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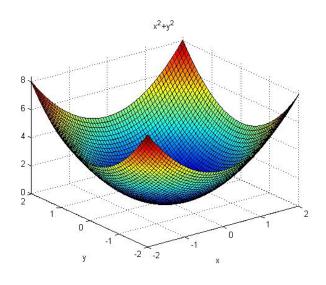
Positive Definite Matrices (正定矩阵)

6.1

MINIMA, MAXIMA AND SADDLE POINTS

(最小值、最大值和鞍点)

Definite vs. Indefinite Quadratic forms (二次型)



- □ The signs of the eigenvalues are often crucial.
- The new and highly important problem is to recognize a *minimum point*. This arises throughout science and engineering and every problem of optimization (优化).
- We will find a test that can be applied directly to *A*, which will *guarantee that all those eigenvalues are positive* (negative, ...).
- □ The test brings together three of the most basic ideas *pivots*, *determinants*, and *eigenvalues*.

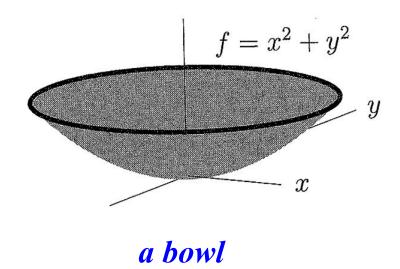
I. Definite vs Indefinite

Every quadratic form (二次型)

$$f(x,y) = ax^2 + 2bxy + cy^2$$

has a stationary point at the origin, where $\frac{\partial f}{\partial x} = \frac{\partial f}{\partial y} = 0$.

A local minimum *would* also be a global minimum. The surface z = f(x, y) will then be shaped like a bowl, resting on the origin.



When f(x, y) is *strictly positive* at all other points (the bowl goes up), it is called **positive definite** (正定), i.e.,

$$f(x,y) > 0, \ \forall (x,y) \neq (0,0).$$

I. Definite vs Indefinite

- **Question.** What conditions on a, b, and c ensure that the quadratic $f(x,y) = ax^2 + 2bxy + cy^2$ is positive definite?
- i) If f(x, y) is positive definite, then necessarily a > 0. (fix y = 0 and look in the x direction where $f(x, 0) = ax^2$)
- ii) If f(x, y) is positive definite, then necessarily c > 0. (fix x = 0 and look in the y direction where $f(0, y) = cy^2$)
- a > 0 and c > 0 do not guarantee that f(x, y) is always positive, a large cross term 2bxy can pull the graph below zero.
- For instance, $f(x, y) = x^2 10xy + y^2$.

Here a = 1 and c = 1 are both positive, but f is not positive definite, because f(1,1) = -8. The conditions a > 0 and c > 0 ensure that f(x,y) is positive on the x and y axes. But this function is negative on the line x = y, because b = -5 overwhelms a and c.

- **Question.** What conditions on a, b, and c ensure that the quadratic $f(x,y) = ax^2 + 2bxy + cy^2$ is positive definite?
- (continued) b > 0 does not guarantee that f(x, y) is always positive.

For instance, in $f(x, y) = 2x^2 + 4xy + y^2$, 2b = 4 > 0, this does not ensure a minimum, the sign of b is not important.

f does not have a minimum at (0,0) because f(1,-1) = 2-4+1=-1.

What really matters?

□ It is the size of b, compared to a and c, that must be controlled.

The simplest technique is to complete the square:

$$f(x,y) = ax^2 + 2bxy + cy^2 = a\left(x + \frac{b}{a}y\right)^2 + \left(c - \frac{b^2}{a}\right)y^2$$

- \Box (iii) If f(x, y) stays positive, then necessarily $ac > b^2$.
- The conditions a > 0 and $ac > b^2$ guarantee c > 0.

Question. What conditions on a, b, and c ensure that the quadratic $f(x, y) = ax^2 + 2bxy + cy^2$ is positive definite?

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□ Theorem (Test for a minimum).

 $ax^2 + 2bxy + cy^2$ is positive definite if and only if

$$a > 0$$
 and $ac > b^2$.

Remark (Test for a maximum). $O = f(x,y) = \alpha x^2 + 2bxy + cy^2$ has a maximum whenever -f has a minimum. $O = f(x,y) = -\alpha x^2 - 2bxy - cy^2$ 'e reverse the signs of a, b and c. $O = f(x,y) = -\alpha x^2 - 2bxy - cy^2$ $O = f(x,y) = -\alpha x^2 - 2bxy - cy^2$ $O = f(x,y) = -\alpha x^2 - 2bxy - cy^2$ $O = f(x,y) = -\alpha x^2 - 2bxy - cy^2$ $O = f(x,y) = -\alpha x^2 - 2bxy - cy^2$ $O = f(x,y) = -\alpha x^2 - 2bxy - cy^2$ $O = f(x,y) = -\alpha x^2 - 2bxy - cy^2$ $O = f(x,y) = -\alpha x^2 - 2bxy - cy^2$ $O = f(x,y) = -\alpha x^2 - 2bxy - cy^2$ $O = f(x,y) = -\alpha x^2 - 2bxy - cy^2$ $O = f(x,y) = -\alpha x^2 - 2bxy - cy^2$ $O = f(x,y) = -\alpha x^2 - 2bxy - cy^2$ $O = f(x,y) = -\alpha x^2 - 2bxy - cy^2$ $O = f(x,y) = -\alpha x^2 - 2bxy - cy^2$ $O = f(x,y) = -\alpha x^2 - 2bxy - cy^2$ $O = f(x,y) = -\alpha x^2 - 2bxy - cy^2$ f has a maximum whenever $\underline{-f}$ has a minimum.

We reverse the signs of a, b and c.

The quadratic form $ax^2 + 2bxy + cy^2$ is negative definite (负定) if $\Leftrightarrow f(x,y) < 0 \quad \forall (x,y) \neq (0,0)$ and only if a < 0 and $ac > b^2$.

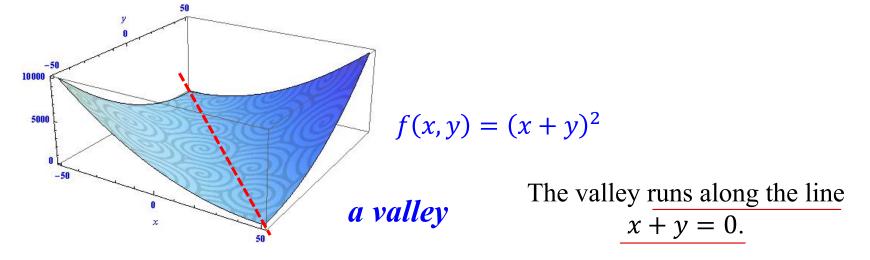
 \supset Singular case $ac = b^2$.

$$f = ax^2 + 2bxy + cy^2 = a\left(x + \frac{b}{a}y\right)^2 + \left(c - \frac{b^2}{a}\right)y^2 = a\left(x + \frac{b}{a}y\right)^2$$

The quadratic form is positive <u>semidefinite</u> (# \mathbb{E} \mathbb{E}) when a > 0.

The quadratic form is negative semidefinite (半负定) when a < 0.

- □ Remark.
- The prefix *semi* allows the possibility that f can equal zero, as it will at the point x = b, y = -a.
- □ The surface z = f(x, y) degenerates from a bowl into a valley.



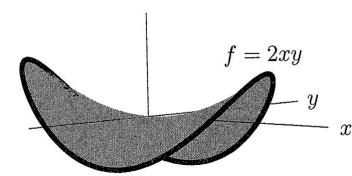
- □ Saddle Point $ac < b^2$.
- \square Example. Saddle points at (0,0)

$$f_1 = 2xy$$
 and $f_2 = x^2 - y^2$ and $ac - b^2 = -1$

In f_1 , b = 1 dominates a = c = 0.

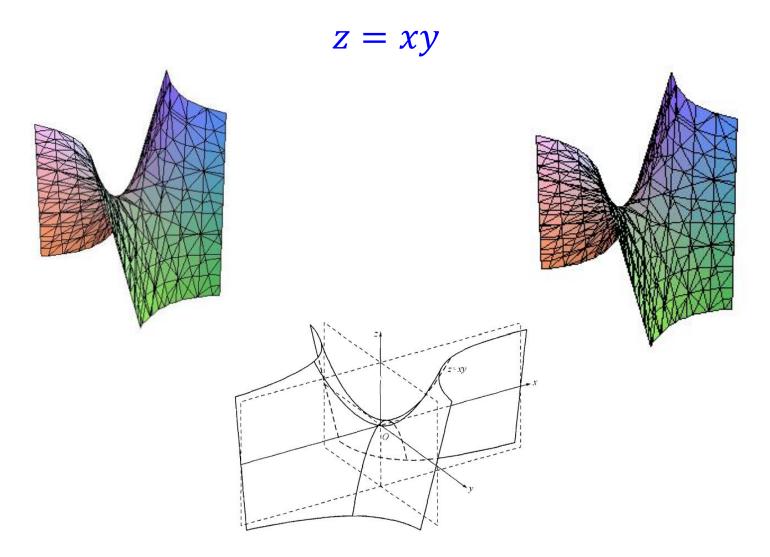
In f_2 , a = 1 and c = -1 have opposite sign.

- These quadratic forms are indefinite (不定), because they can take either sign. So we have a stationary point that is neither a maximum or a minimum. It is called a *saddle point* (鞍点).
- Remark. The saddles 2xy and $x^2 y^2$ are practically the same, if we turn one through 45° we get the other.



a saddle

Saddle (马鞍面)



https://www.geogebra.org/m/dftakvtm

II. Quadratic Forms (二次型) & Real Symmetric Matrices

A quadratic form $f(x, y) = ax^2 + 2bxy + cy^2$ comes directly from a symmetric 2 by 2 matrix A:

$$ax^2 + 2bxy + cy^2 = \begin{bmatrix} x & y \end{bmatrix} \begin{bmatrix} a & b \\ b & c \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = x^T A x$$

where
$$\mathbf{x} = \begin{bmatrix} x \\ y \end{bmatrix}$$
.

For example,
$$4x^2 + 2xy - 3y^2 = \begin{bmatrix} x & y \end{bmatrix} \begin{bmatrix} 4 & 1 \\ 1 & -3 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$
.

It generalizes immediately to n dimensions. (We will only discuss real case: \mathbb{R}^n)

When the variables are $x_1, ..., x_n$, they go into a column vector $\mathbf{x} = (x_1, ..., x_n)^T \in \mathbf{R}^n$.

For any real symmetric matrix \mathbf{A} , the product $\mathbf{x}^{\mathrm{T}}\mathbf{A}\mathbf{x}$ is a pure quadratic form $f(x_1, ..., x_n)$:

For any real symmetric matrix $\mathbf{A} \in \mathbf{R}^{n \times n}$, the product $\mathbf{x}^{\mathsf{T}} \mathbf{A} \mathbf{x}$ is a pure quadratic form $f(x_1, ..., x_n)$:

$$\begin{aligned} \mathbf{x}^{T} \mathbf{A} \mathbf{x} &= [x_{1} \quad x_{2} \quad \cdots \quad x_{n}] \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{bmatrix} \begin{bmatrix} x_{1} \\ x_{2} \\ \vdots \\ x_{n} \end{bmatrix} \\ &= \sum_{i=1}^{n} \sum_{j=1}^{n} a_{ij} x_{i} x_{j} \end{aligned}$$

$$=\sum_{i=1}^n \sum_{j=1}^n a_{ij} x_i x_j$$

(with
$$a_{ij} = a_{ji}$$
, i.e., $A = A^{T}$; $x = (x_1, ..., x_n)^{T} \in \mathbf{R}^n$)

The matrix A is called the matrix of the quadratic form.

For example,
$$f(x_1, x_2, x_3) = 2x_1^2 - 2x_1x_2 + 2x_2^2 - 2x_2x_3 + 2x_3^2$$
:

$$f = \begin{bmatrix} x_1 & x_2 & x_3 \end{bmatrix} \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}.$$

Example 1 Let

$$f(x_1, x_2, x_3, x_4) = 2x_1^2 + x_1x_2 + 2x_1x_3 + 4x_2x_4 + x_3^2 + 5x_4^2$$

The corresponding matrix for this quadratic form is

and matrix for this quadratic form is
$$A = \begin{bmatrix} 2 & \frac{1}{2} & 1 & 0 \\ \frac{1}{2} & 0 & 0 & 2 \\ 1 & 0 & 1 & 0 \\ 0 & 2 & 0 & 5 \end{bmatrix}$$

$$x_1x_2 + 4x_1x_3 - 10x_2x_3$$

$$\begin{bmatrix} 0 & 1 & 2 \\ 1 & 0 & -5 \\ 2 & -5 & 0 \end{bmatrix}$$

For

$$f(x_1, x_2, x_3) = 2x_1x_2 + 4x_1x_3 - 10x_2x_3$$

$$\begin{bmatrix} 0 & 1 & 2 \\ 1 & 0 & -5 \\ 2 & -5 & 0 \end{bmatrix}$$

$$f(x_1, x_2, x_3, x_4) = x_1^2 + 2x_2^2 - x_3^2 + 5x_4^2$$

$$\begin{bmatrix} 1 & & & & \\ & 2 & & & \\ & & -1 & & \\ & & 5 \end{bmatrix}$$

Definition 1 For a *real* quadratic form $f(x_1, x_2, \dots, x_n) = x^T A x$ in n variables, if $x^T A x > 0$ for $any \ x = (x_1, x_2, \dots, x_n)^T \neq \mathbf{0} \ (x \in \mathbf{R}^n)$, then $x^T A x$ is called a **positive definite quadratic form**, and the corresponding real symmetric matrix A is called a **positive definite matrix**.

如果 n 元实二次型 $f(x_1, x_2, \dots, x_n) = \mathbf{x}^T A \mathbf{x}$, $\forall \mathbf{x} = (x_1, x_2, \dots, x_n)^T \neq \mathbf{0} \ (\mathbf{x} \in \mathbf{R}^n), \ \text{恒有 } \mathbf{x}^T A \mathbf{x} > 0,$

就称 x^TAx 为正定二次型; 称实对称矩阵A为正定矩阵.

For example, $f(x, y, z) = x^2 + 4y^2 + 16z^2$

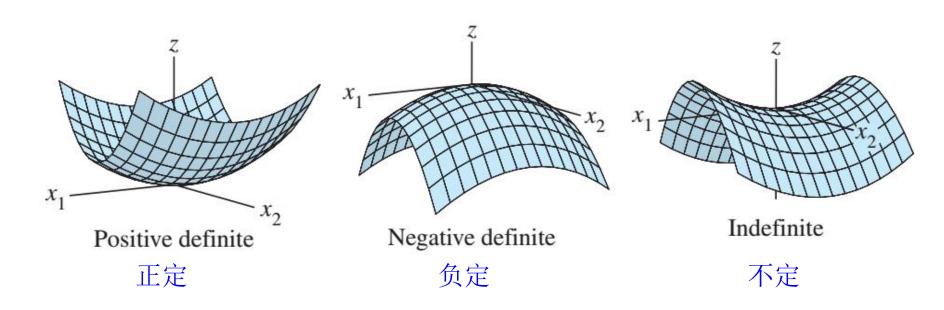
is a positive definite quadratic form.

1 4 16_

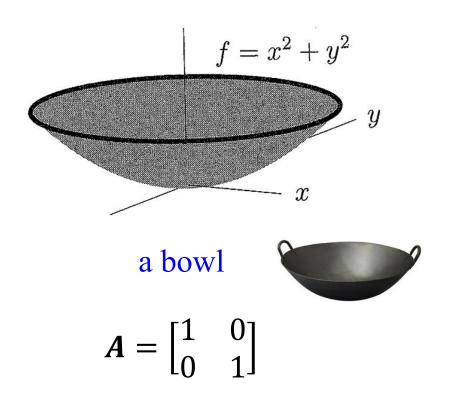
Check the eigenvalue, determinant, pivot, ...?

When \mathbf{A} is an $n \times n$ matrix, the quadratic form $f(\mathbf{x}) = \mathbf{x}^T \mathbf{A} \mathbf{x}$ is a real-valued function with domain \mathbf{R}^n .

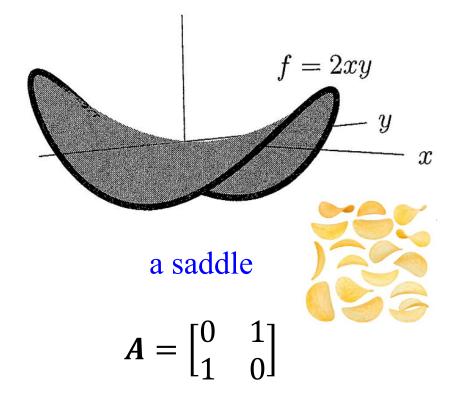
We distinguish several important classes of quadratic forms by the type of their values.



Graphs of quadratic forms



Positive definite (正定)



Indefinite (不定)

Which symmetric matrices have the property that $\mathbf{x}^T A \mathbf{x} > 0$ for all nonzero vectors \mathbf{x} ?

Key words:

Definite vs Indefinite Quadratic Forms and Real Symmetric Matrices

Homework

See Blackboard



