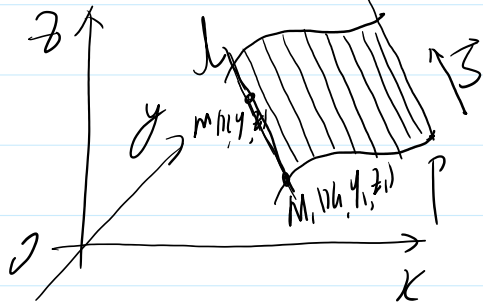


# 空间曲面 (柱面, 锥面, 锥面, 二次曲面)

柱面 准线  $P \begin{cases} F_1(x, y, z) = 0 \\ F_2(x, y, z) = 0 \end{cases}$

法向量  $\vec{s} = (m, n, p)$

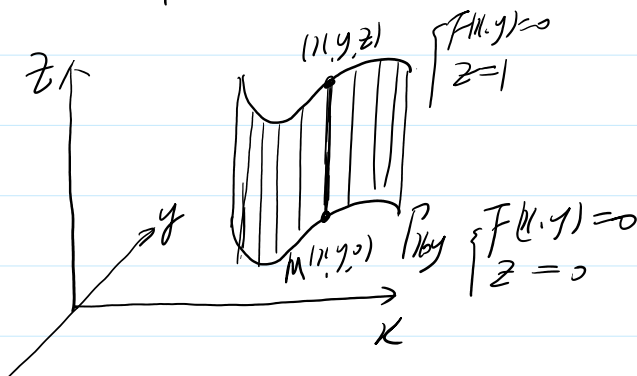


$$d: \frac{x-x_1}{m} = \frac{y-y_1}{n} = \frac{z-z_1}{p} \quad (1) (2)$$

$$P: \begin{cases} F_1(x, y, z) = 0 \\ F_2(x, y, z) = 0 \end{cases} \quad (3) (4)$$

(1) ~ (4) 中消去  $x, y, z \Rightarrow F(x, y, z) = 0$  即为所求柱面方程

## 母线平行于坐标轴的柱面 (准线在坐标面上平面曲线)

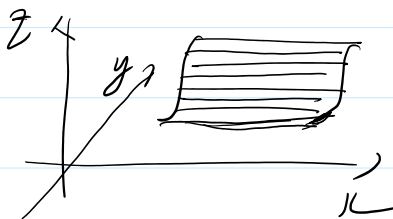


$$1) P \begin{cases} F(x, y) = 0 \\ z = 0 \end{cases} \text{ 准线, 母线平行于 } z \text{ 轴}$$

柱面为  $F(x, y) = 0$

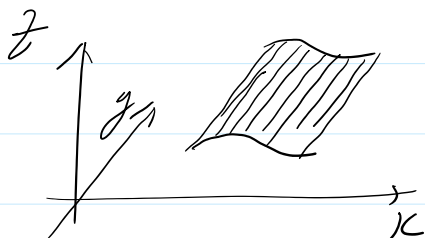
$$2) P \begin{cases} H(y, z) = 0 \\ x = 0 \end{cases} \text{ 准线, 母线平行于 } x \text{ 轴}$$

柱面为  $H(y, z) = 0$



$$3) P \begin{cases} G(z, x) = 0 \\ y = 0 \end{cases} \text{ 准线, 母线平行于 } y \text{ 轴}$$

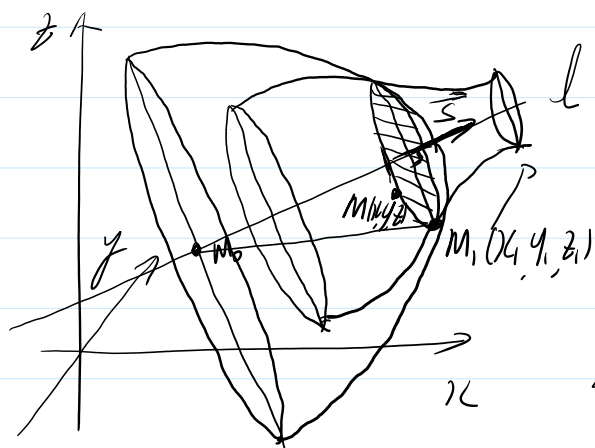
柱面为  $G(z, x) = 0$



## 锥面

$$\text{准线 } P \begin{cases} F(x, y, z) = 0 \end{cases}$$

# 通称曲面



$$\text{曲线} \begin{cases} F(x, y, z) = 0 \\ G(x, y, z) = 0 \end{cases}$$

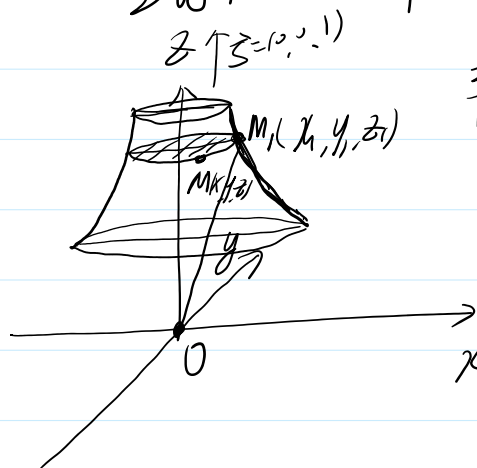
$$\text{过点} \frac{x-x_0}{m} = \frac{y-y_0}{n} = \frac{z-z_0}{p}$$

$M_0 \in l \quad \vec{s} = (m, n, p)$

$$\begin{cases} \text{球面} \begin{cases} \text{过点} m(x-x_0) + n(y-y_0) + p(z-z_0) = 0 & ① \\ \text{球面} (x-x_0)^2 + (y-y_0)^2 + (z-z_0)^2 = (x-x_0)^2 + (y-y_0)^2 + (z-z_0)^2 & ② \end{cases} \\ \text{曲线} \begin{cases} F(x, y, z) = 0 & ③ \\ G(x, y, z) = 0 & ④ \end{cases} \end{cases}$$

① ② ③ ④ 中消去  $x, y, z \Rightarrow F(x, y, z) = 0$  即为所求

## 坐标面上的平面曲线绕坐标轴旋转曲面



$$\text{平面曲线} \begin{cases} F(x, z) = 0 \\ y = 0 \end{cases} \quad \text{为曲线, 以 z 轴为轴}$$

$$\begin{cases} \text{球面} \begin{cases} z = z_1 \\ x^2 + y^2 + z^2 = x_1^2 + y_1^2 + z_1^2 \end{cases} \\ \text{曲线} \begin{cases} F(x, z) = 0 \\ y = 0 \end{cases} \end{cases}$$

$\begin{cases} z_1 = z \\ x_1 = \pm \sqrt{x^2 + y^2} \end{cases}$

$$\Rightarrow F(\pm \sqrt{x^2 + y^2}, z) = 0 \quad \text{即为所求}$$

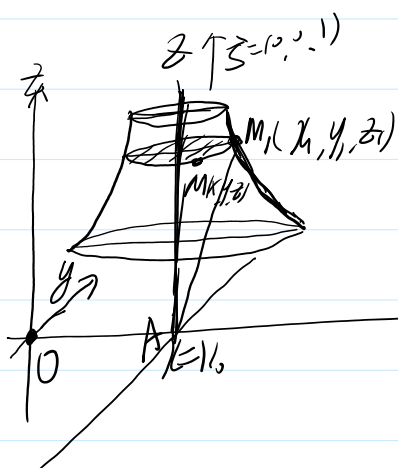
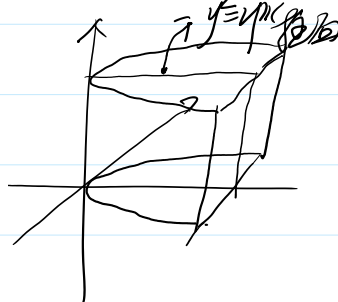
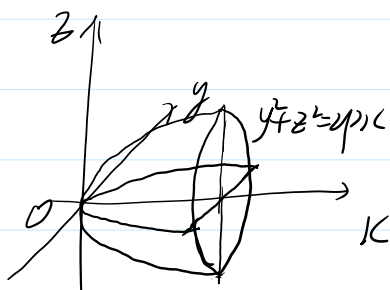
$$\begin{cases} \text{绕 z 轴旋转曲面} & F(\pm \sqrt{x^2 + y^2}, z) = 0 \\ \text{绕 x 轴旋转曲面} & F(x, \pm \sqrt{y^2 + z^2}) = 0 \end{cases}$$

$$\dots \dots \dots F(\pm \sqrt{y^2 + z^2}, x) = 0$$

$$2) \begin{cases} G(y, z) = 0 \\ x = 0 \end{cases} \begin{cases} \text{绕 } z \text{ 轴} & G(\pm\sqrt{y^2+z^2}, z) = 0 \\ \text{绕 } y \text{ 轴} & G(y, \pm\sqrt{x^2+z^2}) = 0 \end{cases}$$

$$3) \begin{cases} H(x, y) = 0 \\ z = 0 \end{cases} \begin{cases} \text{绕 } x \text{ 轴} & H(x, \pm\sqrt{y^2+z^2}) = 0 \\ \text{绕 } y \text{ 轴} & H(\pm\sqrt{x^2+z^2}, y) = 0 \end{cases}$$

例 1 求圆柱面  $y^2 + z^2 = 4\rho^2$  绕  $x$  轴旋转的曲面, 即  $(\pm\sqrt{y^2+z^2})^2 = 2\rho^2$   
 $y^2 + z^2 = 4\rho^2$



平面曲线  $\begin{cases} F(x, z) = 0 \\ y = 0 \end{cases}$  为母线, 以  $\begin{cases} x = x_0 \\ y = 0 \end{cases}$  为轴

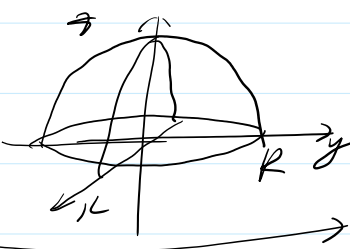
$$\begin{cases} \text{轴} & \begin{cases} z = z_1 \\ (x-x_0)^2 + y^2 + z^2 = (x_0-x_1)^2 + (y_1)^2 + z_1^2 \end{cases} \\ \text{母线} & \begin{cases} y_1 = 0 \\ F(x_1, z_1) = 0 \end{cases} \end{cases}$$

$$\Rightarrow F(x \pm \sqrt{10-x^2-y^2}, z) = 0 \text{ 即为所求}$$

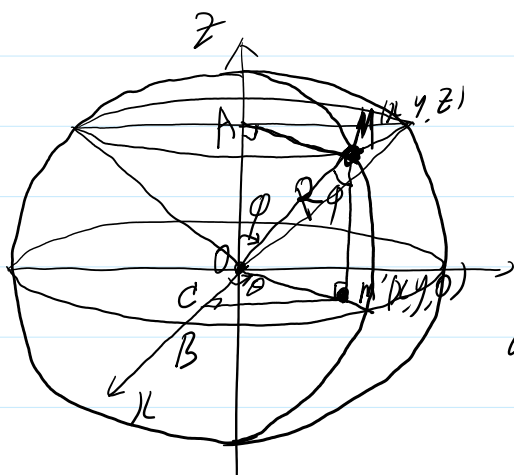
曲面方程  $\Sigma$ :

$$\begin{cases} \text{显式} & z = f(x, y) \\ \text{隐式} & F(x, y, z) = 0 \\ \text{参数式} & \begin{cases} x = x(u, v) \\ y = y(u, v) \\ z = z(u, v) \end{cases} \Rightarrow \begin{cases} u = u(x, y) \\ v = v(x, y) \end{cases} \end{cases}$$

参数式  $\begin{cases} x = x(u, v) \\ y = y(u, v) \\ z = z(u, v) \end{cases} \Rightarrow \begin{cases} u = u(x, y) \\ v = v(x, y) \end{cases}$

$z = \sqrt{R^2 - x^2 - y^2}$   
 $\Rightarrow x^2 + y^2 + z^2 = R^2 \quad (z \geq 0)$   
  
 $F(x, y, z) = x^2 + y^2 + z^2 - R^2 = 0$

球面参数方程  $x^2 + y^2 + z^2 = R^2$

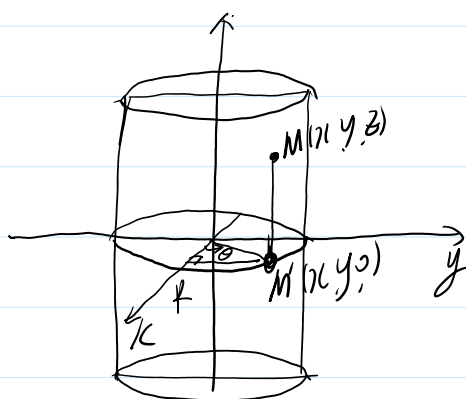


$OM' = R \sin \varphi$

$\begin{cases} x = OM' \cos \theta = R \sin \varphi \cos \theta \\ y = OM' \sin \theta = R \sin \varphi \sin \theta \\ z = R \cos \varphi \end{cases} \quad \begin{matrix} 0 \leq \varphi \leq \pi \\ 0 \leq \theta \leq 2\pi \end{matrix}$

柱面参数方程

$x^2 + y^2 = R^2$



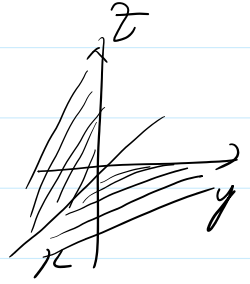
$\begin{cases} x = R \cos \theta \\ y = R \sin \theta \\ z = z \end{cases} \quad \begin{matrix} 0 \leq \theta \leq 2\pi \\ z \in \mathbb{R} \end{matrix}$

空间曲线及其方程

显式  $P: \begin{cases} z = z_1(x, y) & \Sigma_1 \\ z = z_2(x, y) & \Sigma_2 \end{cases}$   
 隐式  $P: \begin{cases} F_1(x, y, z) = 0 & \Sigma_1 \\ F_2(x, y, z) = 0 & \Sigma_2 \end{cases}$

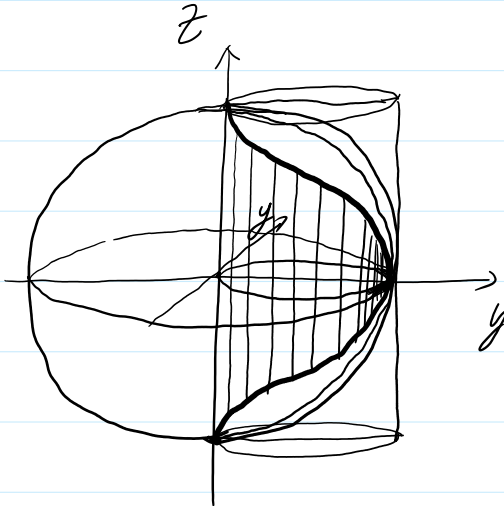
$$\begin{cases} F(x, y, z) = 0 \\ \text{参数 } P: \begin{cases} x = x(t) \\ y = y(t) \\ z = z(t) \end{cases} \end{cases}$$

例  $x$  轴  $\begin{cases} z=0 \\ y=0 \end{cases}$



例  $\frac{x-x_0}{m} = \frac{y-y_0}{n} = \frac{z-z_0}{p} \Leftrightarrow \begin{cases} \frac{x-x_0}{m} = \frac{z-z_0}{p} \\ \frac{y-y_0}{n} = \frac{z-z_0}{p} \end{cases} \Leftrightarrow \begin{cases} F(x, y, z) = 0 \\ G(x, y, z) = 0 \end{cases}$

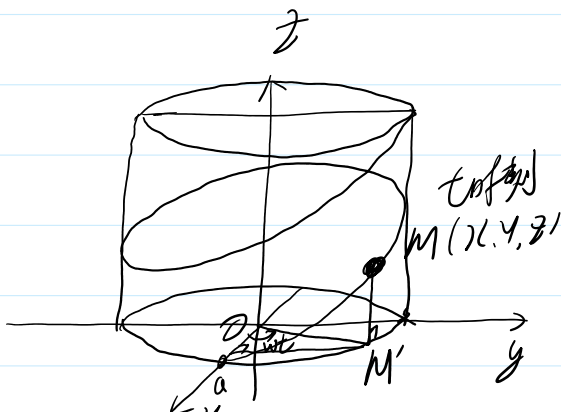
例 Viviani (维维安尼) 曲线  $\begin{cases} x^2 + y^2 + z^2 = R^2 \\ x^2 + y^2 = R^2 \end{cases}$



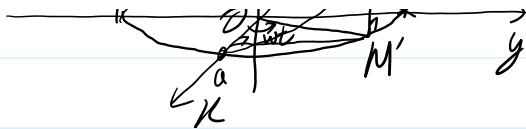
参数  $\begin{cases} x = \frac{R}{2} + \frac{R}{2} \cos t \\ y = \frac{R}{2} \sin t \\ z = \sqrt{R^2 - (\frac{R}{2} + \frac{R}{2} \cos t)^2 - \frac{R^2}{4} \sin^2 t} \end{cases}$

例 螺旋线

动点  $M(x, y, z)$  由  $M_0(a, 0, 0)$  沿柱面运动  $\begin{cases} \text{角速度 } \omega \\ \text{轴向速度 } v \end{cases}$



$\begin{cases} x = a \cos \omega t \\ y = a \sin \omega t \\ z = vt \end{cases} \xrightarrow{t = \frac{\omega}{v} z} \begin{cases} x = a \cos \omega z \\ y = a \sin \omega z \\ z = z \end{cases}$



$$\begin{cases} x = a \sin \theta \\ y = a \cos \theta \\ z = b \theta \end{cases}$$