

We wish to design a controller for the elevator such that the aircraft is able to:

- maintain its elevation even in the presence of disturbances such as wind and sudden wind gusts,
- increase altitude of 1 m in 10s (the settling time to a unit step of the closed loop system should be < 10 s),

\Rightarrow I want $\cdot T_s < 10$
 $\cdot \text{stability margin} \leq 1.5$

$$P(s) = \frac{0.4}{s^3 + 0.1s^2 + 20s + 0.5} = \frac{0.4}{(s+0.025)(s+0.0375+4.47j)(s+0.0375-4.47j)}$$

complex conjugates

Recall:

$$M_r = \frac{\alpha^2 + \beta^2}{2\alpha\beta}$$

$$2\alpha\beta M_r = \alpha^2 + \beta^2$$

$$\alpha^2 - 2 \cdot 1.5 \alpha\beta + \beta^2 = 0$$

$$\alpha^2 - 3\alpha\beta + \beta^2 = 0$$

$$\alpha = \frac{3\beta \pm \sqrt{(3\beta)^2 - 4\beta^2}}{2}$$

$$2\alpha = 3\beta \pm \sqrt{9\beta^2 - 4\beta^2}$$

$$2\alpha = 3\beta \pm \sqrt{5\beta^2}$$

$$\alpha = \frac{3\beta \pm \sqrt{5}\beta}{2}$$

$$\alpha = 2.61\beta \text{ ignore}$$

$$\alpha = 0.382\beta$$

$$T_s < 10$$


$$\frac{4}{\alpha} < 10$$

$$\frac{4}{10} < \alpha$$

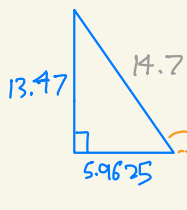
$$0.4 < \alpha$$



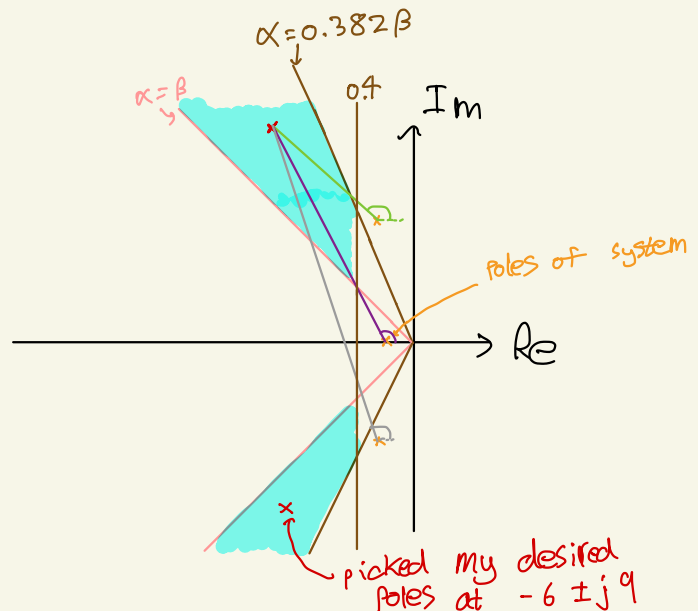
$$\rightarrow 180 - \tan^{-1}\left(\frac{4.53}{5.9625}\right) = 142.8^\circ$$



$$\rightarrow 180 - \tan^{-1}\left(\frac{9}{5.975}\right) = 123.6^\circ$$



$$\rightarrow 180 - \tan^{-1}\left(\frac{13.47}{5.9625}\right) = 113.87^\circ$$



$$\frac{0.4}{7.5 \angle 142.8^\circ \cdot 10.8 \angle 123.6^\circ \cdot 14.73 \angle 113.87^\circ} K_p \frac{M_z \angle \phi_z}{M_p \angle \phi_p} = 1 \angle -180^\circ$$

$$-142.8 - 123.6 - 113.87 + \phi_z - \phi_p = -180$$

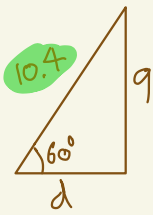
$$\phi_z - \phi_p = 200.27$$

Must use compensator,
 but one is not enough
 should aim for $\phi_z < 60^\circ$
 \therefore use 4 compensators

$$\frac{200.27}{4} = 50.0675$$

$$\phi_z - \phi_p = 50^\circ$$

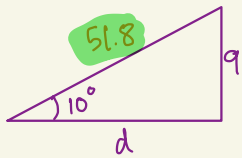
Pick $\phi_z = 60 \rightarrow \therefore \phi_p = 10$



$$\tan(60) = \frac{q}{d}$$

$$\therefore d = 5.2$$

→ place zero at $6 + 5.2 = -11.2$



$$\tan(10) = \frac{q}{d}$$

$$\therefore d = 51$$

→ place pole at $6 + 51 = -57$

$$\frac{0.4}{7.5 \times 10.8 \times 14.73} \times K_{ld} \times \left(\frac{10.4}{51.8}\right)^4 = 1$$

→ $K_{ld} = 1,835,750$

Final design : $1,835,750 \frac{(s+11.2)^4}{(s+57)^4}$

