

## Running Time of Graham-Scan

Although Graham-Scan-Core consists of two nested loop, in fact it runs in linear time! To see this, consider the types of operations and how many each type of operation the algorithm needs to do. There are three types of operations this algorithm does: *push*, *pop*, and *checking-orientation*, and each operation takes  $\Theta(1)$  time. Now let's consider the times of each type will need to execute. First, notice that  $\#(\text{push}) = n$ , as each point will be pushed to the stack exactly once. Second,  $\#(\text{pop}) \leq n$ , as  $\#(\text{push}) \leq \#(\text{pop})$  starting from an empty stack (a point must be pushed into the stack prior to pop). Third, notice that right after *checking-orientation* it is either a *push* or a *pop* operation (i.e., it's not possible to have two *checking-orientation* operations next to each other). This implies that  $\#(\text{checking-orientation}) \leq \#(\text{push}) + \#(\text{pop}) \leq 2n$ . Combined, we have that Graham-Scan-Core takes  $\Theta(n)$  time.

The preprocessing step of Graham-Scan takes  $\Theta(n \log n)$ , as it's dominated by the sorting step. The entire running time of Graham-Scan therefore takes  $\Theta(n \log n)$  time.

## Divide-and-Conquer Algorithm for Convex Hull

We now design a divide-and-conquer algorithm for convex hull problem. As usual, we define recursive function, say,  $\text{CHDC}(P)$ , which takes a set of points  $P$  as input and returns  $\text{CH}(P)$ , represented as the list of vertices of the convex polygon in counter-clockwise order.

```
function CHDC ( $P = \{p_1, p_2, \dots, p_n\}$ )
    if  $n \leq 3$ : resolve this base case and return the convex hull;
     $C_1 = \text{CHDC}(P[1..n/2])$ ;
     $C_2 = \text{CHDC}(P[n/2 + 1..n])$ ;
    return combine ( $C_1, C_2$ );
end algorithm;
```

The “combine” function in above pseudo-code is missing. Before design an algorithm for “combine”, we first make sure that it suffices to only consider points in  $C_1$  and  $C_2$ . Formally, we can write  $\text{CH}(P) = \text{CH}(C_1 \cup C_2)$ . This can be proved using the Property 2 of convex hull. Intuitively, any point *inside*  $C_1$  or  $C_2$  will be inside  $\text{CH}(P)$ , and therefore won't be *on*  $\text{CH}(P)$ .

We can use, for example, Graham-Scan to calculate  $\text{CH}(C_1 \cup C_2)$ , which takes  $\Theta(m \log m)$ , where  $m = |C_1 \cup C_2|$ . Can we do better? Yes. We will design an  $\Theta(m)$  time algorithm to calculate  $\text{CH}(C_1 \cup C_2)$ . The idea is to take advantage of that,  $C_1$  and  $C_2$  are already sorted (in counter-clockwise order along the polygon), and then to use Graham-Scan-Core to calculate  $\text{CH}(C_1 \cup C_2)$ . Recall that, Graham-Scan-Core is linear-time algorithm for convex hull; it just requires that all points in its input is sorted in counter-clockwise order w.r.t. the first point in its input.

The pseudo-code for combine procedure is given below.

function combine ( $C_1, C_2$ )

  find  $p_*$  in  $C_1 \cup C_2$  with smallest y-coordinate;

  assume that  $p_* \in C_1$ ; otherwise exchange  $C_1$  and  $C_2$ ;

  rewrite  $C_1$  into  $C'_1$  with circular shifting so that  $p_*$  is the first point of  $C'_1$ ; (*Note: now points in  $C'_1$  is sorted w.r.t.  $p_*$  in counter-clockwise order.*)

  find  $p_S$  in  $C_2$  with smallest angle (i.e., angle  $\angle p_S p_* p_\infty$ , where  $p_\infty = (+\infty, p_*.y)$ );

  find  $p_L$  in  $C_2$  with largest angle (i.e., angle  $\angle p_L p_* p_\infty$ , where  $p_\infty = (+\infty, p_*.y)$ );

  let  $C_{2a}$  be the sublist of  $C_2$  from  $p_S$  to  $p_L$  in counter-clockwise order; (*Note: now points in  $C_{2a}$  is sorted w.r.t.  $p_*$  in counter-clockwise order.*)

  let  $C_{2b}$  be the sublist of  $C_2$  from  $p_S$  to  $p_L$  in clockwise order; (*Note: now points in  $C_{2b}$  is sorted w.r.t.  $p_*$  in counter-clockwise order.*)

$C'_2 = \text{merge-two-sorted-arrays}(C_{2a}, C_{2b})$ ; (*Note: merging is by the angle w.r.t.  $p_*$  and  $p_\infty$ ; after it points in  $C'_2$  is sorted w.r.t.  $p_*$  in counter-clockwise order.*)

$C' = \text{merge-two-sorted-arrays}(C'_1, C'_2)$ ; (*Note: merging is by the angle w.r.t.  $p_*$  and  $p_\infty$ ; after it points in  $C'$ , i.e., points in  $C_1 \cup C_2$ , is sorted w.r.t.  $p_*$  in counter-clockwise order.*)

  return Graham-Core-Scan ( $C'$ );

end algorithm;

See figure below for explaining above combine step.

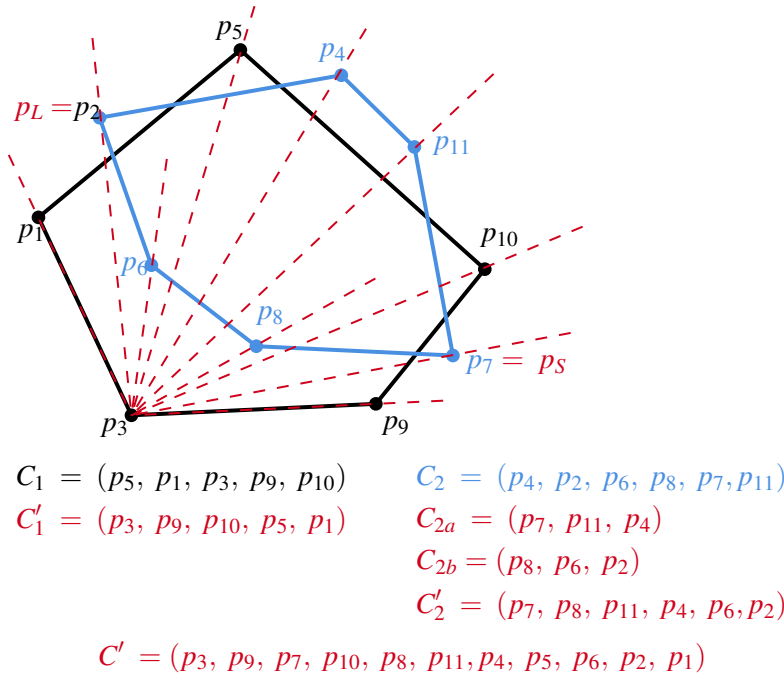


Figure 1: Example of combining  $C_1$  and  $C_2$ .

Clearly each step of above combine takes linear time. Therefore, the entire running time of combine is  $\Theta(|C_1| + |C_2|)$ .

To obtain the running time of CHDC, we write its recursion  $T(n) = 2T(n/2) + \Theta(|C_1| + |C_2|)$ . In worst case,  $|C_1| + |C_2| = \Theta(n)$ , and therefore  $T(n) = 2T(n/2) + \Theta(n)$ , which gives  $T(n) = \Theta(n \log n)$ . In this (worst) case the running time of this divide-and-conquer algorithm is the same with Graham-Scan. However,

if the size of  $|C_1| + |C_2|$  is in the order of  $o(n)$ , we will have improved running time. For example, if  $|C_1| + |C_2| = \Theta(n^{0.99})$ , then  $T(n) = \Theta(n)$ . This might happen in practical cases, although in worst case divide-and-conquer runs in  $\Theta(n \log n)$  time.