

# MODELS & REPRESENTATIONS

Systems in the real world are physical entities or processes that can be described using mathematical models.

## WHY MODELS?

To predict and analyze system behavior under various conditions

## TIME DOMAIN RESPONSE

### INITIAL CONDITIONS

The system's behavior starting from a non-zero state.

### STEP

The system's reaction to a sudden change, typically from zero to one.

### GENERAL INPUT

How the system reacts to any variable input over time

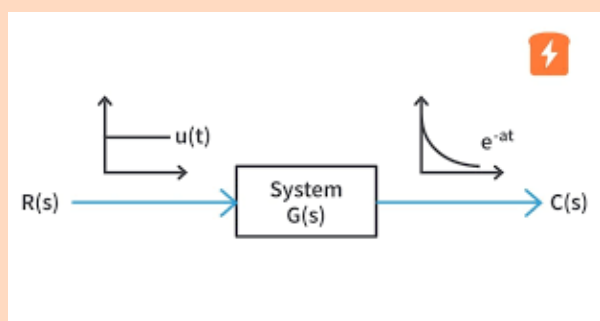
## REPRESENTING THE SYSTEM

Solve the differential equation

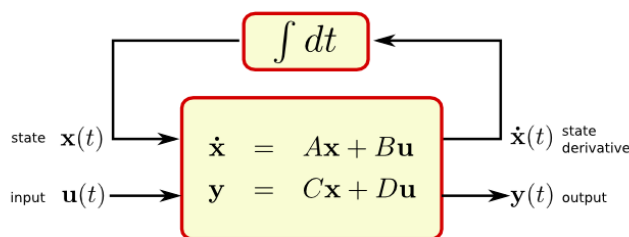
$$\frac{d^2x}{dt^2} + 4\frac{dx}{dt} + 13x = 0$$

with initial conditions

$$x(0) = 1$$
$$x'(0) = 0$$

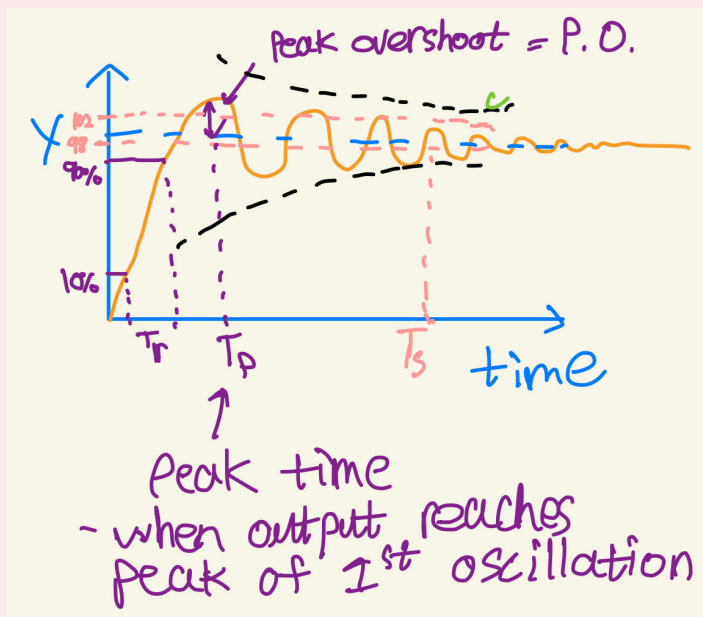


state space



System represented as a collection of coupled linear first-order differential equations.

## SYSTEM CHARACTERISTICS



Stability is the ability of a system to return to its steady state after a disturbance.

Settling Time is the time taken for the response to reach and stay within a certain range of the final value.

Rise Time is the time taken for the response to go from 10% to 90% of its final value.

## POLES AND ZEROS

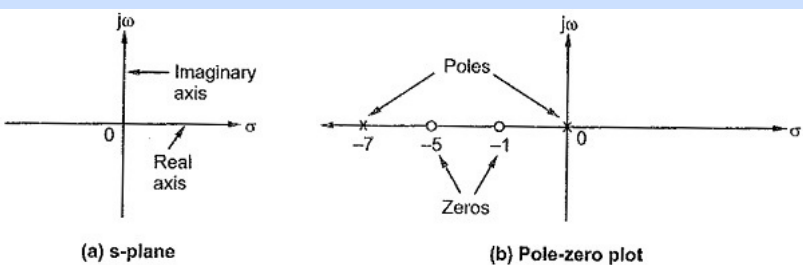


Fig. 3.14

Poles are values of  $s$  that cause the system's transfer function to become infinite.

Zeros are values of  $s$  that cause the system's transfer function to be zero.

S-Plane is a graphical representation of complex poles and zeros in a system's transfer function.