



UNSW
SYDNEY

5. FLOW NETWORKS

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School of Computer Science and Engineering
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Term 2, 2023

1. Flow Networks
2. Solving the Maximum Flow Problem
3. Applications of Network Flow
4. Puzzle

Definition

A *flow network* $G = (V, E)$ is a directed graph in which each edge $e = (u, v) \in E$ has a positive *integer* capacity $c(u, v) > 0$.

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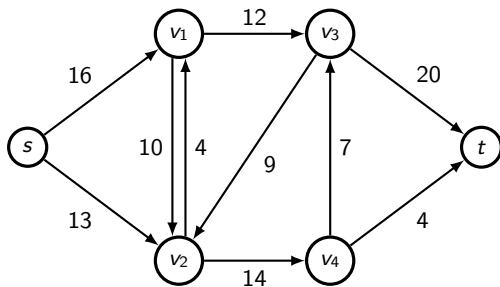
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- 2 *Flow conservation*: for all vertices $v \in V \setminus \{s, t\}$ we require

$$\sum_{(u,v) \in E} f(u, v) = \sum_{(v,w) \in E} f(v, w),$$

i.e. the flow into any vertex (other than the source and the sink) equals the flow out of that vertex.

Definition

The *value* of a flow is defined as

$$|f| = \sum_{v:(s,v) \in E} f(s,v) = \sum_{v:(v,t) \in E} f(v,t),$$

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Given a flow network, our goal is to find a flow of maximum value.

Integrality Property

If all capacities are integers (as we assumed earlier), then there is a flow of maximum value such that $f(u, v)$ is an integer for each edge $(u, v) \in E$.

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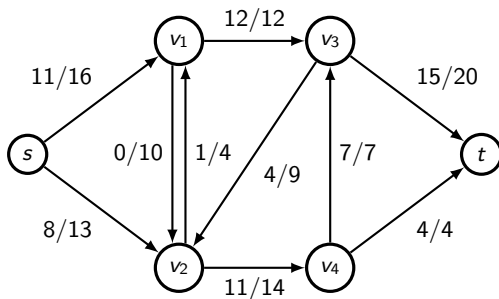
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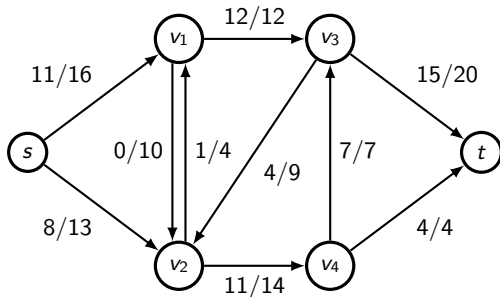
This means that there is always at least one solution entirely in integers. We will only consider integer solutions hereafter.

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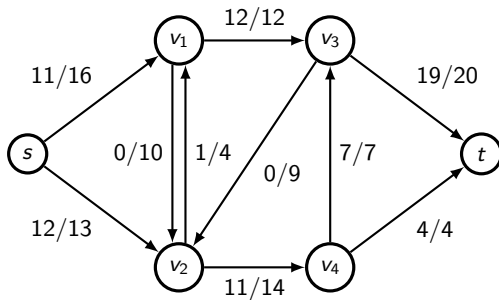
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The pictured flow has a value of 19 units, and it does not appear possible to send another unit of flow. But we can do better!

Here is a flow of value 23 units in the same flow network.

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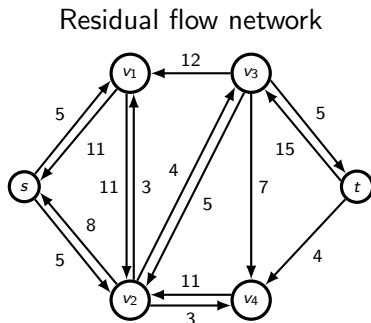
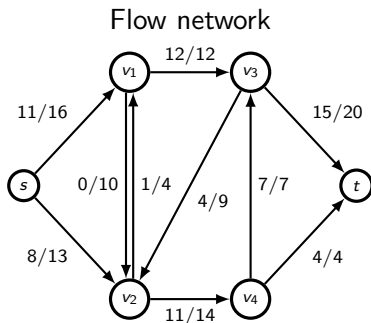
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- It would have been better to send those four units of flow to t directly, but this may not have been obvious at the time this decision was made.
- We need a way to correct mistakes! We would like to send flow from v_2 back to v_3 so as to “cancel out” the earlier allocation.

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- Edges of capacity zero (when $f = 0$ or $f = c$) need not be included.

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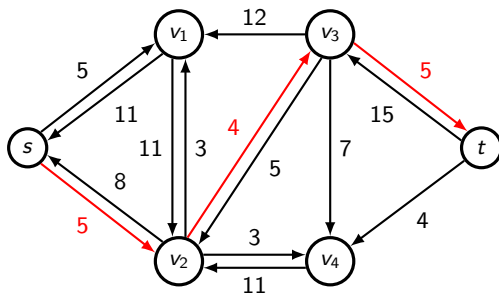
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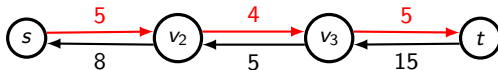


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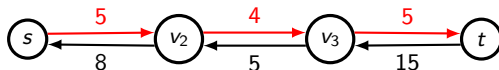
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- We can now send that amount of flow along the augmenting path, recalculating the flow and the residual capacities for each edge used.
- Suppose we have an augmenting path of capacity f , including an edge from v to w . We should:
 - cancel up to f units of flow being sent from w to v ,
 - add the remainder of these f units to the flow being sent from v to w ,
 - increase the residual capacity from w to v by f , and
 - reduce the residual capacity from v to w by f .

Recall that the augmenting path was as follows.

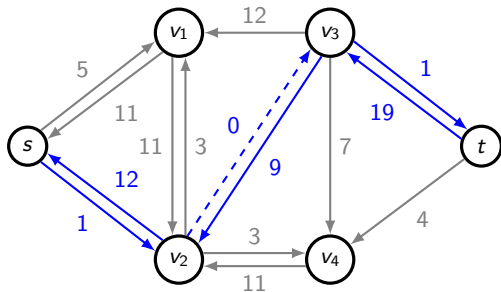


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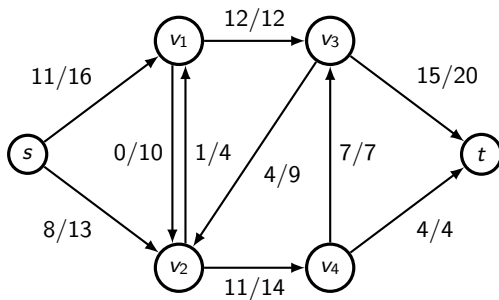


After sending four units of flow along this path, the new residual flow network is pictured below.

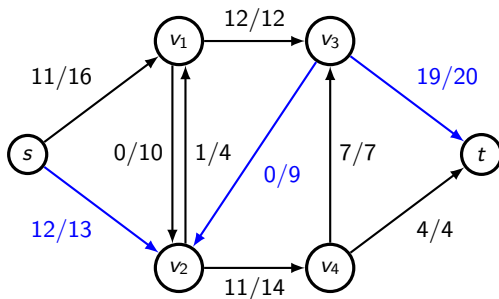
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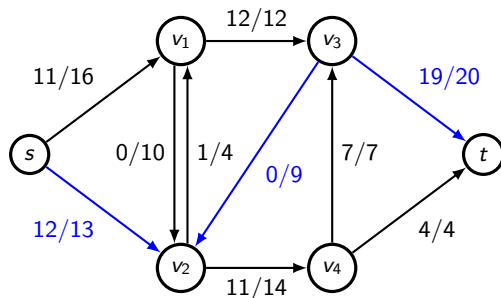
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Pictured below is the new flow, after sending four units of flow along the path $s \rightarrow v_2 \rightarrow v_3 \rightarrow t$.



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Note that the four units of flow previously sent from v_3 to v_2 have been cancelled out.

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- When there are no more augmenting paths, you have achieved the largest possible flow in the network.

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- However, the total flow is finite. In particular, it cannot be larger than the sum of all capacities of all edges leaving the source.
- We conclude that the process must terminate eventually.

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- Maybe we have created bottlenecks by choosing bad augmenting paths; maybe better choices of augmenting paths could produce a larger total flow through the network?
- This is not at all obvious, and to show that this is not the case we need a mathematical proof!

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- 1 $S \cup T = V$
- 2 $S \cap T = \emptyset$
- 3 $s \in S$ and $t \in T$.

Definition

The *capacity* $c(S, T)$ of a cut (S, T) is the sum of capacities of all edges leaving S and entering T , i.e.

$$c(S, T) = \sum_{(u,v) \in E} \{c(u, v) : u \in S, v \in T\}.$$

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Note that the capacities of edges going in the opposite direction, i.e. from T to S , do not count.

Definition

Given a flow f , the *flow* $f(S, T)$ through a cut (S, T) is the total flow through edges from S to T minus the total flow through edges from T to S , i.e.

$$\begin{aligned} f(S, T) = & \sum_{(u,v) \in E} \{f(u, v) : u \in S, v \in T\} \\ & - \sum_{(u,v) \in E} \{f(u, v) : u \in T, v \in S\}. \end{aligned}$$

Fact

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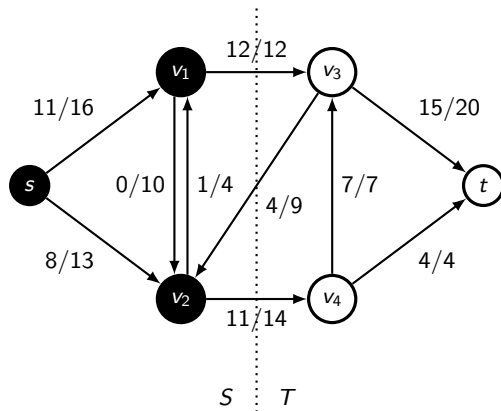
This is a consequence of *flow conservation*.

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- Therefore $f(S, T) \leq c(S, T)$.
- It follows that $|f| \leq c(S, T)$, so the value of any flow is at most the capacity of any cut.



- In the above example the net flow across the cut is given by

$$f(S, T) = f(v_1, v_3) + f(v_2, v_4) - f(v_2, v_3) = 12 + 11 - 4 = 19.$$

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- As we have mentioned, we add only the capacities of edges from S to T and not of edges in the opposite direction.

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- Thus, if we find a flow f which equals the capacity of some cut (S, T) , then such flow must be maximal and the capacity of such a cut must be minimal.

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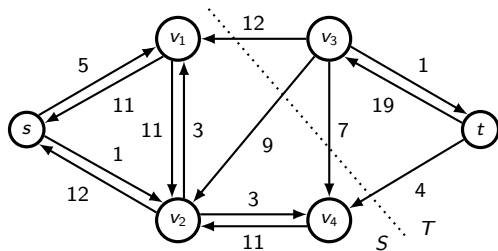
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- Thus, if we find a flow f which equals the capacity of some cut (S, T) , then such flow must be maximal and the capacity of such a cut must be minimal.
- We now show that when the Ford-Fulkerson algorithm terminates, it produces a flow equal to the capacity of an appropriately defined cut.

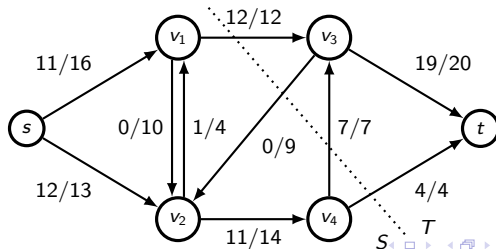
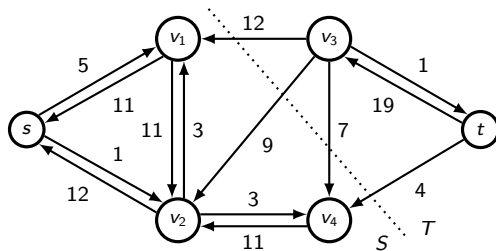
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- Since there are no more augmenting paths from s to t , clearly the sink t belongs to T .



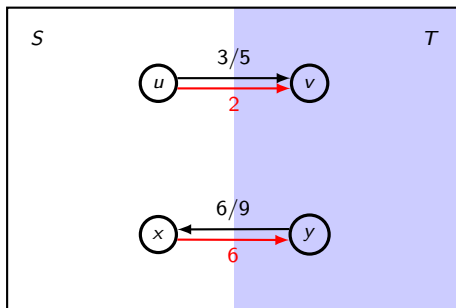


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Proof

- Suppose an edge (u, v) from S to T has any additional capacity left. Then in the residual flow network, the path from s to u could be extended to a path from s to v . This contradicts our assumption that $v \in T$.

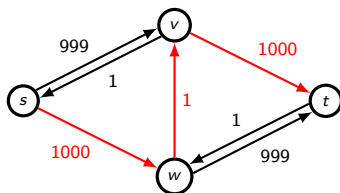
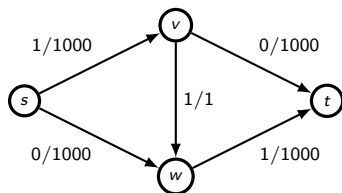
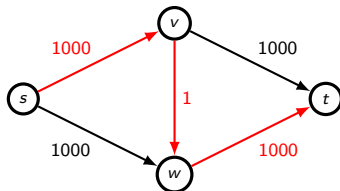
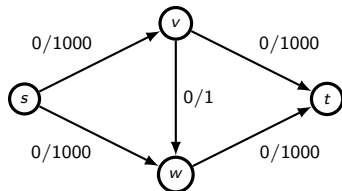
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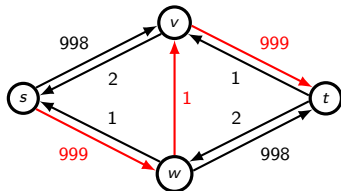
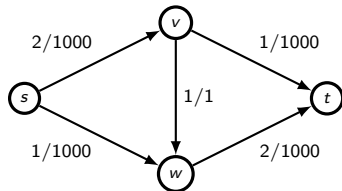
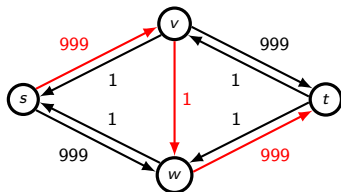
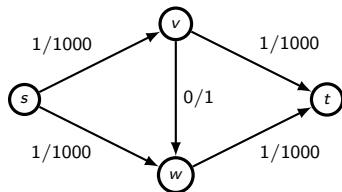
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- Suppose an edge (y, x) from T to S has any flow in it. Then in the residual flow network, the path from s to x could be extended to a path from s to y . This contradicts our assumption that $y \in T$.

- Since all edges from S to T are occupied with flows to their full capacity, and also there is no flow from T to S , the flow across the cut (S, T) is precisely equal to the capacity of this cut, i.e., $f(S, T) = c(S, T)$.

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- Thus, such a flow is maximal and the corresponding cut is a minimal cut, regardless of the particular way in which the augmenting paths were chosen.

How efficient is the Ford-Fulkerson algorithm?





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- Therefore the time complexity of the Ford-Fulkerson algorithm is $O(E|f|)$.

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- However, the value of the maximum flow $|f|$ can be as large as VC in general.
- Therefore, the time complexity $O(E|f|)$ can be exponential in the size of the input, which is unsatisfactory.

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- At each step, we find the next augmenting path using *breadth-first search* in $O(V + E) = O(E)$ time.
- Note that this choice is somewhat counter-intuitive: augmenting paths are chosen based only on length, so we may end up flowing edges with small capacities before edges with large capacities.

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Note also that Edmonds-Karp is a specialisation of Ford-Fulkerson, so the original $O(E|f|)$ bound also applies.

- Faster max flow algorithms exist, e.g. Dinic's in $O(V^2E)$ and Preflow-Push in $O(V^3)$.

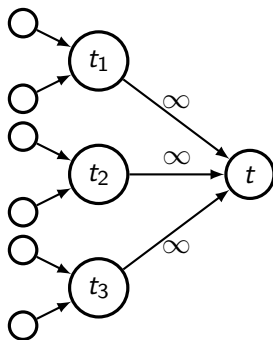
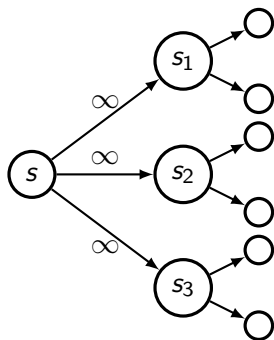
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- In March 2022, Chen et al. developed an “almost linear” time algorithm for max flow.

1. Flow Networks
2. Solving the Maximum Flow Problem
3. Applications of Network Flow
4. Puzzle

- Flow networks with multiple sources and sinks are reducible to networks with a single source and single sink by adding a “super-source” and “super-sink” and connecting them to all sources and sinks, respectively, by edges of infinite capacity.

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- Sometimes not only the edges but also the vertices v_i of the flow graph might have capacities $C(v_i)$, which limit the total throughput of the flow coming to the vertex (and, consequently, also leaving the vertex):

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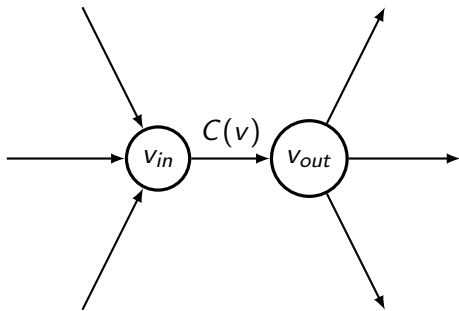
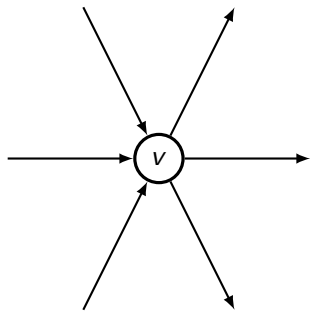
- We can handle this by reducing it to a situation with only edge capacities!

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- Connect v_{in} and v_{out} with an edge $e^* = (v_{in}, v_{out})$ of capacity $C(v)$.



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Task: Design an algorithm which runs in time polynomial in n and k and dispatches the largest possible number of movies.

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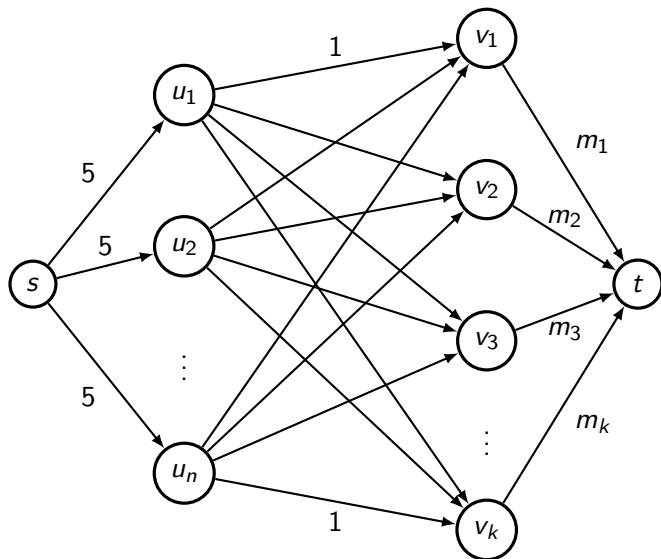
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- Since the value of any flow is constrained by the total capacity from s , which in this case is $5n$, we can achieve a tighter bound of $O(E|f|) = O(n(nk + n + k)) = O(n^2k)$.

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Task: Design an algorithm which runs in time polynomial in n and m and allocates the maximum possible weight of cargo without exceeding any of the cell, row or column capacities.

	col 1	col 2	col 3	col 4	row cap
row 1	$C(1, 1)$	$C(1, 2)$	$C(1, 3)$	$C(1, 4)$	$C_r(1)$
row 2	$C(2, 1)$	$C(2, 2)$	$C(2, 3)$	$C(2, 4)$	$C_r(2)$
row 3	$C(3, 1)$	$C(3, 2)$	0	$C(3, 4)$	$C_r(3)$
row 4	$C(4, 1)$	0	$C(4, 3)$	0	$C_r(4)$
row 5	$C(5, 1)$	$C(5, 2)$	0	$C(5, 4)$	$C_r(5)$
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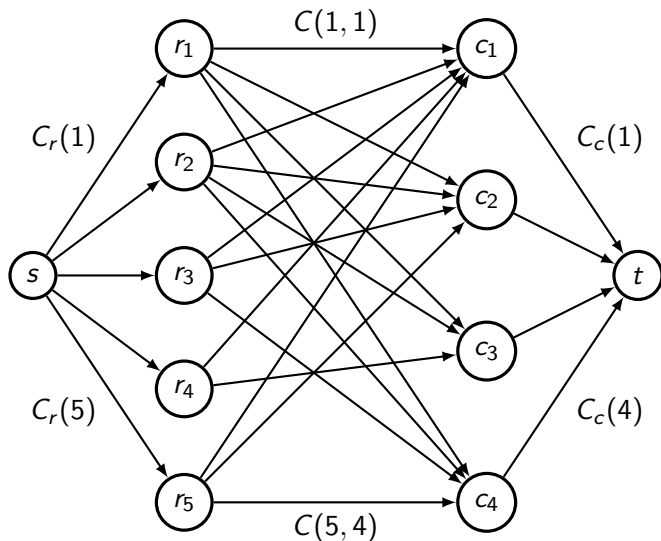
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- There are $n + m + 2$ vertices and up to $nm + n + m$ edges, so the time complexity is

$$\begin{aligned} &O((n + m + 2)(nm + n + m)^2) \\ &= O((n + m)(nm)^2), \end{aligned}$$

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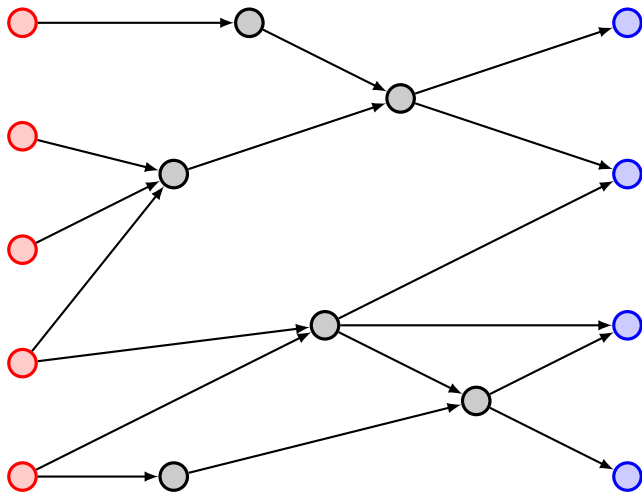
Problem

Instance: You are given a directed graph G with n vertices and m edges. Of these vertices, r are painted red, b are painted blue, and the remaining $n - r - b$ are black. Red vertices have only outgoing edges and blue vertices have only incoming edges.

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Task: Design an algorithm which runs in time polynomial in n and m and determines the largest possible number of vertex-disjoint (i.e. non-intersecting) paths in this graph, each of which starts at a red vertex and finishes at a blue vertex.



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- To use our usual max flow algorithms, we need to introduce a super-source and super-sink.
- To ensure that no black vertex is used twice, we should impose a vertex capacity of 1 for each of them.

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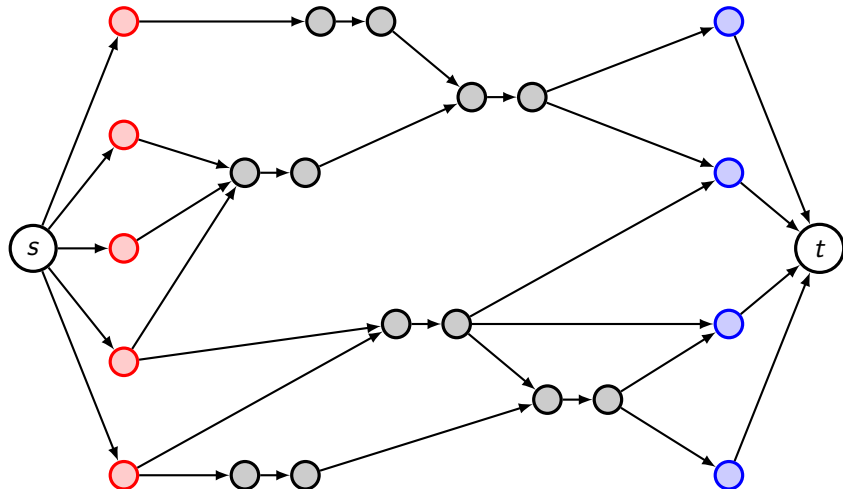
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All edges have capacity 1.



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- *Flow conservation* ensures that each unit of flow travels from s to a red vertex, then to zero or more black vertices, before arriving at a blue vertex and terminating at t .

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- Similarly, each blue vertex is used in at most one path also.
- Likewise, each in-vertex and out-vertex pair contributes to at most one path, so the paths are indeed vertex-disjoint.

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Definition

A graph $G = (V, E)$ is said to be *bipartite* if its vertices can be divided into two disjoint sets A and B such that every edge $e \in E$ has one end in the set A and the other in the set B .

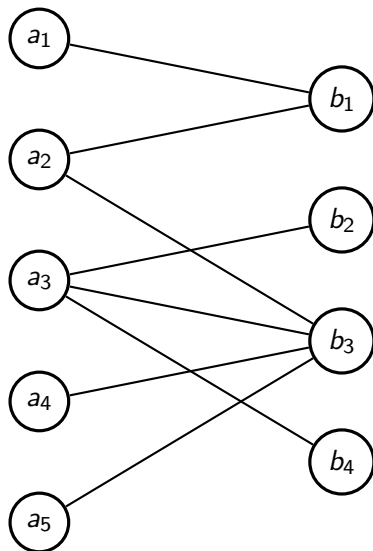
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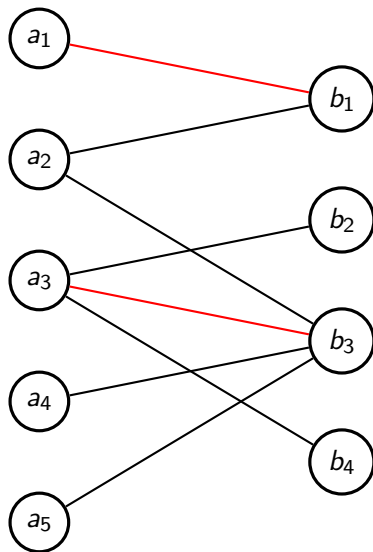
A *matching* in a graph $G = (V, E)$ is a subset $M \subseteq E$ such that each vertex of the graph belongs to at most one edge in M .

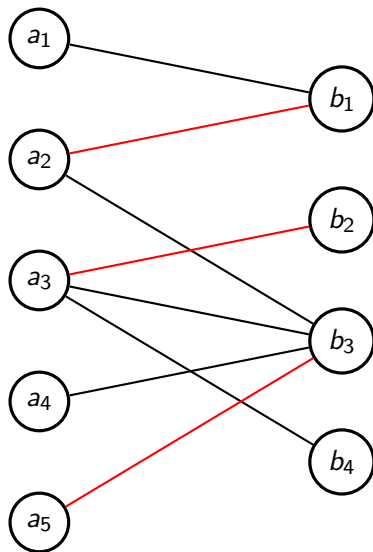
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A *maximum matching* in G is a matching containing the largest possible number of edges.







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Given a bipartite graph G , find the size (i.e. the number of pairs matched) in a maximum matching.

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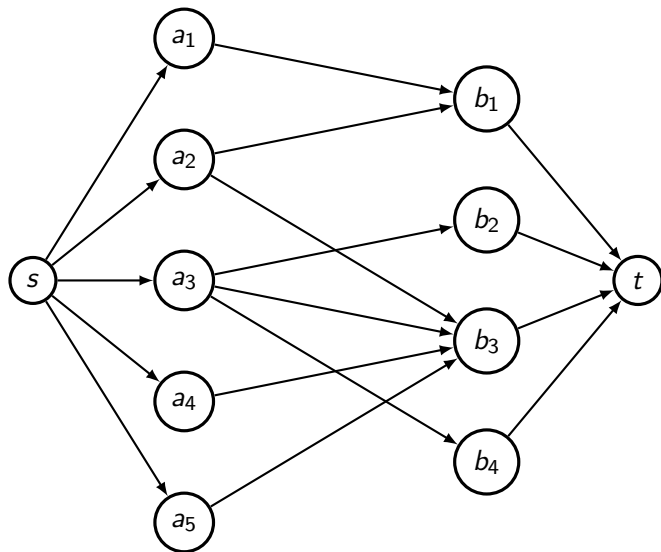
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Question

How can we turn a Maximum Bipartite Matching problem into a Maximum Flow problem?

Answer

Create two new vertices, s and t (the source and sink). Construct an edge from s to each vertex in A , and from each vertex in B to t . Orient the existing edges from A to B . Assign capacity 1 to all edges.



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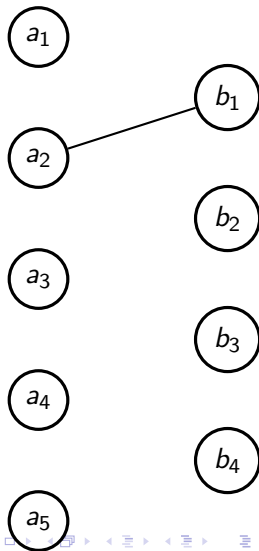
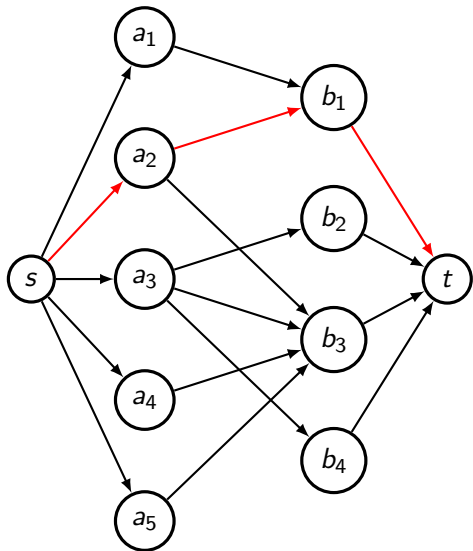
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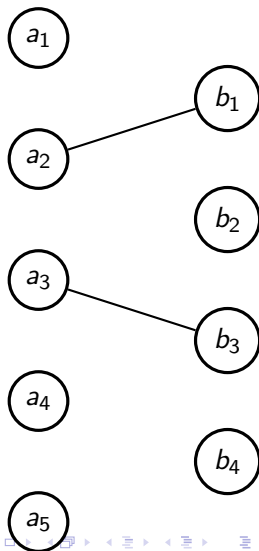
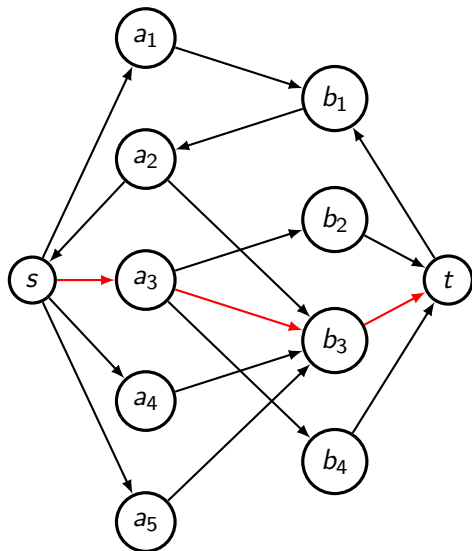
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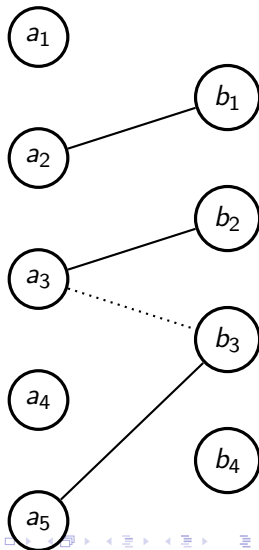
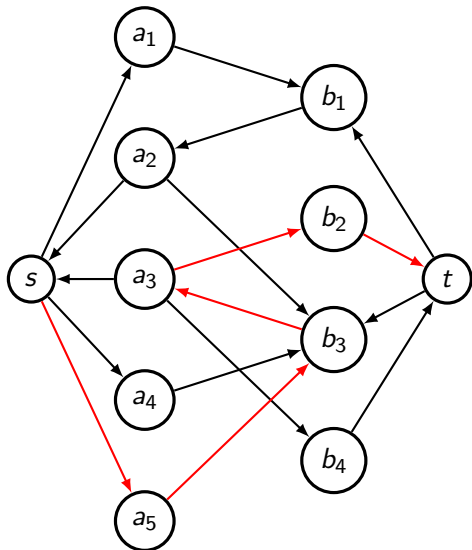
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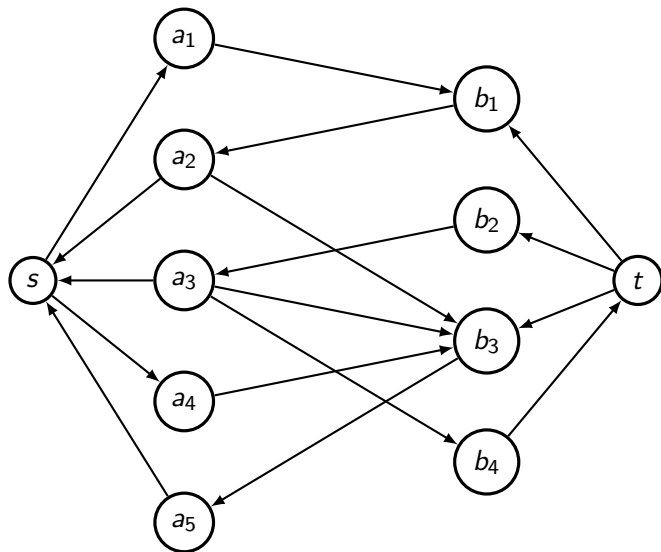
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As always, the residual graph allows us to correct mistakes and increase the total flow.









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Task: Design an algorithm which runs in time polynomial in n , m and k , and places as many people as possible into jobs for which they are qualified. No worker can take more than one job, and no job can employ more than one worker.

- Create an unweighted, undirected graph with vertices a_1, \dots, a_n and b_1, \dots, b_m , representing the workers and jobs respectively.

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- Once again, the tightest bound on the runtime of Edmonds-Karp is of the form $O(E|f|)$, where $E \leq nm + n + m$ and $|f| \leq \min(n, m)$.
- Therefore the total time complexity is $O(nm(k + \min(m, n)))$, which is polynomial in n , m and k as required.

1. Flow Networks
2. Solving the Maximum Flow Problem
3. Applications of Network Flow
4. Puzzle

Problem

You are taking two kinds of medicines, A and B , which each come in identical bottles of 30 pills. Pills of medicine A are completely indistinguishable from pills of medicine B . You take one pill of each medicine every day. The pharmacy will only refill your pill bottles every 28 days.

One day, you are down to the last two pills in each bottle when you drop both bottles on the floor, spilling all four pills. Since you cannot tell which are of type A and which are of type B , how can you continue to take one pill of each medicine for the remaining two days?



That's All, Folks!!