weight corresponds to the jth node in the ith layer:

$$W_{j}^{\text{Ci}} = [W_{j_1}^{\text{Ci}}, W_{j_2}^{\text{Ci}}, \cdots, W_{j_{n'}}^{\text{Ci}}]$$

dimension of the previous layer

weights for the ith layer:

$$W^{(i)} = \begin{bmatrix} -w_1^{(i)} - \\ -w_2^{(i)} - \\ \vdots \\ -w_n^{(i)} - \end{bmatrix} \quad (n \times n')$$
dimension of the current layer

Multiple Training Examples

$$X = \begin{bmatrix} X_{(1)} & X_{(2)} & \cdots & X_{(M)} \\ \vdots & \vdots & \ddots & \vdots \\ & & & & \end{bmatrix} = V_{C0J}$$

$$\mathbf{z}_{ij} = \mathbf{M}_{ij} \mathbf{X} + \mathbf{p}_{ij}$$

$$\mathbf{z}_{ij} = \mathbf{Z}_{ij} \mathbf{n} \cdot \mathbf{z}_{ij} \mathbf{n} \cdot \mathbf{z}_{ij} \mathbf{n} \cdot \mathbf{n}$$

$$A^{\text{Ci}3} = \sigma(z^{\text{Ci}3}) = \begin{bmatrix} \alpha^{\text{Li}3}(1) & \alpha^{\text{Ci}3}(2) & \dots \\ 1 & 1 & 1 \end{bmatrix}$$

$$\alpha^{\text{Li}3} = \sigma(z^{\text{Ci}3}) = \begin{bmatrix} \alpha^{\text{Li}3}(1) & \alpha^{\text{Ci}3}(2) & \dots \\ 1 & 1 & 1 \end{bmatrix}$$

$$\alpha^{\text{Li}3}(1) = \begin{bmatrix} \alpha^{\text{Li}3}(1) & \alpha^{\text{Ci}3}(2) & \dots \\ \alpha^{\text{Li}3}(1) & \alpha^{\text{Ci}3}(2) & \dots \end{bmatrix}$$

$$\alpha^{\text{Li}3}(1) = \begin{bmatrix} \alpha^{\text{Li}3}(1) & \alpha^{\text{Ci}3}(2) & \dots \\ \alpha^{\text{Li}3}(1) & \alpha^{\text{Ci}3}(2) & \dots \end{bmatrix}$$

$$\alpha^{\text{Li}3}(1) = \begin{bmatrix} \alpha^{\text{Li}3}(1) & \alpha^{\text{Ci}3}(2) & \dots \\ \alpha^{\text{Li}3}(1) & \alpha^{\text{Ci}3}(2) & \dots \end{bmatrix}$$

$$\alpha^{\text{Li}3}(1) = \begin{bmatrix} \alpha^{\text{Li}3}(1) & \alpha^{\text{Ci}3}(2) & \dots \\ \alpha^{\text{Li}3}(1) & \alpha^{\text{Ci}3}(2) & \dots \end{bmatrix}$$

$$\alpha^{\text{Li}3}(1) = \begin{bmatrix} \alpha^{\text{Li}3}(1) & \alpha^{\text{Ci}3}(2) & \dots \\ \alpha^{\text{Li}3}(1) & \alpha^{\text{Ci}3}(2) & \dots \end{bmatrix}$$

$$\alpha^{\text{Li}3}(1) = \begin{bmatrix} \alpha^{\text{Li}3}(1) & \alpha^{\text{Ci}3}(2) & \dots \\ \alpha^{\text{Li}3}(1) & \alpha^{\text{Ci}3}(2) & \dots \end{bmatrix}$$

$$\alpha^{\text{Li}3}(1) = \begin{bmatrix} \alpha^{\text{Li}3}(1) & \alpha^{\text{Ci}3}(2) & \dots \\ \alpha^{\text{Li}3}(1) & \alpha^{\text{Ci}3}(2) & \dots \end{bmatrix}$$

$$\alpha^{\text{Li}3}(1) = \begin{bmatrix} \alpha^{\text{Li}3}(1) & \alpha^{\text{Ci}3}(2) & \dots \\ \alpha^{\text{Li}3}(1) & \alpha^{\text{Ci}3}(2) & \dots \end{bmatrix}$$

$$\alpha^{\text{Li}3}(1) = \begin{bmatrix} \alpha^{\text{Li}3}(1) & \alpha^{\text{Ci}3}(2) & \dots \\ \alpha^{\text{Li}3}(1) & \alpha^{\text{Ci}3}(2) & \dots \end{bmatrix}$$

$$\alpha^{\text{Li}3}(1) = \begin{bmatrix} \alpha^{\text{Li}3}(1) & \alpha^{\text{Ci}3}(2) & \dots \\ \alpha^{\text{Li}3}(1) & \alpha^{\text{Ci}3}(2) & \dots \end{bmatrix}$$

$$\alpha^{\text{Li}3}(1) = \begin{bmatrix} \alpha^{\text{Li}3}(1) & \alpha^{\text{Ci}3}(2) & \dots \\ \alpha^{\text{Li}3}(1) & \alpha^{\text{Ci}3}(2) & \dots \end{bmatrix}$$

$$\alpha^{\text{Li}3}(1) = \begin{bmatrix} \alpha^{\text{Li}3}(1) & \alpha^{\text{Ci}3}(2) & \dots \\ \alpha^{\text{Li}3}(1) & \alpha^{\text{Li}3}(2) & \dots \end{bmatrix}$$

Activation Functions 7 great for binary output

sigmoid:  $\alpha = \frac{1}{1+e^{-2}}$ , [0,1]

better hyperbolic tangent:  $\alpha = \tanh(z) = \frac{e^2 - e^{-2}}{e^2 + 0.7^2}$ , [-1,1]

( because it centers the data with a zero mean)

however, the gradient of the above two functions, becomes very small when Z-> 00 or -00.

I slow down gradient descent

derivative at z=0 is not defined, but no decreusing effect in gradient, thus faster training.

Leaky ReLU: a=max(0.012,2)



# Why do we need activation functions?

the NN will become a linear model

if we are performing regression, we might use linear activation function at the output layer.

#### Derivatives of Activation Functions

sigmoid: 
$$g(z) = \frac{1}{1+e^{-z}}$$

When 
$$z \rightarrow \infty$$
 or  $-\infty$ ,  $g'(z) \rightarrow 0$   
when  $z = 0$ ,  $g'(z) = \frac{1}{4}$ 

$$\tan h : g(z) = \frac{e^z - e^{-z}}{e^z + e^{-z}}$$

I when 
$$z \rightarrow \infty$$
 or  $-\infty$ ,  $g'(z) \rightarrow 0$   
when  $z = 0$ ,  $g'(z) = 1$ 

$$g(z) = \begin{cases} 0 & \text{if } z < 0 \\ 1 & \text{if } z > 0 \end{cases}$$
  
undefined  $z = 0$ 

$$g'(z) = \begin{cases} 0.01 & \text{if } z < 0 \\ 1 & \text{if } z > 0 \end{cases}$$
  
undefined  $z = 0$ 

#### Gradient Descent

## consider a 2-layer NN

• parameters : 
$$W^{E13}$$
  $(n^{E13}, n^{E03})$ 

•  $b^{E13}$   $(n^{E13}, 1)$ 

•  $W^{E23}$   $(n^{E23}, n^{E13})$ 

•  $b^{E23}$   $(n^{E23}, 1)$ 

• cost function :  $J = \frac{1}{m} \sum_{i=1}^{m} L(\hat{y}, y)$ 

## Gradient Descent:

initialize the parameters randomly (not zeros)

repeat { compute predictions 
$$\hat{y}^{[i]}$$
,  $\hat{y}^{[i]}$ ,...,  $\hat{y}^{[m]}$   
for i in 2: number of layers
$$dw^{[i]} \cdot db^{[i]}$$

$$w^{[i]} = w^{[i]} - ddw^{[i]}$$

$$b^{[i]} = b^{[i]} - ddb^{[i]}$$

## Forward Propagation:

$$Z^{E_{1}} = W^{E_{1}}X + b^{E_{1}}$$
 $A^{E_{1}} = g(Z^{E_{1}})$ 

$$Z^{[2]} = W^{[2]}A^{[1]} + b^{[2]}$$

$$A^{[2]} = g(Z^{[2]})$$

### Back Propagation:

$$dz^{[2]} = A^{[2]} - Y$$

$$dW^{[2]} = \frac{1}{m} dz^{[2]} \cdot A^{[1]T}$$

$$db^{[2]} = \frac{1}{m} \text{ np. sum} \left(dz^{[2]}, \underbrace{axis=1}_{\text{summing}}, \text{ keepdims=True}\right)$$

$$\underbrace{axis=1}_{\text{summing}}, \text{ horizontally}$$

$$dz^{E13} = \frac{W^{E23T} \cdot dz^{E23}}{n^{E13} \times m} \times \frac{g^{E13'}(z^{E13})}{element-wise} n^{E13} \times m$$

$$dW^{E13} = \frac{1}{m} dz^{E13} X^{T}$$

$$db^{E13} = \frac{1}{m} np. sum(dz^{E13}, axis=1, keepdims=True)$$

#### Random Initialization

if the weights are initialized to zeros, the hidden states become symmetric and the update in gradient descent becomes identical for all weights.

( making no difference)

$$W^{ij}$$
 = np. random. randn ( $(n^{ij}, n^{(i-1)})$ ) x 0.01  
 $b^{(i)}$  = np. zeros ( $(n^{(i)}, 1)$ )

we can
use zeros for b

we want small initial values

if weights are large we will have very small gradients (when we use sigmoid and tanh) which will slow down the training.