Dept. of Math., SUSTech

Lecture 21

2022.04

Operators on Inner Product Spaces

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Positive Operators

7.31 **Definition** positive operator

An operator $T \in \mathcal{L}(V)$ is called *positive* if \underline{T} is self-adjoint and

$$\langle Tv, v \rangle \ge 0$$

for all $v \in V$.

If V is a complex vector space, then the requirement that T is

self-adjoint can be dropped from the definition above (by 7.15).

- 7.32 Example positive operators $V_{\text{subspace}} = V_{\text{vive}} = V_{\text{v$

 - (b) If $T \in \mathcal{L}(V)$ is self-adjoint and $b, c \in \mathbf{R}$ are such that $b^2 < 4c$, then $T^2 + bT + cI$ is a positive operator, as shown by the proof of 7.26.

Square Root

7.33 **Definition** square root

An operator R is called a *square root* of an operator T if $R^2 = T$.

7.34 **Example** If $T \in \mathcal{L}(\mathbf{F}^3)$ is defined by $T(z_1, z_2, z_3) = (z_3, 0, 0)$, then the operator $R \in \mathcal{L}(\mathbf{F}^3)$ defined by $R(z_1, z_2, z_3) = (z_2, z_3, 0)$ is a square root of T.

Characterizations of the Positive Operators

- Specifically, a complex number z is nonnegative if and only if it has a nonnegative square root, corresponding to condition (c).
- Also, z is nonnegative if and only if it has a <u>real square root</u>, corresponding to condition (d).
- **③** Finally, z is nonnegative if and only if there exists a complex number w such that $z = \bar{w}w$, corresponding to condition (e).

Characterizations of positive operators

7.35 Characterization of positive operators

Let $T \in \mathcal{L}(V)$. Then the following are equivalent:

(a) T is positive;

(a)
$$\Rightarrow$$
(b). $0 \le \langle Tv, v \rangle = \langle \lambda v, v \rangle = \lambda \langle v, v \rangle$

- (b) T is self-adjoint and all the eigenvalues of T are nonnegative; (b) \Rightarrow (c) \uparrow self-adjoint, all eigenvalues \geqslant 0
- (c) T has a positive square root; $T = R^2 + R$ positive V complex >7.
- (d) T has a self-adjoint square root; $Te_i = \lambda_i e_i$, $Te_i = \lambda_n e_n$ $Te_i = \lambda_n e_n$
- (e) there exists an operator $R \in \mathcal{L}(V)$ such that $T = R^*R$.

Proof.

We will prove that $(a) \Rightarrow (b) \Rightarrow (c) \Rightarrow (d) \Rightarrow (e) \Rightarrow (a)$.

Each positive operator has only one positive square root

Each nonnegative number has a unique nonnegative square root. The next result shows that positive operators enjoy a similar property.

TeX(V) positive $R^2=T$. R positive (unique) 7.36 Each positive operator has only one positive square root Every positive operator on V has a unique positive square root. $7 \times 10^{-10} \text{ V}_{\odot}$ eigenvector of T R square root of T V_1, V_2, \cdots, V_n orthonormal hairs $T_V = 10^{-10}, \lambda \ge 0$. $R_V = \sqrt{T_V}$. (positive) convicting of eigenvectors of T**Proof.** Suppose $T \in \mathcal{L}(V)$ is positive. Suppose $v \not\subset V$ is an eigenvector of >Tu= livi Tun= lin Vin *T*. Thus there exists $\lambda \geq 0$ such that $Tv = \lambda v$. >Rv.=J\(\bar{L}\v_1, \cdots, \Rv_n=J\(\bar{L}\n\)\u00f3\(\bar{L}\n\) Let *R* be a positive square root of *T*. We will prove that $Rv = \sqrt{\lambda}v$. This will imply that the behavior of R on the eigenvectors of T is uniquely determined. Because there is a basis of V consisting of eigenvectors of T (by the Spectral Theorem), this will imply that R is uniquely determined.

Proof

• To prove that $Rv = \sqrt{\lambda}v$, note that the Spectral Theorem asserts that there is an orthonormal basis e_1, e_2, \cdots, e_n of V consisting of eigenvectors of R. Because R is a positive operator, all its eigenvalues are nonnegative. Thus there exist nonnegative numbers $\lambda_1, \cdots, \lambda_n$ such that

$$Re_j = \sqrt{\lambda_j} e_j$$

for $j = 1, \dots, n$.

• Because e_1, e_2, \dots, e_n is an orthonormal basis of V, we can write

$$v = a_1 e_1 + \dots + a_n e_n$$

for some numbers $a_1, \dots, a_n \in \mathbb{F}$. Thus

$$Rv = a_1 \sqrt{\lambda_1} e_1 + \dots + a_n \sqrt{\lambda_n} e_n$$

and hence

$$\begin{array}{l}
\boxed{V = R^2 v = a_1 \lambda_1 e_1 + \dots + a_n \lambda_n e_n = \lambda V} \\
= \lambda [a_1 e_1 + \dots + a_n e_n]
\end{array}$$

Proof

But $R^2 = T$, and $Tv = \lambda v$. Thus the equation above implies

$$a_1\lambda e_1 + \cdots + a_n\lambda e_n = a_1\lambda_1e_1 + \cdots + a_n\lambda_ne_n.$$

The equation above implies that $a_j(\lambda - \lambda_j) = 0$ for $j = 1, 2, \dots, n$. Hence

$$v = \sum_{\{j: \lambda_j = \lambda\}} a_j e_j,$$

and thus

$$Rv = \sum_{\{j: \lambda_j = \lambda\}} a_j \sqrt{\lambda} e_j = \sqrt{\lambda} v$$
, as desired.

Remarks

- Some mathematicians also use the term positive <u>semidefinite</u> operator, which means the same as positive operator.
- ② A positive operator can have infinitely many square roots(although only one of them can be positive). For example, the identity operator on V has infinitely many roots if $\dim V > 1$.

Isometries

Operators that preserve norms are sufficiently important to deserve a name:

7.37 **Definition** *isometry*

• An operator $S \in \mathcal{L}(V)$ is called an *isometry* if

$$||Sv|| = ||v||$$

for all $v \in V$.

• In other words, an operator is an isometry if it <u>preserves norms</u>.

For example, λI is an isometry whenever $\lambda \in \mathbb{F}$ satisfies $|\lambda| = 1$. We will see soon that if $\mathbb{F} = \mathbb{C}$, then the next example includes all isometries.

λ, ..., λη. ||λi||=1.

7.38 **Example** Suppose $\lambda_1, ..., \lambda_n$ are scalars with absolute value 1 and $S \in \mathcal{L}(V)$ satisfies $Se_j = \lambda_j e_j$ for some orthonormal basis $e_1, ..., e_n$ of V. Show that S is an isometry. $V = \langle V, e_i \rangle e_i + ... + \langle V, e_n \rangle e_n$ $Se_i + ... + \langle V, e_n \rangle e_n$

Solution Suppose
$$v \in V$$
. Then
$$Sv = \langle v, e_i \rangle Se_i + \dots + \langle v, e_n \rangle Se_n$$

$$= \lambda_1 \langle v, e_i \rangle e_1 + \dots + \lambda_n \langle v, e_n \rangle e_n$$

7.39
$$v = \langle v, e_1 \rangle e_1 + \dots + \langle v, e_n \rangle e_n \quad b_0 \ge 0$$

and

7.40
$$||v||^2 = |\langle v, e_1 \rangle|^2 + \dots + |\langle v, e_n \rangle|^2$$
,

where we have used 6.30. Applying S to both sides of 7.39 gives

$$Sv = \langle v, e_1 \rangle Se_1 + \dots + \langle v, e_n \rangle Se_n$$

= $\lambda_1 \langle v, e_1 \rangle e_1 + \dots + \lambda_n \langle v, e_n \rangle e_n$.

The last equation, along with the equation $|\lambda_i| = 1$, shows that

7.41
$$||Sv||^2 = |\langle v, e_1 \rangle|^2 + \dots + |\langle v, e_n \rangle|^2$$
.

Comparing 7.40 and 7.41 shows that ||v|| = ||Sv||. In other words, S is an isometry.

Several Remarks

- The Greek word isos means equal; the Greek word metron means measure. Thus isometry literally means equal measure.
- The next result provides several conditions that are equivalent to being an isometry. The equivalence of (a) and (b) shows that an operator is an isometry if and only if it preserves inner products. The equivalence of (a) and (c) [or (d)] shows that an operator is an isometry if and only if the list of columns of its matrix with respect to every [or some] basis is orthonormal. Exercise 10 implies that in the previous sentence we can replace "columns" with "rows".

Characterization of Isometries

7.42 Characterization of isometries

Suppose $S \in \mathcal{L}(V)$. Then the following are equivalent:

- (a) S is an isometry;
- (b) $\langle Su, Sv \rangle = \langle u, v \rangle$ for all $u, v \in V$;
- (c) Se_1, \ldots, Se_n is orthonormal for every orthonormal list of vectors e_1, \ldots, e_n in V;
- (d) there exists an orthonormal basis e_1, \ldots, e_n of V such that Se_1, \ldots, Se_n is orthonormal;
- (e) $S^*S = I$;
- (f) $SS^* = I$;
- (g) S^* is an isometry;
- (h) S is invertible and $S^{-1} = S^*$.

Proof and Remarks

Proof.

$$(a)\Rightarrow (b)\Rightarrow (c)\Rightarrow (d)\Rightarrow (e)\Rightarrow (f)\Rightarrow (g)\Rightarrow (h)\Rightarrow (a).$$

Remarks:

- An isometry on a real inner product space is often called an orthogonal operator.
- An isometry on a complex inner product space is often called a unitary operator.
- We use the term isometry so that our results can apply to both real and complex inner product spaces.

Description of isometries when $\mathbb{F} = \mathbb{C}$

The previous result shows that every isometry is normal[see (a), (c), and (f) of 7.42]. Thus characterizations of normal operators can be used to give descriptions of isometries. We do this in the next result in the complex case and in Chapter 9 in the real case (see 9.36).

7.43 Description of isometries when $\mathbf{F} = \mathbf{C}$

Suppose V is a complex inner product space and $S \in \mathcal{L}(V)$. Then the following are equivalent:

- (a) S is an isometry.
- (b) There is an orthonormal basis of V consisting of eigenvectors of S whose corresponding eigenvalues all have absolute value 1.

Proof

Proof We have already shown (see Example 7.38) that (b) implies (a).

To prove the other direction, suppose (a) holds, so S is an isometry. By the Complex Spectral Theorem (7.24), there is an orthonormal basis e_1, \ldots, e_n of V consisting of eigenvectors of S. For $j \in \{1, \ldots, n\}$, let λ_j be the eigenvalue corresponding to e_j . Then

$$|\lambda_j| = \|\lambda_j e_j\| = \|Se_j\| = \|e_j\| = 1.$$

Thus each eigenvalue of S has absolute value 1, completing the proof.

Homework Assignment 21

7.C: 1, 2, 3, 7, 8, 9, 10, 11, 13, 14.