## Step-1

We have to apply elimination with the extra column to reach Rx = 0 and Rx = d:

$$\begin{bmatrix} U & 0 \end{bmatrix} = \begin{bmatrix} 3 & 0 & 6 & \mathbf{0} \\ 0 & 0 & 2 & \mathbf{0} \\ 0 & 0 & 0 & \mathbf{0} \end{bmatrix}, \text{ and } \begin{bmatrix} U & c \end{bmatrix} = \begin{bmatrix} 3 & 0 & 6 & \mathbf{9} \\ 0 & 0 & 2 & \mathbf{4} \\ 0 & 0 & 0 & \mathbf{5} \end{bmatrix}$$

We have to find the solutions to Rx = 0 and Rx = d.

### Step-2

$$\begin{bmatrix} U & 0 \end{bmatrix} = \begin{bmatrix} 3 & 0 & 6 & \mathbf{0} \\ 0 & 0 & 2 & \mathbf{0} \\ 0 & 0 & 0 & \mathbf{0} \end{bmatrix}$$

Given that

$$\underline{R_1 - 3R_2} \begin{bmatrix} 3 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\frac{1}{2}R_2 \begin{bmatrix} 3 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

# Step-3

Now this is reduced row echelon form  $x_1, x_3$  are pivots,  $x_2$  is free variable.

$$\begin{bmatrix} 3 & 0 & 1 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$3x_1 = 0$$

$$x_3 = 0$$

$$\Rightarrow x_1=0, x_3=0$$

#### Step-4

Therefore

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ x_2 \\ 0 \end{bmatrix}$$
$$= x_2 \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$$

Therefore the solution to 
$$Rx = 0$$
 is 
$$\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$$

# Step-5

$$\begin{bmatrix} U & c \end{bmatrix} = \begin{bmatrix} 3 & 0 & 6 & 9 \\ 0 & 0 & 2 & 4 \\ 0 & 0 & 0 & 5 \end{bmatrix}$$
Now

$$\underline{R_1 - 3R_2} \begin{bmatrix} 3 & 0 & 0 & -3 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 5 \end{bmatrix}$$

$$\frac{1}{3}R_{1}\begin{bmatrix} 1 & 0 & 0 & -1\\ 0 & 0 & 1 & 2\\ 0 & 0 & 0 & 5 \end{bmatrix}$$

This is reduced row echelon form.

## Step-6

$$Rx = d$$

$$\Rightarrow \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -1 \\ 2 \\ 5 \end{bmatrix}$$

All entries last row in R are zeros, but in Rx = d last entry is 5, therefore there are no solutions for Rx = d.