CMPSC 465 Data Structures and Algorithms Spring 2022

Instructor: Chunhao Wang

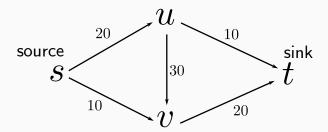
Flow network (Textbook, Section 7.2 Kleinberg & Tardos Section 7.1)

Motivation

We use graphs to model "transportation networks" i.e., networks whose edges allow some sort of traffic, and vertices act as switches

In this setting, edges have **capacities**, and we assume there is a **source vertex** generating traffic, a **sink vertex**, which absorbs traffic.

Example:



Flow network

Definition

A flow network is a directed graph G = (V, E) s.t.

- 1. there is a capacity $c_e \ge 0$ for all $e \in E$
- 2. there is a single source $s \in V$
- 3. there is a single sink $t \in V$

s-t flow

Definition

An **s-t flow** is a function $f: E \to \mathbb{R}^{\geq 0}$ satisfying

- Capacity constraint: $\forall e \in E$, $0 \le f(e) \le c_e$
- Conservation condition: $\forall v \in V \{s, t\}$

$$\sum_{e \text{ into } v} f(e) = \sum_{e \text{ out of } v} f(e)$$

Intuition: f(e) is the amount of flow/traffic carried out by e

Definition

The **value** of a flow f is

$$v(f) = \sum_{e \text{ out of } s} f(e)$$

Intuition: v(f) shows how much traffic can be accommodated

Chunhao Wang

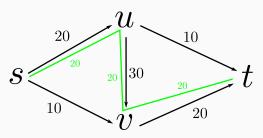
The max-flow problem

Problem (The Max-Flow problem)

Given a flow network, find a flow of the maximum possible value

Natural idea: Find an s-t path and push a flow of value $\min\{c_e: e \text{ along the path}\}$. Then keep doing this

Example:



$$f(s, u) = 20$$

$$f(u, v) = 20$$

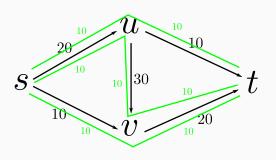
$$f(v, t) = 20$$

$$f(s, v) = 0$$

$$f(u, t) = 0$$

v(f) = 20. Can we do better?

A better flow



$$f(s, u) = 20$$

$$f(u, v) = 10$$

$$f(v, t) = 20$$

$$f(s, v) = 10$$

$$f(u, t) = 10$$

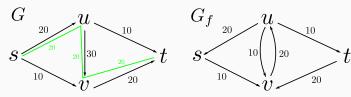
$$v(f) = 30.$$

Residual graph

We use a residual graph to keep track of the "leftover" capacity Given a flow network G, flow f, construct the **residual graph** G_f as follows

- the vertex set of G_f is the same as G
- for each edge e of G with $f(e) < c_e$ (leftover), include e in G_f with capacity $c_e f(e)$ (forward edge)
- for each edge e = (u, v) in G with f(e) > 0 (how much we can undo), include e' = (v, u) in G_f with capacity f(e) (backward edge)

Capacity of an edge in the residual graph is called **residual capacity**



Better idea

We introduce **augmenting paths**

Let P be an s-t path in G_f , we can improve our flow by augmenting along P as follows

Define bottleneck(P, f) as the minimum residual capacity of edges of P def Augment(f, P):

return f;

Any s-t path in G_f is called an **augmenting path**

The Ford-Fulkerson algorithm

```
def FORD-FULKERSON(G, capacities c):

Set f(e) = 0 for all e \in G;

while \exists s-t path in the residual graph G_f:

Let P be a simple s-t path in G_f;

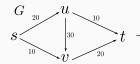
f' = \text{Augment}(f, P);

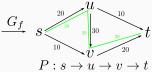
G_f = G_{f'};

f = f';

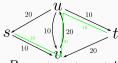
return f;
```

Running example



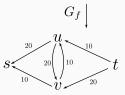






$$P: s \to v \to u \to t$$

| e | $f_1(e)$ | $f_2(e)$ | $f_3(e)$ |
|-----------|----------|----------|----------|
| $s \to u$ | 0 | 20 | 20 |
| $s \to v$ | 0 | 0 | 10 |
| $u \to v$ | 0 | 20 | 10 |
| $u \to t$ | 0 | 0 | 10 |
| v 	o t | 0 | 20 | 20 |



b : 10

No more s-t path