# CMPSC 465 Data Structures and Algorithms Spring 2022

Instructor: Chunhao Wang

# (Textbook, Section 7.1)

**Linear Programming** 

### **Advertisement**

Please consider taking

CMPSC 497 — Quantum Computation in Fall 2022

if you are interested in learning Quantum Computing

Optimization: we want to maximize some function  $f(\mathbf{k})$  for  $\mathbf{x} \in \mathbb{R}^n$ , subject to constraints

$$(\mathbf{x}) \leq (\mathbf{b})$$
 for  $\mathbf{b} \in \mathbb{R}^n$ 

$$C(x), \leq h$$

$$((x))_2 \leq b_2$$

Optimization: we want to maximize some function  $f(\mathbf{x})$  for  $\mathbf{x} \in \mathbb{R}^n$ , subject to constraints

$$C(\mathbf{x}) \leq \mathbf{b}$$
, for  $\mathbf{b} \in \mathbb{R}^n$ 

• If no structures of f or C are known: general purpose constraint optimization

Optimization: we want to maximize some function  $f(\mathbf{x})$  for  $\mathbf{x} \in \mathbb{R}^n$ , subject to constraints

$$C(\mathbf{x}) \leq \mathbf{b}$$
, for  $\mathbf{b} \in \mathbb{R}^n$ 

- If no structures of f or C are known: general purpose constraint optimization
- Given some restrictions on f or C, e.g., f is convex and C is a convex region: convex optimization

Mar 3, 2022

Optimization: we want to maximize some function  $f(\mathbf{x})$  for  $\mathbf{x} \in \mathbb{R}^n$ , subject to constraints

$$C(\mathbf{x}) \leq \mathbf{b}$$
, for  $\mathbf{b} \in \mathbb{R}^n$ 

- If no structures of f or C are known: general purpose constraint optimization
- Given some restrictions on f or C, e.g., f is convex and C is a convex region: convex optimization
- Lot of stuff in between: quadratic programming, 2nd-order cone programming (SOCP), semidefinite programming (SDP)

Optimization: we want to maximize some function  $f(\mathbf{x})$  for  $\mathbf{x} \in \mathbb{R}^n$ , subject to constraints

$$C(\mathbf{x}) \leq \mathbf{b}$$
, for  $\mathbf{b} \in \mathbb{R}^n$ 

- If no structures of f or C are known: general purpose constraint optimization
- Given some restrictions on f or C, e.g., f is convex and C is a convex region: convex optimization
- Lot of stuff in between: quadratic programming, 2nd-order cone programming (SOCP), semidefinite programming (SDP)
- Simplest non-trivial (but still powerful) case: f and C are linear functions, e.g.,  $f(\mathbf{x}) = a_1x_1 + a_2x_2 + \cdots + a_nx_n$

Optimization: we want to maximize some function  $f(\mathbf{x})$  for  $\mathbf{x} \in \mathbb{R}^n$ , subject to constraints

$$C(\mathbf{x}) \leq \mathbf{b}$$
, for  $\mathbf{b} \in \mathbb{R}^n$ 

- If no structures of f or C are known: general purpose constraint optimization
- Given some restrictions on f or C, e.g., f is convex and C is a convex region: convex optimization
- Lot of stuff in between: quadratic programming, 2nd-order cone programming (SOCP), semidefinite programming (SDP)
- Simplest non-trivial (but still powerful) case: f and C are linear functions, e.g.,  $f(\mathbf{x}) = a_1x_1 + a_2x_2 + \cdots + a_nx_n$ 
  - Linear Programming

Mar 3, 2022

Resource allocation: 168 hours in a week

Resource allocation: 168 hours in a week

Resource allocation: 168 hours in a week

S: study time; P: fun/party time; E: everything else

• to survive:  $E \ge 56$ 

Mar 3, 2022

Resource allocation: 168 hours in a week

S: study time; P: fun/party time; E: everything else

• to survive:  $E \ge 56$ 

• to to pass classes:  $S \ge 60$ 

Mar 3, 2022

Resource allocation: 168 hours in a week

- to survive:  $E \ge 56$
- to to pass classes:  $S \ge 60$
- to stay sane:  $P + E \ge 70$

Resource allocation: 168 hours in a week

- to survive:  $E \ge 56$
- to to pass classes:  $S \ge 60$
- to stay sane:  $P + E \ge 70$
- $2S + E 3P \ge 150$ : need more study time if had too much fun or not enough sleep

Resource allocation: 168 hours in a week

- to survive:  $E \ge 56$
- to to pass classes:  $S \ge 60$
- to stay sane:  $P + E \ge 70$
- $2S + E 3P \ge 150$ : need more study time if had too much fun or not enough sleep
- happiness: 2P + E objective function

Resource allocation: 168 hours in a week

- to survive:  $E \ge 56$
- to to pass classes:  $S \ge 60$
- to stay sane:  $P + E \ge 70$
- $2S + E 3P \ge 150$ : need more study time if had too much fun or not enough sleep
- happiness: 2P + E objective function

i.e., 
$$f(S, P, E) = 2P + E$$

Resource allocation: 168 hours in a week

S: study time; P: fun/party time; E: everything else

- to survive:  $E \ge 56$
- to to pass classes:  $S \ge 60$
- to stay sane:  $P + E \ge 70$
- $2S + E 3P \ge 150$ : need more study time if had too much fun or not enough sleep
- happiness: 2P + E objective function

i.e., 
$$f(S, P, E) = 2P + E$$

How to allocate your time?

Maximize happiness: LP formulation:

Maximize happiness: LP formulation:

maximize 2P + E

Maximize happiness: LP formulation:

maximize 2P + E

subject to

Maximize happiness: LP formulation:

$$\begin{array}{ll} \text{maximize} & 2P + E \\ \text{subject to} & E \geq 56 \end{array}$$

Mar 3, 2022

### Maximize happiness: LP formulation:

maximize 
$$2P + E$$
 subject to  $E \geq 56$   $S \geq 60$ 

### Maximize happiness: LP formulation:

maximize 
$$2P+E$$
 subject to  $E \geq 56$   $S \geq 60$   $2S+E-3P \geq 150$ 

### Maximize happiness: LP formulation:

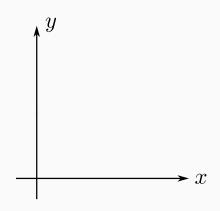
maximize 
$$2P+E$$
 subject to  $E \geq 56$   $S \geq 60$   $2S+E-3P \geq 150$   $S,P,E \geq 0$ 

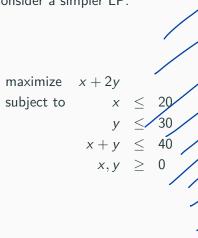
Mar 3, 2022

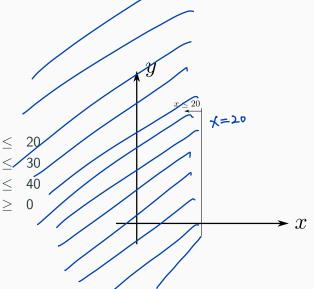
### Maximize happiness: LP formulation:

maximize 
$$2P + E$$
 subject to  $E \geq 56$   $S \geq 60$   $2S + E - 3P \geq 150$   $S, P, E \geq 0$   $S + P + E$  10 168

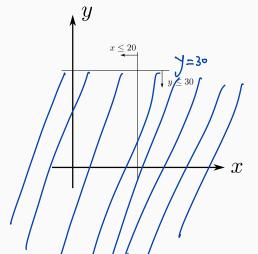
$$\begin{array}{llll} \text{maximize} & x+2y \\ \text{subject to} & x & \leq & 20 \\ & y & \leq & 30 \\ & x+y & \leq & 40 \\ & x,y & \geq & 0 \end{array}$$



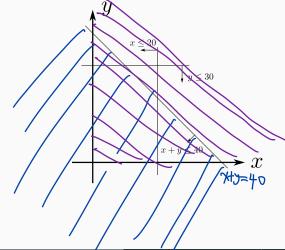




maximize 
$$x + 2y$$
  
subject to  $x \le 20$   
 $y \le 30$   
 $x + y \le 40$   
 $x, y \ge 0$ 

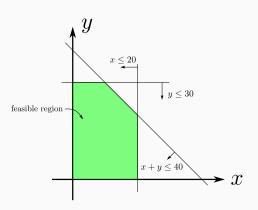


maximize 
$$x + 2y$$
  
subject to  $x \le 20$   
 $y \le 30$   
 $x + y \le 40$   
 $x, y \ge 0$ 



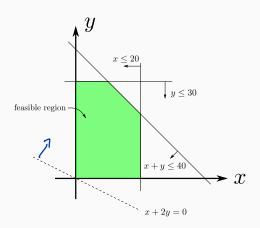
# Consider a simpler LP:

maximize 
$$x + 2y$$
  
subject to  $x \le 20$   
 $y \le 30$   
 $x + y \le 40$   
 $x, y \ge 0$ 

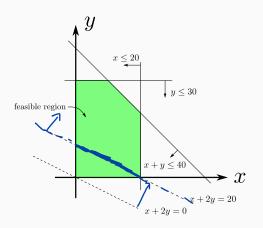


6/19

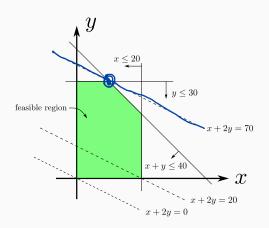
$$\begin{array}{lllll} \text{maximize} & x+2y \\ \text{subject to} & x & \leq & 20 \\ & y & \leq & 30 \\ & x+y & \leq & 40 \\ & x,y & \geq & 0 \end{array}$$



$$\begin{array}{llll} \text{maximize} & x+2y \\ \text{subject to} & x & \leq & 20 \\ & y & \leq & 30 \\ & x+y & \leq & 40 \\ & x,y & \geq & 0 \end{array}$$

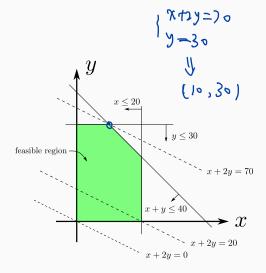


$$\begin{array}{llll} \text{maximize} & x+2y \\ \text{subject to} & x & \leq & 20 \\ & y & \leq & 30 \\ & x+y & \leq & 40 \\ & x,y & \geq & 0 \end{array}$$



# Consider a simpler LP:

$$\begin{array}{llll} \text{maximize} & x+2y \\ \text{subject to} & x & \leq & 20 \\ & y & \leq & 30 \\ & x+y & \leq & 40 \\ & x,y & \geq & 0 \end{array}$$



Optimal solution: x + 2y = 70

at x=10, y=30

**Observation:** (search for an optimal solution)

**Observation:** (search for an optimal solution)

Objective function is linear, and feasible region is convex.

**Observation:** (search for an optimal solution)

Objective function is linear, and feasible region is convex. So a unique direction of maximal increase of objective function exists.

**Observation:** (search for an optimal solution)

Objective function is linear, and feasible region is convex. So a unique direction of maximal increase of objective function exists. Follow it and you will run into the boundary.

**Observation:** (search for an optimal solution)

Objective function is linear, and feasible region is convex. So a unique direction of maximal increase of objective function exists. Follow it and you will run into the boundary. At the boundary, moving in any direction will

**Observation:** (search for an optimal solution)

Objective function is linear, and feasible region is convex. So a unique direction of maximal increase of objective function exists. Follow it and you will run into the boundary. At the boundary, moving in any direction will

(a) Decrease objective function  $\rightarrow$  don't go this way

**Observation:** (search for an optimal solution)

Objective function is linear, and feasible region is convex. So a unique direction of maximal increase of objective function exists. Follow it and you will run into the boundary. At the boundary, moving in any direction will

- (a) Decrease objective function  $\rightarrow$  don't go this way
- (b) Increase objective function  $\rightarrow$  follow to a vertex

Mar 3, 2022

**Observation:** (search for an optimal solution)

Objective function is linear, and feasible region is convex. So a unique direction of maximal increase of objective function exists. Follow it and you will run into the boundary. At the boundary, moving in any direction will

- (a) Decrease objective function  $\rightarrow$  don't go this way
- (b) Increase objective function  $\rightarrow$  follow to a vertex
- (c) Objective function stays constant  $\rightarrow$  follow to a vertex

**Observation:** (search for an optimal solution)

Objective function is linear, and feasible region is convex. So a unique direction of maximal increase of objective function exists. Follow it and you will run into the boundary. At the boundary, moving in any direction will

- (a) Decrease objective function  $\rightarrow$  don't go this way
- (b) Increase objective function  $\rightarrow$  follow to a vertex
- (c) Objective function stays constant  $\rightarrow$  follow to a vertex

#### **Theorem**

For an LP with bounded, nonempty feasible region, the maximum value will be attained at some vertex of the feasible region

The hill climbing approach (the simplex method)

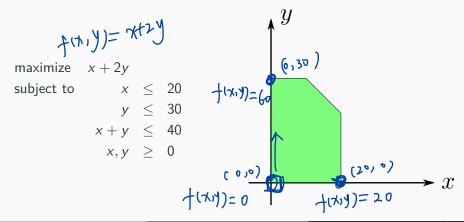
The hill climbing approach (the simplex method)

Start at a vertex, look at adjacent vertices, move in the direction of largest increase to the objective function

maximize 
$$x + 2y$$
  
subject to  $x \le 20$   
 $y \le 30$   
 $x + y \le 40$   
 $x, y \ge 0$ 

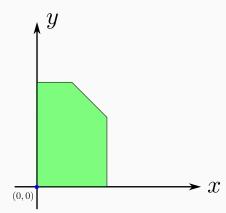
Mar 3, 2022

The hill climbing approach (the simplex method)

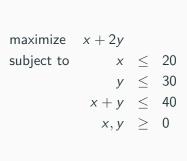


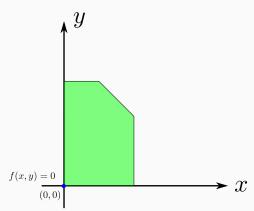
The hill climbing approach (the simplex method)

maximize 
$$x + 2y$$
  
subject to  $x \le 20$   
 $y \le 30$   
 $x + y \le 40$   
 $x, y \ge 0$ 

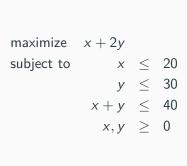


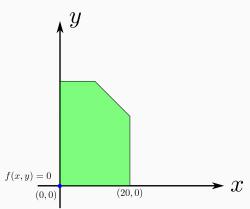
The hill climbing approach (the simplex method)



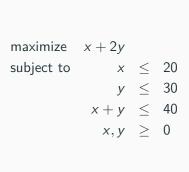


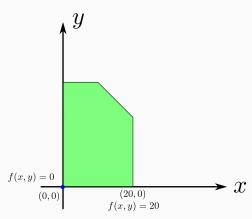
The hill climbing approach (the simplex method)



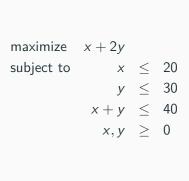


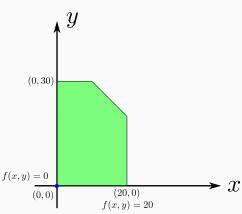
The hill climbing approach (the simplex method)





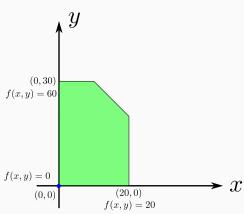
The hill climbing approach (the simplex method)





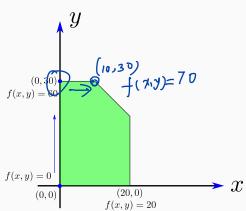
The hill climbing approach (the simplex method)

Start at a vertex, look at adjacent vertices, move in the direction of largest increase to the objective function



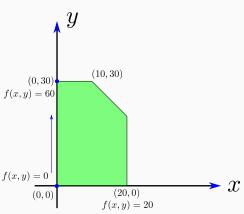
The hill climbing approach (the simplex method)

Start at a vertex, look at adjacent vertices, move in the direction of largest increase to the objective function

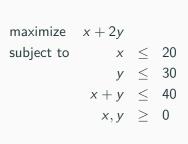


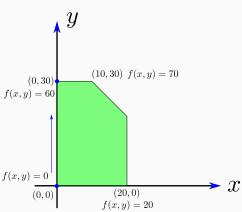
The hill climbing approach (the simplex method)

Start at a vertex, look at adjacent vertices, move in the direction of largest increase to the objective function



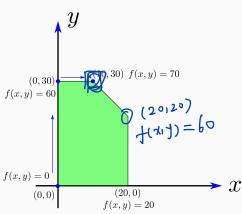
The hill climbing approach (the simplex method)





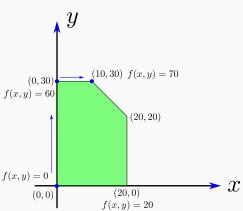
The hill climbing approach (the simplex method)

Start at a vertex, look at adjacent vertices, move in the direction of largest increase to the objective function



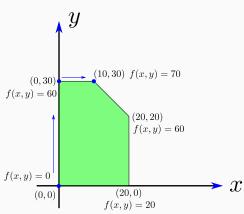
The hill climbing approach (the simplex method)

Start at a vertex, look at adjacent vertices, move in the direction of largest increase to the objective function



The hill climbing approach (the simplex method)

Start at a vertex, look at adjacent vertices, move in the direction of largest increase to the objective function

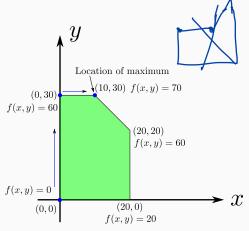


The hill climbing approach (the simplex method)

Start at a vertex, look at adjacent vertices, move in the direction of largest

increase to the objective function

maximize 
$$x + 2y$$
  
subject to  $x \le 20$   
 $y \le 30$   
 $x + y \le 40$   
 $x, y \ge 0$ 

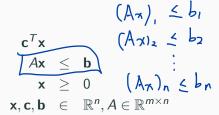


LP solvers, such as MOSEK, Gurobi, CVX, and COIN are implementations of the simplex method. They require the LP to be in certain standard form

LP solvers, such as MOSEK, Gurobi, CVX, and COIN are implementations of the simplex method. They require the LP to be in certain standard form

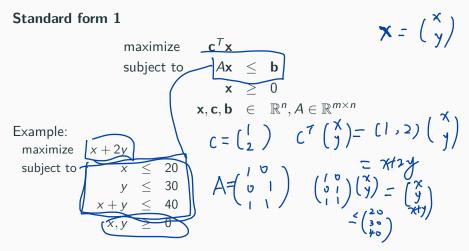
#### Standard form 1

maximize subject to



Mar 3, 2022

LP solvers, such as MOSEK, Gurobi, CVX, and COIN are implementations of the simplex method. They require the LP to be in certain standard form



LP solvers, such as MOSEK, Gurobi, CVX, and COIN are implementations of the simplex method. They require the LP to be in certain standard form

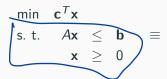
#### Standard form 1

maximize 
$$\mathbf{c}^T \mathbf{x}$$
  
subject to  $A\mathbf{x} \leq \mathbf{b}$   
 $\mathbf{x} \geq 0$   
 $\mathbf{x}, \mathbf{c}, \mathbf{b} \in \mathbb{R}^n, A \in \mathbb{R}^{m \times n}$ 

#### Example:

maximize 
$$x + 2y$$
 maximize  $(1,2) \begin{pmatrix} x \\ y \end{pmatrix}$  subject to  $x \le 20$   $y \le 30 = x + y \le 40$  subject to  $\begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} \le \begin{pmatrix} 20 \\ 30 \\ 40 \end{pmatrix}$   $x, y \ge 0$ 

Minimization to maximization



max

Minimization to maximization

Minimization to maximization

Equality to inequality

$$\begin{array}{cccc}
\text{max} & \mathbf{c}^T \mathbf{x} \\
\text{s. t.} & x_1 + x_2 & = & 7
\end{array}$$

Minimization to maximization

Equality to inequality

Minimization to maximization

Equality to inequality

Wrong inequality direction

$$\max_{\mathbf{s}. \mathbf{t}. \ x_1 + x_2 \ge 7} \mathbf{c}^T \mathbf{x} \equiv$$

Minimization to maximization

Equality to inequality

Wrong inequality direction

Missing nonnegative constraints

max 
$$x_1 + 2x_2$$
  
s. t.  $x_1 \leq 20$   
 $x_1 + x_2 \leq 40$   
 $x_1 \geq 0$ 

missing  $x_2 \geq 0$ 

Missing nonnegative constraints

rewrite 
$$x_2 = x_2^+ - x_2^-$$
  
max  $x_1 + 2(x_2^+ - x_2^-)$   
s. t.  $x_1 \le 20$   
 $x_1 + (x_2^+ - x_2^-) \le 40$   
 $x_1 \ge 0$   
 $x_2^+ \ge 0$   
 $x_2^- > 0$ 

#### Standard form 2

$$\begin{array}{llll} \text{maximize} & \mathbf{c}^T\mathbf{x} \\ \text{subject to} & A\mathbf{x} & = & \mathbf{b} \\ & \mathbf{x} & \geq & \mathbf{0} \\ & \mathbf{x}, \mathbf{c}, \mathbf{b} & \in & \mathbb{R}^n, A \in \mathbb{R}^{m \times n} \end{array}$$

#### Standard form 2

maximize 
$$\mathbf{c}^T \mathbf{x}$$
 subject to  $A\mathbf{x} = \mathbf{b}$   $\mathbf{x} \geq 0$   $\mathbf{x}, \mathbf{c}, \mathbf{b} \in \mathbb{R}^n, A \in \mathbb{R}^{m \times n}$ 

Inequality to equality: use slack variables

maximize 
$$\mathbf{c}^T \mathbf{x}$$
 subject to  $x_1 \le 20$   $x_1 \ge 0$ 

#### Standard form 2

maximize 
$$\mathbf{c}^T \mathbf{x}$$
 subject to  $A\mathbf{x} = \mathbf{b}$   $\mathbf{x} \geq 0$   $\mathbf{x}, \mathbf{c}, \mathbf{b} \in \mathbb{R}^n, A \in \mathbb{R}^{m \times n}$ 

Inequality to equality: use slack variables

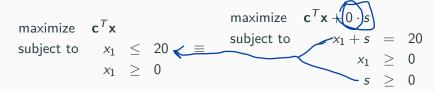
maximize 
$$\mathbf{c}^T \mathbf{x}$$
 subject to  $x_1 \le 20$   $x_1 \ge 0$ 

20 is bigger than  $x_1$  by some positive amount, call it s

#### Standard form 2

maximize 
$$\mathbf{c}^T \mathbf{x}$$
  
subject to  $A\mathbf{x} = \mathbf{b}$   
 $\mathbf{x} \geq 0$   
 $\mathbf{x}, \mathbf{c}, \mathbf{b} \in \mathbb{R}^n, A \in \mathbb{R}^{m \times n}$ 

Inequality to equality: use slack variables



20 is bigger than  $x_1$  by some positive amount, call it s

#### Standard form 2

maximize 
$$\mathbf{c}^T \mathbf{x}$$
 subject to  $A\mathbf{x} = \mathbf{b}$   $\mathbf{x} \geq 0$   $\mathbf{x}, \mathbf{c}, \mathbf{b} \in \mathbb{R}^n, A \in \mathbb{R}^{m \times n}$ 

Inequality to equality: use slack variables

maximize 
$$\mathbf{c}^T \mathbf{x}$$
 subject to  $x_1 \leq 20 = x_1 \geq 0$  maximize  $\mathbf{c}^T \mathbf{x} + 0 \cdot \mathbf{s}$  subject to  $x_1 + \mathbf{s} = 20 = x_1 \geq 0$ 

20 is bigger than  $x_1$  by some positive amount, call it s. The new variable s is call the slack variable

We are given  $G = (V, E), w : E \to \mathbb{R}$ 

We are given  $G=(V,E), w:E \to \mathbb{R}$ Want to compute  $\operatorname{shortest\_path}(s,t)$  for given  $s,t\in V$ 

We are given  $G = (V, E), w : E \to \mathbb{R}$ Want to compute shortest\_path(s, t) for given  $s, t \in V$ Can we model this as an LP?

We are given  $G = (V, E), w : E \to \mathbb{R}$ 

Want to compute  $\operatorname{shortest\_path}(s,t)$  for given  $s,t\in V$ 

Can we model this as an LP?

Recall Bellman-Ford: we calculate  $d_v$  for all  $v \in V$ , s.t.  $d_v \leq d_u + w(u,v)$ 

We are given  $G = (V, E), w : E \to \mathbb{R}$ 

Want to compute  $\operatorname{shortest\_path}(s,t)$  for given  $s,t\in V$ 

Can we model this as an LP?

Recall Bellman-Ford: we calculate  $d_v$  for all  $v \in V$ , s.t.  $d_v \leq d_u + w(u,v)$ 

So we had the greatest lower bound:  $d_v = \min_{u \text{ s.t. } (u,v) \in E} \{d_u + w(u,v)\}$ 

We are given  $G = (V, E), w : E \to \mathbb{R}$ Want to compute  $\operatorname{shortest\_path}(s, t)$  for given  $s, t \in V$ Can we model this as an LP?

Recall Bellman-Ford: we calculate  $d_v$  for all  $v \in V$ , s.t.  $d_v \le d_u + w(u, v)$ So we had the greatest lower bound:  $d_v = \min_{u \text{ s.t. } (u,v) \in E} \{d_u + w(u,v)\}$ i.e.,  $d_v$  is the largest value s.t.  $d_v \le d_u + w(u,v)$  for all  $(u,v) \in E$ 

We are given  $G = (V, E), w : E \to \mathbb{R}$ 

Want to compute  $\operatorname{shortest\_path}(s,t)$  for given  $s,t\in V$ 

Can we model this as an LP?

Recall Bellman-Ford: we calculate  $d_v$  for all  $v \in V$ , s.t.  $d_v \leq d_u + w(u,v)$ 

So we had the greatest lower bound:  $d_v = \min_{u \text{ s.t. } (u,v) \in E} \{d_u + w(u,v)\}$ 

i.e.,  $d_v$  is the largest value s.t.  $d_v \leq d_u + w(u,v)$  for all  $(u,v) \in E$ 

So we have

We are given  $G = (V, E), w : E \to \mathbb{R}$ 

Want to compute  $\operatorname{shortest\_path}(s,t)$  for given  $s,t\in V$ 

Can we model this as an LP?

Recall Bellman-Ford: we calculate  $d_v$  for all  $v \in V$ , s.t.  $d_v \le d_u + w(u, v)$ So we had the greatest lower bound:  $d_v = \min_{u \text{ s.t. } (u,v) \in E} \{d_u + w(u,v)\}$ i.e.,  $d_v$  is the largest value s.t.  $d_v \le d_u + w(u,v)$  for all  $(u,v) \in E$ 

So we have

minimize 
$$d_t$$
 subject to  $d_v \leq d_u + w(u,v) \quad \forall (u,v) \in E$   $d_s = 0$ 

We are given  $G = (V, E), w : E \to \mathbb{R}$ 

Want to compute  $\operatorname{shortest\_path}(s,t)$  for given  $s,t\in V$ 

Can we model this as an LP?

Recall Bellman-Ford: we calculate  $d_v$  for all  $v \in V$ , s.t.  $d_v \le d_u + w(u, v)$ So we had the greatest lower bound:  $d_v = \min_{u \text{ s.t. } (u,v) \in E} \{d_u + w(u,v)\}$ i.e.,  $d_v$  is the largest value s.t.  $d_v \le d_u + w(u,v)$  for all  $(u,v) \in E$ 

So we have

minimize 
$$d_t$$
 subject to  $d_v \leq d_u + w(u,v) \quad \forall (u,v) \in E$   $d_s = 0$ 

There are |V| variables, |E| constraints

We are given  $G = (V, E), w : E \to \mathbb{R}$ 

Want to compute  $\operatorname{shortest\_path}(s,t)$  for given  $s,t\in V$ 

Can we model this as an LP?

Recall Bellman-Ford: we calculate  $d_v$  for all  $v \in V$ , s.t.  $d_v \le d_u + w(u, v)$ So we had the greatest lower bound:  $d_v = \min_{u \text{ s.t. } (u,v) \in E} \{d_u + w(u,v)\}$ i.e.,  $d_v$  is the largest value s.t.  $d_v \le d_u + w(u,v)$  for all  $(u,v) \in E$ 

So we have

minimize 
$$d_t$$
 subject to  $d_v \leq d_u + w(u,v) \quad \forall (u,v) \in E$   $d_s = 0$ 

There are |V| variables, |E| constraints

We just reduced shortest\_path to LP

We are given G = (V, E),  $s, t \in V$ , capacity  $c_e$  for all  $e \in E$  Find a flow  $f : E \to \mathbb{R}^{\geq 0}$  s.t.

We are given G = (V, E),  $s, t \in V$ , capacity  $c_e$  for all  $e \in E$  Find a flow  $f : E \to \mathbb{R}^{\geq 0}$  s.t.

•  $0 \le f(e) \le c_e$ 

We are given G = (V, E),  $s, t \in V$ , capacity  $c_e$  for all  $e \in E$  Find a flow  $f : E \to \mathbb{R}^{\geq 0}$  s.t.

- $0 \le f(e) \le c_e$

We are given G = (V, E),  $s, t \in V$ , capacity  $c_e$  for all  $e \in E$  Find a flow  $f : E \to \mathbb{R}^{\geq 0}$  s.t.

- $0 \le f(e) \le c_e$

LP formulation

We are given G = (V, E),  $s, t \in V$ , capacity  $c_e$  for all  $e \in E$  Find a flow  $f: E \to \mathbb{R}^{\geq 0}$  s.t.

• 
$$0 \le f(e) \le c_e$$

$$0 \le f(e) \le c_e$$

$$F = \frac{1}{2} \cdot E \rightarrow \mathbb{R}^{\geq 0} \text{ s.t.}$$

$$0 \leq f(e) \leq c_e \qquad \text{f.s.}$$

$$\sum_{(u,v)\in E} f(u,v) = \sum_{(v,w)\in E} f(v,w) \qquad \text{f.s.} \qquad \text{f.s.}$$

$$F = \text{formulation}$$

LP formulation

We are given G = (V, E),  $s, t \in V$ , capacity  $c_e$  for all  $e \in E$  Find a flow  $f : E \to \mathbb{R}^{\geq 0}$  s.t.

- $0 \le f(e) \le c_e$

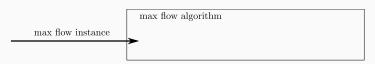
#### LP formulation

We just **reduced** max\_flow to LP

We are given G = (V, E),  $s, t \in V$ , capacity  $c_e$  for all  $e \in E$  Find a flow  $f : E \to \mathbb{R}^{\geq 0}$  s.t.

- $0 \le f(e) \le c_e$

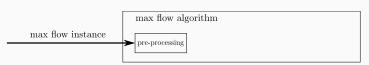
#### LP formulation



We are given G = (V, E),  $s, t \in V$ , capacity  $c_e$  for all  $e \in E$  Find a flow  $f : E \to \mathbb{R}^{\geq 0}$  s.t.

- $0 \le f(e) \le c_e$

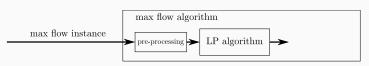
#### LP formulation



We are given G = (V, E),  $s, t \in V$ , capacity  $c_e$  for all  $e \in E$  Find a flow  $f : E \to \mathbb{R}^{\geq 0}$  s.t.

- $0 \le f(e) \le c_e$

#### LP formulation



We are given G = (V, E),  $s, t \in V$ , capacity  $c_e$  for all  $e \in E$  Find a flow  $f : E \to \mathbb{R}^{\geq 0}$  s.t.

- $0 \le f(e) \le c_e$

#### LP formulation

