

Angular Momentum

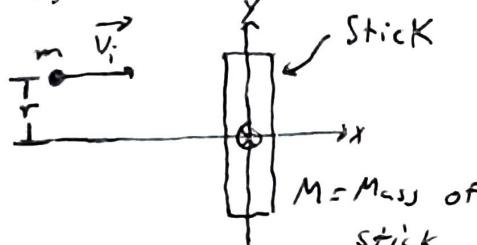
$$\vec{\tau} = \vec{r} \times \vec{F} \quad \vec{F} = \frac{d\vec{p}}{dt}$$

$$\vec{\tau} = \vec{r} \times \frac{d\vec{p}}{dt} = \frac{d}{dt}(\vec{r} \times \vec{p}) \quad \boxed{\vec{L} = \vec{r} \times \vec{p}}$$

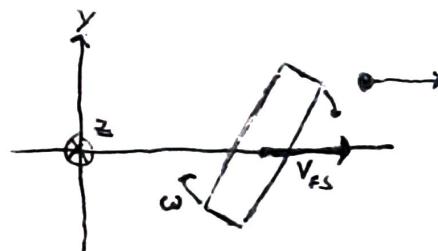
$$\boxed{\vec{\tau} = \frac{d\vec{L}}{dt}}$$

Ex: What is the final velocity of the particle (v_f), the final velocity and final angular velocity of the stick (v_{fs} , ω)?

Before:



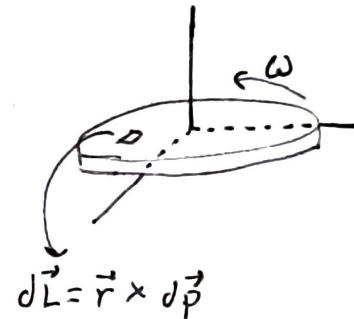
After:



3 equations, 3 unknowns

$$v_f = \frac{I(m-M) + mMr^2}{I(m+M) + mMr^2} v_i$$

$$v_{fs} = \frac{2Im}{I(m+M) + mMr^2} v_i$$



$$d\vec{L} = \vec{r} \times d\vec{p}$$

$$dL = r(dm)v \quad v = r\omega$$

$$dL = rdm r\omega$$

$$dL = \omega r^2 dm$$

$$L = \int \omega r^2 dm = \omega \int r^2 dm$$

$$\boxed{L = I\omega}$$

$$\Delta P = 0 \quad P_i = P_f$$

$$m\vec{v}_i = m\vec{v}_f + M\vec{v}_{fs}$$

$$\Delta L = 0 \quad L_i = L_f$$

$$\vec{r} \times \vec{p}_i = \vec{r} \times \vec{p}_f + I\vec{\omega}$$

$$rm\hat{v}_i \hat{z} = rm\hat{v}_f \hat{z} + I\hat{\omega} \hat{z}$$

$$\Delta K = 0 \quad k_i = k_f$$

$$\frac{1}{2}mv_i^2 = \frac{1}{2}mv_f^2 + \frac{1}{2}Mv_{fs}^2 + \frac{1}{2}I\omega^2$$

$$\omega = \frac{2mMr}{I(m+M) + mMr^2} v_i$$