

PUBLIC TRANSPORT OPTIMIZATION

PHASE 5: Documentation and submission.

OBJECTIVE: Objective: To enhance public transportation efficiency and user experience by collecting, analyzing, and providing real-time access to ridership data and accurate arrival time predictions using sensor systems, GPS modules, and a user-friendly mobile application.

SENSOR SYSTEM DESIGN:

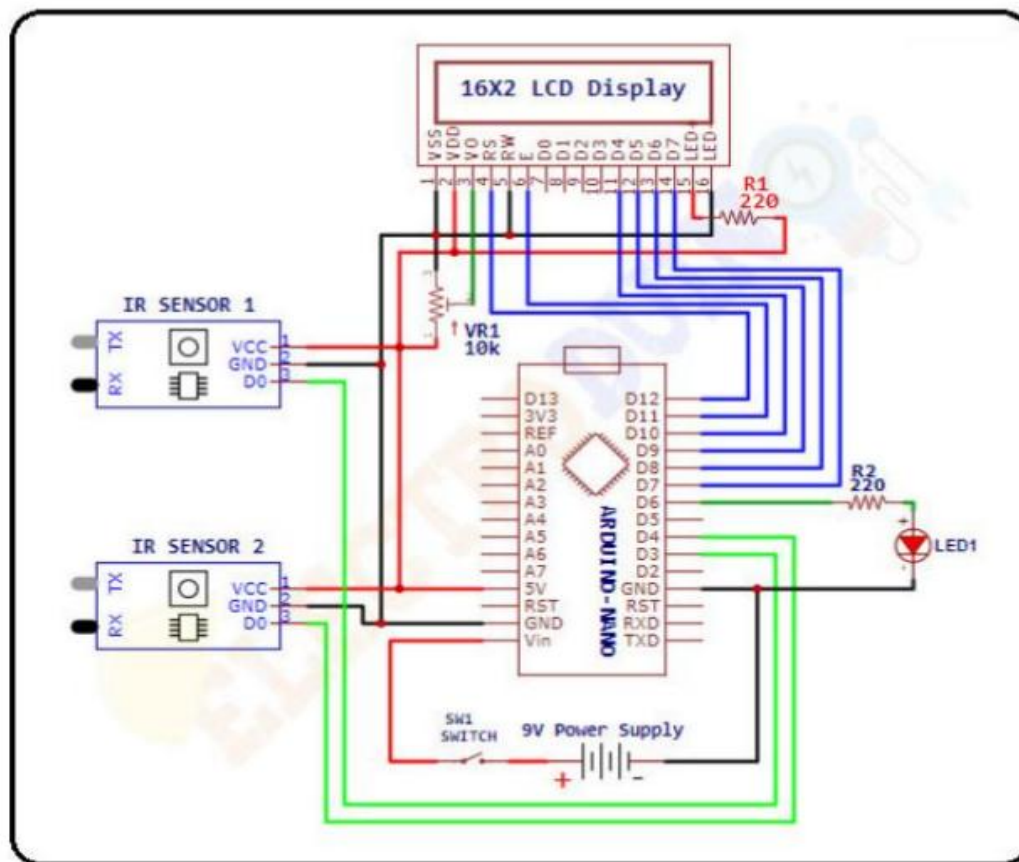
RIDERSHIP MONITORING:

COMPONENTS :

- ARDUINO UNO ATmega328P
- INFRARED (IR) SENSORS (2X)
- LED
- BUZZER
- RESISTOR
- LCD DISPLAY (16 X 2)
- BREADBOARD
- JUMPER CABLES
- POWER SOURCE
- PC WITH ARDUINO IDE



SYSTEM DESIGN:



PYTHON SCRIPT:

```
# Import the necessary libraries
from pyfirmata import Arduino, util

# Define the serial port of your Arduino (e.g., 'COM8' on Windows)
port = 'COM8'

# Initialize the Arduino board
board = Arduino(port)

# Define the pin numbers for sensors and LED
sensor_1_pin = 2
sensor_2_pin = 3
led_pin = 13 # The built-in LED pin on most Arduino boards

# Set up the pins
```

```
sensor_1 = board.get_pin('d:{}:i'.format(sensor_1_pin))
sensor_2 = board.get_pin('d:{}:i'.format(sensor_2_pin))
led = board.get_pin('d:{}:o'.format(led_pin))

# Initialize variables
peopleInside = 0

# Create an Iterator to handle input events
it = util.Iterator(board)
it.start()

try:
    while True:
        # Read the state of the sensors
        sensor1State = sensor_1.read()
        sensor2State = sensor_2.read()

        if sensor1State == 1 and sensor2State == 0:
            # Object entered the room
            led.write(1) # Turn on the LED
            board.pass_time(10) # Wait for 10 seconds
            led.write(0) # Turn off the LED
            peopleInside += 1 # Increment people count
        elif sensor1State == 0 and sensor2State == 1:
            # Object exited the room
            # You can add code to control the buzzer here
            peopleInside -= 1 # Decrement people count
            print("People Inside:", peopleInside)

except KeyboardInterrupt:
    # Exit the program gracefully on Ctrl+C
    board.exit()
```

LOCATION TRACKING:

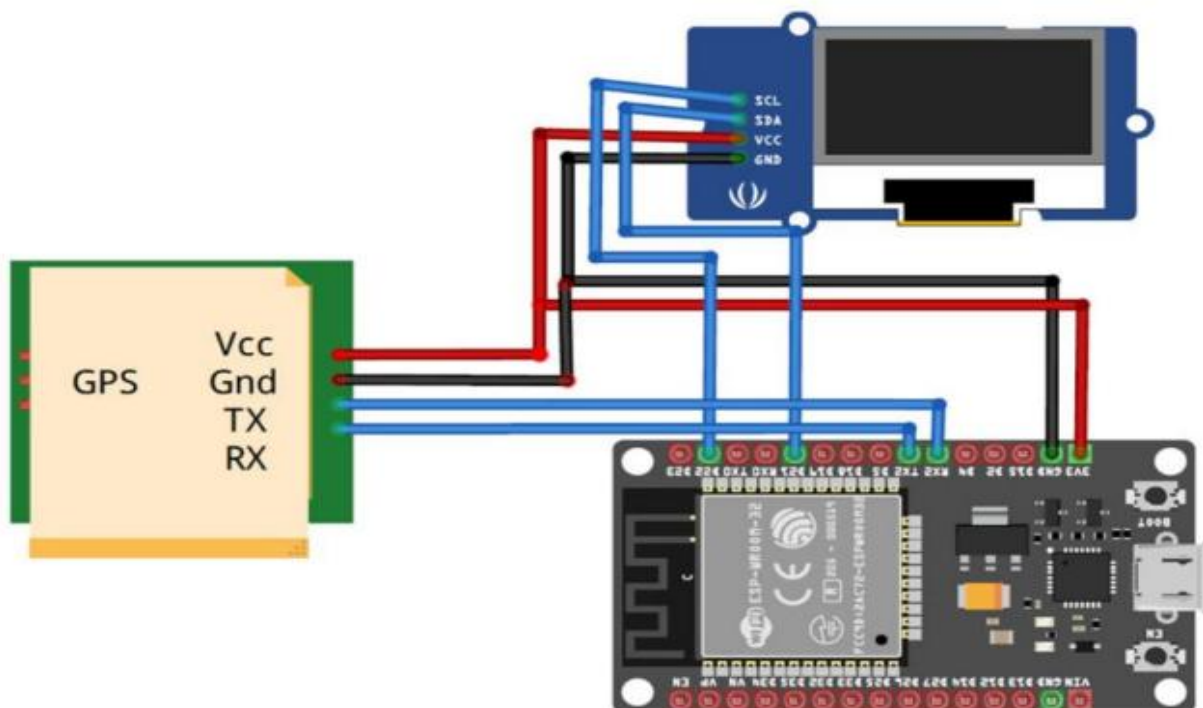
ESP32 GPS tracker- IoT based location tracking system:

COMPONENTS:

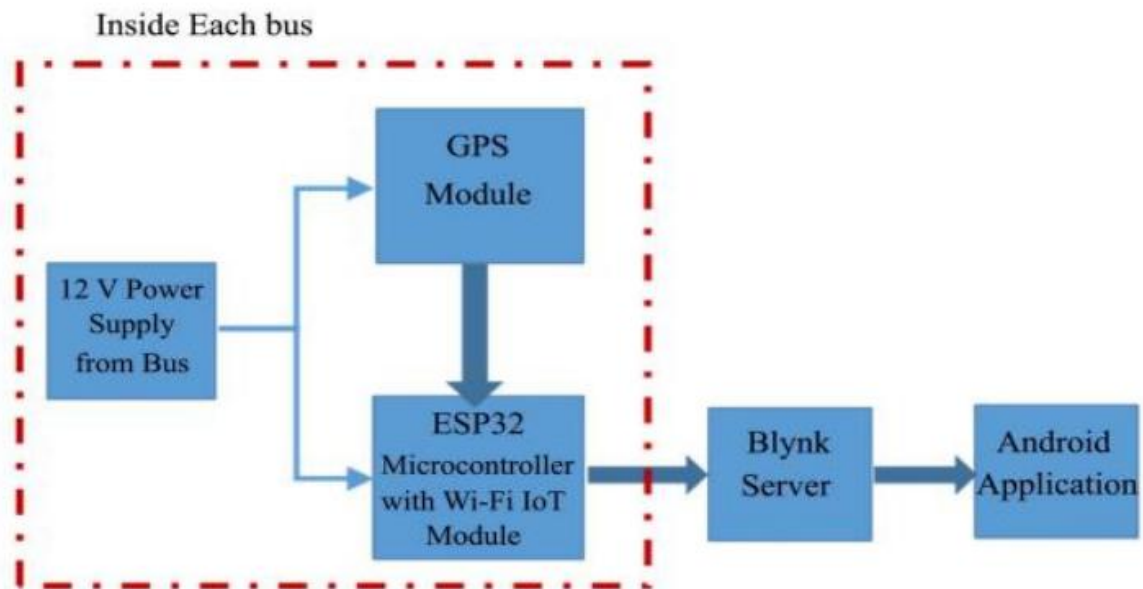
- ESP32
- GPS Module
- OLED Display Module
- Jumper Wires
- Breadboard



SYSTEM DESIGN:



SYSTEM BLOCK DIAGRAM:



STEPS INVOLVED:

1. **SETTING UP BLYNK SERVER:** Install and configure a Blynk server on a host or a cloud-based server. Obtain the necessary credentials, including the server address, port, and authentication token for your Blynk server. These credentials will be used by your devices to connect to the server.

CONFIGURATION RASPBERRY PI AND ESP₃₂:

- Install the Blynk library on your Raspberry Pi and ESP32. We can find the Blynk library and documentation for your respective platforms on the Blynk website.
- Write code on your Raspberry Pi and ESP32 to collect GPS and ridership monitoring data and transmit it to the Blynk server using the Blynk library. Use the provided authentication token to connect to your Blynk server.
- Set up the appropriate virtual pins in your Blynk project to receive and display the data sent by your devices. You can configure widgets in your Blynk project to visualize the data.

CONNECTION ESTABLISHMENT BETWEEN SENSOR SYSTEM

AND BLYNK SERVER:

By using the following code the sensor sytem can be connected to the wifi and can be linked with the Blynk server for data.

```
#include <WiFi.h>

#include <BlynkSimpleEsp32.h>

char auth[] = "qgzP0nerwY0qDliBfNljhGQ-84ZaVP1j";

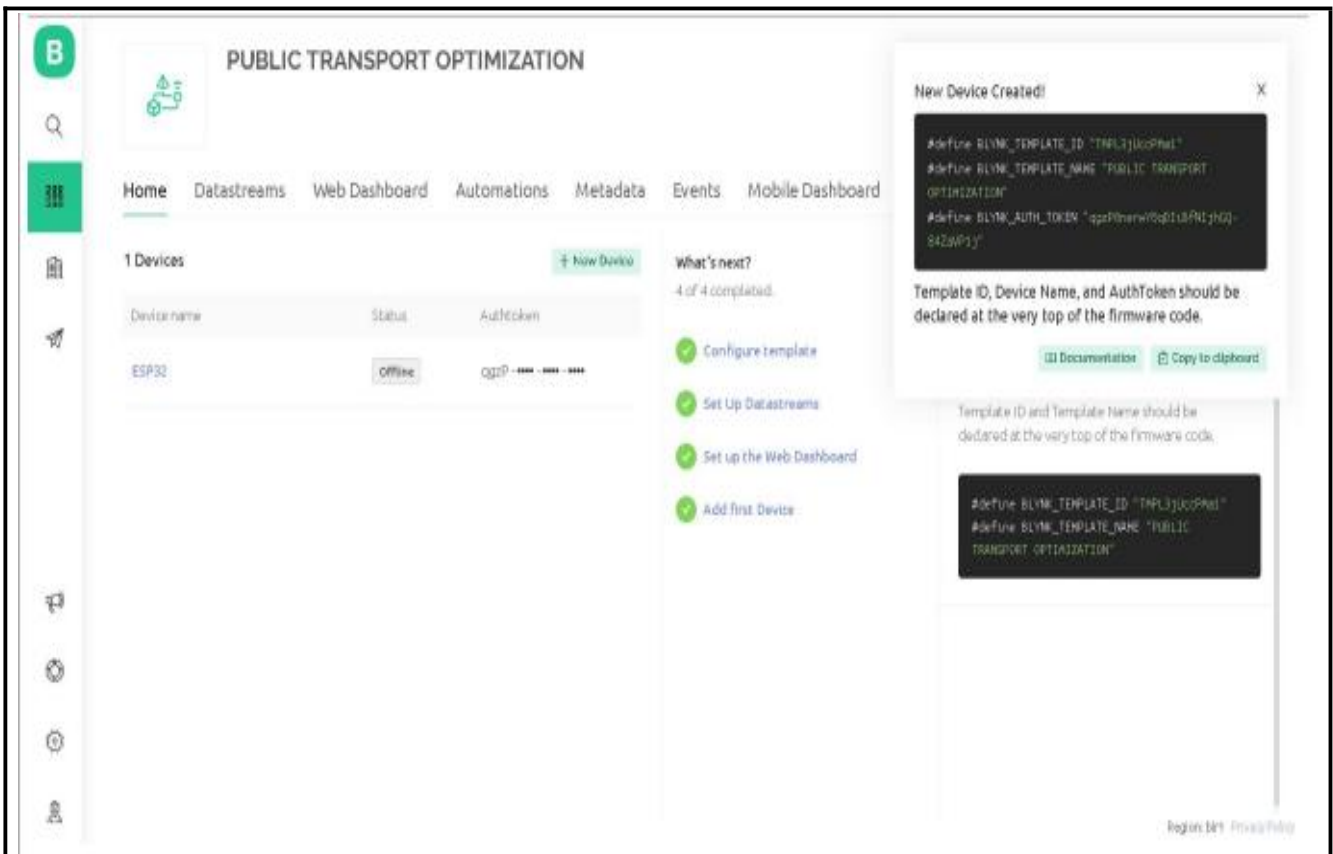
char ssid[] = "My wifi";

char pass[] = "12345678";

BlynkTimer timer;

void setup() {
  Blynk.begin(auth, ssid, pass);
}

void loop() {
  Blynk.run();
}
```



DATA FEEDING FROM GPS TO BLYNK SERVER:

First install blynk python library in ESP32 board using following code,

```
" pip install blynk-library-python "
```

Then load the following code to the ESP32 board.

```
# Import the necessary libraries
```

```
from pyfirmata import Arduino, util
```

```
# Define the serial port of your Arduino (e.g., 'COM8' on Windows)
```

```
port = 'COM8'
```

```
# Initialize the Arduino board

board = Arduino(port)


# Define the pin numbers for sensors and LED

sensor_1_pin = 2
sensor_2_pin = 3
led_pin = 13 # The built-in LED pin on most Arduino boards


# Set up the pins

sensor_1 = board.get_pin('d:{}'.format(sensor_1_pin))
sensor_2 = board.get_pin('d:{}'.format(sensor_2_pin))
led = board.get_pin('d:{}'.format(led_pin))


# Initialize variables

peopleInside = 0


# Create an Iterator to handle input events

it = util.Iterator(board)
it.start()

try:
    while True:
        # Read the state of the sensors
        sensor1State = sensor_1.read()
        sensor2State = sensor_2.read()
```

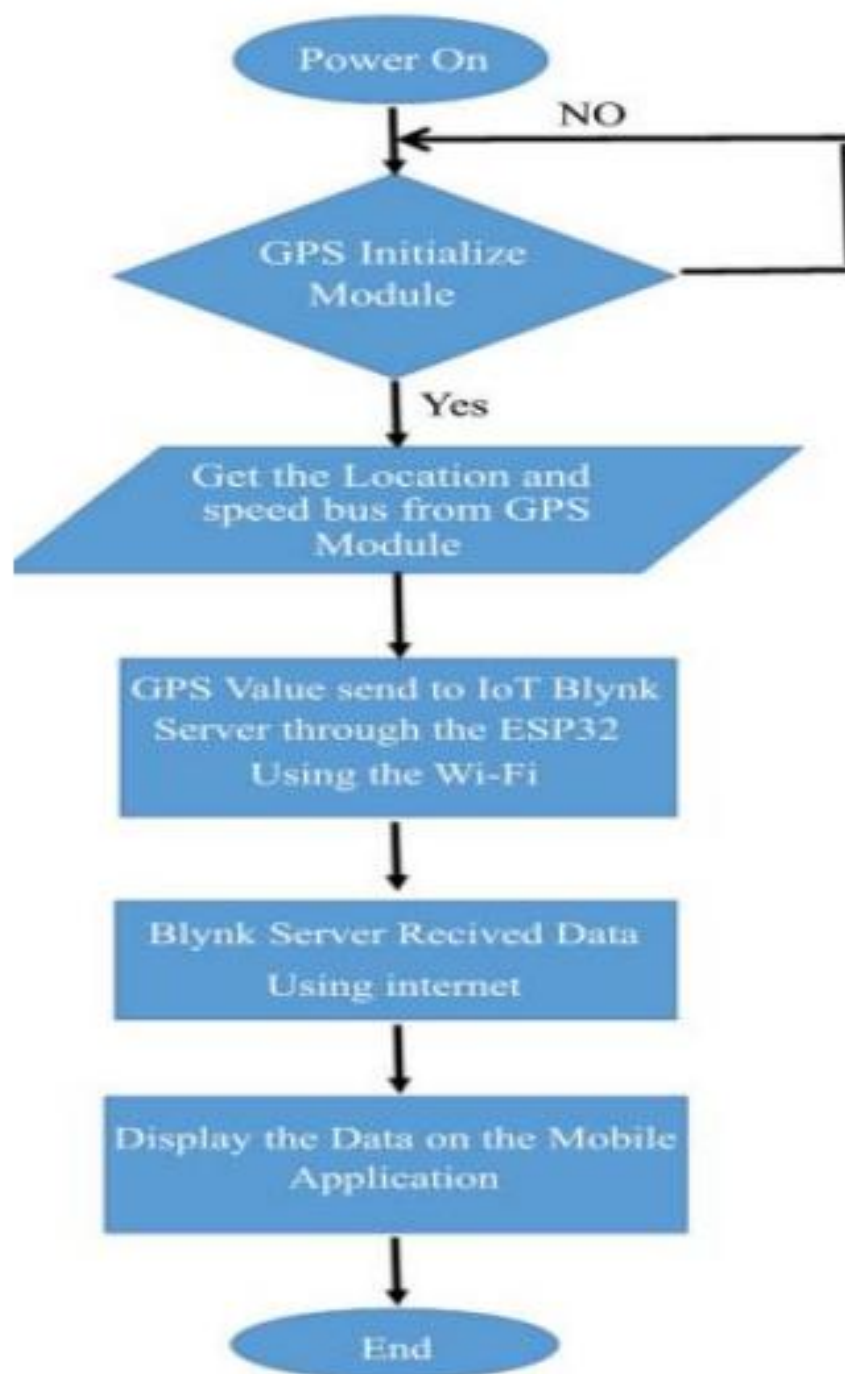


```
if sensor1State == 1 and sensor2State == 0:
    # Object entered the room
    led.write(1) # Turn on the LED
    board.pass_time(10) # Wait for 10 seconds
    led.write(0) # Turn off the LED
    peopleInside += 1 # Increment people count
elif sensor1State == 0 and sensor2State == 1:
    # Object exited the room
    # You can add code to control the buzzer here
    peopleInside -= 1 # Decrement people count
print("People Inside:", peopleInside)

except KeyboardInterrupt:
    # Exit the program gracefully on Ctrl+C
    board.exit()
```

PLATFORM DESIGN USING MIT APP INVENTOR:

- Design the app interface: Use the visual designer to create the user interface for your public platform. You can design screens for viewing GPS data and ridership information.
- Add Blynk components: In MIT App Inventor, add Blynk components that allow your app to communicate with the Blynk server. Configure these components with the server address, port, and authentication token.



REAL-TIME TRANSIT INFORMATION PLATFORM DESIGN

USING MIT APP INVENTOR:

