Assignment 2

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Code:

```
#Question 1
import sympy as sp
import sympy
import numpy as np
import matplotlib.pyplot as plt
# Define the variable and the function
x = sp.Symbol('x')
f = x * sp.sin(x)
# Compute the definite integral
result = sp.integrate(f, (x, 0, sp.pi/2))
print(result)
```

```
#Question 2
a, b = sp.symbols('a b')
A = sp.Matrix([[1, 2], [a, b]])
A_inverse = A.inv()
A_times_A_inverse = A * A_inverse
identity_matrix = sp.eye(2)
print("Matrix A:")
sp.pprint(A)
print("Matrix A^-1:")
sp.pprint(A_inverse)
print("Matrix A * A^-1:")
sp.pprint(A_times_A_inverse)
print("2x2 Identity Matrix:")
sp.pprint(identity_matrix)
is_identity = A_times_A_inverse.equals(identity_matrix)
if is_identity:
 print("A * A^-1 is the 2x2 identity matrix.")
else:
  print("A * A^-1 is NOT the 2x2 identity matrix.")
```

```
#Question 3
def coefficient_of_xn_minus_1(N):
    if N < 1:
        return 0 # Invalid input, return 0

x = sp.symbols('x')
    expanded_expression = (x + 1)**N

# Expand the expression and extract the coefficient of x^(N-1)
    expanded_expression = sp.expand(expanded_expression)
    coefficient_xn_minus_1 = expanded_expression.coeff(x, N-1)

    return coefficient_xn_minus_1, expanded_expression

# Test the function for N = 4

N = 4

result = coefficient_of_xn_minus_1(N)
print(f"The coefficient of x^{N-1} in (x + 1)^{N} is: {result}")
    print("A * A^-1 is NOT the 2x2 identity matrix.")</pre>
```

```
#Question 4
def nth_derivative(N, x):
    # Define the symbolic variable x
    x = sp.symbols('x')
    # Define the original function f(x)
    f_x = x**3 * sp.sin(x**2 + 1)
    # Calculate the N-th derivative of the function
    nth_deriv = sp.diff(f_x, x, N)
    # Create a numeric function from the symbolic expression
    numeric_function = sp.lambdify(x, nth_deriv, 'numpy')
    # Evaluate the numeric function at the specified x_value
    result = numeric_function(x_value)
    return result

# Test the function for N = 2 and x = 0.1
N = 2
x_value = 0.1
result = nth_derivative(N, x_value)

print(f"The {N}-th derivative at x = {x_value} is: {result}")
```

```
#Question 5
x = sp.symbols('x')
f = sp.cos(x**2 + sp.sqrt(x))

power_series = sp.series(f, x, 0, 6) # The last argument '6' represents x^5 term

sympy.pprint(power_series)

#Question 6
x, alpha = sympy.symbols('x alpha', positive=True, real=True)

f = x**2 * sympy.exp(-alpha * x)
```

```
x, alpha = sympy.symbols('x alpha', positive=True, real=True)

f = x**2 * sympy.exp(-alpha * x)

# Calculate the derivative of f(x) with respect to x
f_prime = sympy.diff(f, x)

# Find the critical points by solving f'(x) = 0
critical_points = sympy.solve(f_prime, x)

# Check the second derivative to determine if it's a maximum
maximum_points = []
for point in critical_points:
    f_double_prime = sympy.diff(f_prime, x).subs(x, point)
    if f_double_prime < 0: # Negative second derivative indicates a maximum
    maximum_points.append(point)

maximum_values = [f.subs(x, point) for point in maximum_points]

if not maximum_values:
    print("No maximum found.")
else:
    max_x, max_value = max(zip(maximum_points, maximum_values), key=lambda x: x[1])
    print(f"The maximum of f(x) is {max_value} at x = {max_x}")</pre>
```

```
#Question 7 A
# Define symbolic variables
x, y = sympy.symbols('x y')
fxy = sp.exp(-x**2+2*x-y**2+x*y)
#find the derivative
fxy_diffx = sp.diff(fxy, x)
fxy_diffy = sp.diff(fxy, y)
local_max = sp.solve([fxy_diffx, fxy_diffy], [x,y], dict=True)
print("The local maximums are : ", local_max)
```

```
#Question 7 B
fxy_num = sp.lambdify((x, y) , fxy) # numeric equation in numpy
x_val = np.linspace(-3,3,300)
y_val= np.linspace(-3,3,300)
x_mesh, y_mesh = np.meshgrid(x_val,y_val)

f_mesh = fxy_num(x_mesh, y_mesh)

guadcontset = plt.contourf(x_mesh, y_mesh,f_mesh)
plt.colorbar(label="Value of f(x,y) ", orientation="horizontal")
x_maxval = local_max[0][x]
y_maxval = local_max[0][y]

plt.scatter(x_maxval, y_maxval)
plt.text(x_maxval, y_maxval, "Maximum value of f(x,y)", va="bottom", ha="center")

plt.xlabel("x")
plt.ylabel("y")
plt.title("contour plot")

plt.show()
```

Output:

```
PS C:\Users\omar5> & C:\Users\omar5/anaconda3/python.exe "c:\Users\omar5/Desktop/ENEL 102/2/test.py"
PS C:\Users\omar5> & C:\Users\omar5/anaconda3/python.exe "c:\Users\omar5/Desktop/ENEL 102/2/test.py"
Matrix A:
La bJ
Matrix A^-1:
  -2·a + b -2·a + b
    -a
 -2·a + b
            -2·a + b⊥
 Matrix A * A^-1:
      2∙ a
    -2·a + b -2·a + b
                                2∙ a
                              -2·a + b
                                         -2·a + b
2x2 Identity Matrix:
1 0
0 1
A * A^-1 is the 2x2 identity matrix.
PS C:\Users\omar5> & C:\Users\omar5/anaconda3/python.exe "c:/Users\omar5/Desktop/ENEL 102/2/test.py"
The coefficient of x^3 in (x + 1)^4 is: (4, x^* + 4 + 4^* x^{**} + 6^* x^{**} + 4^* x + 1)
PS C:\Users\omar5> & C:\Users\omar5/anaconda3/python.exe "c:\Users\omar5/Desktop/ENEL 102/2/test.py"
The 2-th derivative at x = 0.1 is: 0.5155112835962654
```

