

convex_{opt}

ryanyuan42

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1 Subgradients and Proximal Operators

(i, 2 pts) Show that $\partial f(x)$ is a convex and closed set.

Convex is easy to show.
Closeness can be shown by arguing the complement of this set is open

(ii, 2 pts) Show that $\partial f(x) \subseteq N_{\{y: f(y) \leq f(x)\}}(x)$, where recall $N_C(x)$ denotes the normal cone to a set C at a point x . Give an example to show that this containment can be strict.

if $g \in \partial f(x)$, then $f(y) \geq f(x) + g^T(y - x)$
 $N_{\{y: f(y) \leq f(x)\}}(x) = \{g : g^T x \geq g^T y, \text{ for } y : f(y) \leq f(x)\}$
If $f(y) \leq f(x)$, $f(x) \geq f(y) \geq f(x) + g^T(y - x)$, $g^T x \geq g^T y$, i.e.,
 $g \in N_{\{y: f(y) \leq f(x)\}}(x)$

(iii, 2 pts) Let $p, q > 0$ such that $\frac{1}{p} + \frac{1}{q} = 1$. Consider the function $f(x) = \|x\|_p = (\sum_{i=1}^n x_i^p)^{1/p}$. Show that $\forall x, y$:

$$x^T y \leq \|x\|_p \|y\|_q.$$

The above inequality is known as Hölder's inequality. Hint: you may use the dual representation of the ℓ_p norm, namely, $\|x\|_p = \max_{\|z\|_q \leq 1} z^T x$.

Proof:
 $f(x) = \|x\|_p = \max_{\|z\|_q \leq 1} z^T x \geq (\frac{y}{\|y\|_q})^T x$ therefore, $\|x\|_p \|y\|_q \geq y^T x$

- (iv, 3 pts) Use Hölder's inequality to show that for $f(x) = \|x\|_p$, its subdifferential is $\partial f(x) = \{z \mid \|z\|_q \leq 1 \text{ and } z^T x = \|x\|_p\}$. (You are not allowed to use the rule for the subdifferential of a max of functions for this problem.)

Proof: we know the $\max_{\|z\|_q \leq 1} z^T x = \|x\|_p$. So we want to show that $\partial \|x\|_p = \{z \mid \|z\|_q \leq 1 \text{ and } z^T x = \|x\|_p\}$,

To show $A = B$, we first show,

1. if $x \in A$, then $x \in B$

If $z \in \partial \|x\|_p$, $\forall y$, we have $\|y\|_p \geq \|x\|_p + z^T(y - x)$

Let $y = 0$ and $y = 2x$, we have $z^T x = \|x\|_p$, plug it into the inequality we have $\|y\|_p \geq z^T y$

$\frac{z^T y}{\|y\|_p} \leq 1$, let $u = \frac{y}{\|y\|_p}$, $u^T z \leq 1$

we know that $\max_{\|u\|_p \leq 1} u^T z = \|z\|_q$, so $\|z\|_q \leq 1$, which means $z \in \{z \mid \|z\|_q \leq 1 \text{ and } z^T x = \|x\|_p\}$

2. if $x \in B$, then $x \in A$

If $z \in \{z \mid \|z\|_q \leq 1 \text{ and } z^T x = \|x\|_p\}$ then by Hölder's inequality

$z^T y \leq \|y\|_p \|z\|_q \leq \|y\|_p$

$\|y\|_p \geq \|x\|_p + z^T(y - x) = \|x\|_p + z^T(y - x)$

therefore, $z \in \partial \|x\|_p$

$\partial \|x\|_p = \{z \mid \|z\|_q \leq 1 \text{ and } z^T x = \|x\|_p\} = \operatorname{argmax}_{\|z\|_q \leq 1} z^T x$

2 Properties of Proximal Mappings and Subgradients

- (a, 4pts) Prove one direction of the finite pointwise maximum rule for subdifferentials: The subdifferential of $f(x) = \max_{i=1, \dots, n} f_i(x)$, for convex f_i , $i = 1, \dots, m$, satisfies

$$\partial f(x) \supseteq \operatorname{conv} \left(\bigcup_{i: f_i(x) = f(x)} \partial f_i(x) \right). \quad (1)$$

Easy Proof, let set $S = \{i : f_i(x) = f(x)\}$ and check the convex combination of those functions and the subgradients of those functions

- (b, 4pts) Recall the definition of the proximal mapping: For a function h , the proximal mapping $prox_t$ is defined as

$$prox_t(x) = \operatorname{argmin}_u \frac{1}{2t} \|x - u\|_2^2 + h(u). \quad (2)$$

Show that $prox_t(x) = u \Leftrightarrow h(y) \geq h(u) + \frac{1}{t}(x - u)^\top (y - u) \quad \forall y$.

Proof:

$$prox_t(x) = \operatorname{argmin}_u \frac{1}{2t} \|x - u\|_2^2 + h(u)$$

1. If $h(y) \geq h(u) + \frac{1}{t}(x - u)^\top (y - u)$, and we know $\frac{1}{t}(x - u)^\top (y - u) \geq \frac{1}{2t}(2x^\top y - 2x^\top u + u^\top u - y^\top y)$ (easy to find out by simple algebra, $(u - y)^\top (u - y) \geq 0$)

then we have $\forall y, \frac{1}{2t} \|x - y\|_2^2 + h(y) \geq \frac{1}{2t} \|x - u\|_2^2 + h(u)$, i.e.
 $u = \operatorname{argmin}_u \frac{1}{2t} \|x - u\|_2^2 + h(u) = prox_t(x)$

2. If $prox_t(x) = u$, we have $0 \in \frac{1}{t}(u - x) + \partial h(u)$, $\frac{1}{t}(x - u) \in \partial h(u)$,
 by the definition of subgradient,
 $\forall y, h(y) \geq h(u) + \frac{1}{t}(x - u)^\top (y - u)$

Therefore, $prox_t(x) = u \Leftrightarrow h(y) \geq h(u) + \frac{1}{t}(x - u)^\top (y - u) \quad \forall y$

- (c, 5 pts) Show how we can compose an affine mapping with the proximal operator. That is, assuming $f(x) = g(Ax + b)$, where $x \in R^n$, $A \in R^{m \times n}$, and $b \in R^m$, and also assuming $AA^\top = aI_m$, for some scalar $a > 0$, then

$$prox_f(x) = x + \frac{1}{a} A^\top (prox_{ag}(Ax + b) - Ax - b) \quad (3)$$

Hint: you may find it helpful to reparameterize $g(Ax + b)$ as $g(z)$ with the constraint that $z = Ax + b$, and then apply this constraint as a Lagrange multiplier.

Proof:

$$\begin{aligned} \text{prox}_f(x) &= \operatorname{argmin}_u \frac{1}{2} \|u - x\|_2^2 + f(u) \\ &= \operatorname{argmin}_u \frac{1}{2} \|u - x\|_2^2 + g(Au + b) \\ &= \operatorname{argmin}_{u,z} \frac{1}{2} \|u - x\|_2^2 + g(z), \text{ s.t. } z = Au + b \end{aligned}$$

Lagrangian multiplier: $L(u, z, v) = \frac{1}{2} \|u - x\|_2^2 + g(z) + v^T (Au + b - z)$

We know the it has strong duality because the constraint satisfy the Slater's condition, so we can apply KKT condition that tells us

$$u = x - A^T v$$

$$z = Au + b$$

$$0 \in \partial g(z) - v$$

by first and second condition, we have $v = \frac{1}{a}(Ax + b - z)$
and by third condition, we have $0 \in \partial g(z) + \frac{1}{a}(z - Ax - b)$ so z
minimize $g(z) + \frac{1}{2a} \|z - Ax - b\|_2^2$, so $z = \text{prox}_{ag}(Ax + b)$
 $u = x - A^T v = x + \frac{1}{a} A^T (\text{prox}_{ag}(Ax + b) - Ax - b) = \text{prox}_f(x)$

(d, 5 pts) Show that if $\forall y \in \text{dom}(g)$, $\partial g(\text{prox}_f(y)) \supseteq \partial g(y)$, then

$$\text{prox}_{f+g}(x) = \text{prox}_f(\text{prox}_g(x)) \quad (4)$$

Hints:

1. Consider $\text{prox}_{f+g}(x)$, $\text{prox}_g(x)$, and $\text{prox}_f(\text{prox}_g(x))$.
2. The solution of the proximal can be characterized as:

$$u = \text{prox}_h(x) := \operatorname{argmin}_u \frac{1}{2} \|u - x\|_2^2 + h(u) \iff 0 \in u - x + \partial h(u)$$

3. $\partial(f + g) = \partial f + \partial g$

Proof:

$$\text{prox}_{f+g} = \operatorname{argmin}_{\frac{1}{2}} \|z - x\|_2^2 + f(z) + g(z)$$

$$\text{prox}_f = \operatorname{argmin}_{\frac{1}{2}} \|z - x\|_2^2 + f(z)$$

$$\text{prox}_g = \operatorname{argmin}_{\frac{1}{2}} \|z - x\|_2^2 + g(z)$$

$$0 \in \text{prox}_{f+g}(x) - x + \partial f(\text{prox}_{f+g}(x)) + \partial g(\text{prox}_{f+g}(x))$$

$$0 \in \text{prox}_g(x) - x + \partial g(\text{prox}_g(x))$$

$$0 \in \text{prox}_f(\text{prox}_g(x)) - \text{prox}_g(x) + \partial f(\text{prox}_f(\text{prox}_g(x)))$$

Sum up the last 2 statement, we know

$$0 \in \text{prox}_f(\text{prox}_g(x)) - x + \partial g(\text{prox}_g(x)) + \partial f(\text{prox}_f(\text{prox}_g(x)))$$

Let $y = \text{prox}_g(x)$, $0 \in \text{prox}_f(y) - x + \partial g(y) + \partial f(\text{prox}_f(y))$ because $\partial g(\text{prox}_f(y)) \supseteq \partial g(y)$, therefore we have

$$0 \in \text{prox}_f(y) - x + \partial g(\text{prox}_f(y)) + \partial f(\text{prox}_f(y))$$

Apparently this says, $\text{prox}_f(y)$ satisfy, $0 \in \text{prox}_{f+g}(x) - x + \partial f(\text{prox}_{f+g}(x)) + \partial g(\text{prox}_{f+g}(x))$, which means

$$\text{prox}_f(\text{prox}_g(x)) = \text{prox}_{f+g}(x)$$

3 Convergence Rate for Proximal Gradient Descent (20 pts) [Po-Wei]

In this problem, you will show the sublinear convergence for gradient descent and proximal gradient descent, which was presented in class.

To be clear, we assume that the objective $f(x)$ can be written as $f(x) = g(x) + h(x)$, where

- (A1) g is convex, differentiable, and $\text{dom}(g) = \mathbb{R}^n$.
 - (A2) ∇g is Lipschitz, with constant $L > 0$.
 - (A3) h is convex, not necessarily differentiable, and we take $\text{dom}(h) = \mathbb{R}^n$ for simplicity.
- (a) We begin with the simple case $f(x) = g(x)$; that is, $h(x) = 0$ and can be ignored. We will prove that the gradient descent converges sublinearly in this case. As a reminder, the iterates of gradient descent is computed by

$$x^+ = x - t\nabla g(x), \tag{5}$$

where x^+ is the iterate succeeding x . Henceforth, we will set $t = 1/L$ for simplicity.

(i, 3pt) Show that

$$g(x^+) - g(x) \leq -\frac{1}{2L} \|\nabla g(x)\|^2.$$

That is, the objective value is monotonically decreasing in each update. This is why gradient descent is called a “descent method.”

By Lipschitz continuity of the gradient, we have $g(y) \leq g(x) + \nabla g(x)^T(y - x) + \frac{L}{2}\|y - x\|_2^2$.
 Let $y = x^+ - t\nabla g(x)$, we have
 $g(x^+) \leq g(x) - (t - \frac{t^2 L}{2})\|\nabla g(x)\|_2^2$
 therefore, $g(x^+) - g(x) \leq -\frac{1}{2L}\|\nabla g(x)\|^2$.

(ii, 3pt) Using convexity of g , show the following helpful inequality:

$$g(x^+) - g(z) \leq \nabla g(x)^T(x - z) - \frac{1}{2L} \|\nabla g(x)\|^2, \quad \forall z \in \mathbb{R}^n.$$

By convexity, $\forall z, g(z) \geq g(x) + \nabla g(x)^T(z - x)$
 $g(x) - g(z) \leq \nabla g(x)^T(x - z)$, and by (i),
 $g(x^+) - g(z) \leq \nabla g(x)^T(x - z) - \frac{1}{2L}\|\nabla g(x)\|^2$

(iii, 2pt) Show that

$$g(x^+) - g(x^*) \leq \frac{L}{2} (\|x - x^*\|^2 - \|x^+ - x^*\|^2),$$

By (ii), we have $g(x^+) - g(x^*) \leq \nabla g(x)(x - x^*) - \frac{1}{2L}\|\nabla g(x)\|^2 = \frac{L}{2}(\frac{2}{L}\nabla g(x)^T(x - x^*) - \frac{1}{L^2}\|\nabla g(x)\|^2) = -\frac{L}{2}(\|\frac{1}{L}\nabla g(x) - (x - x^*)\|^2 - \|x - x^*\|^2) = \frac{L}{2}(\|x - x^*\|^2 - \|x^+ - x^*\|^2)$

where x^* is the minimizer of g , assuming $g(x^*)$ is finite.

(iv, 2pt) Now, aggregating the last inequality over all steps $i = 0, \dots, k$, show that the accuracy of gradient descent at iteration k is $O(1/k)$, i.e.,

$$g(x^{(k)}) - g(x^*) \leq \frac{L}{2k} \|x^{(0)} - x^*\|^2.$$

Put differently, for an ϵ -level accuracy, you need to run at most $O(1/\epsilon)$ iterations.

By summing over iteration, we have $\sum_{i=1}^k g(x^{(i)}) - g(x^*) \leq \frac{L}{2}(\|x^{(0)} - x^*\|_2^2)$
 And we know the iteration is always decreasing in value, so $\sum_{i=1}^k g(x^{(i)}) - g(x^*) \geq kg(x^{(k)}) - kg(x^*)$ therefore,
 $g(x^{(k)}) - g(x^*) \leq \frac{L}{2k}(\|x^{(0)} - x^*\|_2^2)$

- (b) Now consider the general h in assumption (A3). We will prove that the proximal gradient descent converges sublinearly under such assumptions. Specifically, the iterates of proximal gradient descent is computed by

$$x^+ = \text{prox}_{th}(x - t\nabla g(x)), \quad (6)$$

where again we will set $t = 1/L$ for simplicity. Further, we define the useful notation

$$G(x) = \frac{1}{t}(x - x^+).$$

We will see (in the following proofs) that $G(x)$ behaves like $\nabla g(x)$ in gradient descent.

- (i, 3pt) Show that

$$g(x^+) - g(x) \leq -\frac{1}{L}\nabla g(x)^T G(x) + \frac{1}{2L}\|G(x)\|^2.$$

we know $g(x^+) - g(x) \leq -\frac{1}{2L}\|\nabla g(x)\|^2$
 and $\frac{1}{2L}(\|G(x)\|^2 - 2\nabla g(x)^T G(x) + \|\nabla g(x)\|^2) \geq 0$ therefore
 $g(x^+) - g(x) \leq -\frac{1}{L}\nabla g(x)^T G(x) + \frac{1}{2L}\|G(x)\|^2$

- (ii, 3pt) Show that

$$f(x^+) - f(z) \leq G(x)^T(x - z) - \frac{1}{2L}\|G(x)\|^2, \quad \forall z \in \mathbb{R}^n.$$

Note that setting $z := x$ verifies the proximal gradient descent is a “descent method.” (Hint: Look back at what you did in Q2 part (b) and add the missing h to (i).)

By looking at Q2 part (b), we know $x^+ = \text{prox}_{th}(x - t\nabla g(x))$ means that

$$h(x^+) - h(z) \leq -\frac{1}{t}(x - t\nabla g(x) - x^+)^T(z - x^+) = G(x)^T(x^+ - x) + \nabla g(x)^T(z - x^+)$$

$$g(x^+) - g(z) \leq \nabla g(x)^T(x - z) - \frac{1}{L}\nabla g(x)^TG(x) + \frac{1}{2L}\|G(x)\|^2$$

Sum up the two inequalities,

$$f(x^+) - f(z) \leq \nabla g(x)^T(x - x^+) - \frac{1}{L}\nabla g(x)^TG(x) + \frac{1}{2L}\|G(x)\|^2 + G(x)^T(x^+ - z)$$

By some simple algebra, we can prove that $\nabla g(x)^T(x - x^+) - \frac{1}{L}\nabla g(x)^TG(x) + \frac{1}{2L}\|G(x)\|^2 + G(x)^T(x^+ - z) = G(x)^T(x - z) - \frac{1}{2L}\|G(x)\|^2$

Therefore, $f(x^+) - f(z) \leq G(x)^T(x - z) - \frac{1}{2L}\|G(x)\|^2, \quad \forall z \in \mathbb{R}^n$.

(iii, 4pt) Show that

$$f(x^+) - f(x^*) \leq \frac{L}{2} (\|x - x^*\|^2 - \|x^+ - x^*\|^2),$$

where x^* is the minimizer of f . Then show that

$$f(x^{(k)}) - f(x^*) \leq \frac{L}{2k} \|x^{(0)} - x^*\|^2.$$

That is, the proximal descent method achieves $O(1/k)$ accuracy at the k -th iteration.

Proof:

It's very easy, let $z = x^*$ in b(ii), the rest follows the exact same logic as in a(iii)

Bonus. If we further assume g being strongly convex with constant m , show that the proximal gradient descent converges linearly, that is,

$$f(x^+) - f(x^*) \leq \left(1 - \frac{m}{L}\right) (f(x) - f(x^*)).$$

You can use the following lemma. [Proximal Polyak-Łojasiewicz Inequality] Let $\lambda > 0$ be a scalar. Define

$$\phi(x; \lambda) = -2\lambda \min_y \left(\nabla g(x)^T(y - x) + \frac{\lambda}{2}\|y - x\|^2 + h(y) - h(x) \right),$$

then

$$\phi(x; \lambda_1) \leq \phi(x; \lambda_2) \quad \text{if} \quad \lambda_1 \leq \lambda_2.$$

Note that $\phi(x; \lambda)$ is related the minimum objective value in the proximal operators.

Hint: Bound $f(x) - f(x^*)$ and $f(x) - f(x^+)$ using ϕ .

A very useful conclusion, remember, a lipschitz continuous gradient is suggesting a bound on the hessian matrix, why?

Proof:

$$\|\nabla f(x) - \nabla f(y)\| \leq L\|x - y\|$$

$$\|\nabla f(x + hv) - \nabla f(x)\| \leq L\|hv\|$$

By the definition of hessian, $\nabla^2 f(x)v = \lim_{h \rightarrow 0} \frac{\nabla f(x+hv) - \nabla f(x)}{h}$
and the definition of matrix norm(operator norm)

$$\|A\| = \sup\{\|Ax\|, \|x\| = 1\}$$

from $\|\nabla f(x + hv) - \nabla f(x)\| \leq L\|hv\|$, we have

$$\lim_{h \rightarrow 0} \frac{\|\nabla f(x+hv) - \nabla f(x)\|}{h} \leq L\|v\|, \text{ i.e., } \|\nabla^2 f(x)v\| \leq L\|v\|,$$

take supreme on both side, $\|\nabla^2 f(x)\| \leq \sup_{\|v\|=1} L\|v\| = L$

since we have operator norm less or equal to L,

and from $\|\nabla^2 f(x)v\| \leq L\|v\|, \forall v$ we know that, $\forall v, \frac{\|\nabla^2 f(x)v\|}{\|v\|} \leq L$

Say v is one of the eigenvector of the hessian, we have, $\lambda \leq L$, therefore, the largest eigenvalue is less than L, that is saying, $\nabla^2 f(x) \preceq LI$

Strong convexity is giving lower bounds of the hessian, i.e., $\nabla^2 f(x) \succeq mI$, why?

strong convexity says:

$$g(x) = f(x) - \frac{m}{2}\|x\|_2^2 \text{ is convex, i.e., } \nabla^2 g(x) \succeq 0, \text{ i.e., } \nabla^2 f(x) \succeq mI$$

This lemma is saying that, the condition number of the hessian is critical to the convergence speed, if the condition number is very large, i.e., ill-conditioned, $\frac{m}{L}$ is very small, close to 0, which makes each iteration doesn't get closer to optimal value