

Ryan Punamiya

CONTACT INFORMATION	4th Year Undergraduate Student @ Georgia Tech Advised by Danfei Xu and Judy Hoffman LinkedIn Website E-mail: rpunamiya6@gatech.edu
RESEARCH INTERESTS	My research is centered at the intersection of machine learning, computer, vision and robotics. I am interested by how we can maximize transfer from scalable human data for robot learning. Additionally, I am also interested in finding better ways of making vision, language, and action interact within robot learning.
RESEARCH EXPERIENCE	<div>Georgia Institute of Technology Atlanta, GAAug 2023 – Present</div> <div>Research with Danfei Xu and Judy Hoffman</div> <div>Domain adaptation from egocentric human video to robots for scalable and generalizable robot learning. Also exploring language steering and vision-language-action alignment within large foundation models for robotics.</div>
EDUCATION	<div>Georgia Institute of TechnologyAug 2022 – Present</div> <div>Bachelor of Science, Computer ScienceGPA: 4.0</div> <div>Advised by Danfei Xu and Judy Hoffman</div>
CONFERENCE PUBLICATIONS	<div>[1] Ryan Punamiya, Dhruv Patel, Patcharapong Aphiwetsa, Pranav Kuppili, Lawrence Y. Zhu, Simar Kareer[†], Judy Hoffman[†], Danfei Xu[†]. “EgoBridge: Domain Adaptation for Generalizable Imitation from Egocentric Human Data”, <i>NeurIPS</i>, 2025. ego-bridge.github.io</div> <div>[2] Simar Kareer, Dhruv Patel*, Ryan Punamiya*, Pranay Mathur*, Shuo Cheng, Chen Wang, Judy Hoffman[†], Danfei Xu[†]. “EgoMimic: Scaling Imitation Learning through Egocentric Video”, <i>ICRA</i>, 2025. egomimic.github.io</div>
WORKSHOP PUBLICATIONS	<div>[3] Ryan Punamiya, Dhruv Patel, Patcharapong Aphiwetsa, Pranav Kuppili, Lawrence Y. Zhu, Simar Kareer[†], Judy Hoffman[†], Danfei Xu[†]. “EgoBridge: Domain Adaptation for Generalizable Imitation from Egocentric Human Data”, <i>CoRL H2R Workshop</i>, 2025. Best Paper Finalist</div>
UNDER REVIEW	<div>[4] Lawrence Y. Zhu, Pranav Kuppili*, Ryan Punamiya*, Patcharapong Aphiwetsa, Dhruv Patel, Simar Kareer, Sehoon Ha, Danfei Xu. “EMMA: Scaling Mobile Manipulation via Egocentric Human Data”, <i>Preprint</i>, 2025. ego-moma.github.io</div>
AWARDS	<div>Best Paper Finalist at CoRL Human2Robot Workshop2025</div> <div>President’s Undergraduate Research Award x 32024,2025</div> <div>Overall Event Winner AI ATL Hackathon (1 of 225)2023</div> <div>Georgia Tech Grand Challenges Grant (\$700)2023</div>
PROFESSIONAL ACTIVITIES	<div>Reviewing</div> <div>Conference on Robot Learning Human2Robot Workshop2025</div> <div>Advising</div> <div>Patcharapong Aphiwetsa (BS Georgia Tech)</div>

SELECT PROJECTS	Partnr. RAG and AI agents to make an intelligent co-pilot for consultants. (Website)	Fall 2023
	van.Go Computer vision and deep learning to generate brushstroke-by-brushstroke painting tutorials. (Website)	Fall 2023
	RoadSense Passive embedded system to autonomously detect potholes while vehicles drive around. (Poster)	Spring 2023