

# **Linear IV Regression Estimators for Structural Dynamic Discrete Choice Models**

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Standard dynamic discrete choice estimators may be biased due to

1. Unobservable state variables that are serially correlated, or correlated with observable state variables (endogeneity)<sup>1</sup>
2. Measurement error in observable state variables

In a reduced form world we would use IV to deal with these issues. How can we use these IV's in a structural model?

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<sup>1</sup>e.g. in Rust (1987) or Hotz and Miller (1993), the only unobservables are iid shocks.

- Euler equation in CCP (ECCP) method for estimating dynamic discrete choice models → we know how to do this for continuous choices (Hansen and Singleton, 1982).
- ECCP does not require stating how unobservable state variables evolve, and is robust to bias from measurement error or endogeneity.
- Recent papers have used this approach (Scott 2013, Diamond et al. 2018) but there hasn't been a comprehensive econometric treatment of the methodology.

- Agent  $i$  in market  $m$  at time  $t$  chooses an action  $a_{imt}$  to maximize discounted payoffs given the state

$$s_{imt} = \left( \underbrace{k_{imt}, w_{mt}}_{\text{observed}}, \underbrace{\eta_{mt}, \varepsilon_{imt}}_{\text{unobserved}} \right)$$

- Agents are small:  $i$ 's actions affect  $k_{imt}$  but not  $\omega_{mt} = (w_{mt}, \eta_{mt})$

$$F(s_{imt+1}|a, s_{imt}) = F^k(k_{imt+1}|a, k_{imt}, w_{mt})F^\omega(\omega_{mt+1}|\omega_{mt})F^\varepsilon(\varepsilon_{imt+1})$$

- Per period payoff includes unobservables other than iid errors

$$\Pi(a, s_{imt}) = \bar{\pi}(a, k_{imt}, w_{mt}) + \xi(a, k_{imt}, \omega_{mt}) + \varepsilon_{aimt}$$

## Value functions

$$V(s_{imt}) = \max_{a \in \mathcal{A}} \Pi(a, s_{imt}) + \beta E[V(s_{imt})|a, s_{imt}] \quad (\text{VF})$$

$$V(k_{imt}, \omega_{mt}) \equiv \int V(k_{imt}, \omega_{mt}, \varepsilon_{imt}) dF^\varepsilon(\varepsilon_{imt}) \quad (\text{EA})$$

$$v_a(k_{imt}, \omega_{mt}) = \pi(a, k_{imt}, \omega_{mt}) + \beta E[V(k_{imt+1}, \omega_{mt+1})|a, k_{imt}, \omega_{mt}] \quad (\text{C})$$

## Conditional choice probabilities

$$p_a(k, \omega) = \int 1\{v_a(k, \omega) + \varepsilon_a \geq v_j(k, \omega) + \varepsilon_j, \forall j \in \mathcal{A}\} dF^\varepsilon(\varepsilon) \quad (\text{CCP})$$

## Important relationships

$$v_a(k, \omega) - v_j(k, \omega) = \psi_a(p(k, \omega)) - \psi_j(p(k, \omega)) \quad (\text{HM Inversion})$$

$$V(k, \omega) - v_a(k, \omega) = \psi_a(p(k, \omega)) \quad (\text{AM Lemma})$$

With no unobservable states ( $\xi = 0$ ) we know how to estimate this:

1. Estimate CCP's directly from the data.
2. Choose a reference action  $j_r$  and set  $\pi(j_r, k, w) = 0 \forall (k, w)$  so that you can solve for  $v_{j_r}(k, w)$ .
3. Back out  $v_j(k, w) \forall j \neq j_r$  using the HM inversion.
4. Use conditional value functions to back out  $\pi(a, k, w; \theta)$ .
5. Estimate  $\theta$  using  $\pi(a, k, w; \theta)$ .

If we apply this method to a DGP where  $\xi \neq 0$  our estimates will be biased.

# Key assumptions

1. Rational expectations (RE): allows us to write expected values as their realization + a forecast error that is serially uncorrelated
2. Finite dependence (FD): allows future value functions to cancel out.
3. Instruments (IV) :  $E[\tilde{\xi}_{ajmt}|z_{mt}] = 0$  and  $E[\tilde{e}_{ajmt}^V|z_{mt}] = 0$

# Obtaining the ECCP equations

From Conditional VF + AM Lemma

$$\pi(a, k_{imt}, \omega_{mt}) = V(k_{imt}, \omega_{mt}) - \underbrace{\beta E[V(k_{imt+1}, \omega_{imt+1}) | a, k_{imt}, \omega_{imt}]}_{\text{realization + a forecast error under RE}} - \psi_a(k_{imt}, \omega_{mt})$$

In matrix form,

$$\pi_{amt} = V_{mt} - \psi_{amt} - \beta F_{amt}^k V_{mt+1} - \beta e_{am,t,t+1}^V \quad (\text{MF})$$

Taking differences wrt to another action  $j$  eliminates  $V_{mt}$

$$\underbrace{\psi_{jmt} - \psi_{amt}}_{\text{observable}} = \underbrace{\bar{\pi}_{amt} - \bar{\pi}_{jmt}}_{\text{observable}} + \underbrace{\xi_{amt} - \xi_{jmt} + \beta(e_{am,t,t+1}^V - e_{jm,t,t+1}^V)}_{\text{unobservable}} - \underbrace{\beta(F_{jmt}^k - F_{amt}^k)}_{\text{observable}} \underbrace{V_{mt+1}}_{\text{remove with FD}}$$



- Work recursively on MF using a renewal action  $J$ .

$$\begin{aligned}\pi_{amt} = & V_{mt} - \psi_{amt} - \beta e_{am,t,t+1}^V \\ & - \beta F_{amt}^k [\pi_{Jmt+1} + \beta F_{amt}^k E_{t+1}[V_{mt+2}] + \psi_{Jmt+1}]\end{aligned}$$

- Do the same for  $j$  and subtract from  $a \rightarrow V_{mt}$  and  $E_{t+1}[V_{mt+2}]$  will cancel since  $F_{amt}^k F_{jmt}^k = F_{jmt}^k F_{jmt}^k$  (due to FD). The ECCP is then,

$$\begin{aligned}\pi_{jmt} - \pi_{amt} + \beta(F_{jmt}^k - F_{amt}^k)\psi_{Jmt+1} = & \bar{\pi}_{amt} - \bar{\pi}_{jmt} - \beta(F_{jmt}^k - F_{amt}^k)\bar{\pi}_{Jmt+1} \\ & + u_{ajmt}\end{aligned}$$

$$\begin{aligned}\text{where } u_{ajmt} \equiv & \tilde{\xi}_{ajmt} + \tilde{e}_{ajmt}^V \\ \tilde{\xi}_{ajmt} \equiv & (\xi_{amt} - \xi_{jmt}) + \beta(F_{amt}^k - F_{jmt}^k)\xi_{Jmt+1} \\ \tilde{e}_{ajmt}^V = & \beta(e_{am,t,t+1}^V - e_{jm,t,t+1}^V)\end{aligned}$$

Two step implementation

1. Estimate  $\delta_{amt} = \{p_{amt}(k), F_{amt}^k(k'|k)\}$  nonparametrically
2. Use Step 1 results to construct  $u_{mt}(\theta, \delta_{mt})$  residually and use instruments  $z_{mt}$  to construct moment conditions.

$$E[h(z_{mt})u_{mt}(\theta, \delta_{mt})] = 0$$

# Durable goods application

- $a \in \{b, nb\}$ ,  $k \in \{0, 1\}$ ,  $w_{mt}$  = price,  $\xi_{mt}$  = unobserved quality

$$\pi(a, k_{imt}, \omega_{mt}) = \begin{cases} \theta_0 + \theta_1 w_{mt} + \xi_{mt} & \text{if } a = b \\ \theta_0 & \text{if } a = nb, k_{imt} = 1 \\ 0 & k_{imt} = 0 \end{cases}$$

- ECCP equation

$$\ln \left( \frac{p_b(0, \omega_{mt})}{p_{nb}(0, \omega_{mt})} \right) + \beta \ln \left( \frac{p_b(1, \omega_{mt+1})}{p_{nb}(0, \omega_{mt+1})} \right) = \theta_0 + \theta_1 w_{mt} + u_{mt}$$

where  $u_{mt} \equiv \xi_{mt} + \beta (e^V(1, \omega_{mt}, \omega_{mt+1}) - e^V(0, \omega_{mt}, \omega_{mt+1}))$

- Instrument for  $w_{mt}$  with a cost-shifter.
- Monte Carlo results show Standard CCP and ECCP OLS are biased, ECCP IV is not.

# Advantages and Limitations of ECCP

## Advantages

- Estimates are robust to endogeneity, as evident from MC results.
- Do not need to take a stand on how market level states evolve, and thus computationally light.
- The method can also leverage quasi-experimental data: instead of deriving a linear IV regression equation from the structural model, Diamond et al (2018) derive a diff-in-diff style equation to exploit a quasi-experiment.

## Limitations

- Agents must be atomistic → rules out precisely the questions that define IO as a field, but it may be useful for other fields.
- Since we do not take a stand on how market level states evolve, the type of counterfactuals we may carry out are limited.