

## Section 7.6 Problems

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November 17, 2021

Is the zero state a stable equilibrium?

##1.

Stable, since the diagonal eigenvalues are less than 0.

##2.

Not stable.

**3.**

$$\lambda^2 - 1.6\lambda + 1.13$$
$$\lambda = .8 \pm .98i$$

Since  $1.6^2 + .98^2 = 1.6004$ , not stable.

**11.**

$$-1.1 \leq k \leq .1.$$

**12.**

$$|k| \leq .8$$

**13.**

All possible values.

**14.**

$$|k| < 1/2$$

**15.**

No possible values, since  $\lambda_1 + \lambda_2 = 2$  means one or both has absolute value greater than 1.

16.

17.

$$\lambda = .6 \pm .8i$$

I pick  $.6 + .8i$ .

$$S = \begin{bmatrix} 1 & 1 \\ -i & i \end{bmatrix}$$

$$v = \begin{bmatrix} 1 \\ 0 \end{bmatrix} + i \begin{bmatrix} 0 \\ -1 \end{bmatrix}$$

$$S = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$$

$$c = S^{-1} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} -1 \\ 0 \end{bmatrix}$$

The big dumb formula, with  $\theta = \arctan .8/.6 \approx .92$ :

$$u_{k+1} = (1^k) \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} \cos 1^k \theta & -\sin 1^k \theta \\ \sin 1^k \theta & \cos 1^k \theta \end{bmatrix} \begin{bmatrix} -1 \\ 0 \end{bmatrix}$$

$$= \begin{bmatrix} \sin \theta & \cos \theta \\ -\cos \theta & \sin \theta \end{bmatrix} \begin{bmatrix} -1 \\ 0 \end{bmatrix}$$

$$= \begin{bmatrix} -\sin \theta \\ \cos \theta \end{bmatrix}$$

Interesting - is  $r$  always the square root of the determinant for skew-symmetric?

19.

$$A = \begin{bmatrix} 2 & -3 \\ 3 & 2 \end{bmatrix}$$

$$\lambda = 2 \pm 3i$$

$$S_1 = \begin{bmatrix} 1 \\ -i \end{bmatrix}$$

$$s = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$$

$$c = S^{-1} x_0 = \begin{bmatrix} -1 \\ 0 \end{bmatrix}$$

$$\theta = \arctan \frac{3}{2} = 0.9827937$$

$$r = \sqrt{13}$$

$$u_{k+1} = \sqrt{13}^k \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} \cos \theta k & -\sin \theta k \\ \sin \theta k & \cos \theta k \end{bmatrix} \begin{bmatrix} -1 \\ 0 \end{bmatrix}$$

$$= \sqrt{13}^k \begin{bmatrix} -\cos \theta k \\ \sin \theta k \end{bmatrix}$$

**21.**

$$A = \begin{bmatrix} 1 & 5 \\ -2 & 7 \end{bmatrix}$$

$$S_1 = \begin{bmatrix} 1 \\ 3/5 + 5/i \end{bmatrix}$$

$$S = \begin{bmatrix} 0 & 1 \\ 1/5 & 3/5 \end{bmatrix}$$

$$r = \sqrt{17}$$

$$\theta = \arctan \frac{1}{4}$$

$$c = -5 \begin{bmatrix} -1 \\ 0 \end{bmatrix} = \begin{bmatrix} 5 \\ 0 \end{bmatrix}$$

$$\begin{aligned} u_{k+1} &= \sqrt{17} \begin{bmatrix} 0 & 1 \\ 1/5 & 3/5 \end{bmatrix} \begin{bmatrix} \cos \theta k & -\sin \theta k \\ \sin \theta k & \cos \theta k \end{bmatrix} \begin{bmatrix} 5 \\ 0 \end{bmatrix} \\ &= \sqrt{17} \begin{bmatrix} 0 & 1 \\ 1/5 & 3/5 \end{bmatrix} \begin{bmatrix} 5 \cos \theta k \\ 5 \sin \theta k \end{bmatrix} \\ &= \sqrt{17} \begin{bmatrix} 5 \sin \theta k \\ \cos \theta k + 3 \sin \theta k \end{bmatrix} \end{aligned}$$

**25.**

Unstable. If  $A$  is stable, each  $\lambda$  must be less than 1 in absolute value, so  $1/\lambda$  of the inverse must be greater.

**26.**

Stable, since  $A^T$  has the same eigenvalues as  $A$ .

**27.**

Stable, since the eigenvalues just have to be less than 1 in absolute value.

**28.**

Unstable.

$$\begin{aligned} |\lambda| &< 1 \\ |\lambda - 2| &< -1 \end{aligned}$$

**29.**

Stable if  $\lambda < 0$ , the square is smaller.

**30.**

**31.**

By the rule that  $|\lambda| < 1$  for stability:

$$\begin{aligned} |\operatorname{tr} A| - 1 &< \det A < 1 \\ |\lambda_1 + \lambda_2| - 1 &< \lambda_1 \lambda_2 < 1 \\ 1 &< 1 < 1 \end{aligned}$$

This holds only if both have absolute value less than 1.

**33.**

If  $x_0$  is real, then  $c_1 i w = -\bar{c}_1 i w$  - the complex components cancel. Since  $\bar{c}_1 i w = -c_1 i w$ , that means  $c_1 = \bar{c}_1$ .

**34.**

- a. It cannot be stable, because at least one eigenvalue is too large.
- b. If  $|\det A| < 1$ , it may be stable. Otherwise, at least one eigenvalue is too large.

**35.**

- a.  $u_{k+1} = Au_k$  may be rewritten  $A^k u_0$ . Since all eigenvalues are less than 1 in absolute value,  $A$  is stable at zero, so  $A^k$  approaches 0 as  $k$  increases. Thus the length of the vector diminishes with each iteration.
- b. No. All eigenvalues are 1, so the matrix is unstable and approaches no limit.

**38.**

a.

$$\begin{aligned} x &= Ax + b \\ Ax &= x - b \\ x &= A^{-1}(x - b) \\ x &= \frac{1}{\lambda}(x - b) \end{aligned}$$

- b. If  $x$  is an eigenvector with a nonzero eigenvalue.

**39.**

The eigenvector with highest  $\lambda$  is  $\begin{bmatrix} 1 \\ 2 \end{bmatrix}$ , so

$$\begin{bmatrix} 1 \\ 2 \end{bmatrix} + \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 2 \\ 4 \end{bmatrix}$$

because  $\begin{bmatrix} 1 \\ 2 \end{bmatrix}$  gets added after *each iteration*.