoint':
    style, linewidth = 'dotted', 4.0

# Main plot (full range)
ax1.plot(x_num, y_num, linestyle=style, linewidth=linewidth,
color=color_dict[method_name],
label=f'{method_name}: n={static_num_steps}, h={h_static:.4f}, error={error:.2e}')

# Zoomed plot 1 (0.9999 to 1.0)
ax2.plot(x_num, y_num, linestyle=style, linewidth=linewidth,
color=color_dict[method_name],
label=f'{method_name} (n={static_num_steps})')
x = 1e-5
zoom_x_min, zoom_x_max = 1-x, 1.0
ax2.set_xlim(zoom_x_min, zoom_x_max)
# Auto-adjust y-limits based on data in zoomed region
zoom_idx = (x_exact >= zoom_x_min) & (x_exact <= zoom_x_max)
x = 1e-5
zoom_y_min = y_exact[zoom_idx].min() * (1-x)
zoom_y_max = y_exact[zoom_idx].max() * (1+x)
ax2.set_ylim(zoom_y_min, zoom_y_max)

# Zoomed plot 2 (0 to 0.2)
ax3.plot(x_num, y_num, linestyle=style, linewidth=linewidth,
color=color_dict[method_name],
label=f'{method_name} (n={static_num_steps})')

# Plot exact solution on all axes
ax1.plot(x_exact, y_exact, 'k-', linewidth=1, label='Exact Solution',
alpha=0.8)
ax2.plot(x_exact, y_exact, 'k-', linewidth=1, label='Exact Solution',
alpha=0.8)
ax3.plot(x_exact, y_exact, 'k-', linewidth=1, label='Exact Solution',
alpha=0.8)

# Customize main plot
ax1.set_xlabel('x')
ax1.set_ylabel('y(x)')
ax1.set_title('All Methods Comparison with Method-Optimal Step Sizes - Full View', fontsize=14)
ax1.legend(loc='upper right', fontsize=8)
ax1.grid(True, alpha=0.3)

```

The document was converted with Code-Format: <https://code-format.com/>

```
x = 1e-5

# Customize zoomed plot (focus on region where lines overlap, e.g., x=[0.9, 1.0])
zoom1_x_min, zoom1_x_max = 1-x, 1.0
ax2.set_xlim(zoom1_x_min, zoom1_x_max)
# Auto-adjust y-limits based on data in zoomed region
x = 1e-5
zoom_idx = (x_exact >= zoom1_x_min) & (x_exact <= zoom1_x_max)
zoom_y_min = y_exact[zoom_idx].min() * (1-x)
zoom_y_max = y_exact[zoom_idx].max() * (1+x)
ax2.set_ylim(zoom_y_min, zoom_y_max)

ax2.set_xlabel('x')
ax2.set_ylabel('y(x)')
ax2.set_title(rf'Zoomed View 1: $x \in [{zoom1_x_min}, {zoom1_x_max}]$ (Near Endpoint)', fontsize=12)
ax2.legend(loc='upper right', fontsize=8)
ax2.grid(True, alpha=0.3)

# Customize zoomed plot 2 (0 to 0.2)
zoom2_x_min, zoom2_x_max = 0.0, 0.1
ax3.set_xlim(zoom2_x_min, zoom2_x_max)
# Auto-adjust y-limits based on data in zoomed region
zoom2_idx = (x_exact >= zoom2_x_min) & (x_exact <= zoom2_x_max)
zoom2_y_min = y_exact[zoom2_idx].min() * 0.99
zoom2_y_max = y_exact[zoom2_idx].max() * 1.01
ax3.set_ylim(zoom2_y_min, zoom2_y_max)

ax3.set_xlabel('x')
ax3.set_ylabel('y(x)')
ax3.set_title(rf'Zoomed View 2: $x \in [{zoom2_x_min}, {zoom2_x_max}]$ (Initial Region)', fontsize=12)
ax3.legend(loc='lower right', fontsize=8)
ax3.grid(True, alpha=0.3)

# Add rectangles to main plot showing zoom regions
import matplotlib.patches as patches

# Zoom region 1 rectangle
rect1 = patches.Rectangle((zoom1_x_min, ax1.get_ylim()[0]),
                           zoom1_x_max - zoom1_x_min,
                           ax1.get_ylim()[1] - ax1.get_ylim()[0],
                           linewidth=2, edgecolor='red',
                           facecolor='none',
                           linestyle='--', alpha=0.6)
ax1.add_patch(rect1)
ax1.text(zoom1_x_max + 0.005, ax1.get_ylim()[0] + 0.2, 'Zoom 1',
         color='red', fontweight='bold', fontsize=10)
```

Color source was converted with code 10 mat: <https://code-format.com/>

```
# Zoom region 2 rectangle
rect2 = patches.Rectangle((zoom2_x_min, ax1.get_ylim()[0]),
                           zoom2_x_max - zoom2_x_min,
                           ax1.get_ylim()[1] - ax1.get_ylim()[0],
                           linewidth=2, edgecolor='blue',
                           facecolor='none',
                           linestyle='--', alpha=0.6)
ax1.add_patch(rect2)
ax1.text(zoom2_x_max + 0.005, ax1.get_ylim()[0] + 0.4, 'Zoom 2',
          color='blue', fontsize=10)
plot_data = {}

# Combined convergence study plot with all methods
plt.figure(figsize=(10, 6))

for method_name, method_func in methods.items():
    config = method_step_ranges[method_name]
    min_steps = config['min_steps']

    num_steps_list = [int(min_steps * 2**i) for i in
range(num_values)]

    inv_h = []
    errors = []

    for num_steps in num_steps_list:
        h = (x_end - x_start) / num_steps
        x_num, y_num = method_func(f, y0, x_range, h)
        y_exact_interp = sol_exact.sol(x_num)[0]
        error = compute_error(y_num, y_exact_interp)

        inv_h.append(num_steps) # since h = 1 / n on [0,1]
        errors.append(error)

    # store for later order estimation
    plot_data[method_name] = (inv_h, errors)

    plt.plot(inv_h, errors, 'o-', label=f'{method_name}')
plt.grid(True, alpha=0.3)
plt.xscale('log')
plt.yscale('log')
plt.xlim(0, max(num_steps_list)+1000)
plt.xlabel('Number of Steps (n)')
plt.ylabel('Absolute Error')
plt.title('Convergence Study: Error vs. Number of Steps')
plt.legend()
plt.tight_layout()
```

This document was converted with Code-Format: <https://code-format.com/>

```
# Add reference slopes for convergence order
x_ref = np.array([10, 10000], dtype=float)
for order, label in [(1, '1st order'), (2, '2nd order'), (4, '4th
order')]:
    y_ref = 10 * x_ref**(-order) # Arbitrary scaling for visibility
    plt.plot(x_ref, y_ref, 'k:', alpha=0.5, linewidth=0.5)
    plt.text(x_ref[-1]*1.15, y_ref[-1]*2.1, label, fontsize=8,
alpha=0.7)

os.makedirs('convergence', exist_ok=True)
plt.savefig('convergence/error_vs_steps_method_ranges.png', dpi=150,
bbox_inches='tight')
plt.show()

# Print computational efficiency comparison
print("\n" + "="*100)
print("COMPUTATIONAL EFFICIENCY COMPARISON")
print("="*100)
print(f"{'Method':<20} {'Steps to Error < 1e-3':<25} {'Function
Evals':<20} {'Step Size':<15}")
print("-"*100)

target_error = 1e-3
for method_name, method_func in methods.items():
    config = method_step_ranges[method_name]
    min_steps = config['min_steps']
    max_steps = config['max_steps']

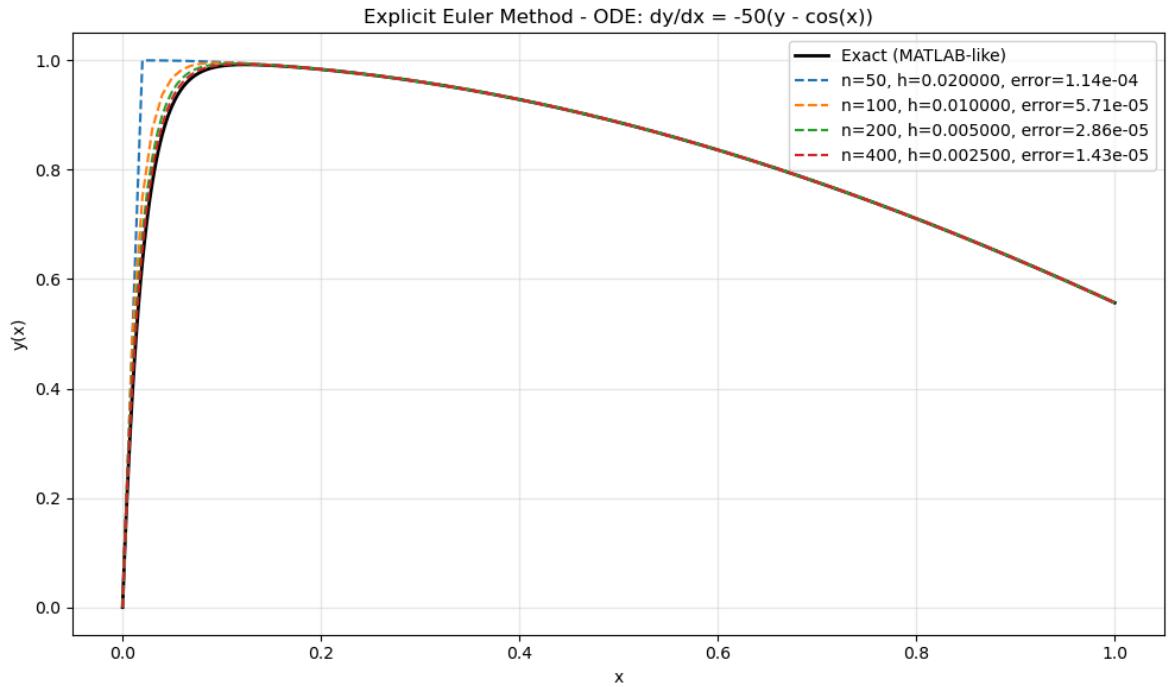
    # Find steps needed for target accuracy
    test_steps = [int(min_steps * 2**i) for i in range(num_values)]

    for num_steps in sorted(test_steps):
        h = (x_end - x_start) / num_steps
        x_num, y_num, n_evals = method_func(f, y0, x_range, h,
return_evals=True)
        y_exact_interp = sol_exact.sol(x_num)[0]
        error = compute_error(y_num, y_exact_interp)

        if error < target_error:
            print(f"{method_name:<20} {num_steps:<25} {n_evals:<20}
{h:<15.6f}")
            break
        else:
            print(f"{method_name:<20} {'> ' + str(max_steps):<25} {'-':
<20} {'-':<15}")

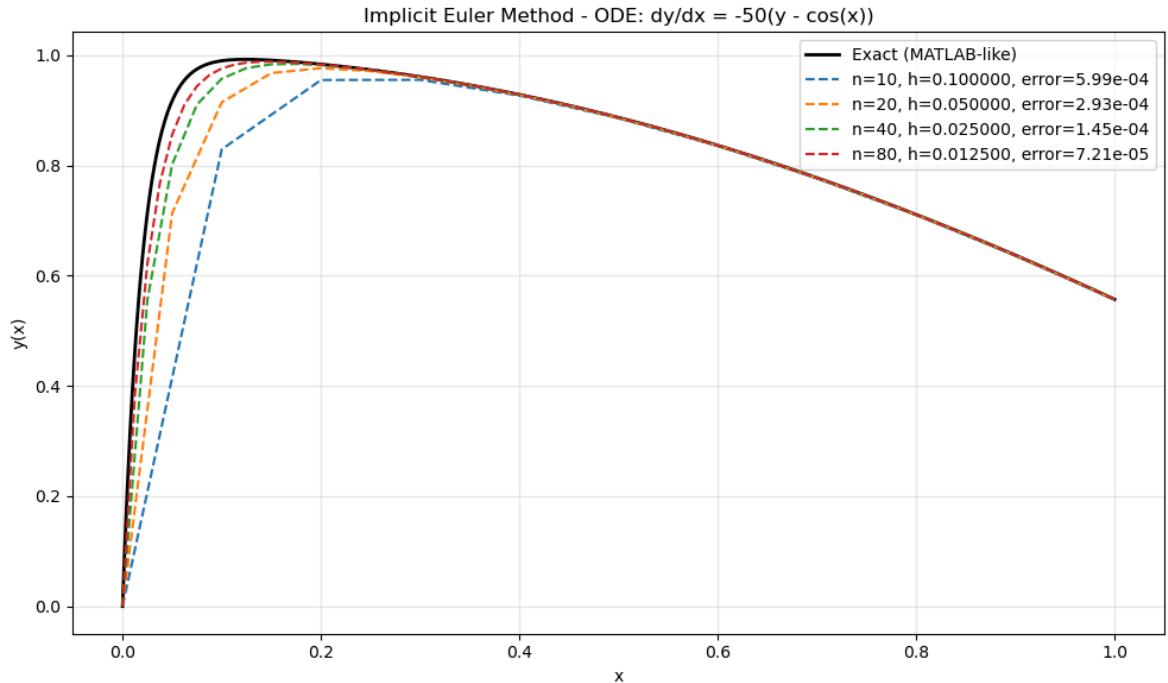

```

```
print("=*100)
```



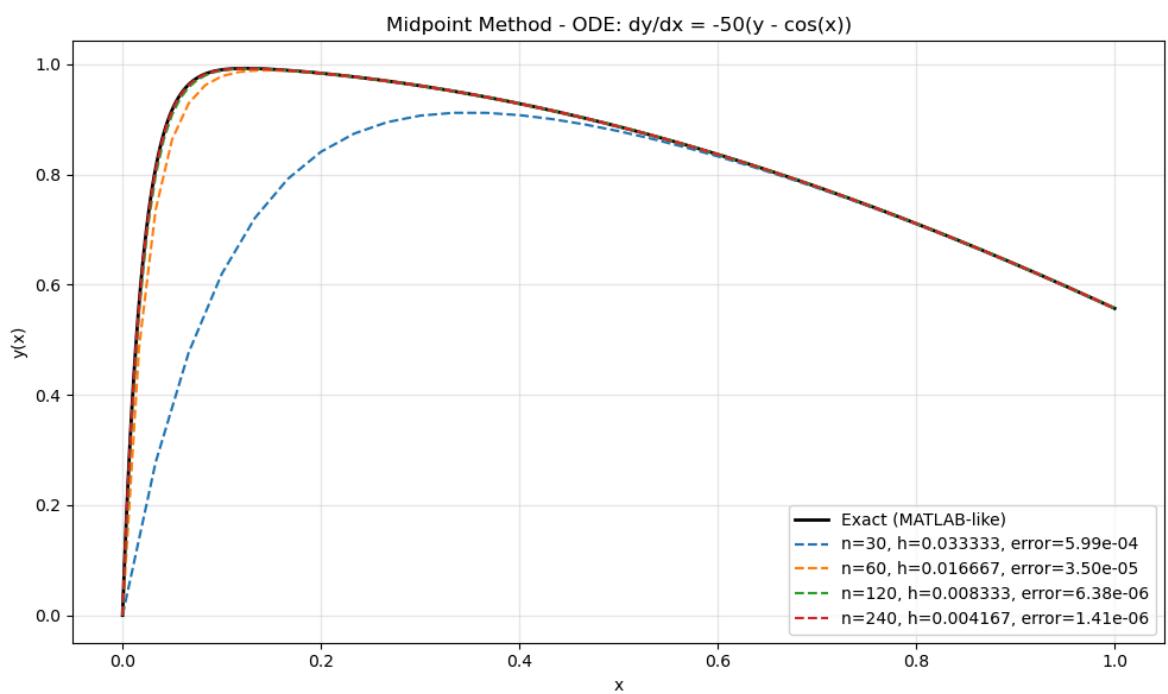
Explicit Euler Errors:

Num Steps	Step size h	Relative L2 Error
50	0.020000	1.1358e-04
100	0.010000	5.7061e-05
200	0.005000	2.8597e-05
400	0.002500	1.4315e-05



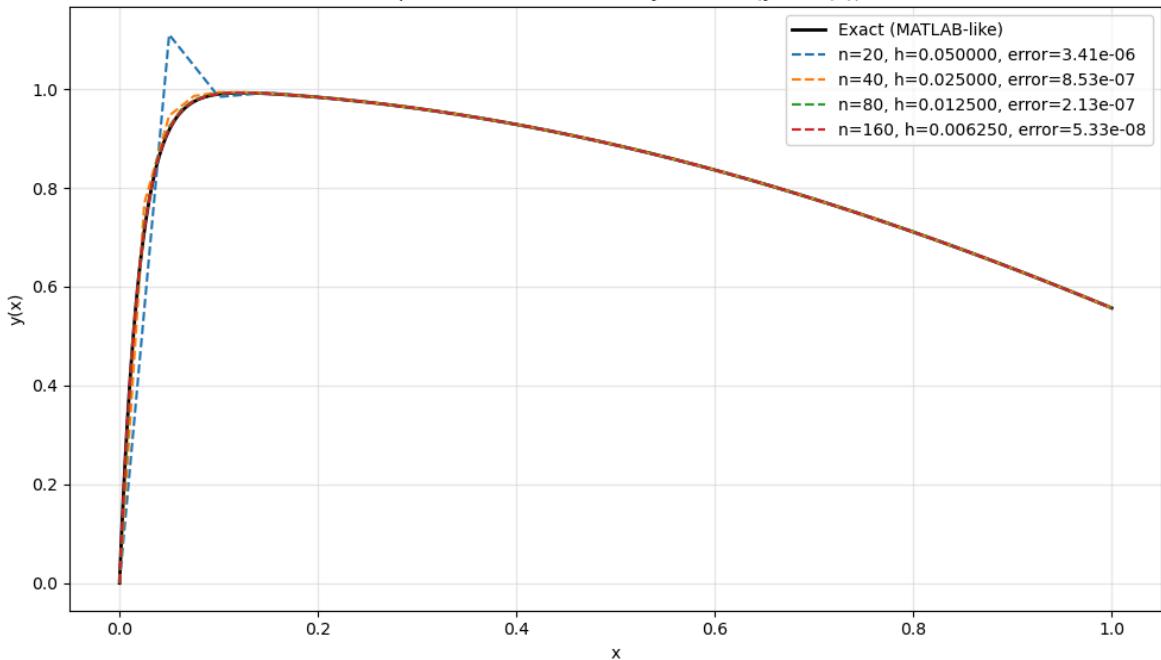
Implicit Euler Errors:

Num Steps	Step size h	Relative L2 Error
10	0.100000	5.9947e-04
20	0.050000	2.9325e-04
40	0.025000	1.4498e-04
80	0.012500	7.2077e-05



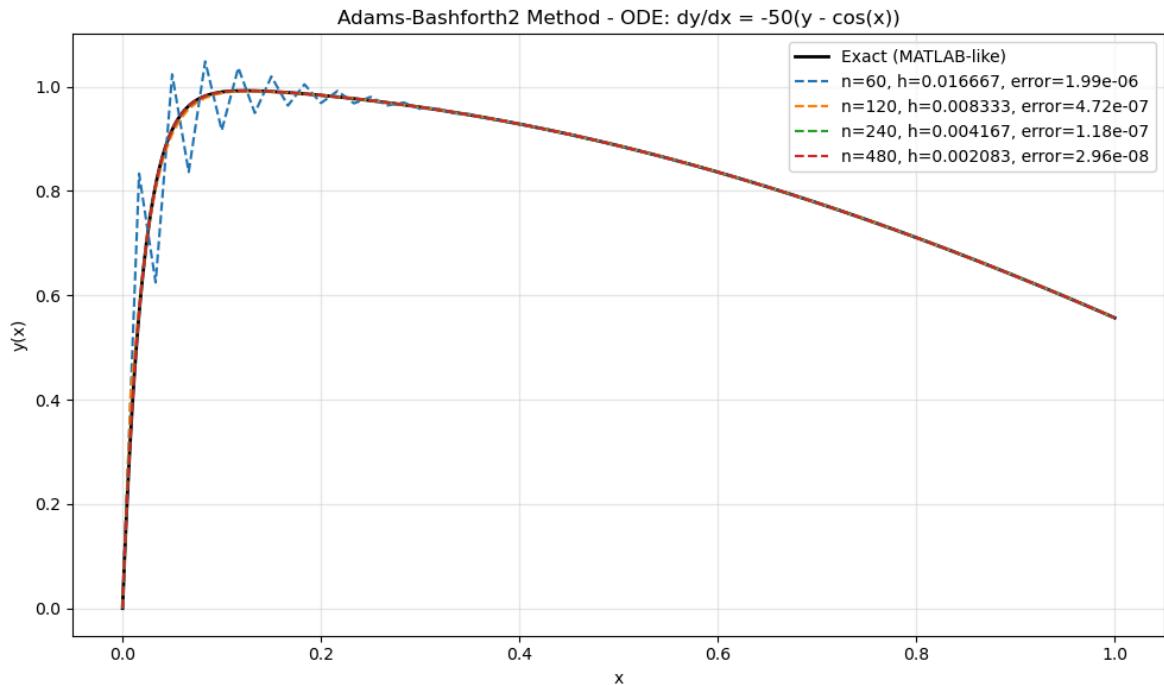
Midpoint Errors:

Num Steps	Step size h	Relative L2 Error
30	0.033333	5.9879e-04
60	0.016667	3.5003e-05
120	0.008333	6.3805e-06
240	0.004167	1.4052e-06

Trapezoidal Method - ODE: $dy/dx = -50(y - \cos(x))$ 

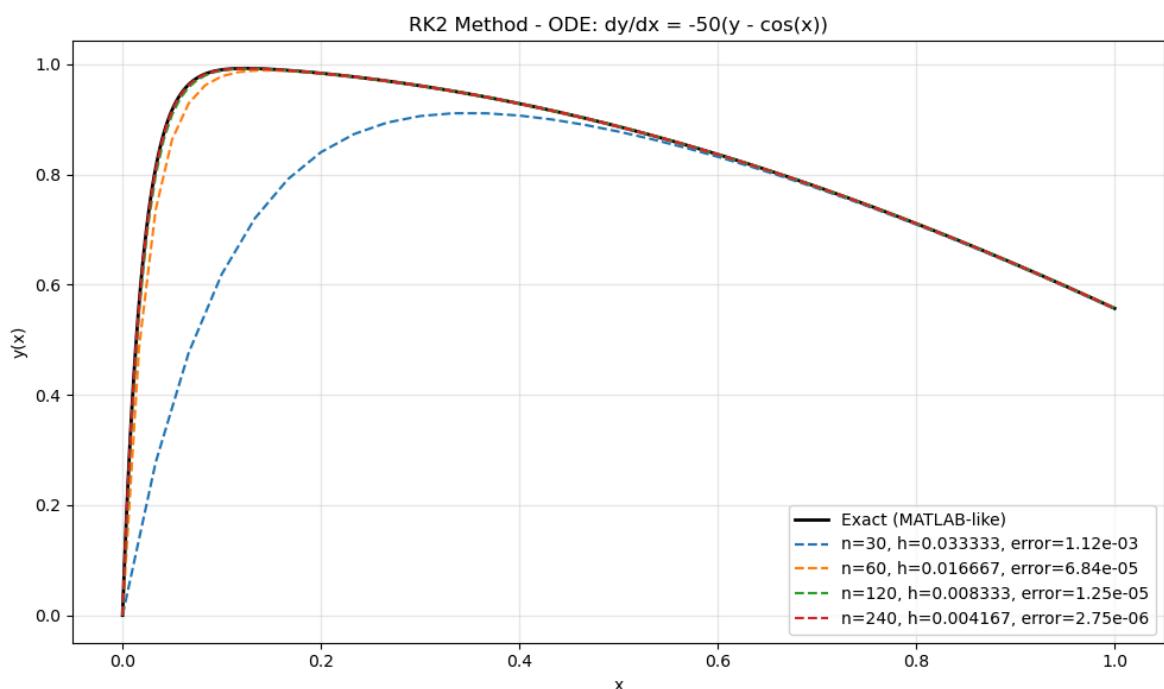
Trapezoidal Errors:

Num Steps	Step size h	Relative L2 Error
20	0.050000	3.4128e-06
40	0.025000	8.5304e-07
80	0.012500	2.1325e-07
160	0.006250	5.3312e-08



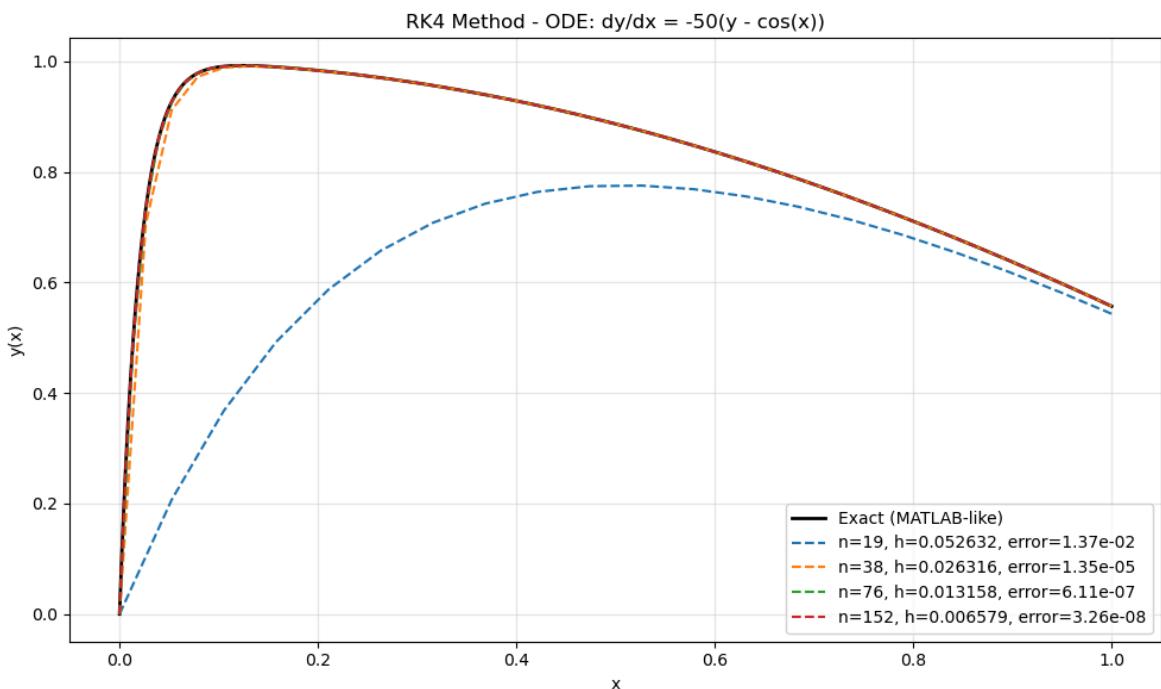
Adams-Bashforth2 Errors:

Num Steps	Step size h	Relative L2 Error
60	0.016667	1.9949e-06
120	0.008333	4.7220e-07
240	0.004167	1.1826e-07
480	0.002083	2.9591e-08



RK2 Errors:

Num Steps	Step size h	Relative L2 Error
30	0.033333	1.1160e-03
60	0.016667	6.8442e-05
120	0.008333	1.2497e-05
240	0.004167	2.7548e-06



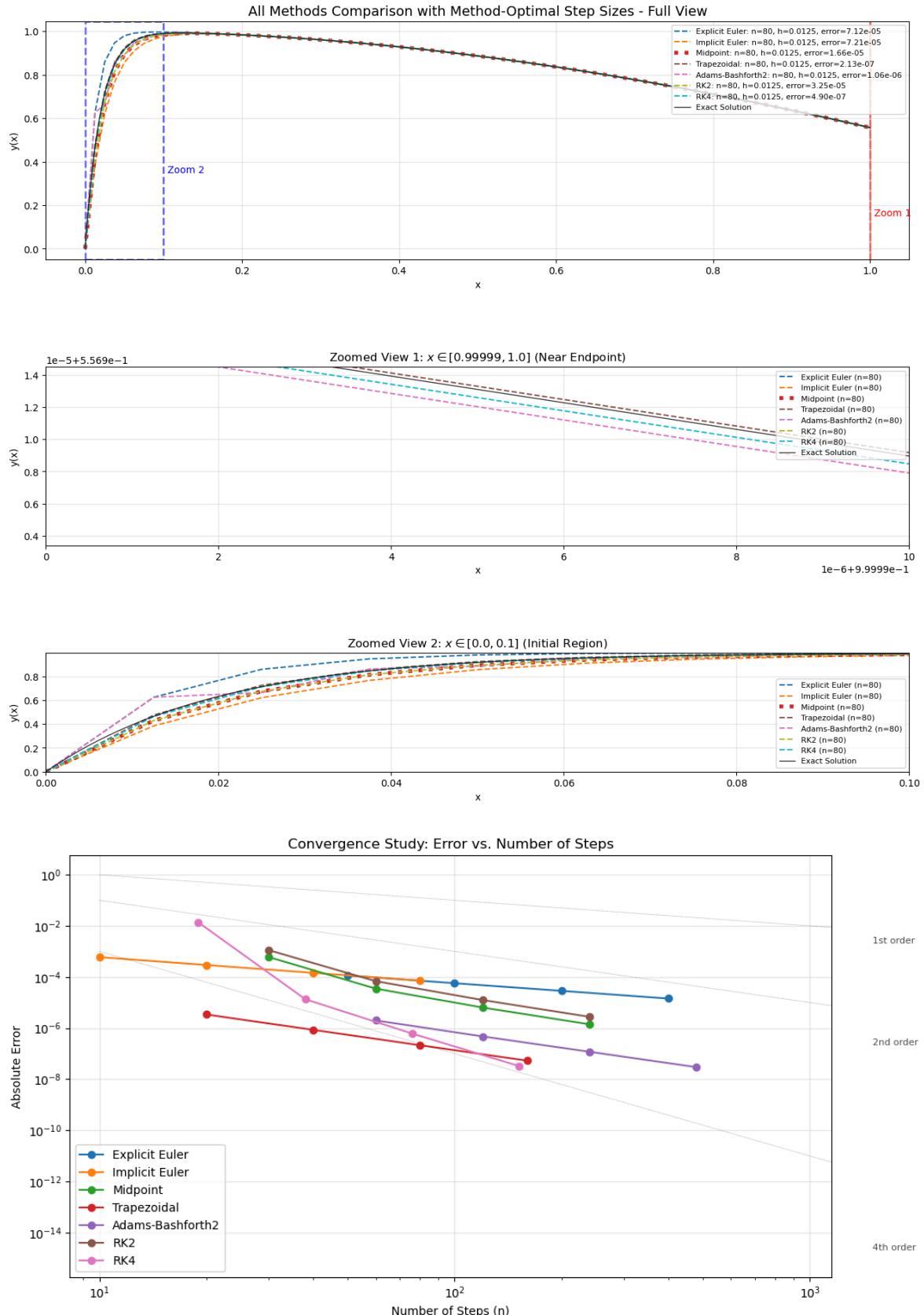
RK4 Errors:

Num Steps	Step size h	Relative L2 Error
19	0.052632	1.3661e-02
38	0.026316	1.3483e-05
76	0.013158	6.1054e-07
152	0.006579	3.2620e-08

```
/tmp/ipykernel_1112918/3634423248.py:255: UserWarning: Attempt to set
non-positive xlim on a log-scaled axis will be ignored.
plt.xlim(0, max(num_steps_list)+1000)
```

<Figure size 1600x1400 with 0 Axes>

The document was converted with Code-Format: <https://code-format.com/>



=====		
=====		
COMPUTATIONAL EFFICIENCY COMPARISON		
=====		
Method	Steps to Error < 1e-3	Function Evals
Step Size		

Explicit Euler 0.020000	50	50
Implicit Euler 0.100000	10	70
Midpoint 0.033333	30	60
Trapezoidal 0.050000	20	258
Adams-Bashforth2 0.016667	60	119
RK2 0.016667	60	120
RK4 0.026316	38	152
=====		
=====		

1.3

In [23]:

```

expected_order = {
    "Explicit Euler": 1,
    "Implicit Euler": 1,
    "Midpoint": 2,
    "Trapezoidal": 2,
    "Adams-Bashforth2": 2,
    "RK2": 2,
    "RK4": 4,
}

for method, (inv_h, errors) in plot_data.items():
    h = 1.0 / np.array(inv_h)
    E = np.array(errors)

    # Build least-squares system: log(E) = alpha * log(h) + log(C)
    X = np.column_stack([
        np.log(h),                      # slope term
        np.ones_like(h)                  # intercept term
    ])
    y = np.log(E)

    # Solve least squares
    coeffs, residuals, rank, svals = np.linalg.lstsq(X, y, rcond=None)
    alpha, logC = coeffs

    alpha_exp = expected_order.get(method, None)

    if alpha_exp is not None:
        print(f"{method:20s}: alpha ≈ {alpha:.2f} (expected {alpha_exp})")
    else:
        print(f"{method:20s}: alpha ≈ {alpha:.2f}")

```

Explicit Euler	: alpha ≈ 1.00 (expected 1)
Implicit Euler	: alpha ≈ 1.02 (expected 1)
Midpoint	: alpha ≈ 2.87 (expected 2)
Trapezoidal	: alpha ≈ 2.00 (expected 2)
Adams-Bashforth2	: alpha ≈ 2.02 (expected 2)
RK2	: alpha ≈ 2.84 (expected 2)
RK4	: alpha ≈ 6.05 (expected 4)

1.4

In [31]:

```
# Minimal all_data creation
common_num_steps = [50*2**i for i in range(0,8)] # Choose
appropriate values
all_data = {}

for method_name, method_func in methods.items():
    errors = []
    evals = []

    for num_steps in common_num_steps:
        h = (x_end - x_start) / num_steps
        x_num, y_num, n_evals = method_func(f, y0, x_range, h,
return_evals=True)
        y_exact_interp = sol_exact.sol(x_num)[0]
        error = compute_error(y_num, y_exact_interp)
        errors.append(error)
        evals.append(n_evals)

    all_data[method_name] = {
        'errors': np.array(errors),
        'evals': np.array(evals),
        'num_steps': common_num_steps,
        'step_sizes': [(x_end - x_start)/n for n in common_num_steps]
    }
```

```
/home/mili/COE-347/HW02/solvers/euler_implicit.py:20: RuntimeWarning:
The iteration is not making good progress, as measured by the
improvement from the last ten iterations.
y[i+1] = fsolve(F, y_guess)[0]
/home/mili/COE-347/HW02/solvers/trapezoidal.py:19: RuntimeWarning: The
iteration is not making good progress, as measured by the
improvement from the last ten iterations.
y[i+1] = fsolve(F, y_guess)[0]
```

In [32]:

```

plt.figure(figsize=(12, 5))

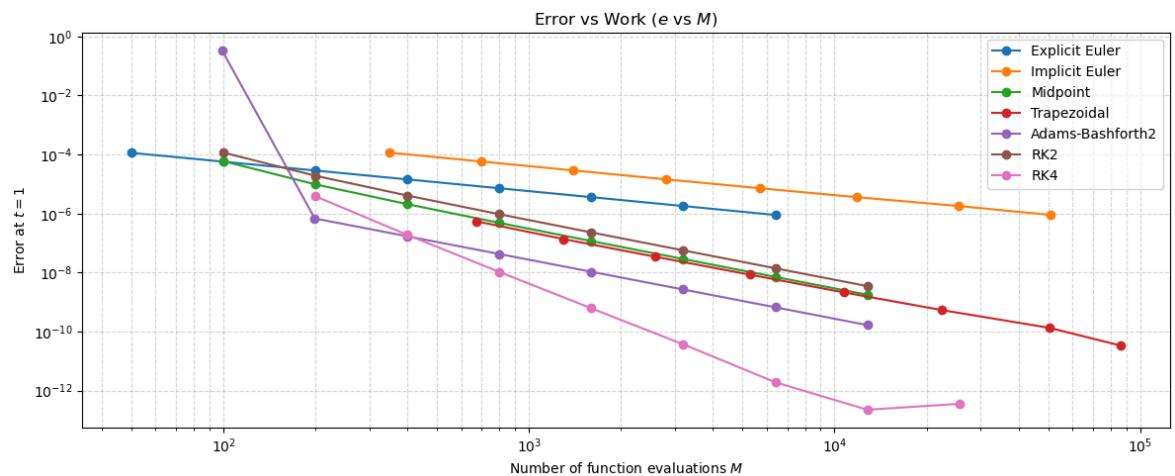
for method_name in all_data.keys():
    M_vals = all_data[method_name]['evals']           # Function
    evaluations
    e_vals = all_data[method_name]['errors']          # Errors

    # Ensure numpy arrays
    M_vals = np.array(M_vals, dtype=float)
    e_vals = np.array(e_vals, dtype=float)

    plt.loglog(M_vals, e_vals, marker='o', label=method_name)

plt.xlabel(r'Number of function evaluations $M$')
plt.ylabel(r'Error at $t = 1$')
plt.title(r'Error vs Work ($e$ vs $M$)')
plt.legend()
plt.grid(True, which="both", ls="--", alpha=0.5)
plt.tight_layout()
plt.show()

```



The log–log plot of error e versus number of function evaluations M reveals the relative efficiency of the time integration methods.

1. Error decreases monotonically with increasing work for all methods, confirming convergence as the number of function evaluations grows.
2. First-order methods such as Explicit Euler require significantly more function evaluations to achieve a given accuracy, as evidenced by their shallow slope.
3. Implicit Euler does not provide accuracy benefits over explicit Euler when work is measured in function evaluations, despite its improved stability properties.
4. In general, implicit methods incur additional function evaluations due to nonlinear solves at each time step; higher-order implicit schemes (e.g. trapezoidal) can be competitive (with higher-order explicit methods, e.g., midpoint and adams-bashforth2), but low-order implicit methods (implicit euler over forward euler) do not improve (rather decrease) accuracy per unit work.
5. Higher-order methods achieve lower error for the same computational effort, resulting in steeper curves.
6. Among second-order methods, midpoint, trapezoidal, and RK2 show comparable efficiency, with Adams–Bashforth 2 being significantly better at higher work/number of function evaluations. Adams–Bashforth 2 performs poorly at low work due to startup effects but approaches second-order behavior asymptotically.
7. For moderate to high accuracy requirements, increasing method order is far more effective than simply increasing the number of steps in low-order methods.
8. For implicit methods, the computational work per time step is not fixed and depends on how the nonlinear implicit equation is solved, including solver tolerances and convergence behavior. As a result, the number of function evaluations reflects both the time integration method and the nonlinear solver implementation.