

# Review of Machine Learning

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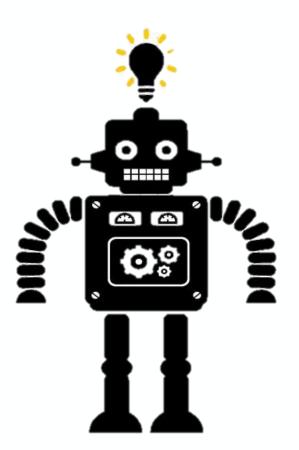
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### What is Machine Learning?

Machine learning allows computers to learn and infer from data.





### Types of Machine Learning

Supervised

data points have known outcome

Unsupervised

data points have unknown outcome



### Types of Supervised Learning

Regression

outcome is continuous (numerical)

Classification

outcome is a category



### Machine Learning Vocabulary

- Target: predicted category or value of the data (column to predict)
- Features: properties of the data used for prediction (non-target columns)
- Example: a single data point within the data (one row)
- Label: the target value for a single data point

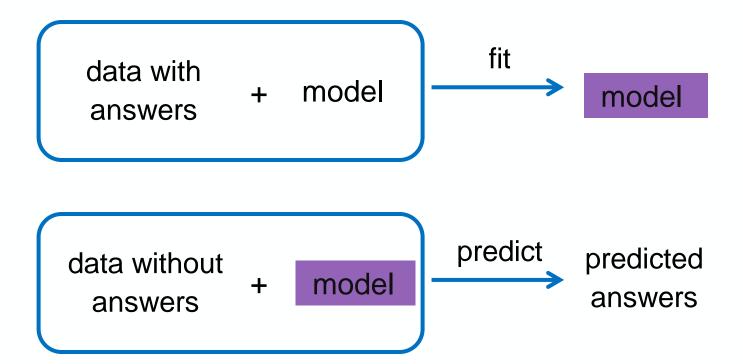


### Machine Learning Vocabulary (Synonyms)

- Target: Response, Output, Dependent Variable, Labels
- Features: Predictors, Input, Independent Variables, Attributes
- Example: Observation, Record, Instance,
   Datapoint, Row
- Label: Answer, y-value, Category

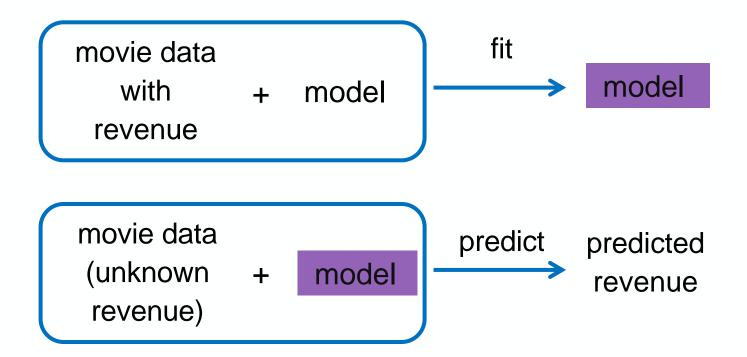


### Supervised Learning Overview



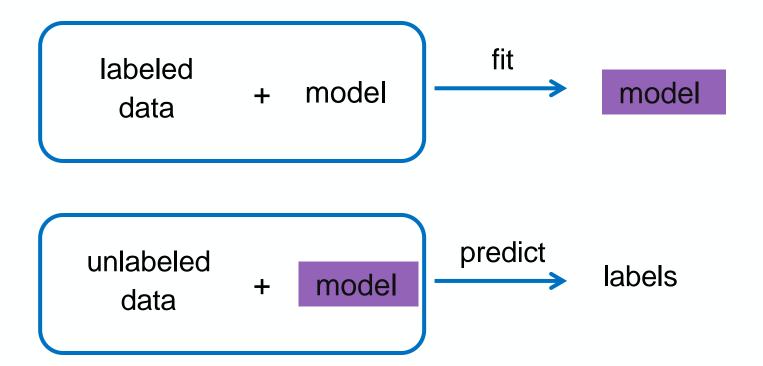


#### Regression: Numeric Answers



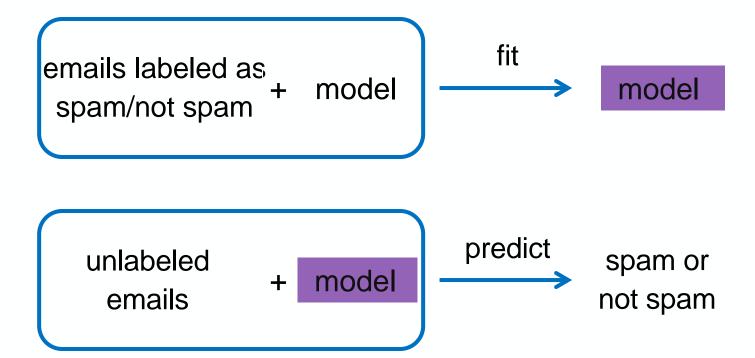


#### Classification: Categorical Answers





### Classification: Categorical Answers





#### Three Types of Classification Predictions

- Hard Prediction: Predict a single category for each instance.
- Ranking Prediction: Rank the instances from most likely to least likely. (binary classification)
- Probability Prediction: Assign a probability distribution across the classes to each instance.



#### Metrics for Classification

- Hard Prediction: Accuracy, Precision, Recall (Sensitivity), Specificity, F1 Score
- Ranking Prediction: AUC (ROC), Precision-Recall Curves
- Probability Prediction: Log-loss (aka Cross-Entropy), Brier Score



### Metrics for Regression

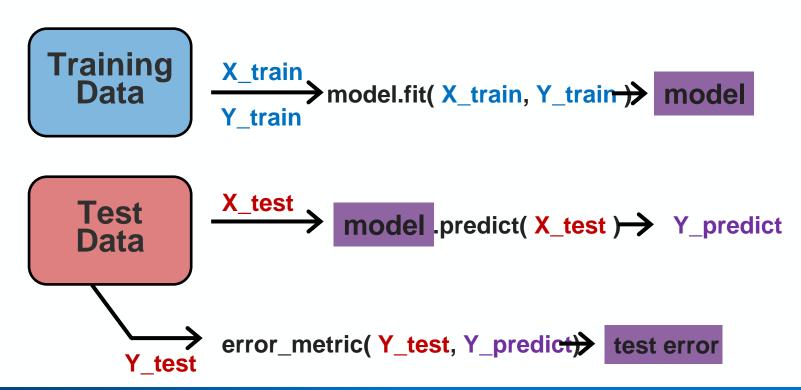
Root Mean Square Error (RMSE)

$$RMSE = \sqrt{\frac{1}{n} \sum_{i=1}^{n} (y_i - \hat{y}_i)^2}$$

Mean Absolute Deviation

$$MAD = \frac{1}{n} \sum_{i=1}^{n} |y_i - \hat{y}_i|$$

### Fitting Training and Test Data







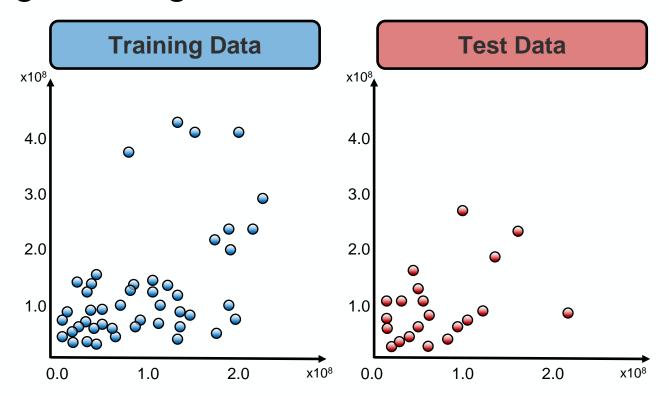
fit the model



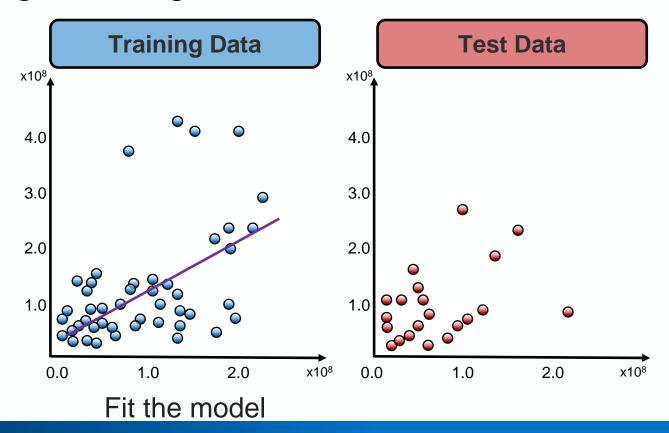
#### measure performance

- predict label with model
- compare with actual value
- measure error

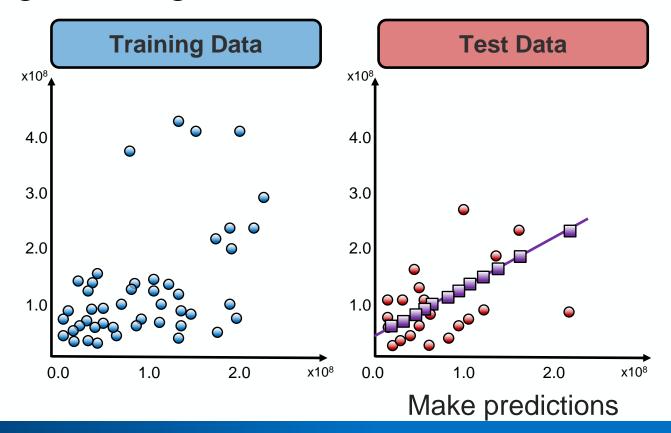




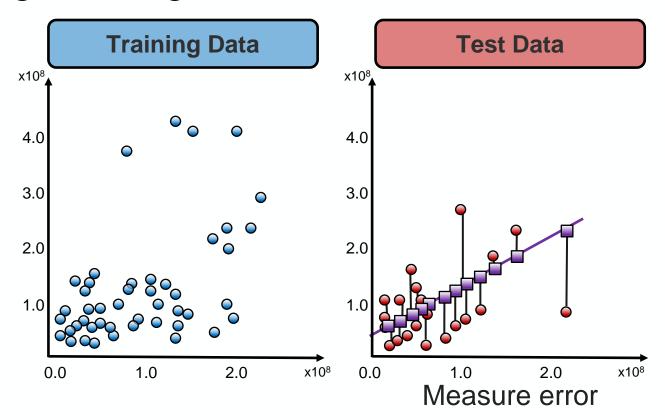








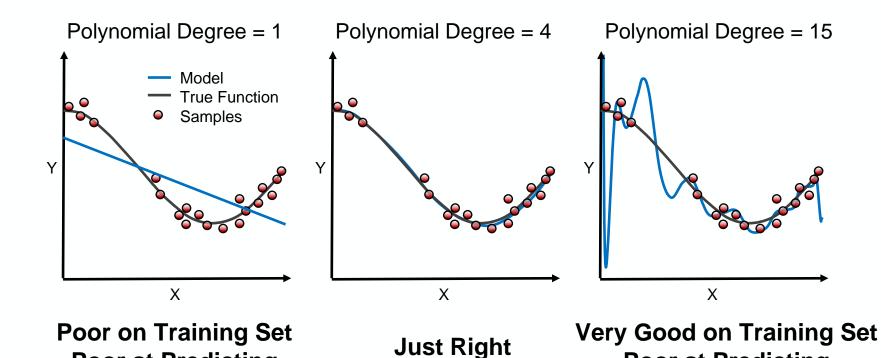






#### How Well Does the Model Generalize?

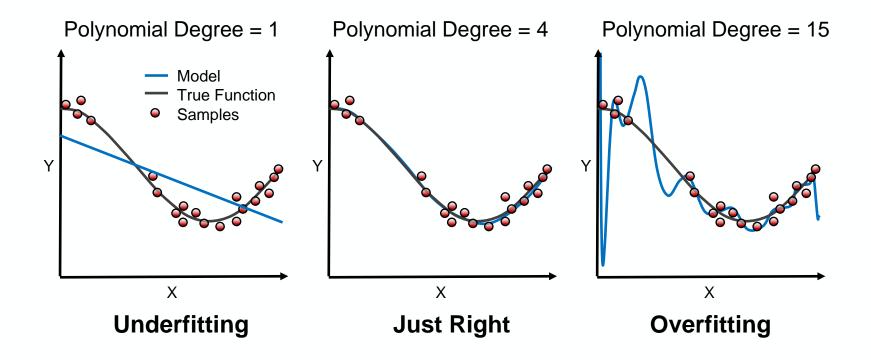
**Poor at Predicting** 





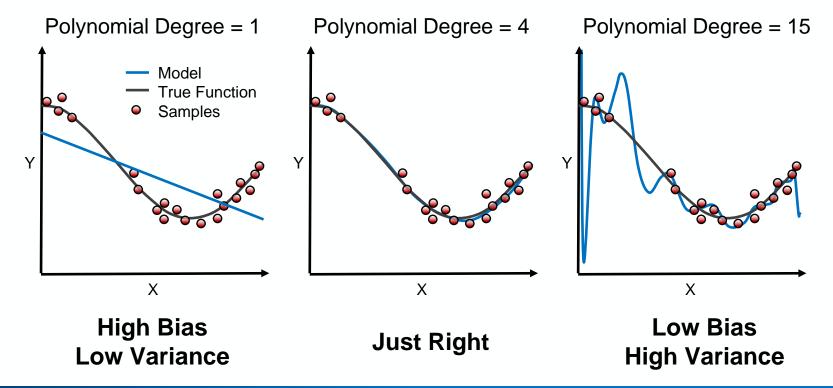
**Poor at Predicting** 

## Underfitting vs Overfitting





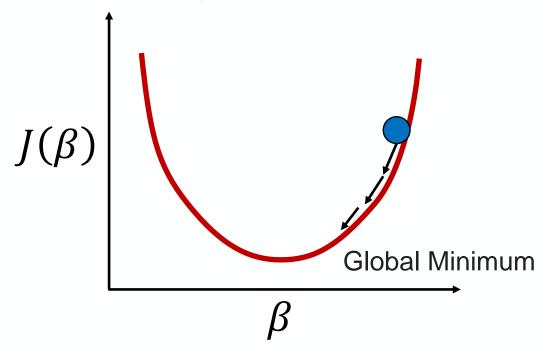
#### Bias – Variance Tradeoff





#### **Gradient Descent**

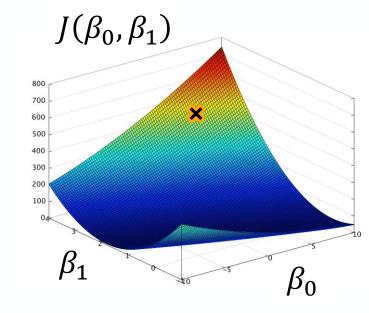
Start with a cost function  $J(\beta)$ :



Then gradually move towards the minimum.

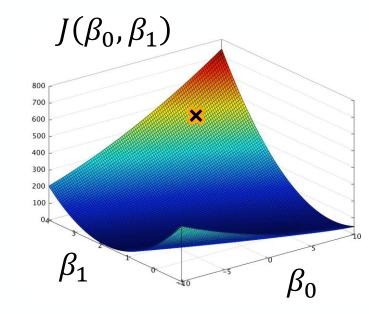


- Now imagine there are two parameters  $(\beta_0, \beta_1)$
- This is a more complicated surface on which the minimum must be found
- How can we do this without knowing what  $J(\beta_0, \beta_1)$  looks like?





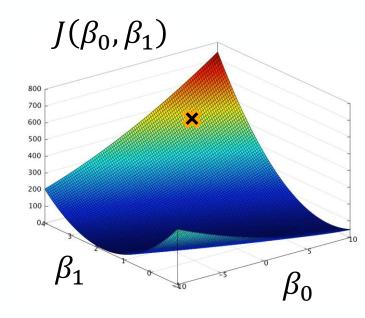
- Compute the gradient,  $\nabla J(\beta_0, \beta_1)$ , which points in the direction of the biggest increase!
- $-\nabla J(\beta_0, \beta_1)$  (negative gradient) points to the biggest decrease at that point!





 The gradient is the a vector whose coordinates consist of the partial derivatives of the parameters

$$\nabla J(\beta_0, ..., \beta_n) = \langle \frac{\partial J}{\partial \beta_0}, ..., \frac{\partial J}{\partial \beta_n} \rangle$$

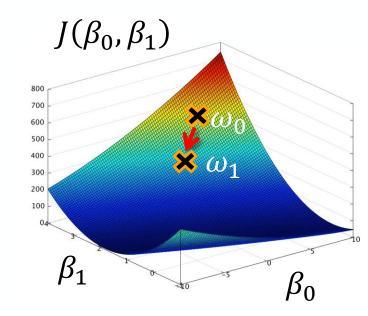




• Then use the gradient  $(\nabla)$  and the cost function to calculate the next point  $(\omega_1)$  from the current one  $(\omega_0)$ :

$$\omega_{1} = \omega_{0} - \alpha \nabla \frac{1}{2} \sum_{i=1}^{m} \left( \left( \beta_{0} + \beta_{1} x_{obs}^{(i)} \right) - y_{obs}^{(i)} \right)^{2}$$

• The learning rate  $(\alpha)$  is a tunable parameter that determines step size

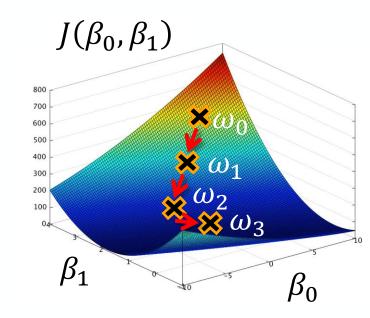




 Each point can be iteratively calculated from the previous one

$$\omega_2 = \omega_1 - \alpha \nabla \frac{1}{2} \sum_{i=1}^{m} \left( \left( \beta_0 + \beta_1 x_{obs}^{(i)} \right) - y_{obs}^{(i)} \right)^2$$

$$\omega_{3} = \omega_{2} - \alpha \nabla \frac{1}{2} \sum_{i=1}^{m} \left( \left( \beta_{0} + \beta_{1} x_{obs}^{(i)} \right) - y_{obs}^{(i)} \right)^{2}$$



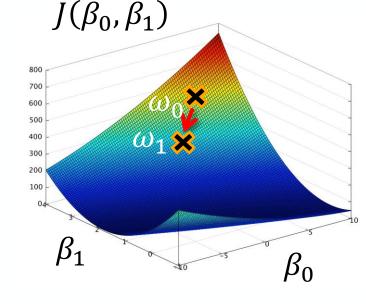


#### Stochastic Gradient Descent

 Use a single data point to determine the gradient and cost function instead of all the data

$$\omega_{1} = \omega_{0} - \alpha \nabla \frac{1}{2} \sum_{i=1}^{m} \left( \left( \beta_{0} + \beta_{1} x_{obs}^{(i)} \right) - y_{obs}^{(i)} \right)^{2}$$

$$\omega_{1} = \omega_{0} - \alpha \nabla \frac{1}{2} \left( \left( \beta_{0} + \beta_{1} x_{obs}^{(0)} \right) - y_{obs}^{(0)} \right)^{2}$$





#### Stochastic Gradient Descent

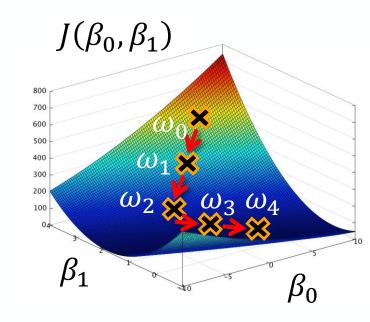
 Use a single data point to determine the gradient and cost function instead of all the data

$$\omega_1 = \omega_0 - \alpha \nabla \frac{1}{2} \left( \left( \beta_0 + \beta_1 x_{obs}^{(0)} \right) - y_{obs}^{(0)} \right)^2$$

. . .

$$\omega_4 = \omega_3 - \alpha \nabla \frac{1}{2} \left( \left( \beta_0 + \beta_1 x_{obs}^{(3)} \right) - y_{obs}^{(3)} \right)^2$$

 Path is less direct due to noise in single data point—"stochastic"





#### Mini Batch Gradient Descent

Perform an update for every n training examples

$$\omega_{1} = \omega_{0} - \alpha \nabla \frac{1}{2} \sum_{i=1}^{n} \left( \left( \beta_{0} + \beta_{1} x_{obs}^{(i)} \right) - y_{obs}^{(i)} \right)^{2}$$

#### Best of both worlds:

- Reduced memory relative to "vanilla" gradient descent
- Less noisy than stochastic gradient descent

