

## De La Salle ICPC Team Notebook (2018-19)

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## 1 Advanced Data Structures Without Libraries

## 1.1 Union Find Disjoint Set

```
#include <vector>
using namespace std;
typedef vector<int> vi;

class UnionFind {
public:
    vi p, rank;
    UnionFind(int n) {
        p.assign(n,0);
        rank.assign(n,0);
        for(int i = 0; i < n; i++) { p[i] = i; }
    }

    void unionSet(int i, int j) {
        if(!isSameSet(i,j)) {
            int x = findSet(i), y = findSet(j);
            if(rank[x] > rank[y]) {
                p[y] = x;
            }
        }
    }
};
```

```
        } else {
            p[x] = y;
            if(rank[x] == rank[y]) { rank[y]++; }
        }
    }

    int findSet(int i) {
        if(p[i] != i) {
            p[i] = findSet(p[i]);
        }
        return p[i];
    }

    bool isSameSet(int i, int j) { return findSet(i) == findSet(j); }
};
```

## 1.2 Segment Tree

```
#include <vector>
using namespace std;
typedef vector<int> vi;

/**
 * Segment tree for Range Maximum Queries
 */
class SegmentTree {
public:
    vi st, A;
    int n;
    SegmentTree(const vi &_A) {
        A = _A;
        n = (int)A.size();
        st.assign(4 * n, 0);
        build(1, 0, n - 1);
    }

    int left(int p) { return 1 << p; }
    int right(int p) { return (1 << p) + 1; }
    void build(int p, int l, int r) {
        if(l == r) {
            st[p] = l;
        } else {
            int m = l + (r - l) / 2;
            build(left(p), l, m);
            build(right(p), m + 1, r);
            int l = st[left(p)];
            int r = st[right(p)];
            st[p] = A[l] >= A[r] ? l : r;
        }
    }

    int rmq(int i, int j) {
        return rmq(1, 0, n-1, i, j);
    }
    int rmq(int p, int l, int r, int i, int j) {
        if(l > j || r < i) { return -1; }
        else if(l >= i && r <= j) { return st[p]; }
        else {
            int m = l + (r - l) / 2;
            int s1 = rmq(left(p), l, m, i, j);
            int s2 = rmq(right(p), m + 1, r, i, j);
            if(s1 == -1) { return s2; }
            else if(s2 == -1) { return s1; }
            else { return A[l] >= A[r] ? l : r; }
        }
    }

    void pointUpdate(int i, int val) {
        pointUpdate(1, 0, n-1, i, val);
    }
    void pointUpdate(int p, int l, int r, int i, int val) {
        if(l == r) {
            A[i] = val;
        } else {
            int m = l + (r - l) / 2;
            if(i >= l && i <= m) {
                pointUpdate(left(p), l, m, i, val);
            } else {
                pointUpdate(right(p), m + 1, r, i, val);
            }
            int l = st[left(p)];
            int r = st[right(p)];
            st[p] = A[l] >= A[r] ? l : r;
        }
    }
};
```

## 1.3 Fenwick Tree/Binary Indexed Tree

```
#include <vector>

using namespace std;

typedef vector<int> vi;

class FenwickTree {
public:
    vi ft;
    int n;
    FenwickTree(int _n) {
        n = _n;
        ft.assign(n + 1, 0);
    }

    void update(int index, int increment) {
        while(index <= n) {
            ft[index] += increment;
            index += (index & (-index));
        }
    }

    int rmq(int end) {
        int res = 0;
        while(end) {
            res += ft[end];
            end -= (end & (-end));
        }
        return res;
    }

    int rmq(int i, int j) {
        if(i > j) { return 0; }
        else if(i <= 0) { return rmq(j); }
        else { return rmq(j) - rmq(i - 1); }
    }
};
```

## 2 Problem Solving Paradigms

### 2.1 Maximum 1D/2D Range Sum

```
#include <vector>

using namespace std;

typedef vector<int> vi;

int max1DRangeSum(const vi &arr) {
    int ans = 0;
    int cur = 0;
    for(int i = 0; i < (int)arr.size(); i++) {
        cur += arr[i];
        if(cur < 0) cur = 0;
        ans = max(ans, cur);
    }
    return ans;
}

int max2DRangeSum(const vector<vi> &arr) {
    vi rowSums(arr.size(), 0);
    for(int i = 0; i < (int)arr.size(); i++) {
        for(int j = 0; j < (int)arr[i].size(); j++) {
            rowSums[i] += arr[i][j];
        }
    }

    int ans = 0;
    for(int leftCol = 0; leftCol < (int)arr[0].size(); leftCol++) {
        for(int rightCol = leftCol; rightCol < (int)arr[0].size(); rightCol++) {
            vi arr2(arr.size(), 0);
            for(int i = 0; i < (int)arr.size(); i++) {
                arr2[i] = leftCol == 0 ? rowSums[rightCol] :
                    (rowSums[rightCol] - rowSums[leftCol - 1]);
            }
            int temp = max1DRangeSum(arr2);
            ans = max(ans, temp);
        }
    }
}
```

```
    }
    return ans;
}
```

### 2.2 Longest Increasing Subsequence

```
#include <algorithm>
#include <vector>

using namespace std;

typedef vector<int> vi;

int lisSlow(const vi &arr) {
    vi memo(arr.size(), 1);
    int ans = 1;
    for(int i = 1; i < (int)arr.size(); i++) {
        for(int j = 0; j < i; j++) {
            if(arr[i] > arr[j]) {
                memo[i] = max(memo[i], memo[j] + 1);
            }
        }
        ans = max(ans, memo[i]);
    }
    return ans;
}

int lisNLogN(const vi &arr) {
    vi memo;

    for(int i = 0; i < (int)arr.size(); i++) {
        vi::iterator itr = lower_bound(memo.begin(), memo.end(), arr[i]);
        if(itr == memo.end()) {
            memo.push_back(arr[i]);
        } else {
            *itr = arr[i];
        }
    }
    return (int)memo.size();
}
```

### 2.3 0/1 Knapsack

```
#include <vector>

using namespace std;

typedef pair<int, int> ii;
typedef vector<int> vi;
typedef vector<ii> vii;

/**
 * item.first - weight of item
 * item.second - value of item
 */

int zeroOneKnapsack(const vii &items, int maxWeight) {
    vector<vi> memo(items.size(), vi(maxWeight + 1, 0));
    for(int i = 0; i < (int)items.size(); i++) {
        for(int j = 0; j <= maxWeight; j++) {
            if(i == 0) {
                memo[i][j] = j >= items[0].first ? items[0].second : 0;
            } else {
                memo[i][j] = memo[i - 1][j];
                if(j >= items[i].first) {
                    memo[i][j] = max(memo[i][j],
                        memo[i - 1][j - items[i].first] + items[i].second);
                }
            }
        }
    }
    return memo[(int)items.size() - 1][maxWeight];
}
```

### 2.4 Coin Change

```
#include <vector>

using namespace std;
```

```

typedef pair<int,int> ii;
typedef vector<int> vi;

/**
 * returns minimum coins
 */
int coinChangeV1(const vi &denoms, int total) {
    vi memo(total + 1, 1 << 29);
    memo[0] = 0;
    for(int i = 1; i <= total; i++) {
        for(int j = 0; j < (int)denoms.size(); j++) {
            if(i - denoms[j] >= 0) {
                memo[i] = min(memo[i], memo[i - denoms[j]] + 1);
            }
        }
    }
    return memo[total];
}

/**
 * returns number of ways to give change
 */
int coinChangeV2(const vi &denoms, int total) {
    vector<vi> memo(denoms.size(), vi(total + 1, 0));
    for(int i = 0; i < (int)denoms.size(); i++) {
        for(int j = 0; j <= total; j++) {
            if(i == 0) {
                memo[i][j] = j % denoms[0] ? 1 : 0;
            } else {
                memo[i][j] = 0;
                int count = 0;
                while(j - count * denoms[i] >= 0) {
                    memo[i][j] += memo[i - 1][j - count * denoms[i]];
                    count++;
                }
            }
        }
    }
    return memo[(int)denoms.size() - 1][total];
}

```

## 2.5 Traveling Salesman Problem

```

#include <vector>

using namespace std;

typedef vector<int> vi;

int n; // number of nodes
int start; //start node

vector<vi> memo(n, vi(1 << n, -1));
vector<vi> dists; // 2D distance matrix

int tsp(int pos, int mask) {
    if(mask == (1 << n) - 1) {
        return dists[pos][start];
    } else if(memo[pos][mask] != -1) {
        return memo[pos][mask];
    } else {
        int &res = memo[pos][mask];
        for(int i = 0; i < n; i++) {
            if((mask & (1 << i)) == 0) {
                res = min(res, dists[pos][i] + tsp(i, mask | (1 << i)));
            }
        }
        return res;
    }
}

```

## 3 Graphs

### 3.1 Depth First Search

```

#include <vector>
#include <utility>

using namespace std;

```

```

#define UNVISITED 1
#define VISITED 2

typedef pair<int,int> ii;
typedef vector<int> vi;
typedef vector<ii> vii;

vector<vii> adjList;
vi dfs_num;

void dfs(int u) {
    dfs_num[u] = VISITED;
    for(int i = 0; i < (int)adjList[u].size(); i++) {
        ii v = adjList[u][i];
        if(dfs_num[v.first] == UNVISITED) {
            dfs(v.first);
        }
    }
}

```

### 3.2 Breadth First Search

```

#include <vector>
#include <utility>
#include <queue>
#include <bitset>

using namespace std;

#define MAX_N 1000

typedef pair<int,int> ii;
typedef vector<int> vi;
typedef vector<ii> vii;

vector<vii> adjList;

void bfs(int s) {
    bitset<MAX_N> visited;
    queue<int> q;
    q.push(s);
    visited.set(s);
    while(!q.empty()) {
        int u = q.front(); q.pop();
        for(int i = 0; i < (int)adjList[u].size(); i++) {
            ii v = adjList[u][i];
            if(!visited.test(v.first)) {
                visited.set(v.first);
                q.push(v.first);
            }
        }
    }
}

```

### 3.3 Connected Components

```

#include <vector>
#include <utility>

using namespace std;

#define UNVISITED 1
#define VISITED 2

typedef pair<int,int> ii;
typedef vector<int> vi;
typedef vector<ii> vii;

vector<vii> adjList;
vi dfs_num;
int V;

void dfs(int u) {
    dfs_num[u] = VISITED;
    for(int i = 0; i < (int)adjList[u].size(); i++) {
        ii v = adjList[u][i];
        if(dfs_num[v.first] == UNVISITED) {
            dfs(v.first);
        }
    }
}

```

```

int countCC() {
    int cc = 0;
    for(int i = 0; i < V; i++) {
        if(dfs_num[i] == UNVISITED) {
            cc++;
            dfs(i);
        }
    }
    return cc;
}

```

## 3.4 Flood Fill

```

#include <vector>
#include <utility>
#include <queue>

using namespace std;

#define MAX_R 1000
#define MAX_C 1000

typedef pair<int,int> ii;
typedef vector<int> vi;
typedef vector<ii> vii;

int grid[MAX_R][MAX_C];
int dr[] = {-1,-1,-1,0,0,1,1,1};
int dc[] = {-1,0,1,-1,1,-1,0,1};

int iterativeFloodFill(int r, int c, int v1, int v2) {
    if(r >= 0 && r < MAX_R && c >= 0 && c < MAX_C && grid[r][c] == v1) {
        queue<int> q;
        q.push(r * MAX_C + c);
        int area = 0;
        while(!q.empty()) {
            int u = q.front(); q.pop();
            int inR = u / MAX_C;
            int inC = u % MAX_C;
            grid[inR][inC] = v2;
            area++;
            for(int i = 0; i < 4; i++) {
                int nr = inR + dr[i];
                int nc = inC + dc[i];
                if(nr >= 0 && nr < MAX_R && nc >= 0 && nc < MAX_C &&
                    grid[nr][nc] == v1) {
                    q.push(nr * MAX_C + nc);
                }
            }
        }
        return area;
    }
    return 0;
}

int recursiveFloodFill(int r, int c, int v1, int v2) {
    if(r >= 0 && r < MAX_R && c >= 0 && c < MAX_C && grid[r][c] == v1) {
        grid[r][c] = v2;
        int area = 1;
        for(int i = 0; i < 4; i++) {
            int nr = r + dr[i];
            int nc = c + dc[i];
            area += recursiveFloodFill(nr, nc, v1, v2);
        }
        return area;
    } else {
        return 0;
    }
}

```

## 3.5 Bipartite Graph Check

```

#include <vector>
#include <utility>
#include <queue>
#include <bitset>

using namespace std;

#define MAX_N 1000
#define NO_COLOR -1

typedef pair<int,int> ii;

```

```

typedef vector<int> vi;
typedef vector<ii> vii;

int V;
vector<vii> adjList;

bool isBipartite(int s) {
    queue<int> q;
    q.push(s);
    vi color(V, NO_COLOR);
    color[s] = 0;
    bool isBipartite = true;
    while(!q.empty() && isBipartite) {
        int u = q.front(); q.pop();
        for(int i = 0; i < (int)adjList[u].size(); i++) {
            ii v = adjList[u][i];
            if(color[v.first] == NO_COLOR) {
                color[v.first] = 1 - color[u];
                q.push(v.first);
            } else if(color[v.first] == color[u]) {
                isBipartite = false;
            }
        }
    }
    return isBipartite;
}

```

## 3.6 Edge Property Check

```

#include <cstdio>
#include <vector>
#include <utility>

using namespace std;

#define UNVISITED 1
#define VISITED 2
#define EXPLORED 3

typedef pair<int,int> ii;
typedef vector<int> vi;
typedef vector<ii> vii;

vector<vii> adjList;
vi dfs_parent;
vi dfs_num;

void dfs(int u) {
    dfs_num[u] = VISITED;
    for(int i = 0; i < (int)adjList[u].size(); i++) {
        ii v = adjList[u][i];
        if(dfs_num[v.first] == UNVISITED) {
            printf("Edge (%d,%d): Tree Edge\n", u, v.first);
            dfs_parent[v.first] = u;
            dfs(v.first);
        } else if(dfs_num[v.first] == VISITED) {
            if(v.first == dfs_parent[u]) {
                printf("Edge (%d,%d): Two-Way Edge\n", u, v.first);
            } else {
                printf("Edge (%d,%d): Back Edge\n", u, v.first);
            }
        } else {
            printf("Edge (%d,%d): Forward/Cross Edge\n", u, v.first);
        }
    }
    dfs_num[u] = EXPLORED;
}

```

## 3.7 Finding Articulation Points And Bridges

```

#include <vector>
#include <utility>
#include <bitset>

using namespace std;

#define MAX_N 1000

typedef pair<int,int> ii;
typedef vector<int> vi;
typedef vector<ii> vii;

vector<vii> adjList;

```

```

vi dfs_num, dfs_low, dfs_parent;
bitset<MAX_N> isArticulationPoint;

int dfsCtr = 0, V, children, dfsRoot;

void dfs(int u, vii &bridges){
    dfs_num[u] = dfs_low[u] = dfsCtr++;
    for(int i = 0; i < (int)adjList[u].size(); i++) {
        ii v = adjList[u][i];
        if(dfs_num[v.first] == -1) {
            dfs_parent[v.first] = u;
            dfs(v.first, bridges);
            if(u == dfsRoot) {
                children++;
            }

            dfs_low[u] = min(dfs_low[u], dfs_low[v.first]);
            if(dfs_num[u] <= dfs_low[v.first]) {
                isArticulationPoint.set(u);
            }

            if(dfs_num[u] < dfs_low[v.first]) {
                bridges.push_back(ii(u, v.first));
            }
        } else if(v.first != dfs_parent[u]) {
            dfs_low[u] = min(dfs_low[u], dfs_num[v.first]);
        }
    }
}

pair<vi, vii> findArticulationPointsAndBridges() {
    vii bridges;
    isArticulationPoint.reset();
    dfs_num.assign(V, -1);
    dfs_low.assign(V, -1);
    dfs_parent.assign(V, -1);
    for(int i = 0; i < V; i++) {
        if(dfs_num[i] == -1) {
            children = 0;
            dfsRoot = i;
            dfs(i, bridges);
            if(children > 1) {
                isArticulationPoint.set(i);
            } else {
                isArticulationPoint.reset(i);
            }
        }
    }

    vi artPoints;
    for(int i = 0; i < V; i++) {
        if(isArticulationPoint.test(i)) {
            artPoints.push_back(i);
        }
    }

    return pair<vi, vii>(artPoints, bridges);
}

```

### 3.8 Finding Strongly Connected Components

```

#include <vector>
#include <utility>
#include <bitset>
#include <stack>

using namespace std;

#define MAX_N 1000

typedef pair<int, int> ii;
typedef vector<int> vi;
typedef vector<ii> vii;

vector<vii> adjList;
vi dfs_num, dfs_low;
bitset<MAX_N> visited;

int dfsCtr = 0, V, scc;

void tarjan(int u, stack<int> &s){
    // printf("Tarjan(%d)\n", u);
    dfs_num[u] = dfs_low[u] = dfsCtr++;
    s.push(u);
    visited.set(u);
    for(int i = 0; i < (int)adjList[u].size(); i++) {
        ii v = adjList[u][i];
        if(dfs_num[v.first] == -1) {
            tarjan(v.first, s);
        }
    }
}

```

```

        if(visited.test(u)) {
            dfs_low[u] = min(dfs_low[u], dfs_low[v.first]);
        }

        if(dfs_low[u] == dfs_num[u]) {
            printf("SCC #%d:", ++scc);
            while(s.top() != u) {
                int temp = s.top();
                printf(" %d", temp);
            }
            printf(" %d\n", s.top());
            s.pop();
        }
    }

    int printAndCountSCCs() {
        scc = 0;
        visited.reset();
        stack<int> s;
        dfs_num.assign(V, -1);
        dfs_low.assign(V, -1);
        for(int i = 0; i < V; i++) {
            // printf("dfs_num[%d] = %d\n", i, dfs_num[i]);
            if(dfs_num[i] == -1) {
                tarjan(i, s);
            }
        }

        return scc;
    }
}

```

### 3.9 Single Source Shortest Path using Dijkstra's Algorithm

```

#include <vector>
#include <utility>
#include <queue>

using namespace std;

typedef pair<int, int> ii;
typedef vector<int> vi;
typedef vector<ii> vii;

#define INF 1000000000

int V;
vector<vii> adjList;

vi dijkstras(int s){
    vi dist(V, INF);
    priority_queue<ii, vii, greater<ii>> > q;
    q.push(s);
    dist[s] = 0;
    while(!q.empty()) {
        ii u = q.top(); q.pop();
        if(u.first > dist[u.second]) {
            continue;
        }
        for(int i = 0; i < (int)adjList[u.second].size(); i++) {
            ii v = adjList[u.second][i];
            if(dist[v.first] > dist[u.second] + v.second) {
                dist[v.first] = dist[u.second] + v.second;
            }
        }
    }

    return dist;
}

```

### 3.10 All Pairs Shortest Path using Floyd Warshall's Algorithm

```

#include <vector>

using namespace std;

typedef vector<int> vi;

#define INF 1000000000

int V;
vector<vi> adjMat;

vector<vi> dijkstras(int s){

```

```

for(int k = 0; k < V; k++)
    for(int i = 0; i < V; i++)
        for(int j = 0; j < V; j++)
            adjMat[i][j] = min(adjMat[i][j], adjMat[i][k] + adjMat[k][j]);

return adjMat;
}

```

## 3.11 Max Flow with Edmonds Karp Algorithm

```

#include <vector>
#include <bitset>
#include <queue>

using namespace std;

#define MAX_N 1000
#define INF 1000000000

typedef vector<int> vi;

class Edge {
public:
    int u, v, cap, rem;
    Edge(int _u, int _v, int _cap) : u(_u), v(_v), cap(_cap), rem(_cap) {}
};

int V, f, s, t;
vi p;
vector<vector<Edge*>> > adjList;
Edge *res[MAX_N][MAX_N];

void augment(int v, int minEdge) {
    // printf("augmenting %d\n", v);
    if(v == s) {
        f = minEdge;
    } else if(p[v] != -1) {
        augment(p[v], min(minEdge, res[p[v]][v]->rem));
        res[p[v]][v]->rem -= f;
        res[v][p[v]]->rem += f;
    }
}

int edmondsKarp(int source, int sink) {
    int mf = 0;
    s = source;
    t = sink;
    while(true) {
        f = 0;
        bitset<MAX_N> visited;
        queue<int> q;
        q.push(s);
        p.assign(V, -1);
        visited.set(s);
        while(!q.empty()) {
            int u = q.front(); q.pop();
            // printf("exploring %d\n", u);
            if(u == t) {
                break;
            } else {
                for(int i = 0; i < (int)adjList[u].size(); i++) {
                    Edge *e = adjList[u][i];
                    if(e->rem > 0 && !visited.test(e->v)) {
                        p[e->v] = u;
                        visited.set(e->v);
                        q.push(e->v);
                    }
                }
            }
        }
        augment(t, INF);
        if(f == 0) {
            break;
        }
        mf += f;
    }
    return mf;
}

typedef pair<int, int> ii;
typedef pair<int, ii> iii;

int main() {
    V = 7;
    adjList.assign(V, vector<Edge*>());
    /**

```

```

    * This is a sample graph.
    */
    vector<iii> edges;
    edges.push_back(iii(0, ii(1, 10)));
    edges.push_back(iii(0, ii(4, 10)));
    edges.push_back(iii(1, ii(2, 20)));
    edges.push_back(iii(2, ii(3, 10)));
    edges.push_back(iii(4, ii(1, 10)));
    edges.push_back(iii(2, ii(5, 5)));
    edges.push_back(iii(3, ii(6, 10)));
    edges.push_back(iii(5, ii(6, 10)));

    for(int i = 0; i < (int)edges.size(); i++) {
        /**
        * This is how to add an edge.
        */
        iii cur = edges[i];
        Edge *e = new Edge(cur.first, cur.second.first, cur.second.second);
        Edge *eRev = new Edge(cur.second.first, cur.first, 0);
        adjList[cur.first].push_back(e);
        adjList[cur.second.first].push_back(eRev);
        res[cur.first][cur.second.first] = e;
        res[cur.second.first][cur.first] = eRev;
    }
    printf("maxflow: %d\n", edmondsKarp(0, 6));
    return 0;
}

```

## 3.12 Max Flow with Dinic's Algorithm

```

#include <vector>
#include <bitset>
#include <queue>

using namespace std;

#define MAX_N 1000
#define INF 1000000000

typedef vector<int> vi;

class Edge {
public:
    int u, v, cap, rem;
    Edge(int _u, int _v, int _cap) : u(_u), v(_v), cap(_cap), rem(_cap) {}
};

int V, f, s, t;
vi p;
vector<vector<Edge*>> > adjList;
Edge *res[MAX_N][MAX_N];

void augment(int v, int minEdge) {
    // printf("augmenting %d\n", v);
    if(v == s) {
        f = minEdge;
    } else if(p[v] != -1) {
        augment(p[v], min(minEdge, res[p[v]][v]->rem));
        res[p[v]][v]->rem -= f;
        res[v][p[v]]->rem += f;
    }
}

int dinicMaxFlow(int source, int sink) {
    int mf = 0;
    s = source;
    t = sink;
    bool hasFlow = true;
    while(hasFlow) {
        vi dist(V, INF);
        queue<int> q;
        q.push(s);
        dist[s] = 0;
        while(!q.empty()) {
            int u = q.front(); q.pop();
            // printf("exploring %d\n", u);
            if(u == t) {
                break;
            } else {
                for(int i = 0; i < (int)adjList[u].size(); i++) {
                    Edge *e = adjList[u][i];
                    if(e->rem > 0 && dist[e->v] == INF) {
                        dist[e->v] = dist[u] + 1;
                        q.push(e->v);
                    }
                }
            }
        }
    }
}

```

```

    }
    hasFlow = false;
    while(true) {
        f = 0;
        bitset<MAX_N> visited;
        q = queue<int>();
        q.push(s);
        p.assign(V,-1);
        visited.set(s);
        while(!q.empty()) {
            int u = q.front(); q.pop();
            if(u == t) {
                break;
            } else {
                for(int i = 0; i < (int)adjList[u].size(); i++) {
                    Edge *e = adjList[u][i];
                    if(e->rem > 0 && !visited.test(e->v) && dist[e->v] ==
                        dist[u] + 1) {
                        p[e->v] = u;
                        visited.set(e->v);
                        q.push(e->v);
                    }
                }
            }
        }
        augment(t, INF);
        if( f == 0) {
            break;
        }
        mf += f;
        hasFlow = true;
    }
}

return mf;
}

typedef pair<int,int> ii;
typedef pair<int,ii> iiii;

int main() {
    V = 7;
    adjList.assign(V,vector<Edge*>());

    /**
     * This is a sample graph.
     */
    vector<iiii> edges;
    edges.push_back(iiii(0,ii(1,10)));

```

```

    edges.push_back(iiii(0,ii(4,10)));
    edges.push_back(iiii(1,ii(2,20)));
    edges.push_back(iiii(2,ii(3,10)));
    edges.push_back(iiii(4,ii(1,10)));
    edges.push_back(iiii(2,ii(5,5)));
    edges.push_back(iiii(3,ii(6,10)));
    edges.push_back(iiii(5,ii(6,10)));

    for(int i = 0; i < (int)edges.size(); i++) {
        /**
         * This is how to add an edge.
         */
        iiii cur = edges[i];
        Edge *e = new Edge(cur.first,cur.second.first,cur.second.second);
        Edge *eRev = new Edge(cur.second.first,cur.first,0);
        adjList[cur.first].push_back(e);
        adjList[cur.second.first].push_back(eRev);
        res[cur.first][cur.second.first] = e;
        res[cur.second.first][cur.first] = eRev;
    }
    printf("maxflow: %d\n",dinicsMaxFlow(0,6));
    return 0;
}

```

## 4 Combinatorics

## 5 Number Theory

## 6 Miscellaneous Mathematics

## 7 String Processing

## 8 Computational Geometry