

# Backpropagation in Neural Nets

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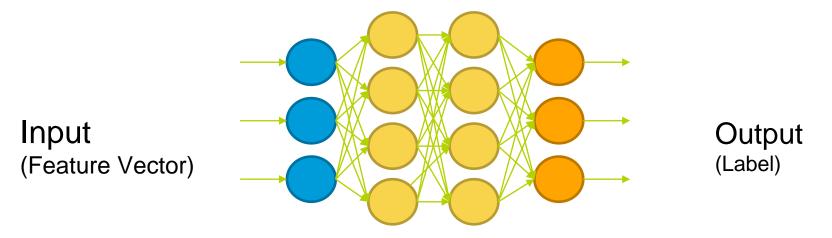
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#### How to Train a Neural Net?



- Put in Training inputs, get the output
- Compare output to correct answers: Look at loss function J
- Adjust and repeat!
- Backpropagation tells us how to make a single adjustment using calculus.



#### How have we trained before?

- Gradient Descent!
- 1. Make prediction
- 2. Calculate Loss
- 3. Calculate gradient of the loss function w.r.t. parameters
- 4. Update parameters by taking a step in the opposite direction
- 5. Iterate

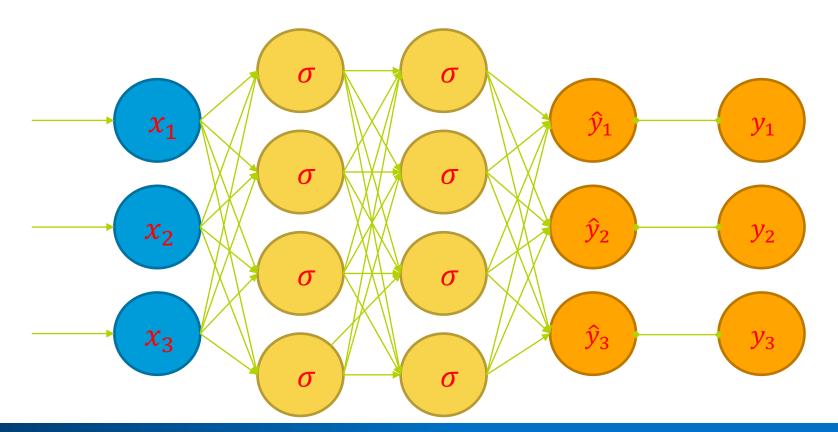


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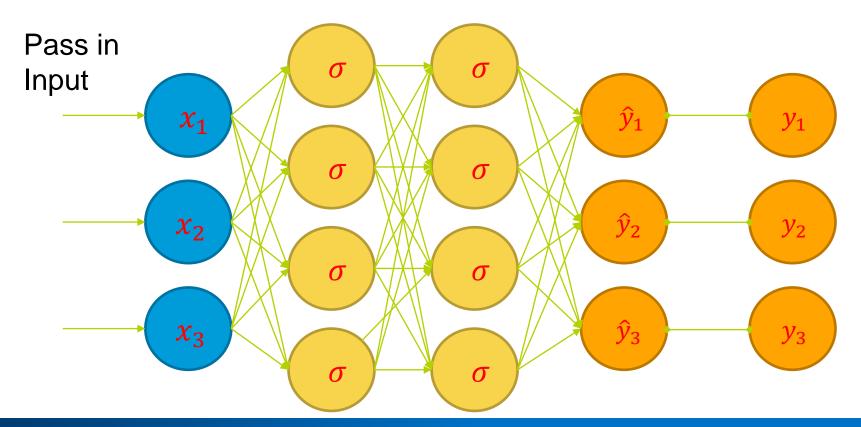
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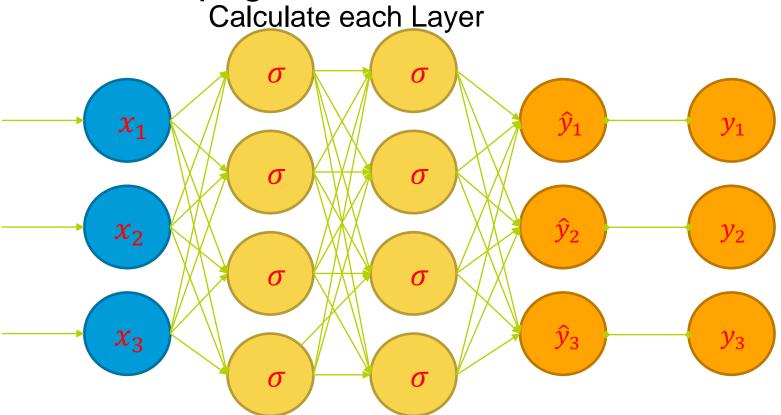
#### Feedforward Neural Network



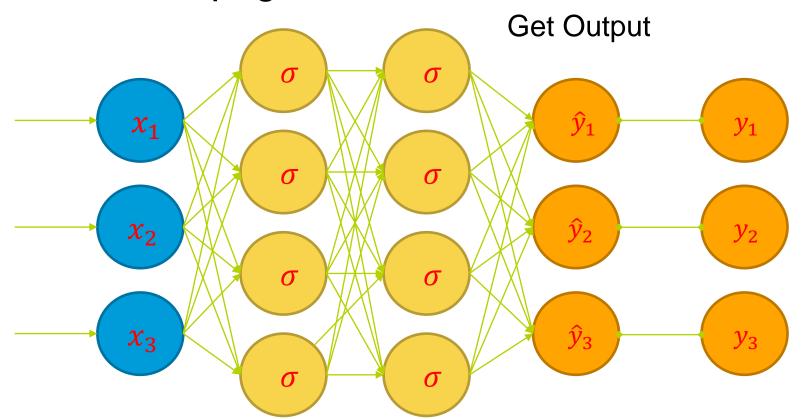




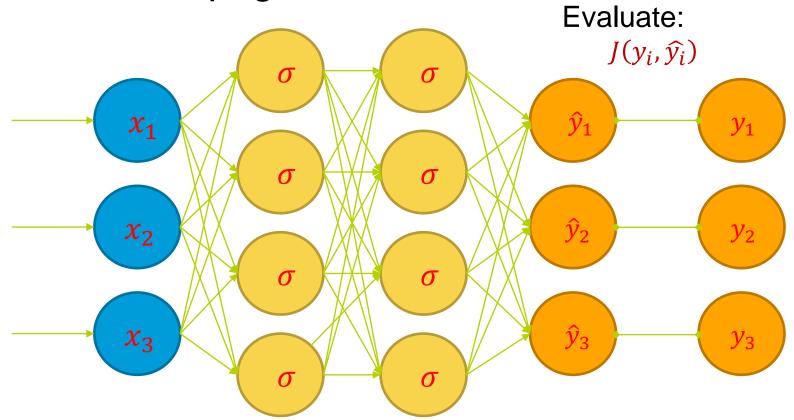














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## How to calculate gradient?

Chain rule





#### How to Train a Neural Net?

- How could we change the weights to make our Loss Function lower?
- Think of neural net as a function F: X -> Y
- F is a complex computation involving many weights W\_k
- Given the structure, the weights "define" the function F (and therefore define our model)
- Loss Function is J(y,F(x))

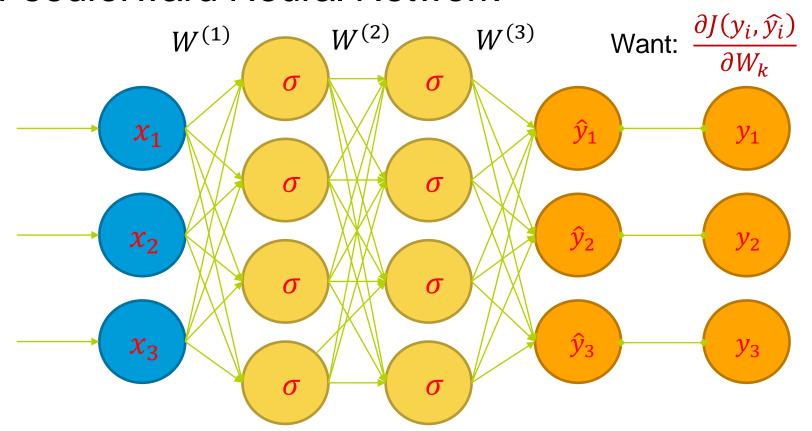


#### How to Train a Neural Net?

- Get  $\frac{\partial J}{\partial W_k}$  for every weight in the network.
- This tells us what direction to adjust each W<sub>k</sub> if we want to lower our loss function.
- Make an adjustment and repeat!



#### Feedforward Neural Network





#### Calculus to the Rescue

- Use calculus, chain rule, etc. etc.
- Functions are chosen to have "nice" derivatives
- Numerical issues to be considered



#### **Punchline**

$$\frac{\partial J}{\partial W^{(3)}} = (\hat{y} - y) \cdot a^{(3)}$$

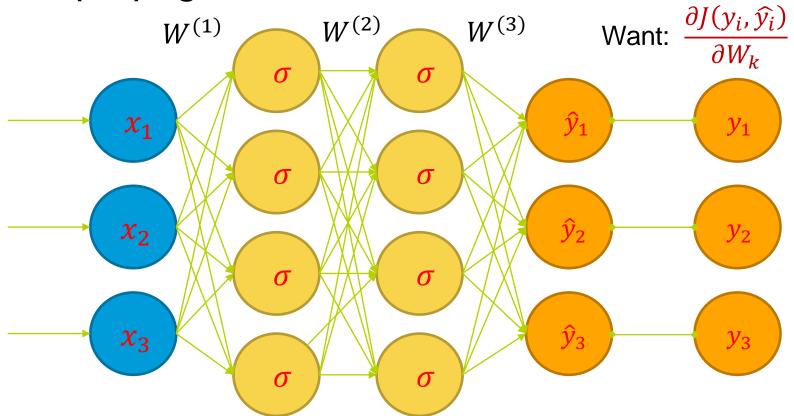
$$\frac{\partial J}{\partial W^{(2)}} = (\hat{y} - y) \cdot W^{(3)} \cdot \sigma'(z^{(3)}) \cdot a^{(2)}$$

$$\frac{\partial J}{\partial W^{(1)}} = (\hat{y} - y) \cdot W^{(3)} \cdot \sigma'(z^{(3)}) \cdot W^{(2)} \cdot \sigma'(z^{(2)}) \cdot X$$

- Recall that:  $\sigma'(z) = \sigma(z)(1 \sigma(z))$
- Though they appear complex, above are easy to compute!

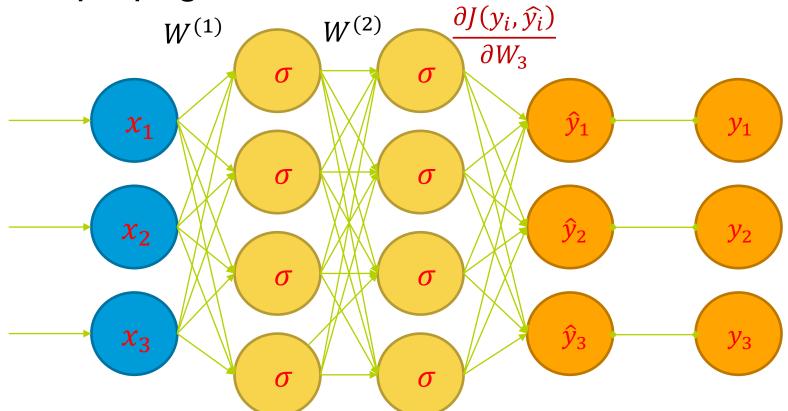


## Backpropagation



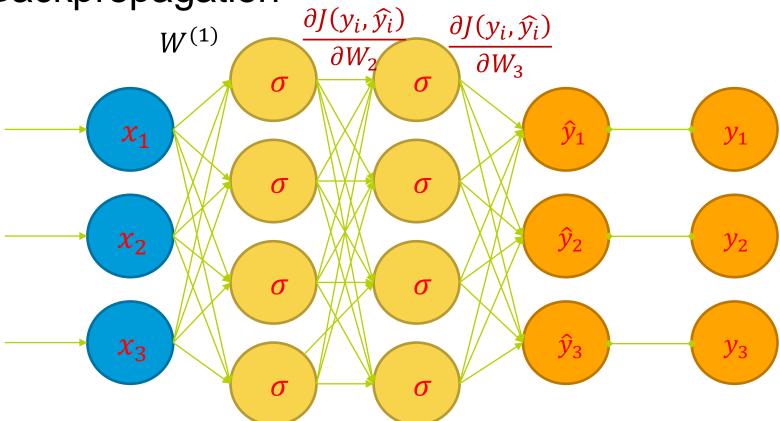


## Backpropagation

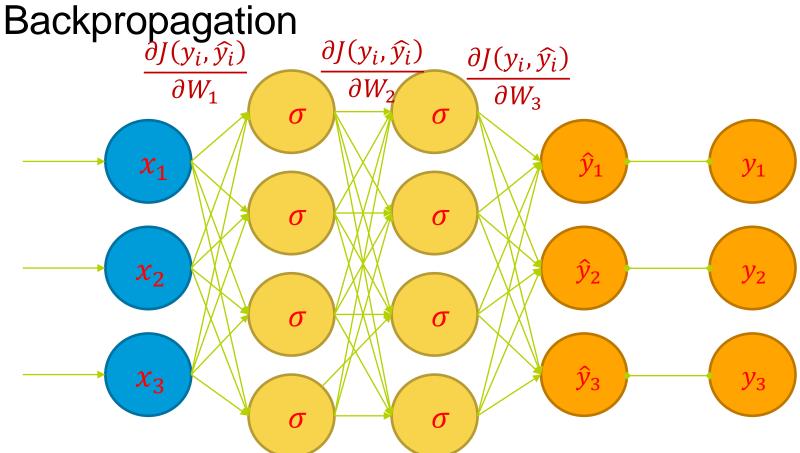




Backpropagation









#### How have we trained before?

- Gradient Descent!
- 1. Make prediction
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## Vanishing Gradients

#### Recall that:

$$\frac{\partial J}{\partial W^{(1)}} = (\hat{y} - y) \cdot W^{(3)} \cdot \sigma'(z^{(3)}) \cdot W^{(2)} \cdot \sigma'(z^{(2)}) \cdot X$$

- Remember:  $\sigma'(z) = \sigma(z)(1 \sigma(z)) \le .25$
- As we have more layers, the gradient gets very small at the early layers.
- This is known as the "vanishing gradient" problem.
- For this reason, other activations (such as ReLU) have become more common.



## Other Activation Functions



## Hyperbolic Tangent Function

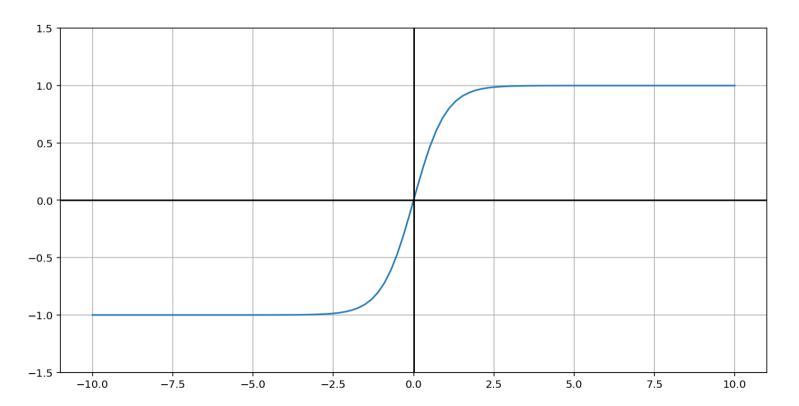
- Hyperbolic tangent function
- Pronounced "tanch"

$$tanh(z) = \frac{\sinh(z)}{\cosh(z)} = \frac{e^{2x} - 1}{e^{2x} + 1}$$

$$tanh(0) = 0$$
$$tanh(\infty) = 1$$
$$tanh(-\infty) = -1$$



## Hyperbolic Tangent Function





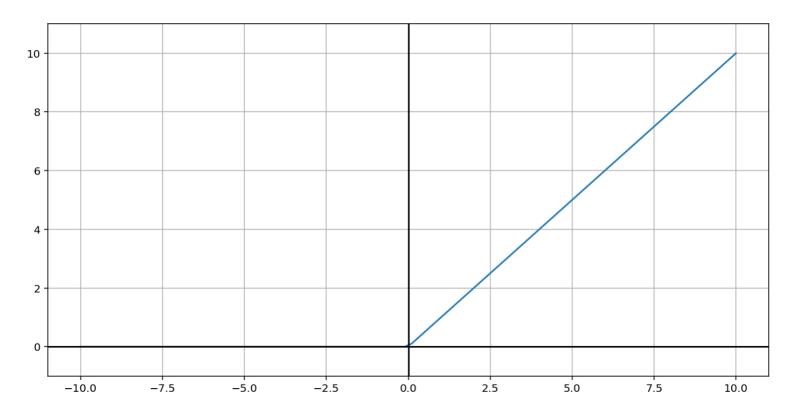
## Rectified Linear Unit (ReLU)

$$ReLU(z) = \begin{cases} 0, & z < 0 \\ z, & z \ge 0 \end{cases}$$
$$= \max(0, z)$$

$$ReLU(0) = 0$$
  
 $ReLU(z) = z$  for  $(z \gg 0)$   
 $ReLU(-z) = 0$ 



## Rectified Linear Unit (ReLU)





## "Leaky" Rectified Linear Unit (ReLU)

$$LReLU(z) = \begin{cases} \alpha z, & z < 0 \\ z, & z \ge 0 \end{cases}$$

$$= \max(\alpha z, z) \quad \text{for } (\alpha < 1)$$

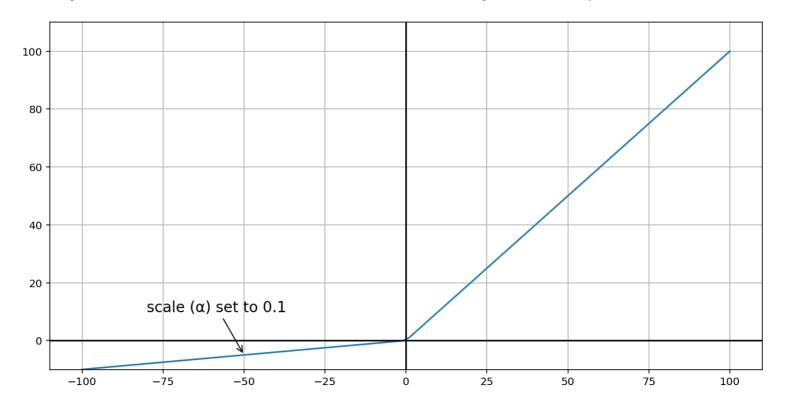
$$LReLU(0) = 0$$

$$LReLU(z) = z \quad \text{for } (z \gg 0)$$

$$LReLU(-z) = -\alpha z$$



## "Leaky" Rectified Linear Unit (ReLU)





#### What next?

- We now know how to make a single update to a model given some data.
- But how do we do the full training?
- We will dive into these details in the next lecture.



