(7.24) Complex spectral Thm

IF= C. Thormal .TT = T\*T IF=IR. T self-adjoint operator V real owner product space Operators on Real Inner Product Spaces

eigenvalue?  $T(\underline{v_1}, \underline{v_2}) = (v_1, v_2) \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix}$ Thormal but not self-adjoint orthonormal Lecture 28 dim V = 2 TELLV) Dept. of Math., SUSTech

Keal Spectral Theorem (7.29)

2023.05

## Operators on Real Inner Product Spaces

- Normal Operators on Real Inner Product Spaces
- Isometries on Real Inner Product Spaces
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### Introduction

We now switch out focus to the context of inner product spaces. We will give a complete description of normal operators on real inner product spaces; a key step in the proof of this result (9.34) requires the result from the previous section that an operator on a finite-dimensional real vector space has an invariant subspace of dimension 1 or 2 (9.8).

After describing the normal operators on real inner product spaces, we will use that result to give a complete description of isometries on such spaces.

## Normal Operators on Real Inner Product Spaces

#### $(a) \Rightarrow (b) \Rightarrow (a)$ Theorem

(9.27) Suppose V is a 2-dimensional real inner product space and

- (a) T is normal but not self-adjoint.  $T \in \mathcal{L}(V)$ . Then the following are equivalent:  $|T \in \mathcal{L}(V)| = |T \cap V| = |T \cap V|$   $|T \cap V| = |T \cap V| = |T \cap V|$   $|T \cap V| = |T \cap V| = |T \cap V|$   $|T \cap V| = |T \cap V| = |T \cap V|$

(b) The matrix of T with respect to every orthonormal basis of V has the form  $\begin{pmatrix} 0 & 0 & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} \begin{pmatrix} a & b \\ b & a \end{pmatrix} \begin{pmatrix} a & b \\ \cos \theta & \cos \theta \end{pmatrix} \begin{pmatrix} a & b \\ c & d \end{pmatrix}$  with  $b \neq 0$ . with  $b \neq 0$ .

(c) The matrix of T with respect to some orthonormal basis of V has the form

$$\left(\begin{array}{cc} a & -b \\ b & a \end{array}\right)$$

with b > 0.

### Proof.

First suppose (a) holds, so that T is normal but not self-adjoint. Let  $e_1, e_2$  be an orthonormal basis of V. Suppose

$$\mathcal{M}(T,(e_1,e_2)) = \left( \begin{array}{cc} a & c \\ b & d \end{array} \right).$$

Then

$$||Te_1||^2 = a^2 + b^2$$
 and  $||T^*e_1||^2 = a^2 + c^2$ .

Because T is normal,  $||Te_1||^2 = ||T^*e_1||^2$  (See 7.20); thus these equations imply that  $b^2 = c^2$ . Thus c = b or c = -b. But  $c \neq b$ , because otherwise T would be self-adjoint, as can be seen from the matrix in 9.28.

Hence 
$$c = -b$$
, so

$$\mathscr{M}(T,(e_1,e_2)) = \left(\begin{array}{cc} a & -b \\ b & d \end{array}\right).$$

### Proof.

The matrix of  $T^*$  is the transpose of the matrix above. Use matrix multiplication to compute the matrices of  $TT^*$  and  $T^*T$  (do it now). Because T is normal, these two matrices are equal. Equating the entries in the upper-right corner of the two matrices you computed, you will discover that bd = ab. Now  $b \neq 0$ , because otherwise T would be self-adjoint, as can be seen from the matrix in 9.29. Thus d = a, completing the proof that (a) implies (b).

Now suppose (b) holds. We want to prove that (c) holds. Choose an orthonormal basis  $e_1, e_2$  of V. We know that the matrix of T with respect to this basis has the form give by (b), with  $b \neq 0$ . If b > 0, then (c) holds and we have proved that (b) implies (c).

### Proof.

If b<0, then, as you should verify, the matrix of T with respect to the orthonormal basis  $e_1,-e_2$  equals  $\begin{pmatrix} a & b \\ -b & a \end{pmatrix}$ , where -b>0; thus in this case we also see that (b) implies (c).

Now suppose (c) holds, so that the matrix of T with respect to some orthonormal basis has the form given in (c) with b>0. Clearly the matrix of T is not equal to its transpose (because  $b\neq 0$ ). Hence T is not self-adjoint. Now use the matrix multiplication to verify that the matrices of  $TT^*$  and  $T^*T$  are equal. We conclude that  $TT^* = T^*T$ . Hence T is normal. Thus (c) implies that (a), completing the proof.

# Normal operators and invariant subspaces

(9.8) invariant subspace U. dim U=1,2

7.28 9.30 Normal operators and invariant subspaces

Suppose V is an inner product space,  $T \in \mathcal{L}(V)$  is normal, and U is a subspace of V that is invariant under T. Then  $\operatorname{dim} V = n$ ,  $V = U \oplus U^{\perp}$ 

(a) 
$$U^{\perp}$$
 is invariant under  $T$ ;  $U$  or the normal basis  $e_1, e_2, \cdots, e_m$  of  $v \in \mathbb{R} = O_{m \times n}$ ; Extend  $e_1, \cdots, e_m$  to a basis  $e_1, \cdots, e_m$  from  $f_1$ 

U is invariant under  $T^*$ ; (b)

(c) 
$$(T|_U)^* = (T^*)|_U; T(e_1, \dots, e_m, f_1, \dots, f_n) = (e_1, \dots, e_m, f_1, \dots, f_n) = (A_{num}, B_{num}, e_1, \dots, e_n) = (A_{num}, e_1, \dots, e_n) = ($$

 $T|_{U} \in \mathcal{L}(U)$  and  $T|_{U^{\perp}} \in \mathcal{L}(U)$ 

$$\frac{1}{\sum_{j=1}^{m} ||Te_{j}||^{2}} = \sum_{j=1}^{m} \sum_{i=1}^{m} Q_{ij}^{2} \iff (T|_{U^{\perp}}) (T|_{U^{\perp}})^{*} = (T|_{U^{\perp}})^{*} (T|_{U^{\perp}})^{*}$$

$$(c) S = T|_{U}, v \in U$$

$$(c)$$

## Characterization of normal operators

### Characterization of normal operators when $\mathbf{F} = \mathbf{R}$

Suppose <u>V</u> is a real inner product space and  $T \in \mathcal{L}(V)$ . Then the following are equivalent:

- self-adjoint (7.29) T is normal. (a)
- There is an orthonormal basis of V with respect to which T has a block diagonal matrix such that each block is a 1-by-1 matrix or a  $\frac{\text{dim}V=2 (9.27)2'-\text{by-2 matrix of the form}}{\text{T[e_1, ..., e_n]}=/}$ dim V > 2  $V = U \oplus U^{\perp}$ important under  $T = \frac{4e}{b}$  (a - b), with b > 0. (dim U = 1 or 2)

with 
$$b > 0$$
. (dim  $U = 1$  or  $19.30$ )  $U^{\perp}$  is invariant under  $T$ 

(9.30) U' is invariant under T

## Isometries on Real Inner Product Spaces

9.35 **Example** Let  $\theta \in \mathbf{R}$ . Then the operator on  $\mathbf{R}^2$  of counterclockwise rotation (centered at the origin) by an angle of  $\theta$  is an isometry, as is geometrically obvious. The matrix of this operator with respect to the standard basis is

$$\left(\begin{array}{cc} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{array}\right).$$

If  $\theta$  is not an integer multiple of  $\pi$ , then no nonzero vector of  $\mathbf{R}^2$  gets mapped to a scalar multiple of itself, and hence the operator has no eigenvalues.

## Description of isometries when $\mathbb{F} = \mathbb{R}$

### 9.36 Description of isometries when $\mathbf{F} = \mathbf{R}$

Suppose V is a real inner product space and  $S \in \mathcal{L}(V)$ . Then the following are equivalent:

- (a) S is an isometry.
- (b) There is an orthonormal basis of V with respect to which S has a block diagonal matrix such that each block on the diagonal is a 1-by-1 matrix containing 1 or -1 or is a 2-by-2 matrix of the form

$$\left(\begin{array}{cc} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{array}\right),\,$$

with  $\theta \in (0, \pi)$ .

## Homework Assignment 28

9.B: 1, 2, 3, 4, 8.