EDS 212: Day 3, Lecture 1

Integration and differential equations - reading, understanding, solving numerically in R

August 7th, 2024

Integration fundamentals - initial conditions for particular solutions

If your lemonade stand makes \$200/yr, how much money do you make from your lemonade stand over 4 years?

Do you know how much **total** money you have in your bank account from the information above?

Big takeaway: We can know how much an amount *changes* without knowing the absolute amount in our bucket. But if we *want* to know the absolute amount, then we need an initial condition!

Integration blitz

Integration: A tool to get from rates back to amounts (e.g. $rac{df}{dx}
ightarrow f(x)$)

We can think of it as antiderivation.

- ullet If $f(x)=x^2$, then $rac{df}{dx}=2x$
- If $\frac{df}{dx}=2x$, then f(x)=?

Question: if you don't know the original function and only have an expression for the rate (slope), then from the slope can you know the exact solution?

One rule for practice: the power rule for integration

$$\int x^n dx = rac{x^{n+1}}{n+1} + C$$

Example: If
$$\frac{df}{dx}=3.8x^2-2.1$$
:

- a. Find a general expression for f(x)
- b. Given the initial condition f(1.4)=5.9, find the particular solution for f(x)

Introduction to differential equations & solving them

A **differential equation** is an equation containing a differential expression. So it describes rates, often related to a function containing our variables of interest.

For example:

$$\frac{df}{dt} = 3.2 - f(t)$$

is a differential equation because it contains both a the function f(t) and it's derivative, $\frac{df}{dt}$.

Differential equations: terms

Ordinary differential equation (ODE): Does not contain partial derivatives

$$\frac{df}{dt} = 3.2 - f(t)$$

• Partial differential equations (PDE): Does contain partial derivatives

$$\frac{\partial B}{\partial t} = \alpha B + 0.31x - 21.6$$

Order of an ODE

Order: The order of a differential equation is the highest order for any differential expression in the equation

Example:

$$rac{df}{dt} = 3.2 - f(t)$$
 is a first order ordinary differential equation

Example:

$$\frac{\partial^3 x}{\partial t^3} = 2x - 4.5 \frac{\partial x}{\partial t}$$
 is a third order partial differential equation

Practice:

Use the terms from the previous slide to describe the following different equations:

$$rac{\partial^2 f}{\partial x^2} = 1.4 imes 10^{-3} f(x) + 5.2$$

$$2.9t^2 - lpha B = rac{dB}{dt}$$

$$\frac{dC}{dt} = 4.1C - 8.0$$

Example: Lotka-Volterra (predator-prey) equations

Prey:
$$rac{dV}{dt} = rV - lpha VP$$

Predator:
$$\frac{dP}{dt} = \beta VP - qP$$

Where:

- ullet V is number of prey (e.g. rabbits)
- ullet P is number of predators (e.g. wolves)
- r, α, β, q are positive parameters

Thinking about differential equations: break it down

Instantaneous rate of change in prey population size:

$$\frac{dV}{dt} = rV - \alpha VP$$

Where:

- ullet V is number of prey (e.g. rabbits)
- ullet P is number of predators (e.g. wolves)
- r, α, β, q are positive parameters

What do the different pieces of the equation mean?

Interpretation of prey equation:

$$\frac{dV}{dt} = rV - \alpha VP$$

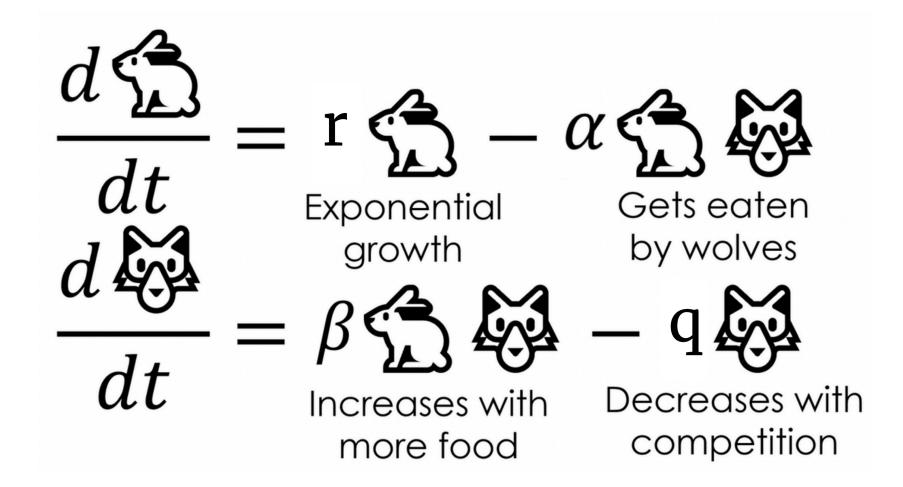
The pieces:

Interpretation of predator equation:

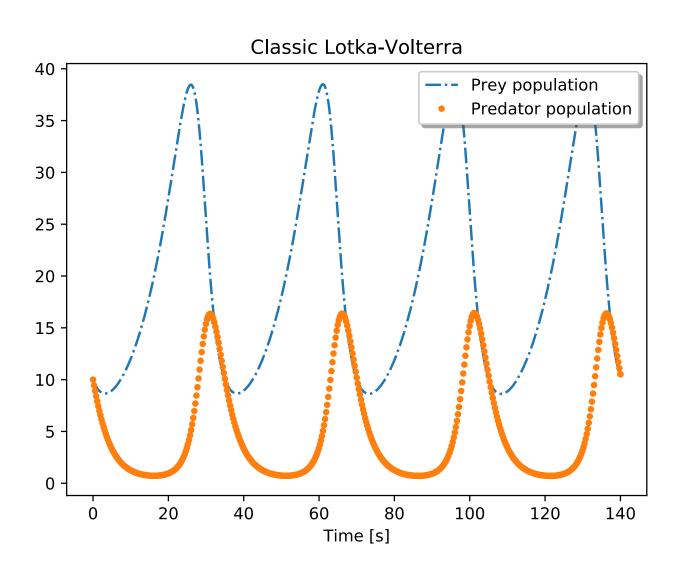
$$\frac{dP}{dt} = \beta VP - qP$$

The pieces:

Or, in pictures:



Finding V(t) and P(t)?



Some differential equations can be solved analytically:

$$\frac{dy}{dx} = y$$

Separate variables and integrate both sides:

$$\int \frac{1}{y} dy = \int 1 dx$$

Yielding:

$$ln(y) = x$$
 or $y = e^x$

Numerical solutions versus analytical solutions

"Differential equations textbooks are cookbooks that give you lots of suggestions about approaches, but there are lots of differential equations (DEs) that simply don't have analytic solutions — that is, solutions that you can write down. These equations can only be solved numerically..."

- Dr. Liz Bradley (CS, University of Colorado)

Solving differential equations numerically

Find *approximate* solutions to differential equations when finding an analytical solution would be really challenging (...which is pretty often).

Instead, computers can numerically approximate solutions by predicting nearby values based on the *slope*.

There are many methods for solving differential equations numerically. Here we'll just get a little flavor.

The general process (many methods) exist

From the expression for *slope* and using an initial condition & parameter estimates, start at one endpoint and incrementally calculate values of the solution from the slope expression until reaching the other endpoint.

This means that the approximate solution is found by approximating values of the solution at equal intervals of the independent variable (often, time).

Example: numerical approximation of DE solution

Let's say that we have a differential equation, $\frac{dP}{dt}=0.4P(0.5-P)$, and we don't know how to solve analytically for P(t). Using the initial condition P(0)=0.2, let's numerically estimate the solution.

We'll create a table that estimates P at increments of t based on an approximation of the slope estimate $\frac{dP}{dt}$. WHAT?

It's OK, follow along by hopping over the Interactive Session 3A (and afterwards, we'll learn how to use the {deSolve} package in R to make this process a lot easier).