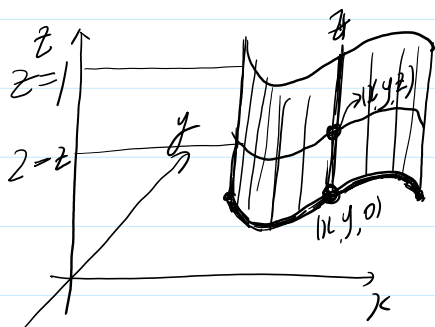
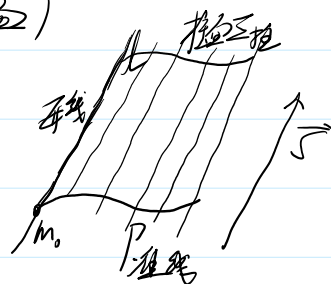
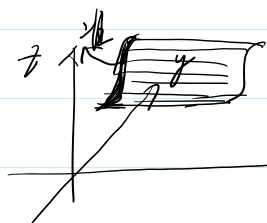


空间曲面 (柱面 锥面 旋转曲面 二次曲面)

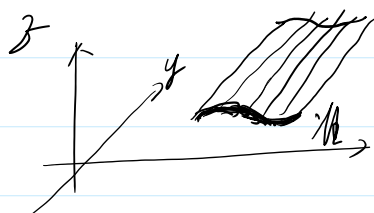
1) 柱面 ($\Sigma \parallel$ 轴, P 坐标面上曲线)



$\begin{cases} F(x, y) = 0 \\ z = 0 \end{cases}$ 曲线 (在 xy 面上) 再沿 z 轴 的柱面 $F(x, y) = 0$

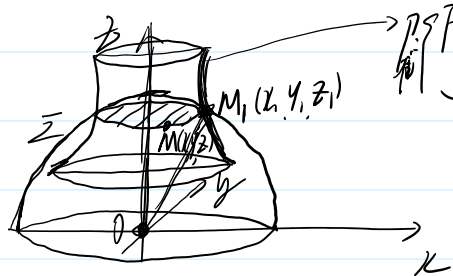


$\begin{cases} H(y, z) = 0 \\ x = 0 \end{cases}$ 曲线 (在 yz 面上) 再沿 x 轴 的柱面 $H(y, z) = 0$

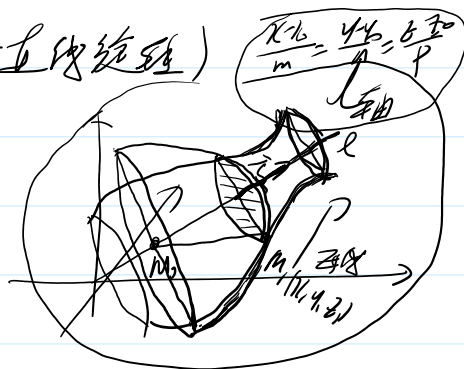


$\begin{cases} G(x, z) = 0 \\ y = 0 \end{cases}$ 曲线 (在 xz 面上) 再沿 y 轴 的柱面 $G(x, z) = 0$

旋转曲面 (空间曲线 绕任意一条直线旋转)



$\begin{cases} F(x, z) = 0 \\ y = 0 \end{cases}$ 为 xz 面上曲线
以 P 为曲线绕 z 轴旋转一周
的旋转曲面



$M(x, y, z) \in \Sigma$ 过程, 过 M 点作 z 轴垂平面 $z = z_1$, 此平面交旋转面 Σ 为一个纬圆, 交于曲线 P 上的 $m_1(x_1, y_1, z_1)$

$$\begin{cases} \text{纬圆} \\ \begin{cases} z = z_1 \\ (x - x_0)^2 + (y - y_0)^2 + (z - z_0)^2 = (x_1 - x_0)^2 + (y_1 - y_0)^2 + (z_1 - z_0)^2 \end{cases} \end{cases}$$

①

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$$\left\{ \begin{array}{l} \text{球面} \\ \text{平面} \end{array} \right\} \begin{cases} z = z_1 \\ (x-0)^2 + (y-0)^2 + (z-0)^2 = (x_1-0)^2 + (y_1-0)^2 + (z_1-0)^2 \\ F(x, z) = 0 \\ y_1 = 0 \end{cases}$$

(2) 消去参数 x_1
(3) 参数 (x, y, z_1)
(4)

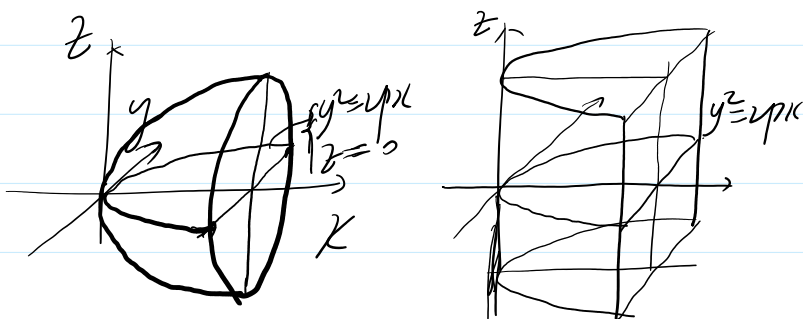
$$\left\{ \begin{array}{l} z = z_1 \\ x^2 + y^2 + z^2 = x_1^2 + y_1^2 + z_1^2 \\ y_1 = 0 \\ F(x, z) = 0 \end{array} \right. \Rightarrow \left\{ \begin{array}{l} z_1 = z \\ x_1 = \pm \sqrt{x^2 + y^2} \\ F(x, z) = 0 \end{array} \right. \Rightarrow F(\pm \sqrt{x^2 + y^2}, z) = 0$$

即 $\left\{ \begin{array}{l} \text{柱面曲线 } F(x, z) = 0 \text{ 绕 } z \text{ 轴旋转一周生成的柱面 } F(\pm \sqrt{x^2 + y^2}, z) = 0 \\ \text{柱面上曲线 } F(x, z) = 0 \text{ 绕 } x \text{ 轴} \text{-----} F(x, \pm \sqrt{x^2 + y^2}) = 0 \end{array} \right.$

$\left\{ \begin{array}{l} \text{柱面曲线 } H(y, z) = 0, \text{ 绕 } z \text{ 轴} \text{-----} H(\pm \sqrt{x^2 + y^2}, z) = 0 \\ \text{-----} y \text{-----} H(y, \pm \sqrt{x^2 + y^2}) = 0 \end{array} \right.$

$\left\{ \begin{array}{l} \text{柱面上曲线 } G(x, y) = 0 \text{-----绕 } x \text{-----} G(x, \pm \sqrt{x^2 + y^2}) = 0 \\ \text{-----绕 } y \text{-----} G(\pm \sqrt{x^2 + y^2}, y) = 0 \end{array} \right.$

1) $y^2 = 4\rho x$ 在 xy 面上抛物线. 绕 x 轴旋转一周生成的曲面

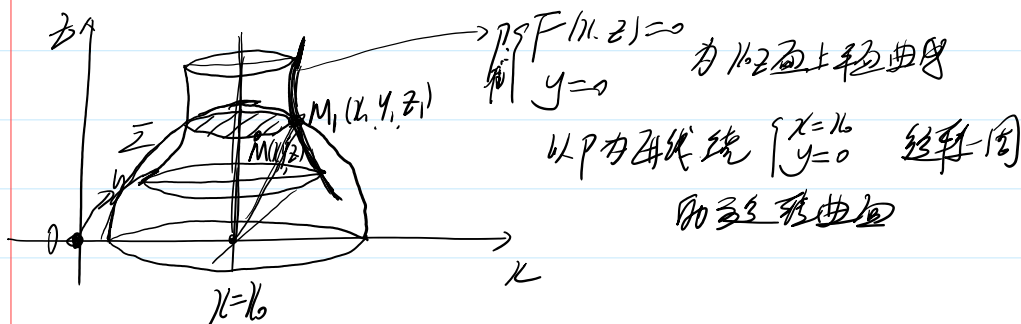


$$(\pm \sqrt{y^2 + z^2})^2 = 4\rho x$$

$$y^2 + z^2 = 4\rho x \text{ 即为所求}$$

$z=0$ 为 xy 面的平面方程

2) $\text{-----} \rightarrow \text{若 } F(x, z) = 0 \text{ 为柱面上曲线}$



①

② 消去参数 M

③ 消去参数 (x, y, z)

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$$\begin{cases} (x-x_1)^2 + y^2 + z^2 = (x_1-x_1)^2 + y_1^2 + z_1^2 \\ y_1 = 0 \\ z = z_1 \\ F(x_1, z_1) = 0 \end{cases}$$

$$(x-x_1)^2 + y^2 = (x_1-x_1)^2 \Rightarrow x = x_1 \pm \sqrt{(x-x_1)^2 + y^2}$$

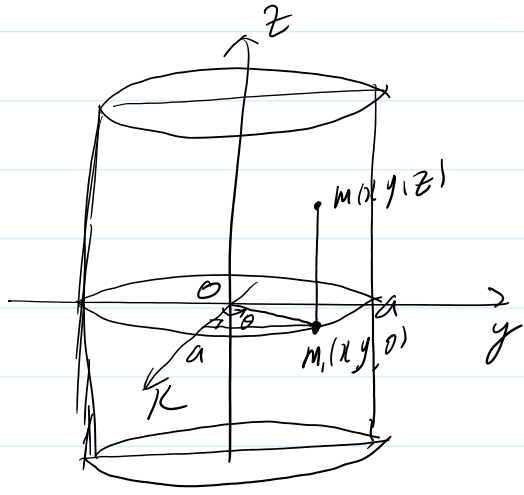
$$z_1 = z_1$$

$$F(x_1, z_1) = 0 \Rightarrow F(x_1 \pm \sqrt{(x-x_1)^2 + y^2}, z_1) = 0$$

由白参数方程

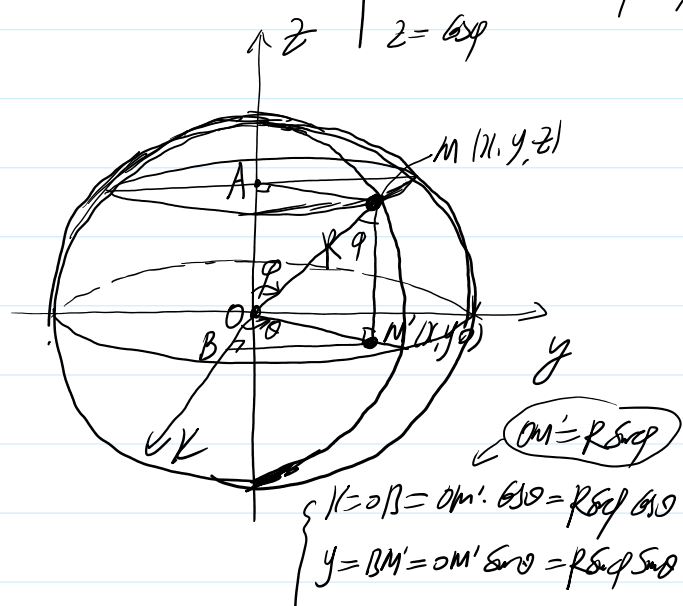
① 圆柱面 $x^2 + y^2 = a^2$

$$\begin{cases} x = a \cos \theta \\ y = a \sin \theta \\ z = z \end{cases} \quad \begin{matrix} 0 \leq \theta < 2\pi \\ z \in \mathbb{R} \end{matrix}$$



② 球面 $x^2 + y^2 + z^2 = R^2$

$$\begin{cases} x = R \sin \varphi \cos \theta \\ y = R \sin \varphi \sin \theta \\ z = R \cos \varphi \end{cases} \quad \begin{matrix} 0 \leq \varphi \leq \pi \\ 0 \leq \theta < 2\pi \end{matrix}$$





$$\begin{cases} y = BM = OM' \sin \theta = R \sin \theta \sin \theta \\ z = OA = OM \cos \theta = R \cos \theta \end{cases}$$

$$\Sigma \begin{cases} x = x(u, v) \\ y = y(u, v) \\ z = z(u, v) \end{cases}$$

$$\text{即 } Ax + By + Cz + D = 0$$

$$\begin{cases} x = x \\ y = y \\ z = \frac{1}{C} (-Ax - By - D) \end{cases} \quad \text{其中 } x, y \text{ 为参数}$$

曲线方程

(1) 一般式方程

$$\begin{cases} F(x, y, z) = 0 \\ G(x, y, z) = 0 \end{cases}$$

(2) 参数式

$$\begin{cases} x = x(t) \\ y = y(t) \\ z = z(t) \end{cases}$$

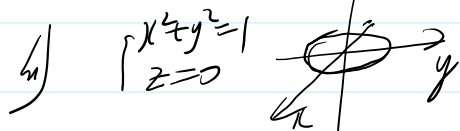
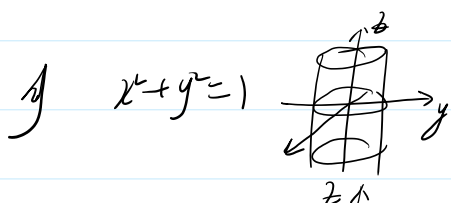
$$\begin{cases} \Sigma_1: z = z_1(x, y) \\ \Sigma_2: z = z_2(x, y) \end{cases}$$

$$\text{例 2} \begin{cases} z = f(x, y) \\ F(x, y, z) = 0 \end{cases}$$

$$\text{③} \begin{cases} x = x(u, v) \\ y = y(u, v) \\ z = z(u, v) \end{cases}$$

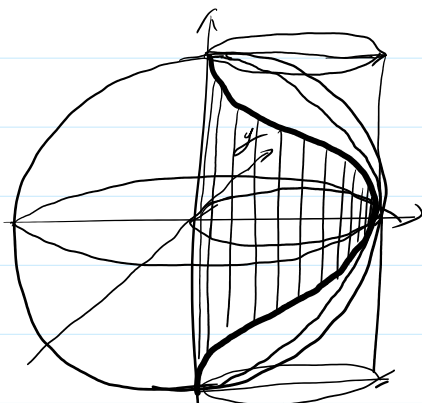
$$\frac{x-b}{m} = \frac{y-a}{n} = \frac{z-c}{p}$$

$$\begin{cases} \frac{x-b}{m} = \frac{y-a}{n} \quad \pi_1 \\ \frac{y-a}{n} = \frac{z-c}{p} \quad \pi_2 \end{cases}$$



3) Viviani (维维安尼) 曲线

$$\begin{cases} x^2 + y^2 + z^2 = R^2 \\ x^2 + y^2 = R^2 \\ (x - R)^2 + y^2 = (R/2)^2 \end{cases}$$



1.1 曲线方程

2

1.2 曲面方程

1) 螺旋线

$$\begin{cases} x = a \cos \omega t \\ y = a \sin \omega t \\ z = v_0 t \end{cases}$$

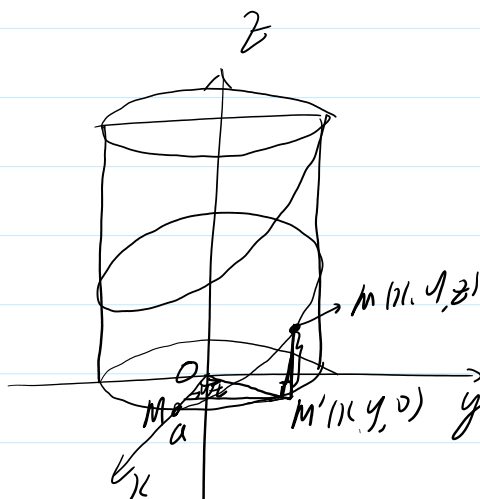
$\omega t = \theta$

$$\begin{cases} x = a \cos \theta \\ y = a \sin \theta \\ z = v_0 \frac{\theta}{\omega} \end{cases}$$

\Rightarrow

$$b = \frac{v_0}{\omega}$$

$$\begin{cases} x = a \cos \theta \\ y = a \sin \theta \\ z = b \theta \end{cases} \quad \theta \in (0, +\infty)$$



ω 角速度
 v_0 线速度