Deep Learning with Structured Data



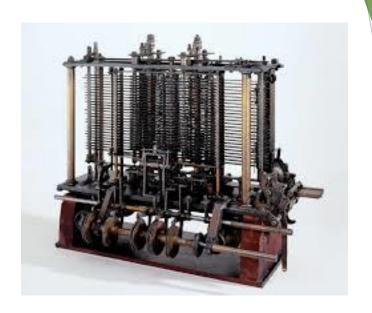
June 17, 2020

Mark Ryan



Introduction

- Hands-on follow on to Apr. 29 session
- Agenda:
 - ► Review environment & set up steps
 - Run training experiments for MNIST
 - Run training experiments for streetcar delay prediction model
 - Complete exercises that allow you to make your own updates to the model training and re-run training
 - Wrap up
- You'll learn how to:
 - ► Clone a repo into Drive and access its code in Colab
 - ► Train a simple deep learning model and assess the trained model's performance
 - ► Take advantage of the specialized hardware that is available in Colab



1

Review Environment



Google Drive:

- Target for repo clone
- Location of files used for training



Google Colaboratory (Colab):

- Environment for running notebooks
- Offers deep learning specific hw (GPUs and TPUs)



Repo directory structure:

```
2014 2019 df cleaned remove bad values may16 2020.pkl
    routedirection.csv
-models
-notebooks
    custom classes.py
    exercises streetcar model training.ipynb
    keras functional api mnist.ipynb
    keras sequential api mnist.ipynb
    streetcar model training.ipynb
    streetcar model training config.yml
-pipelines
```

Review Set Up Steps

- 1. Access Drive using Google ID
- 2. Create new folder in Drive and use Colab to clone repo into it https://github.com/ryanmark1867/dl_structured_data_hands_on
- 3. Open notebook from the repo in Colab
- 4. Mount Drive in notebook
- 5. Make /notebooks directory the current directory in the notebook

NOTE: Steps 3-5 can be reused for new Colab sessions or to work with new notebooks

Hands-on Gameplan

- 1. Run Keras sampler training notebooks:
 - keras_sequential_api_mnist.ipynb
 - keras_functional_api_mnist.ipynb
- 2. Run basic streetcar delay training notebook streetcar_model_training.ipynb
 - ▶ Start with config file streetcar_model_training_config.yml as-is to get a basic run
 - Update the runtime for the notebook to use a GPU
 - Re-run experiment 1
- Work through exercises in notebook exercises_streetcar_model_training



Experiment Summary

Experiment	Epochs	Early stop enabled?	Weight for "1" (delay) values	Early stop controls	
				monitor	mode
0	1	no	1.0	NA	NA
1	10	no	1.0	NA	NA
2	50	no	1.0	NA	NA
3	50	no	No delay / delay	NA	NA
4	50	yes	No delay / delay	Validation loss	min
5	50	yes	No delay / delay	Validation accuracy	max
9	20	yes	No delay / delay	Validation accuracy	max

► Control which experiment is run with the current_experiment parameter in the config file streetcar model training config.yml

```
test_parms:
    testproportion: 0.2 # proportion of data reserved for test set
    trainproportion: 0.8 # proportion of non-test data dedicated to training (vs. validation)
    current_experiment: 0
    repeatable_run: False # switch to control whether runs are repeated identically
    get test train acc: False # switch to control whether block to get test and train accuracy is after training
```

Monitoring Model Training Runs

Output of fit command (feedback on what's happening for each epoch):

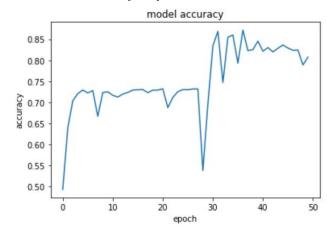
Output of evaluate (controlled by get test train acc parameter):

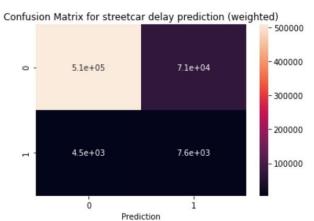
```
metrics names ['loss', 'accuracy', 'accuracy_1']
Train: 0.873, Test: 0.873
```

Output of %%time command:

Wall time: 12min 12s

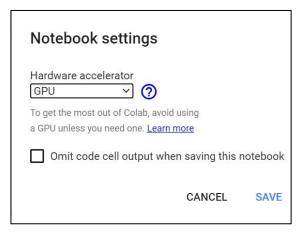
Results by epoch chart and confusion matrix:





Monitoring Model Training Runs

In Colab, you can request GPU/TPU by Runtime -> Change runtime type:



Once you have done that, run !nvidia-smi in a new cell to get details:

Wrap up

- Let Dragos know if you found this session useful and would like to have a hands-on session on model deployment
- Check out the book: <u>Deep Learning with</u> Structured Data
- Check out the full repo: https://github.com/ryanmark1867/deep_learn ing_for_structured_data
- Connect with me:

Image: brittanica.com

- LinkedIn: https://www.linkedin.com/in/mark-ryan-31826743/
- Medium: https://medium.com/@markryan_69718

