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The Kruskal and Prim Algorithms can efficiently create minimum spanning trees And these are the "best" trees that span all nodes

Getting the Shortest Path
 However, it doesn't necessarily produce the minimum path for each vertex to reach other vertices
 In other words, the shortest path for each, between two vertices, might not be reflected in the MST

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This is the spanning tree created by both the Prim and Kruskal Algorithms
 Let's say we want to get the minimal path from B to D

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Prim-Jarník Algorithm Example

The incident edge from vertex B to D has a weight of 8

However, following the spanning tree, the total weight would be 22

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Getting the Shortest Path

- We need to compute the best path for <u>each</u> vertex
- This is called the distance
- Given 2 vertices a and b ...
 - find a path with the "best" total weight between a and b
 - · ...with the minimum sum



Some Real World Examples

- Internet packet routing
 - · fastest route faster downloads
 - · load distribution
- Driving directions
 - · shortest route in miles
 - fastest route given traffic and speed limit data

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Shortest Path Attributes

- A sub-path of a shortest path
 - · ...is itself a shortest path
 - so, any subset of a optimal solution is optimal
- There is a tree of shortest paths
 - there are multiple solutions from the start vertex to all the other vertices
 - might be multiple equally-optimal solutions

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Edsger Dijkstra

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- The algorithm used today to find the optimal path was written by Edsger Dijkstra
- In fact, his algorithm runs the Internet – a self healing, load distributing, network
- No Dijkstra → No Internet



Dijkstra's Algorithm

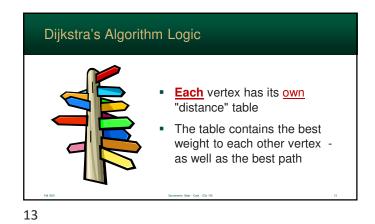
- Dijkstra's Shortest Path First Algorithm computes the distances of all the vertices from a given start vertex s
- Works on directed and undirected graphs
- However...
 - · all edges must have nonnegative weight, and...
 - · the graph is connected

Dijkstra's Algorithm

- Dijkstra's Algorithm is greedy
 - <u>always</u> takes the <u>best</u> immediate or local solution while finding an answer
 - they find optimal solutions for some optimization problems very efficiently
 - · ...but may find less-than-optimal solutions
- Extra analysis is needed to determine if they work -Dijkstra's does

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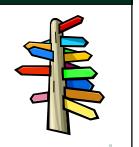
Dijkstra's Algorithm Logic

- 1. Initialize a distance table
 - · table represents the best distance (weight) to get to the specific vertices
 - set all to infinity (worst possible)
 - · it will be updated as we see more vertices
- 2. Analyze vertices until all are known (visited)
 - · always select the one with the smallest distance
 - · treat the vertices as being in a priority queue

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Dijkstra's Algorithm Logic

- Given table D, vertex ν, edge weight w with target t: $\mathbf{D}(\mathbf{t}) = \mathbf{D}(\mathbf{v}) + \mathbf{w}$
- For example:
 - if it takes 12 to get to v
 - ... and an edge of 6 goes to t
 - it takes 12 + 6 total to get to t



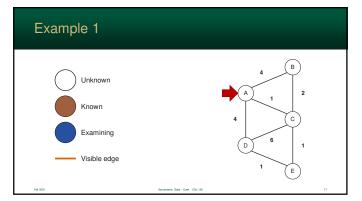
Dijkstra's Algorithm Logic

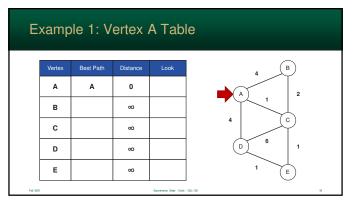
- For each vertex v...
 - · compute the total distance to get each vertex t that is adjacent to v
 - if the value is better than the current table value then update the table



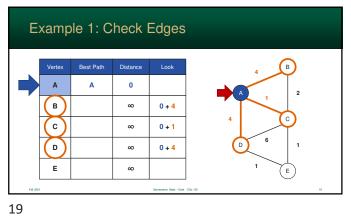
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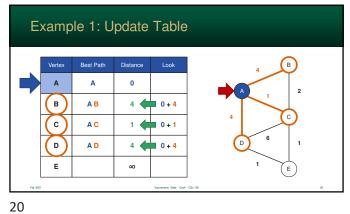
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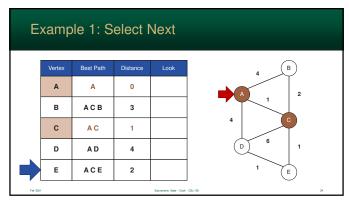


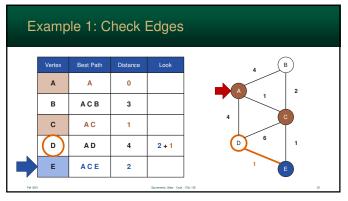


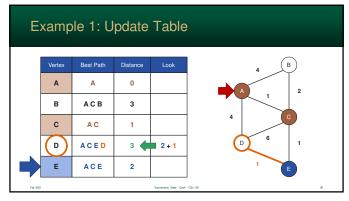
E	xamp	ole 1: S	elect I	Next	
	Vertex	Best Path	Distance	Look	4 B
	Α	Α	0		
	В	АВ	4		7 1
	С	AC	1		4 (C)
	D	A D	4		D 6 1
	E		∞		1 (E)
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E	xamp	le 1: C	heck I	Edges	
	Vertex	Best Path	Distance	Look	4 B
	Α	Α	0		2
	В	АВ	4	1 + 2	
	С	AC	1		4
	D	A D	4	1+6	D 6 1
	E		∞	1+1	1 E
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E	xamp	le 1: U	pdate	Table	
	Vertex	Best Path	Distance	Look	4 B
	А	Α	0		2
	В	ACB	3 🛑	1 + 2	701
	С	AC	1		4
	(D)	A D	4	1+6	D 6
	E	ACE	2	1+1	1 E
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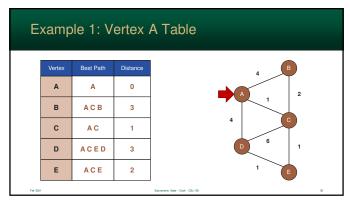


E	xamp	ole 1: S	elect 1	Vext	
	Vertex	Best Path	Distance	Look	4 B
	Α	Α	0		A
	В	ACB	3		7
	С	AC	1		4
	D	ACED	3		D 6 1
	E	ACE	2		1 E
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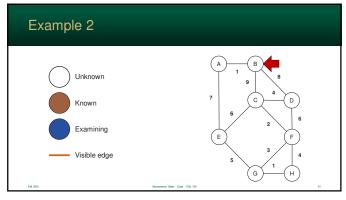
E	kamp	le 1: V	ertex /	A Tabl	е
	Vertex	Best Path	Distance	Look	4 B
	Α	Α	0		A 2
	В	ACB	3		1
	С	AC	1		4 C
	D	ACED	3		D 6 1
	Е	ACE	2		1 E
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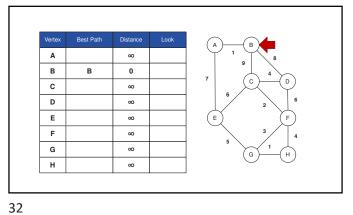
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E	xamp	ole 1: V	ertex <i>i</i>	A Tabl	le
	Vertex	Best Path	Distance	Look	4 B
	А	Α	0		A
	В	ACB	3		1
	С	AC	1		4 C
	D	ACED	3		D 6 1
	E	ACE	2		1 E
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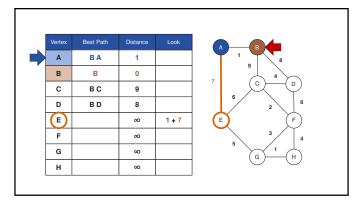




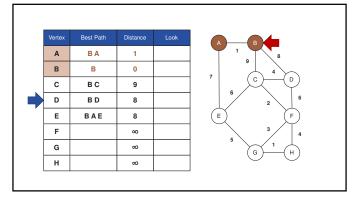
Vertex	Best Path	Distance	Look	A B
A		∞	0 + 1	1 , 1 8
В	В	0		
(c)		∞	0 + 9	
D		∞	0 + 8	6
E		∞		E F
F		∞		3 4
G		∞		1 H
Н		∞		

Vertex	Best Path	Distance	Look
A	ВА	1	0+1
В	В	0	
(C)	ВС	9	0 + 9
D	B D	8	0+8
E		∞	
F		∞	
G		∞	
Н		∞	

Vertex	Best Path	Distance	Look	(A) B	
Α	ВА	1		1 9	8
В	В	0			4
С	вс	9		7 c	<u> </u>
D	B D	8			
Е		∞		E	(F
F		∞		3	/ `
G		∞			1
н		∞			



ertex	Best Path	Distance	Look	A	4
Α	ВА	1		1 9	8
В	В	0			4
С	ВС	9			$\downarrow -$
D	B D	8		6	2
E	BAE	8	1+7		(
F		∞			3
G		∞		5 G	<u> </u>
н		∞			/ \

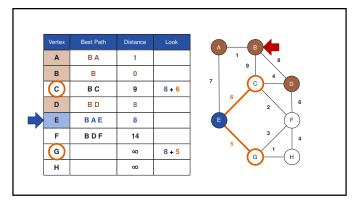


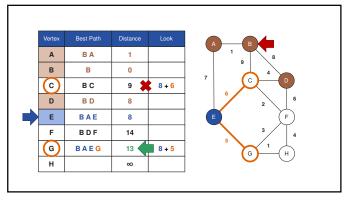
Vertex	Best Path	Distance	Look	A B
A BA 1 B B 0 C BC 9 8+4 D BD 8	1 9 8			
	4			
(c)	ВС	9	8 + 4	7 6 0
D	B D	8		2
E	BAE	8		E F
F		∞	8+6	3
G		∞		1 H
Н		∞		

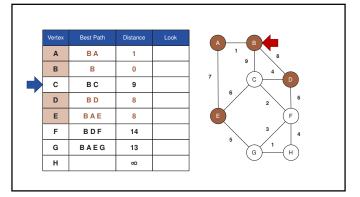
	Vertex	Best Path	Distance	Look
	Α	ВА	1	
	В	В	0	
	C	ВС	9	8 + 4
	D	B D	8	
Í	E	BAE	8	
	F	BDF	14	8+6
	G		∞	
	н		∞	

39 40

Vertex	Best Path	Distance	Look
Α	ВА	1	
В	В	0	
С	ВС	9	
D	B D	8	
E	BAE	8	
F	BDF	14	
G		∞	
Н		∞	





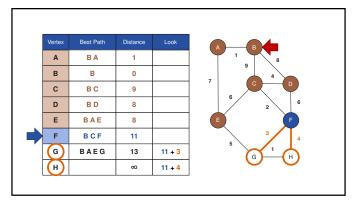


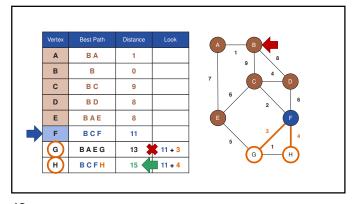
ertex	Best Path	Distance	Look	A B
Α	ВА	1		1 1
В	В	0		9 4
С	ВС	9		7 C D
D	B D	8		6 6
Е	BAE	8		E F
F	BDF	14	9 + 2	3 4
G	BAEG	13		5 G 1 H
н		∞		

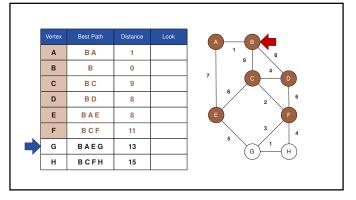
Vertex	Best Path	Distance	Look	A B
Α	ВА	1		1 9 8
В	В	0		
С	ВС	9		
D	B D	8		6 6
Е	BAE	8		E F
F	BCF	11	9 + 2	3 4
G	BAEG	13) G 1 H
Н		∞		

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Vertex	Best Path	Distance	Look
Α	ВА	1	
В	В	0	
С	ВС	9	
D	B D	8	
Е	BAE	8	
F	BCF	11	
G	BAEG	13	
н		∞	





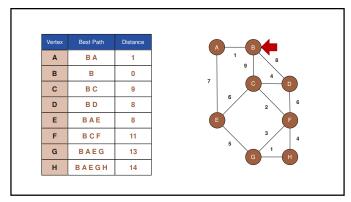


Vertex	Best Path	Distance	Look
Α	ВА	1	
В	В	0	
С	ВС	9	
D	B D	8	
Е	BAE	8	
F	BCF	11	
G	BAEG	13	
(H)	BCFH	15	13 + 1

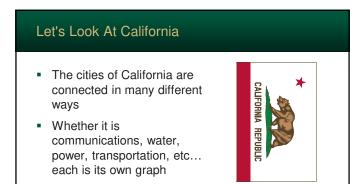
Vertex	Best Path	Distance	Look
Α	ВА	1	
В	В	0	
С	ВС	9	
D	B D	8	
Е	BAE	8	
F	BCF	11	
G	BAEG	13	
 H	BAEGH	14	13 + 1

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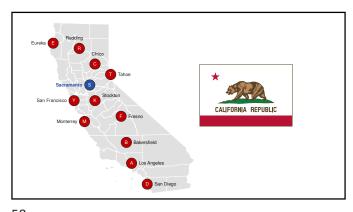
Vertex	Best Path	Distance	Look
Α	ВА	1	
В	В	0	
С	ВС	9	
D	B D	8	
E	BAE	8	
F	BCF	11	
G	BAEG	13	
Н	BAEGH	14	





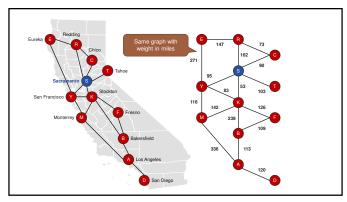


Let's look at the California freeway system and run the Prim-Jarník and Dijkstra algorithms on it
 So, let's get a MST and a nice shortest-path for Sacramento

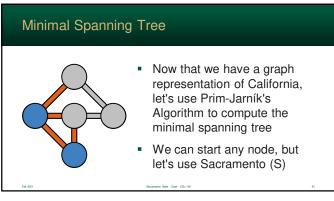


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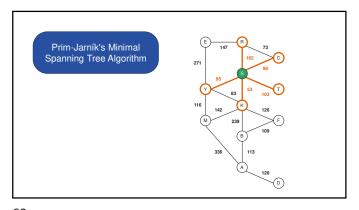


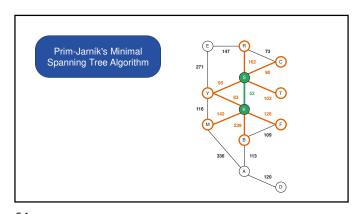


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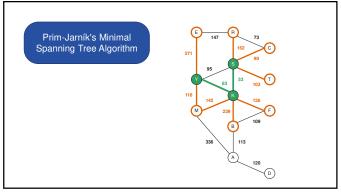


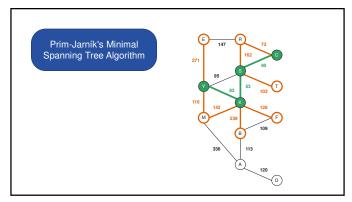
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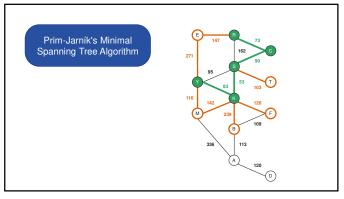


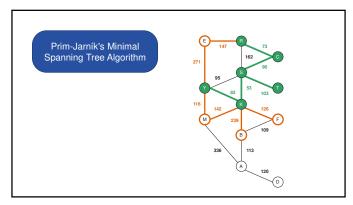


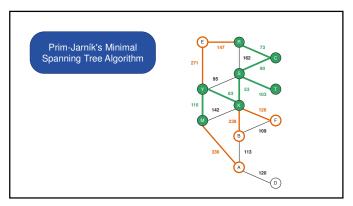
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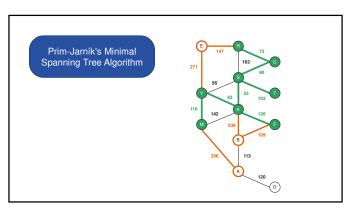




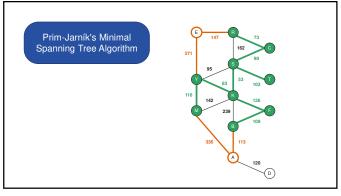


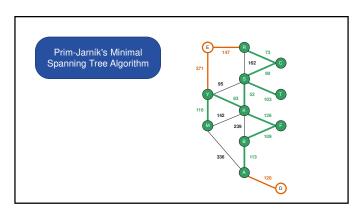


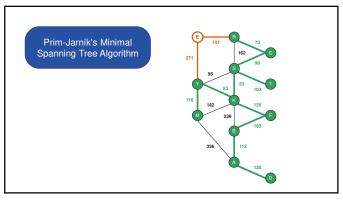


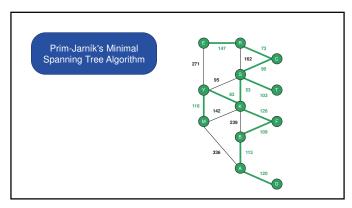


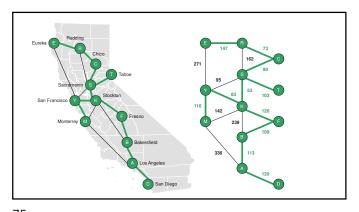
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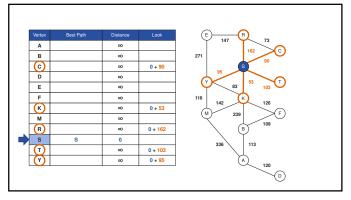


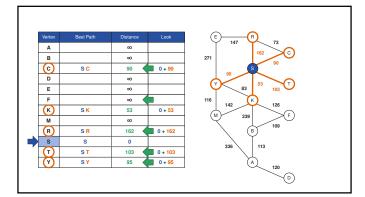


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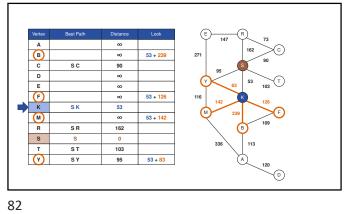
Sacramento, California	a Example
Unknown Known Examining	CALIFORNIA REPUBLIC
Visible edge	5 Stee - Cook - Cdc 133 77

Vertex	Best Path	Distance	Look	E 147 R 7	
Α		∞0			, >0
В		∞0		271 162	\sim
С				9	U
D		∞0		95	\ O
Е		- 00		83 53 10)3 (T)
F		- 00		116 (K)	
К		- 00		142	_
м		- 00		M) 239	>(F)
R		- 00		B) 11	9
S	s	0		1\ Y	
т		- 00		336 113	
Υ		- 00] A 1:	



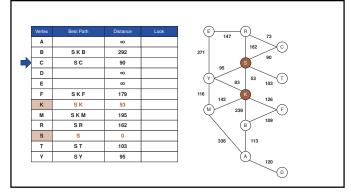


Vertex	Best Path	Distance	Look	(E) (R)
Α		∞		147 73
В		∞		271 162 C
С	sc	90		90
D		∞		95 Y 53
Е		∞		83 53 103
F		- 00		116 K 126
K	SK	53		
М		∞		M 239 F
R	SR	162		B 109
S	S	0		336 113
Т	ST	103] 330 113
Υ	SY	95		A 120

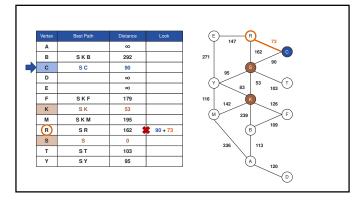


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	Vertex	Best Path	Distance		E 147 R 73
Г	Α		∞0		162 (C)
Г	В	SKB	292	53 + 239	271
Г	С	sc	90		95
Γ	D		-00		
Г	Е		∞0		83 53 T)
	(F)	SKF	179	53 + 126	116 K
	К	SK	53		142 126 F
	(M)	SKM	195	53 + 142	
Г	R	SR	162		B 109
	S	s	0		336 113
Г	Т	ST	103		336 \ 113
Г	(Y)	SY	95	53 + 83	A 120



Vertex	Best Path	Distance	Look	(E) (R)
Α		∞		147 73
В	SKB	292		271
С	sc	90		(s)
D		∞		95 Y 53
E		∞0		83 53 103
F	SKF	179		116 K
K	SK	53		142 126 F
М	SKM	195		
(R)	SR	162	90 + 73	B) 109
S	S	0		336 113
т	ST	103] 330 113
Υ	SY	95		A 120

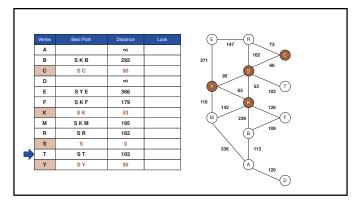


Vertex	Best Path	Distance	Look
Α		∞	
В	SKB	292	
С	s c	90	
D		∞	
Е			
F	SKF	179	
К	SK	53	
М	SKM	195	
R	SR	162	
S	s	0	
Т	ST	103	
Y	SY	95	

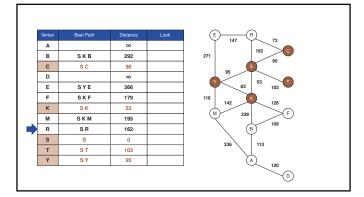
Vertex	Best Path	Distance	Look	E 147 R 73
Α		- 00		162
В	SKB	292		271
С	sc	90		90
D		-00		95
(E)		∞0	95 + 271	83 53 103
F	SKF	179		116 K
К	SK	53		142 126
(M)	SKM	195	95 + 116	M 239 F
R	SR	162		B 109
s	S	0		\ \ \ \ \ \
т	ST	103		336 113
Υ	SY	95		Â
		'		120 D

87 88

Vertex	Best Path	Distance	Look
Α		∞0	
В	SKB	292	
С	s c	90	
D		-00	
(E)	SYE	366 ◀	95 + 271
F	SKF	179	
K	SK	53	
(M)	SKM	195	95 + 116
R	SR	162	
S	S	0	
Т	ST	103	
Υ	SY	95	



Vertex	Best Path	Distance	E 147 R	73
Α		∞0	147	'3
В	SKB	292	271	90
С	sc	90	(s)	30
D		∞	95	
Е	SYE	366	83 53	103
F	SKF	179	116 K	126
К	SK	53		120 F)
М	SKM	195	1 \(\sigma \	109
R	SR	162] \ B	109
S	S	0	336 113	
Т	ST	103] 336 \ 113	
Υ	SY	95] (A)	120

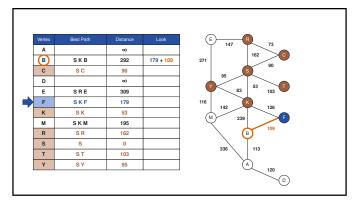


Ve	rtex	Best Path	Distance	Look
	Α		∞	
	В	SKB	292	
	С	sc	90	
	D		∞	
7	E)	SYE	366	162 + 147
Г	F	SKF	179	
	К	SK	53	
	м	SKM	195	
	R	SR	162	
	s	s	0	
	т	ST	103	
	Υ	SY	95	

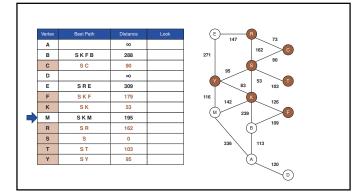
	Vertex	Best Path	Distance	Look
	Α		- 00	
Ī	В	SKB	292	
Ì	С	s c	90	
	D		∞	
Ī	E	SRE	309	162 + 147
	F	SKF	179	
Ī	К	SK	53	
ĺ	М	SKM	195	
	R	SR	162	
	S	s	0	
	Т	ST	103	
Ì	Υ	SY	95	

93 94

Vertex	Best Path	Distance	E 147 R 73
Α		∞	162
В	SKB	292	271
С	s c	90	(s)
D		∞0	95
Е	SRE	309	83 53 103
F	SKF	179	116 K
K	s K	53	142 126
М	SKM	195	M) 239 F)
R	SR	162	B) 109
S	S	0	1 Y
Т	ST	103	336 113
Υ	SY	95	A 120



Vertex	Best Path	Distance	
Α		-00	
В	SKFB	288	179 + 109
С	s c	90	
D		-00	
Е	SRE	309	
F	SKF	179	
K	SK	53	
М	SKM	195	
R	SR	162	
S	S	0	
Т	ST	103	
Υ	SY	95	

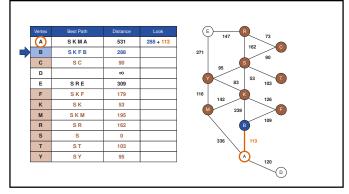


Vertex	Best Path	Distance	Look
A		-00	195 + 336
В	SKFB	288	
С	sc	90	
D		-00	
Е	SRE	309	
F	SKF	179	
К	SK	53	
М	SKM	195	
R	SR	162	
S	S	0	
Т	ST	103	
Y	SY	95	

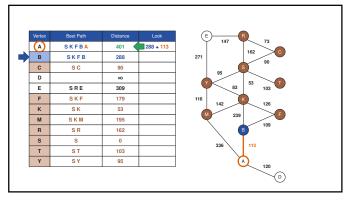
	Best Path	Distance	Look	E 147	73
A)	SKMA	531	195 + 336	147 162	,s
В	SKFB	288		271	90
С	s c	90		95	90
D		∞0			
E	SRE	309		83 53	03
F	SKF	179		116 K	
K	SK	53			26
И	SKM	195		239	
2	SR	162		(B)	09
s	S	0		, J	
Т	ST	103		336 113	
Y	SY	95		A	20

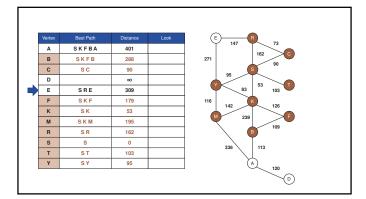
99 100

Verte	x Best Path	Distance	
Α	SKMA	531	
В	SKFB	288	
С	s c	90	
D		∞	
Е	SRE	309	
F	SKF	179	
К	SK	53	
M	SKM	195	
R	SR	162	
S	s	0	
Т	ST	103	
Y	SY	95	



101 102



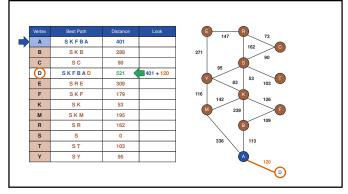


Vertex	Best Path	Distance	Look	E 147	73
Α	SKFBA	401			_
В	SKFB	288		271 162	90
С	sc	90			90
D		∞0		95	
Е	SRE	309		83 53	103
F	SKF	179		116 142 K	126
K	SK	53			120
М	SKM	195		239	109
R	SR	162		B	109
S	S	0		336 113	
Т	ST	103		336 113	
Υ	SY	95		(A)	120

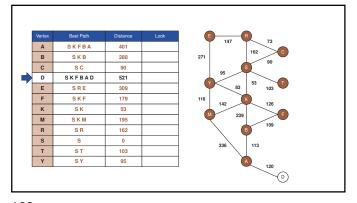
ertex	Best Path	Distance	Look	E 147 R	73
Α	SKFBA	401			13
В	SKFB	288		271 162	
С	sc	90		S	90
D		∞		95	\ <u></u>
Е	SRE	309		83 53	103
F	SKF	179		116 K	
K	SK	53		142	126
М	SKM	195		239	
R	SR	162		B	109
s	S	0		1\ T	
Т	ST	103		336 113	
Υ	SY	95		T (A)	120

105 106

/ertex	Best Path	Distance	
Α	SKFBA	401	
В	SKB	288	
С	s c	90	
D		∞	401 + 120
Е	SRE	309	
F	SKF	179	
К	SK	53	
М	SKM	195	
R	SR	162	
S	s	0	
Т	ST	103	
Υ	SY	95	



107 108

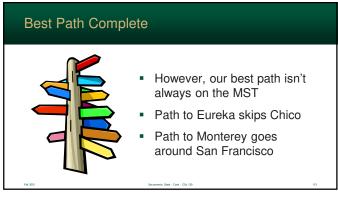


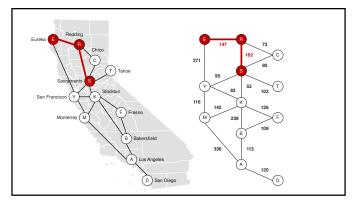
Vertex	Best Path	Distance	Look	E 147 R 73
Α	SKFBA	401		
В	SKB	288		271 162 0
С	sc	90		(s)
D	SKFBAD	521		95
E	SRE	309		83 53 103
F	SKF	179		116 K 126
К	SK	53		
М	SKM	195		M 239 F
R	SR	162		B 109
S	s	0		336 113
Т	ST	103		330 113
Υ	SY	95		A 120

Vertex	Best Path	Distance	E R
Α	SKFBA	401	147 73
В	SKB	288	271
С	s c	90	(s)
D	SKFBAD	521	95
E	SRE	309	83 53 103
F	SKF	179	116 K 126
K	SK	53	
М	SKM	195	M 239
R	SR	162	B 109
S	S	0	1
Т	ST	103	336 113
Υ	SY	95	

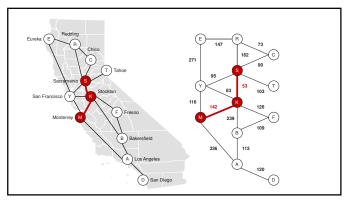


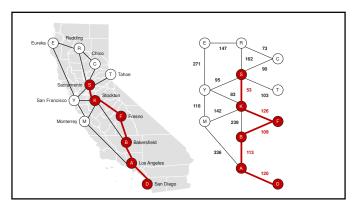
111 112





113 114





California Result

- But, of course, if you going to go to San Diego, then you might want to take Hwy 5
- It goes around Fresno –
 which while a great city –
 does have some traffic (which
 will slow you down)

