

Math 228B: Homework 2

1b): Using von Neumann analysis, show that the method

$$U_j^{n+1} = U_j^n + \frac{k\kappa}{2h^2} [U_{j-1}^n - 2U_j^n + U_{j+1}^n + U_{j-1}^{n+1} - 2U_j^{n+1} + U_{j+1}^{n+1}] - k\gamma[(1-\theta)U_j^n + \theta U_j^{n+1}]$$

for $\kappa, \gamma > 0$ is unconditionally stable if $\theta \geq 1/2$

Inspired by Plancharel's theorem we know that the stability of the method $U^{n+1} = AU^n$ depends on

$$\|U^{n+1}\|_2 \leq \|\hat{A}\|_\infty \|U^n\|_2$$

(since our stencil is a discrete convolution) where we take the Fourier transform in only space:

$$\hat{U}(\xi) = \sum_{j=-\infty}^{\infty} U_j e^{-ihj \cdot \xi}.$$

In particular

$$e^{-ih\xi} \hat{U}(\xi) = \sum_{j=-\infty}^{\infty} U_j e^{-ih(j+1) \cdot \xi} = \sum_{j'=-\infty}^{\infty} U_{j'-1} e^{-ihj' \cdot \xi}.$$

We see that in our example taking the Fourier transform of both sides

$$\hat{U}^{n+1} = \hat{U}^n + \frac{k\kappa}{2h^2} \left(e^{-ih\xi} \hat{U}^n - 2\hat{U}^n + e^{ih\xi} \hat{U}^n + e^{-ih\xi} \hat{U}^{n+1} - 2\hat{U}^{n+1} + e^{ih\xi} \hat{U}^{n+1} \right) - k\gamma \left((1-\theta)\hat{U}^n + \theta\hat{U}^{n+1} \right)$$

Collecting \hat{U}^{n+1}

$$\left(1 + \frac{k\kappa}{h^2} (1 - \cos(h\xi)) + k\gamma\theta \right) \hat{U}^{n+1} = \left(1 - \frac{k\kappa}{h^2} (1 - \cos(h\xi)) - k\gamma(1-\theta) \right) \hat{U}^n$$

so that

$$\hat{U}^{n+1} = \frac{1 - \frac{k\kappa}{h^2} (1 - \cos(h\xi)) - k\gamma(1-\theta)}{1 + \frac{k\kappa}{h^2} (1 - \cos(h\xi)) + k\gamma\theta} \hat{U}^n$$

Now each term in the denominator is positive (as long as we keep h and k positive) and for $\theta \geq 1/2$, we get

$$|1 - \theta| = \left| \frac{1}{2} + \frac{1}{2} - \theta \right| \leq \left| \frac{1}{2} \right| + \left| \frac{1}{2} - \theta \right| = \frac{1}{2} + \theta - \frac{1}{2} = \theta.$$

Note that equality holds *only* when $\theta = 1/2$. Then by the triangle inequality and the positivity of the denominator

$$\left| \frac{1 - \frac{k\kappa}{h^2} (1 - \cos(h\xi)) - k\gamma(1-\theta)}{1 + \frac{k\kappa}{h^2} (1 - \cos(h\xi)) + k\gamma\theta} \right| \leq \frac{1 + \frac{k\kappa}{h^2} (1 - \cos(h\xi)) + k\gamma|1-\theta|}{1 + \frac{k\kappa}{h^2} (1 - \cos(h\xi)) + k\gamma\theta} \leq 1$$

Now, Lax-Richtmyer stability demands that $\left\| \hat{A}(k)^n \right\|_{\infty} \leq C_T$ for all $k > 0$ and n such that $kn \leq T$ (where T is the final time). Since our symbol is bounded by 1 we can set $C_T = 1$ and get our stability independent of the final time T !

1c): Show that if $\theta = 0$ then the method is stable provided $k \leq 2/\gamma$

We use our expression from the previous problem:

$$\hat{U}^{n+1} = \frac{1 - \frac{k\kappa}{h^2}(1 - \cos(h\xi)) - k\gamma(1 - \theta)}{1 + \frac{k\kappa}{h^2}(1 - \cos(h\xi)) + k\gamma\theta} \hat{U}^n = \frac{1 - \frac{k\kappa}{h^2}(1 - \cos(h\xi)) - k\gamma}{1 + \frac{k\kappa}{h^2}(1 - \cos(h\xi))} \hat{U}^n$$

Again we check the L^{∞} norm of the symbol, checking that n th powers of the symbol are bounded for all k sufficiently small, whenever $kn < T$.

If $0 \leq k \leq 2/\gamma$ we see that

$$-1 = 1 - 2 \leq 1 - k\gamma \leq 1$$

so that $|1 - k\gamma| \leq 1$ and

$$\left| \frac{1 - \frac{k\kappa}{h^2}(1 - \cos(h\xi)) - k\gamma}{1 + \frac{k\kappa}{h^2}(1 - \cos(h\xi))} \right| \leq \frac{|1 - k\gamma| + \frac{k\kappa}{h^2}(1 - \cos(h\xi))}{1 + \frac{k\kappa}{h^2}(1 - \cos(h\xi))} \leq 1$$

which shows stability in the same way as before.

2a): Consider the *skewed leapfrog* method for solving $u_t + au_x = 0$ with $a > 0$:

$$U_j^{n+1} = U_{j-2}^n - \left(\frac{ak}{h} - 1 \right) (U_j^n - U_{j-2}^n).$$

What is the order of accuracy of this method?

We calculate the local truncation error by plugging in a true solution to the equation and Taylor expanding. Notice that there is an ambiguity in the scheme (multiplying everything by k for instance gives the same scheme.) To remedy this we will study $\|u - U\|_2$ below.

First we calculate the local truncation error:

$$\begin{aligned} \tau_j^n &= u(x_j, t_n + k) - u(x_j - 2h, t_n - k) + \left(\frac{ak}{h} - 1 \right) (u(x_j, t_n) - u(x_j - 2h, t_n)) \\ &= u + ku_t + \frac{1}{2}k^2u_{tt} + \mathcal{O}(k^3) \\ &\quad - u + 2hu_x + ku_t - \frac{1}{2}4h^2u_{xx} - 2khu_{xt} - \frac{1}{2}k^2u_{tt} + \mathcal{O}((h+k)^3) \\ &\quad + \left(\frac{ak}{h} - 1 \right) (u - u + 2hu_x - \frac{1}{2}4h^2u_{xx} + \mathcal{O}(h^3)) \\ &= 2k(u_t + au_x) - 2kh(u_{xt} + au_{xx}) + \mathcal{O}((k+h)^3) = \mathcal{O}((k+h)^3) \end{aligned}$$

We analyze the error with the benefit of having already completed the third part which makes A in

$$U^{n+1} = AU^n$$

bounded as an operator on ℓ^2 (given $h \approx k$) so that we have something like

$$u^N - U^N = A^N U^1 + \sum A^{N-k} \tau^n$$

$\|A^{N-k}\|_2$ doesn't grow as we change h and k , however, the number of τ terms grows like $1/k$, so that (for $h \approx k$) the method only works out to be second order!

2b): For what range of Courant number ak/h does this method satisfy the CFL condition?

To satisfy the CFL condition we recognize that at position x and time t the true solution (which will look like $f(x - at)$) depends, at time $t - k$, only the value at $x - ak$. So we need $x - ak$ to be contained in our method for the value of U_j^{n+1} (so that it has a chance to interpolate). In other words we need

$$x - 2h \leq x - ak \leq x$$

or

$$0 \leq ak/h \leq 2$$

2c): Show that the method is in fact stable for this range of Courant numbers.

We take the fourier transform in space as in the last problem and assume that there is a functional relationship $\hat{U}^{n+1} = g(\xi)\hat{U}^n$ and see if we can solve for $g(\xi)$

$$g(\xi)^2 \hat{U}^{n-1} = e^{-2ih\xi} \hat{U}^{n-1} - \left(\frac{ak}{h} - 1 \right) (g(\xi) \hat{U}^{n-1} - g(\xi) e^{-2ih\xi} \hat{U}^{n-1})$$

so that

$$g(\xi)^2 + (ak/h - 1)(1 - e^{-2ih\xi})g(\xi) - e^{-2ih\xi} = g^2(\xi) + 2ie^{-ih\xi}(ak/h - 1) \sin(h\xi)g(\xi) - e^{-2ih\xi} = 0$$

We get two solutions

$$g(\xi) = -ie^{-ih\xi}(ak/h - 1) \sin(h\xi) \pm e^{-ih\xi} \sqrt{1 - (ak/h - 1)^2 \sin^2(h\xi)}.$$

Since $|ak/h - 1| \leq 1$, the square root is real! Thus the length of $g(\xi)$ is the sum of the squares of the real and imaginary parts (after dividing through by $e^{-ih\xi}$ which is of length 1)

$$|g(\xi)|^2 = (ak/h - 1)^2 \sin^2(h\xi) + 1 - (ak/h - 1)^2 \sin^2(h\xi) = 1$$

Note that choosing g to be one of these roots corresponds to choosing exactly how we set up the initial condition: there are only two choices that result in the next time step depending only on the previous by a multiplier. To analyze the other ones a more complex recursion relation needs to be analyzed.

In these two cases though, we get convergence!


```

    for i in (1:len)
        row = umap(i)
        push!(LHS, (row, umap(i-1), 1.0))
        push!(LHS, (row, umap(i), 4.0))
        push!(LHS, (row, umap(i+1), 1.0))

        push!(RHS, (row, umap(i+1), 3.0))
        push!(RHS, (row, umap(i-1), -3.0))
    end
    LHS = sparse((x->x[1]).(LHS), (x->x[2]).(LHS), (x->x[3]).(LHS), len, len)
    RHS = sparse((x->x[1]).(RHS), (x->x[2]).(RHS), (x->x[3]).(RHS), len, len)
    _div_memo[len] = (LHS,RHS)
    return LHS, RHS
end

```

3c): Write a compact filter

```

"""
    Computes a compact filter on u with parameter alpha in 2D by applying to the
    x and y directions independently. This is achieved by calculating the normal
    matrices and then computing the kronecker product: a representation of the tensor
    product in the usual x first then y ordered basis

    We have optional arguments for the size of x and y grid sizes to be different. Spe
    (x size) * ymul = (y size) * xmul, so that if we want twice as many xs as ys set
    xmul/ymul = 2
"""
function compact_filter(u, alpha; xmul::Int64=1, ymul::Int64=1)
    xlen = isqrt(div(size(u)[1]*xmul, ymul))
    ylen = div(size(u)[1], xlen)
    xI = sparse(Matrix{1.0I},xlen,xlen)
    yI = sparse(Matrix{1.0I},ylen,ylen)
    xLHS, xRHS = compact_filter_matrices(xlen, alpha)
    yLHS, yRHS = compact_filter_matrices(ylen, alpha)
    return kron(yLHS, xLHS) \ (kron(yRHS, xRHS) * u)
end

const _filter_memo = Dict{()
function compact_filter_matrices(len::Int64, alpha, xmul::Int64=1, ymul::Int64=1)
    if (len,alpha) in keys(_filter_memo)
        return _filter_memo[(len, alpha)]
    end

```

```

    ext = [len-1:len; 1:len ; 1:2]
    a = 5.0/8.0 + 3.0*alpha/4.0
    b = alpha + 1.0/2.0
    c = alpha/4.0 - 1.0/8.0
    umap(i) = ext[i+2]

    LHS = Tuple{Int64, Int64, Float64}[]
    RHS = Tuple{Int64, Int64, Float64}[]
    for i in (1:len)
        row = umap(i)
        push!(LHS, (row, umap(i-1), alpha))
        push!(LHS, (row, umap(i), 1.0))
        push!(LHS, (row, umap(i+1), alpha))

        push!(RHS, (row, umap(i), a))
        push!(RHS, (row, umap(i+1), b/2.0))
        push!(RHS, (row, umap(i-1), b/2.0))
        push!(RHS, (row, umap(i+2), c/2.0))
        push!(RHS, (row, umap(i-2), c/2.0))
    end
    LHS = sparse((x->x[1]).(LHS), (x->x[2]).(LHS), (x->x[3]).(LHS), len, len)
    RHS = sparse((x->x[1]).(RHS), (x->x[2]).(RHS), (x->x[3]).(RHS), len, len)
    _filter_memo[(len, alpha)] = (LHS,RHS)
    return LHS, RHS
end
end

```

3d): Write the euler right side

```

function euler_rhs(r, ru, rv, rE, h)
    Frx, Fry, Frux, Fruy, Frvx, Frvy, FrEx, FrEy = euler_fluxes(r, ru, rv, rE)
    Fx = hcat(Frx, Frux, Frvx, FrEx)
    Fy = hcat(Fry, Fruy, Frvy, FrEy)
    return (-compact_div(Fx, Fy, h)[: ,i] for i in (1:4))
end

```

3e):

```

function euler_rh4step(r, ru, rv, rE, h, k, alpha)
    f(u) = stack(euler_rhs(u[: ,1], u[: ,2], u[: ,3], u[: ,4], h))
    return [compact_filter(rk4(hcat(r,ru,rv,rE), f, k), alpha)[: ,i] for i in (1:4)]
end

```

```

function rk4(u, f, k)
    du1 = f(u)

```

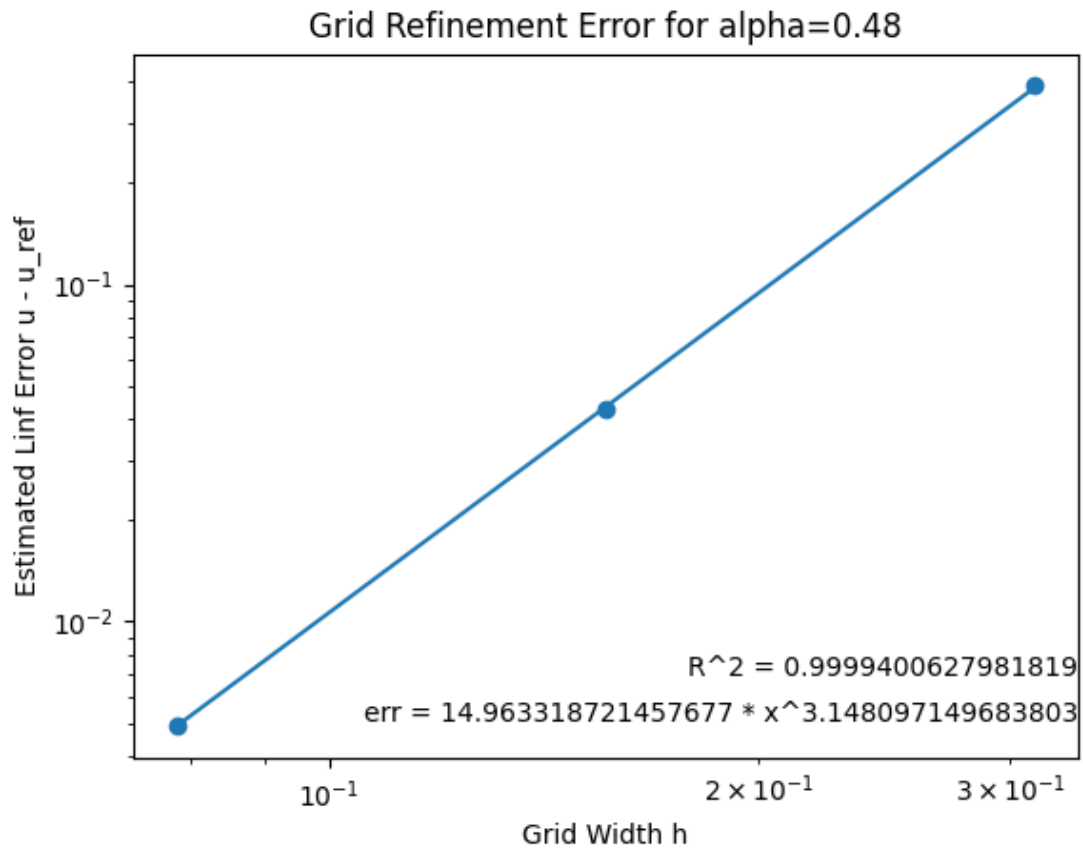
```

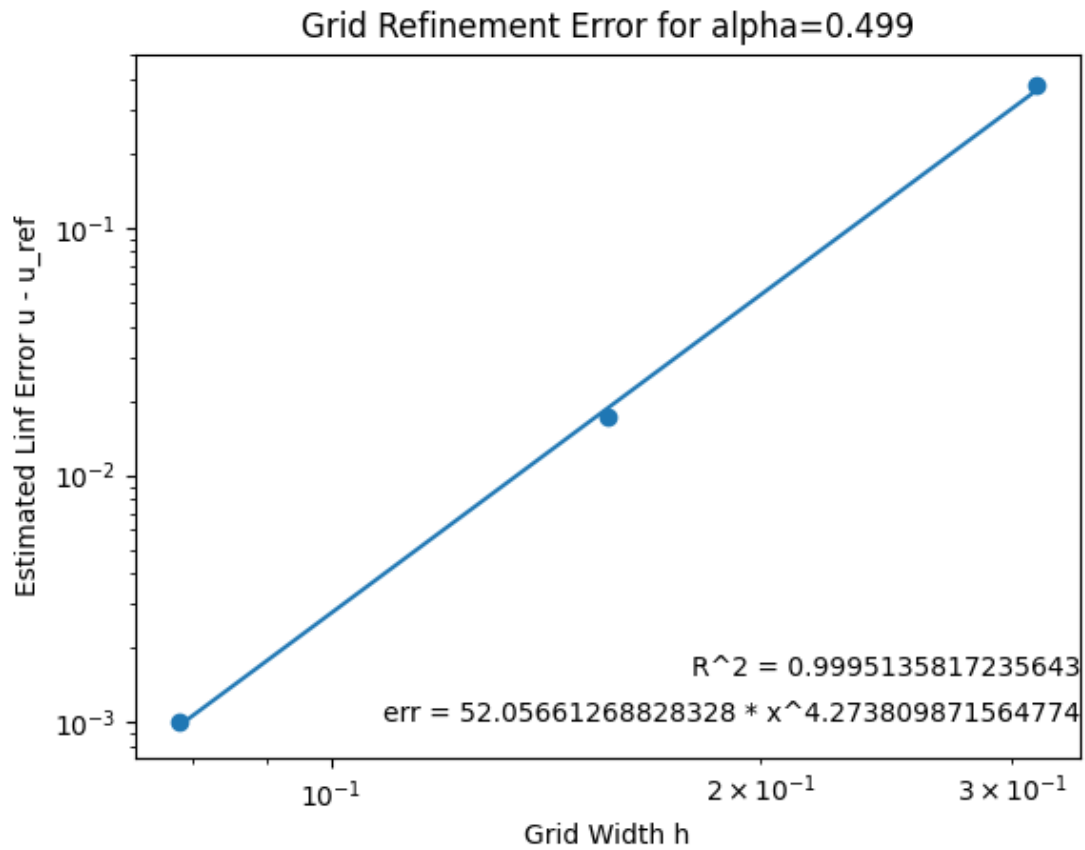
    du2 = f(u + (k/2.0)*du1)
    du3 = f(u + (k/2.0)*du2)
    du4 = f(u + k*du3)
    return u + (k/6.0)*(du1 + 2*du2 + 2*du3 + du4)
end

```

3f): Make error plots against the given euler vortex exact solution

Here is a plot of the L^∞ error to the true solution in space and time up to time $2\sqrt{5}$





3g): Kelvin Helmholtz instability

I think the plot is making 2 white for some reason? Not going to change it now though.

