

Chapter 3: Euclidean Geometry

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February 23, 2022

1 Isometries of \mathbb{R}^3

1

Consider

$$\begin{aligned} |C(p+a) - C(p) - C(a)|^2 &= C(p+a) \cdot C(p+a) + C(p) \cdot C(p) + C(a) \cdot C(a) \\ &\quad - 2C(p+a) \cdot C(p) - 2C(p+a) \cdot C(a) + 2C(p) \cdot C(a) \\ &= (p+a)^2 + p^2 + a^2 - 2(p+a)p - 2(p+a)a + 2pa \\ &= p^2 + 2pa + a^2 + p^2 + a^2 - 2p^2 - 2pa - 2pa - 2a^2 + 2pa \\ &= 0 \end{aligned}$$

Therefore $C(p+a) = C(p) + C(a)$. It follows that $CT_a(p) = C(p+a) = C(p) + C(a) = T_{C(a)}C(p)$ ■

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From the result in problem 1.1 $FG = T_aAT_bB = T_aT_{A(b)}AB$ and $GF = T_bBT_aA = T_bT_{B(a)}BA$. The transnational parts are $T_{a+A(b)}$ and $T_{b+B(a)}$ respectively.

3

Suppose $Cp = Cq$, Then

$$\begin{aligned} &\Leftrightarrow \langle Cp - Cq, Cp - Cq \rangle = 0 \\ &\Leftrightarrow CpCp - 2CpCq - CqCq = 0 \\ &\Leftrightarrow p^2 - 2pq - q^2 = 0 \\ &\Leftrightarrow p = q \end{aligned}$$

C is 1-1. Therefore there exists inverse C^{-1} . To show C^{-1} is orthogonal transformation. Suppose p, q such that $C^{-1}p = \tilde{p}$ and $C^{-1}q = \tilde{q}$

$$\langle C^{-1}p, C^{-1}q \rangle = \langle \tilde{p}, \tilde{q} \rangle = \langle C\tilde{p}, C\tilde{q} \rangle = \langle p, q \rangle$$

So C^{-1} is orthogonal transformation. We can define the inverse of F . $F^{-1} = (T_a C)^{-1} = C^{-1} T_{-a}$. F^{-1} is isometry.

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$$C = \frac{1}{3} \begin{pmatrix} -2 & 2 & -1 \\ 2 & 1 & -2 \\ 1 & 2 & 2 \end{pmatrix}$$

It's trivial to check orthogonality after factoring out $1/3$.

$Cp = \frac{1}{3}(2, 19, -7)$ and $Cq = \frac{1}{3}(-5, -4, 7)$. Then $\langle Cp, Cq \rangle = \frac{1}{9}(-135) = -15 = \langle p, q \rangle$.

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(a) $q = F(p) = T_a C(p) = (-3\sqrt{2} + 1, 1, 5\sqrt{2} - 1)^T$

(b) $q = F^{-1}(p) = (T_a C)^{-1}(p) = C^{-1} T_{-a}(p) = C^T T_{-a}(p) = (5\sqrt{2}, -5, 4\sqrt{2})^T$

(c) $q = (C T_a)(p) = (5\sqrt{2}, 1, 2\sqrt{2})^T$

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(a) $C = \text{diag}(-1, -1, -1)$ and $a = (0, 0, 0)$.

(b) Not isometry. If $p \perp a$, then $d(F(p), 0) = d(0, 0) = 0 \neq d(p, 0)$.

(c) $C = I$, $a = (-1, -2, -3)$.

(d) $C = \text{diag}(1, 1, 0)$, $a = (0, 0, 1)$.

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For $F_1, F_2 \in \text{Iso}(3)$, $F_1 F_2 = T_a C_1 T_b C_2 = T_a T_{C_1(b)} C_1 C_2 \in \text{Iso}(3)$. Associative is trivial since they are functions. Inverse exists for every F as proven in problem 3.

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Only Identity is in both subgroups.

9

(a) For an orthogonal matrix $\begin{pmatrix} a & b \\ c & d \end{pmatrix}$, it satisfies

$$\begin{cases} ac + bd = 0 \\ a^2 + b^2 = 1 \\ c^2 + d^2 = 1 \end{cases}$$

We have a free parameter. Let $d = \pm \sin \theta$, then

$$\begin{cases} d = \pm \sin \theta \\ c = \cos \theta \\ b = \mp \cos \theta \\ a = \sin \theta \end{cases}$$

So $\begin{pmatrix} a & b \\ c & d \end{pmatrix} = \begin{pmatrix} \sin \theta & \mp \cos \theta \\ \cos \theta & \pm \sin \theta \end{pmatrix}$

(b) $F = T_a C$. $CpCp = p^2 \Rightarrow c^2 p^2 = p^2 \Rightarrow c = 1$. So an isometry in \mathfrak{R} is just a displacement by a constant a .