

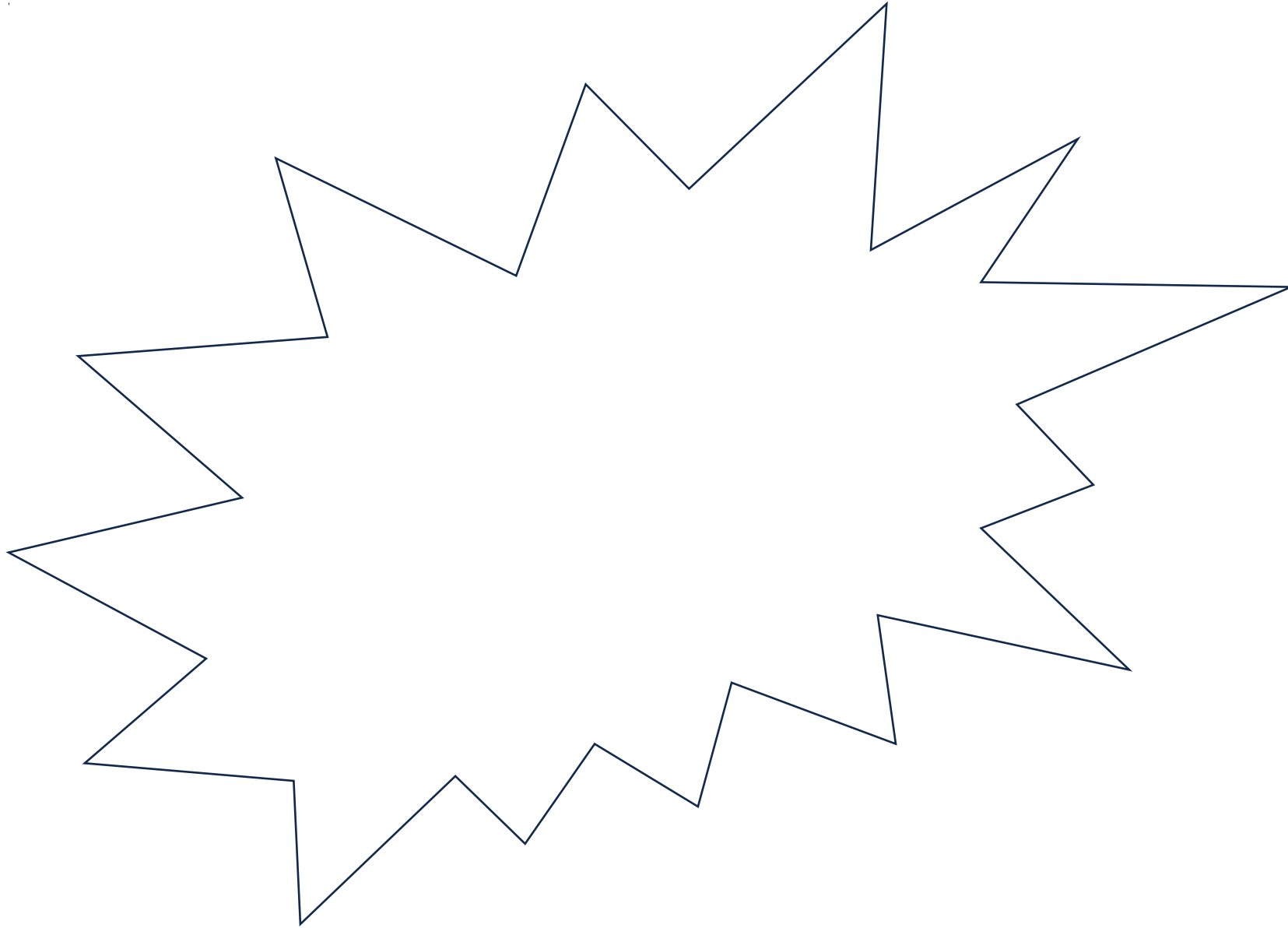


# CS 400

## Heap - Introduction

**ID: 10-01**

# Priority Queue

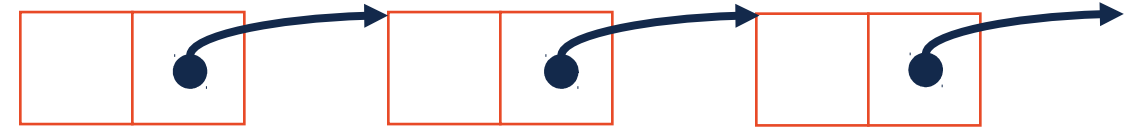


# Priority Queue Implementation

insert	removeMin
$O(1)^*$	$O(n)$
$O(1)$	$O(n)$
$O(n)$	$O(1)$
$O(n)$	$O(1)$



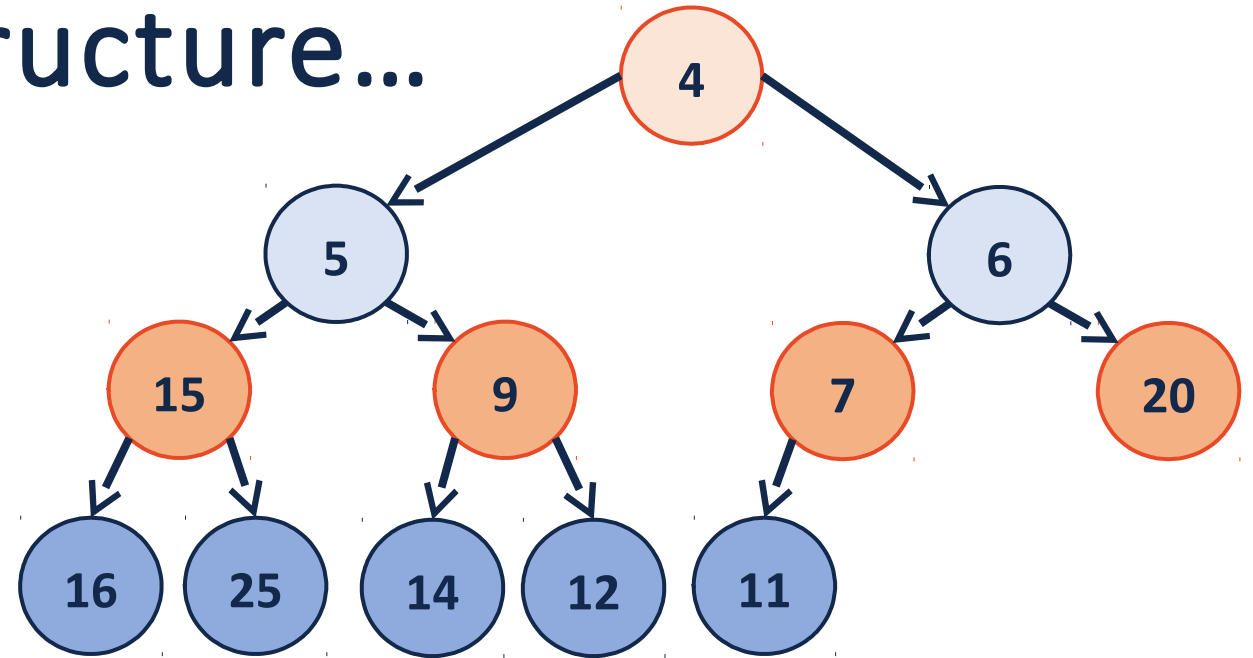
unsorted



sorted



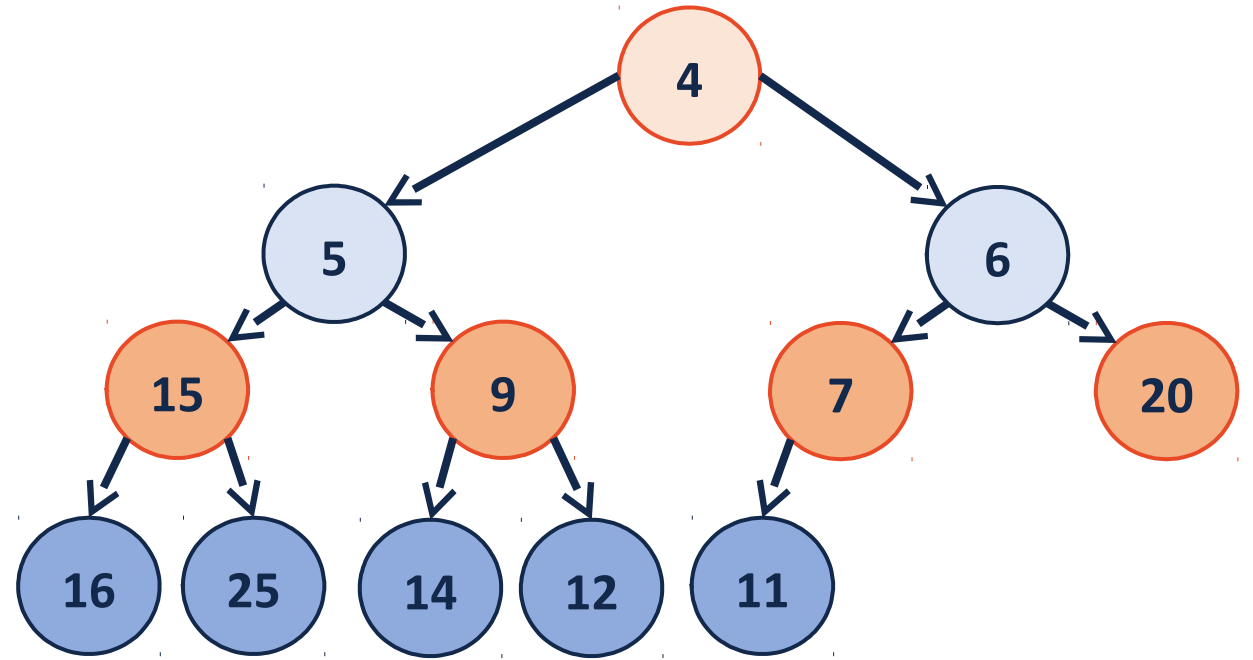
# Another possibly structure...



# (min)Heap

A complete binary tree  $T$  is a min-heap if:

- $T = \{\}$  or
- $T = \{r, T_L, T_R\}$ , where  $r$  is less than the roots of  $\{T_L, T_R\}$  and  $\{T_L, T_R\}$  are min-heaps.

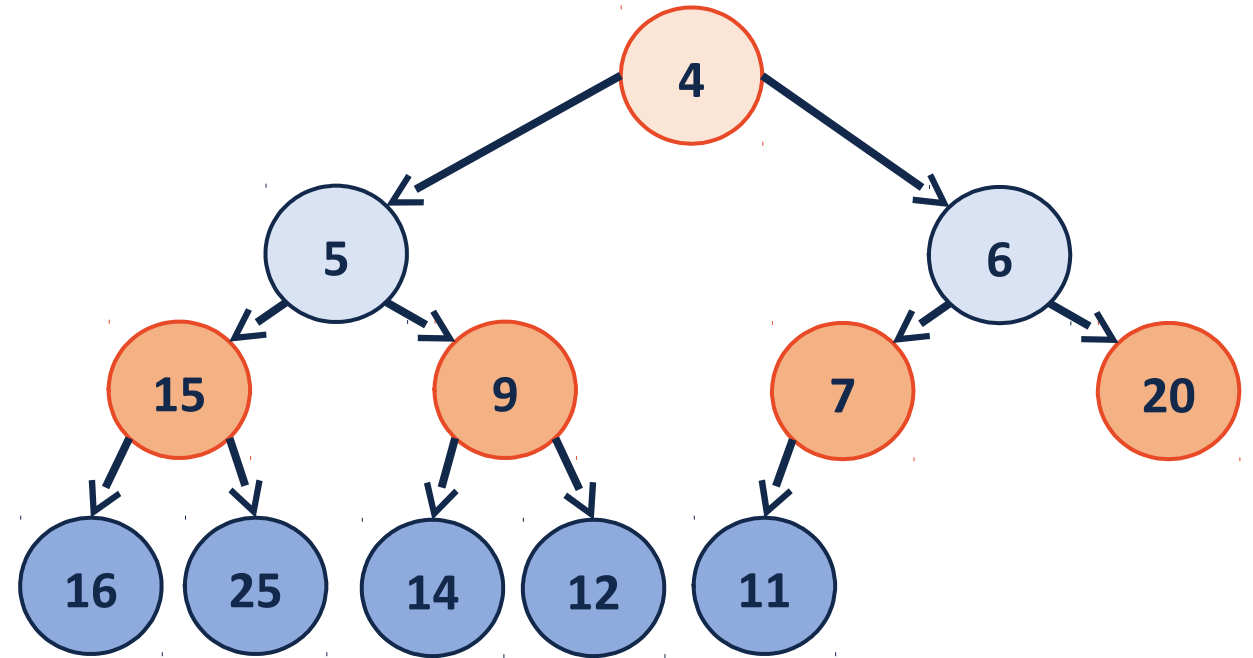


# (min)Heap

parent = index / 2

Left Child = index \* 2

Right Child = index \* 2 + 1



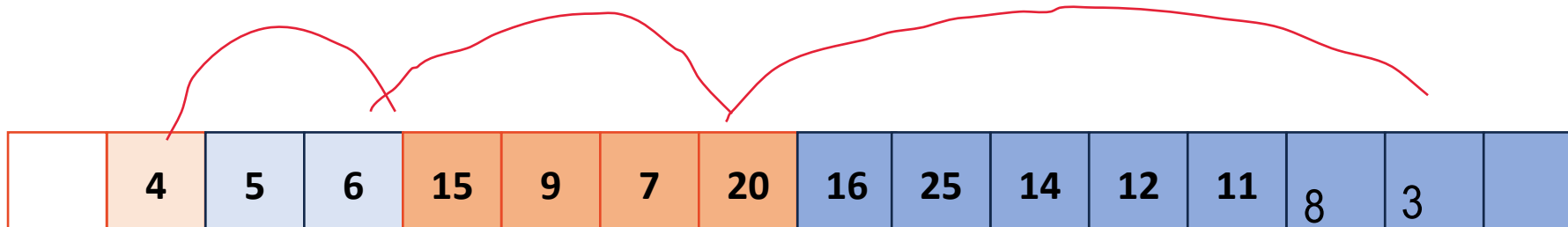
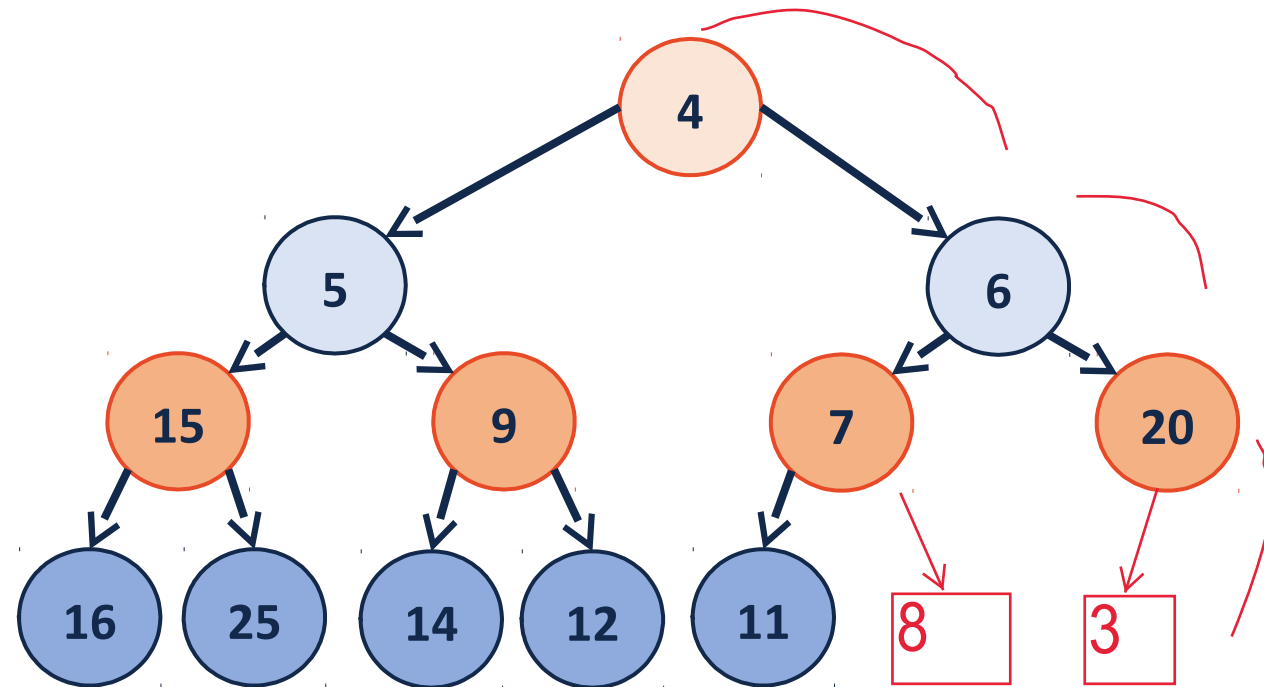
4	5	6	15	9	7	20	16	25	14	12	11			
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**Heap – Insert and removeMin**

**ID: 10-02**

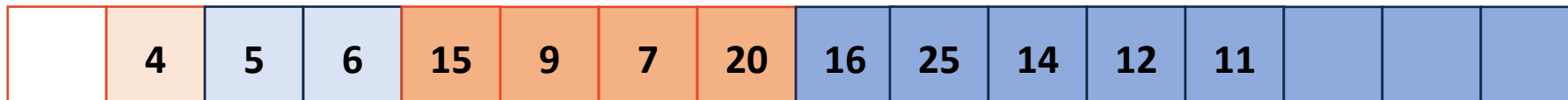
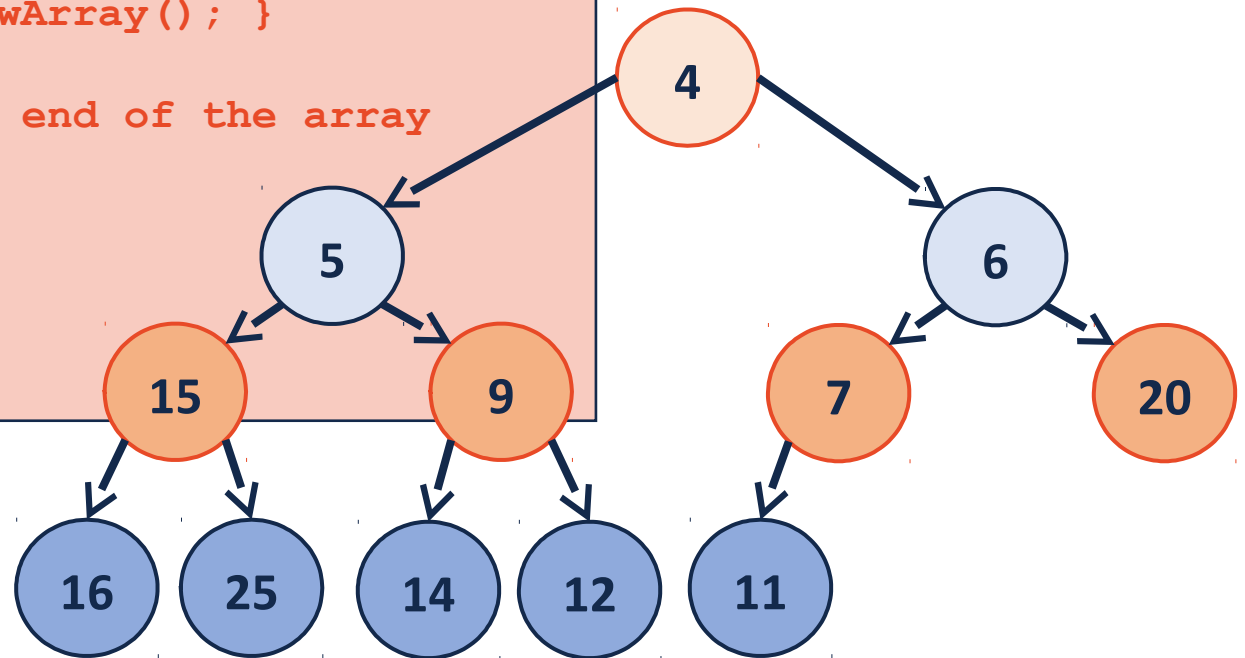
# insert





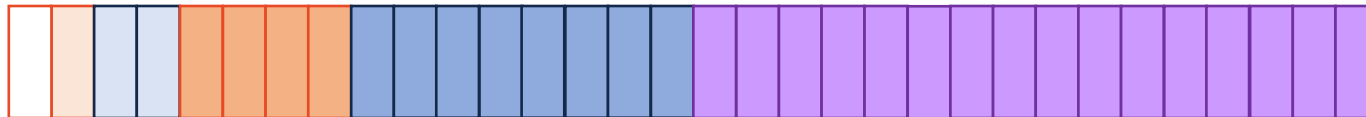
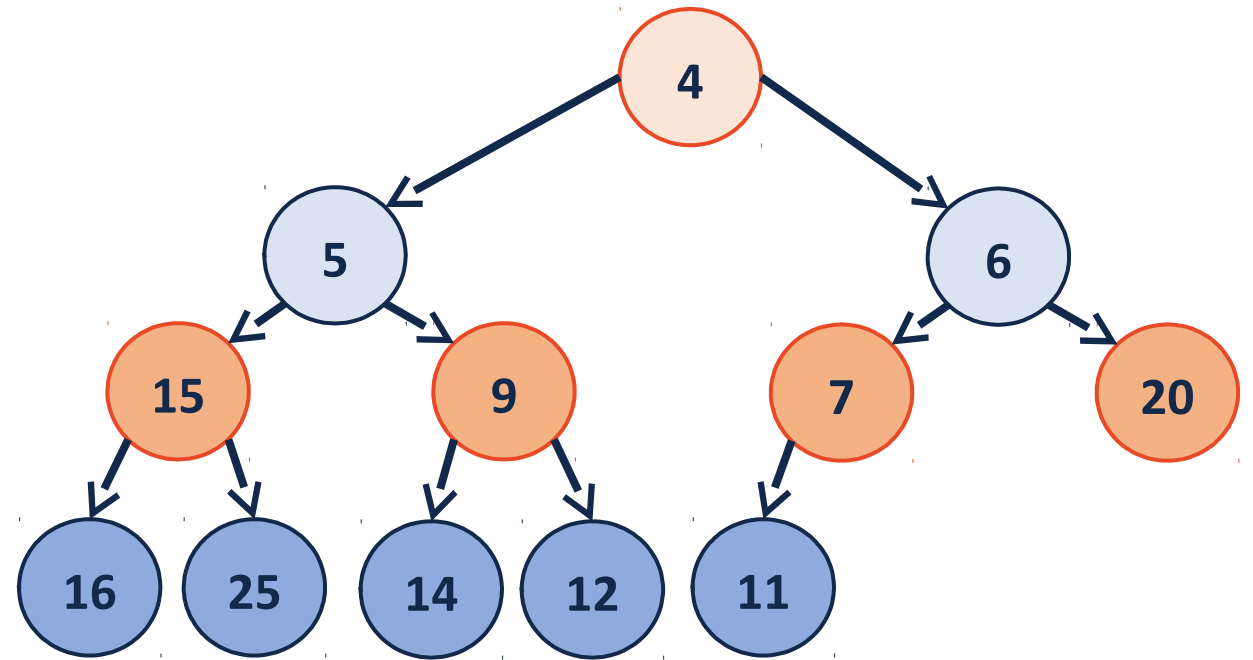
# insert

```
1 template <class T>
2 void Heap<T>::_insert(const T & key) {
3     // Check to ensure there's space to insert an element
4     // ...if not, grow the array
5     if ( size_ == capacity_ ) { _growArray(); }
6
7     // Insert the new element at the end of the array
8     item_[++size] = key;
9
10    // Restore the heap property
11    _heapifyUp(size);
12 }
```



# growArray

double size every time



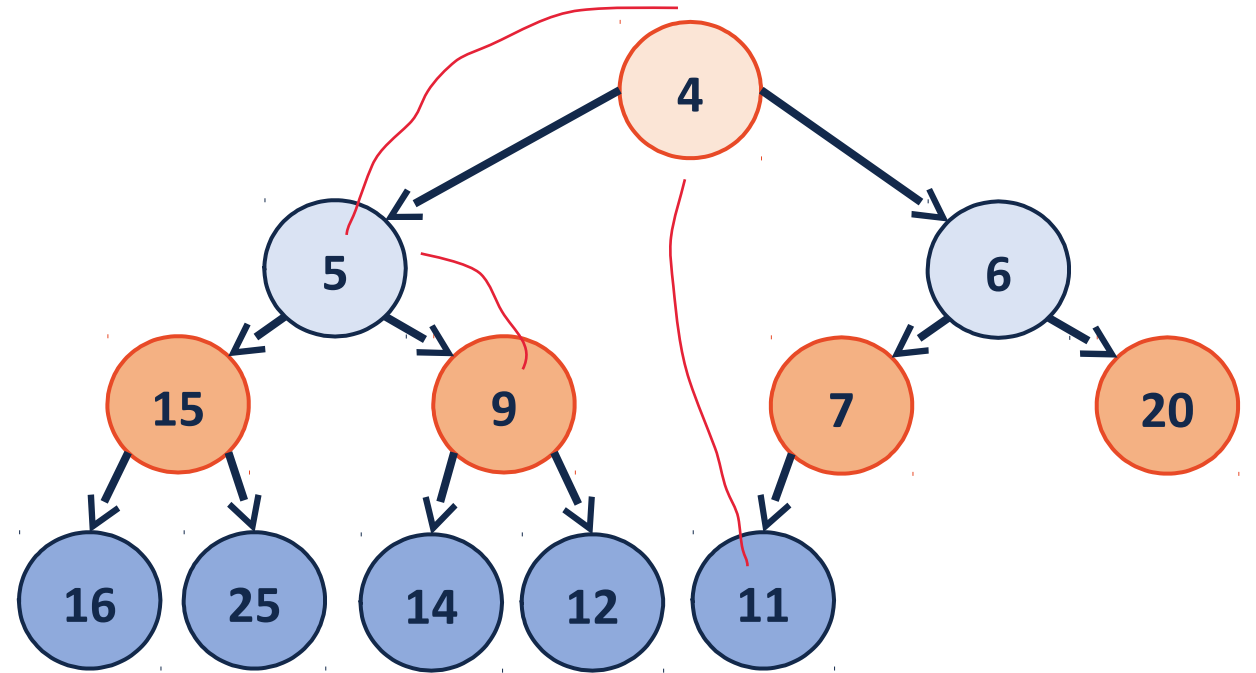
# insert- heapifyUp

```
1  template <class T>
2  void Heap<T>::_insert(const T & key) {
3      // Check to ensure there's space to insert an element
4      // ...if not, grow the array
5      if ( size_ == capacity_ ) { _growArray(); }
6
7      // Insert the new element at the end of the array
8      item_[++size] = key;
9
10     // Restore the heap property
11     _heapifyUp(size);
12 }
```

```
1  template <class T>
2  void Heap<T>::_heapifyUp( int index ) {
3      if ( index > 1 ) {
4          if ( item_[index] < item_[ parent(index) ] ) {
5              std::swap( item_[index], item_[ parent(index) ] );
6              _heapifyUp( parent(index) );
7          }
8      }
9  }
```

index / 2

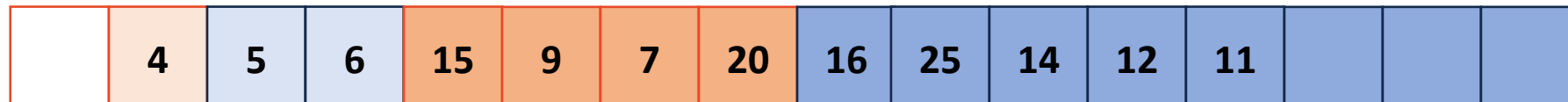
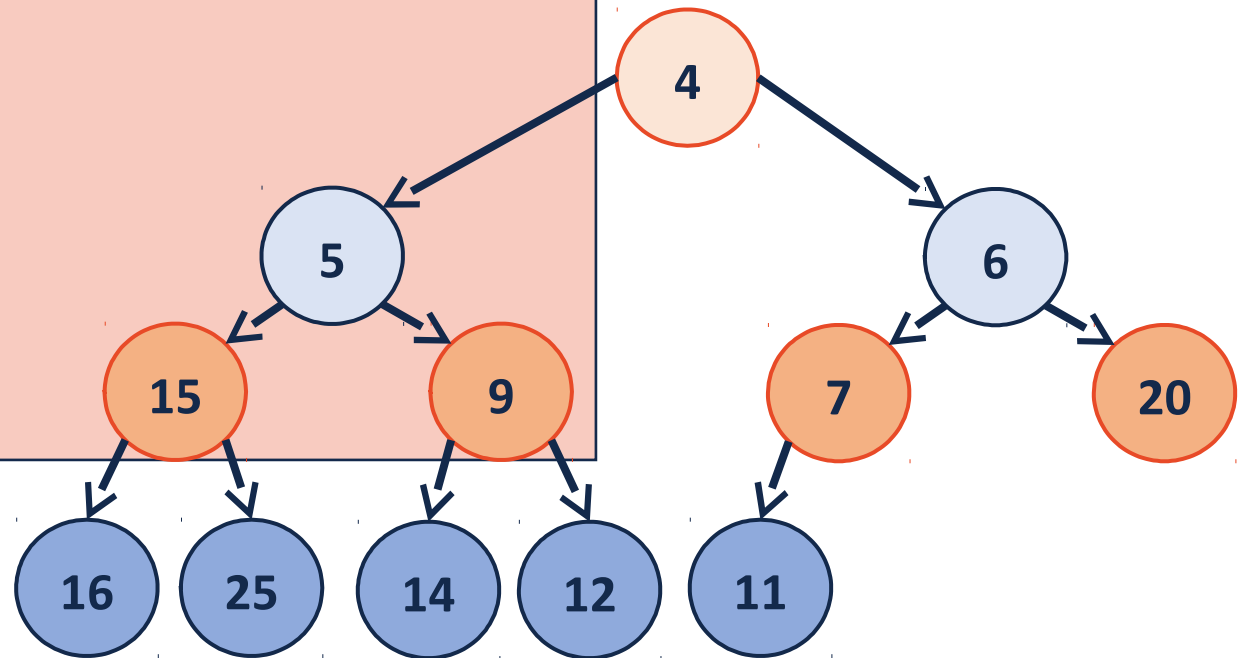
# removeMin



	4	5	6	15	9	7	20	16	25	14	12	11			
--	---	---	---	----	---	---	----	----	----	----	----	----	--	--	--

# removeMin

```
1  template <class T>
2  void Heap<T>::_removeMin() {
3      // Swap with the last value
4      T minValue = item_[1];
5      item_[1] = item_[size_];
6      size--;
7
8      // Restore the heap property
9      heapifyDown();
10
11     // Return the minimum value
12     return minValue;
13 }
```



# removeMin - heapifyDown

```
1  template <class T>
2  void Heap<T>::_removeMin() {
3      // Swap with the last value
4      T minValue = item_[1];
5      item_[1] = item_[size_];
6      size--;
7
8      // Restore the heap property
9      _heapifyDown();
10
11     // Return the minimum value
12     return minValue;
13 }
```

```
1  template <class T>
2  void Heap<T>::_heapifyDown(int index) {
3      if ( !_isLeaf(index) ) {
4          T minChildIndex = _minChild(index);
5          if ( item_[index] > item_[minChildIndex] ) {
6              std::swap( item_[index], item_[minChildIndex] );
7              _heapifyDown( minChildIndex );
8          }
9      }
10 }
```

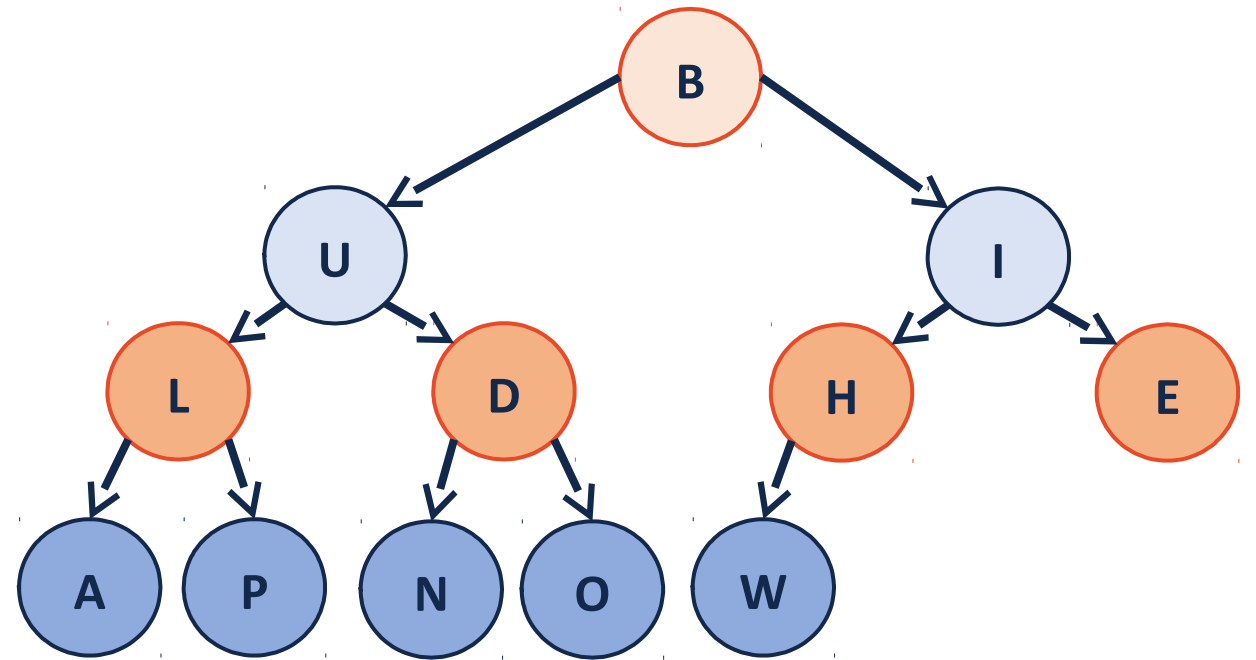


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**Heap – buildHeap**

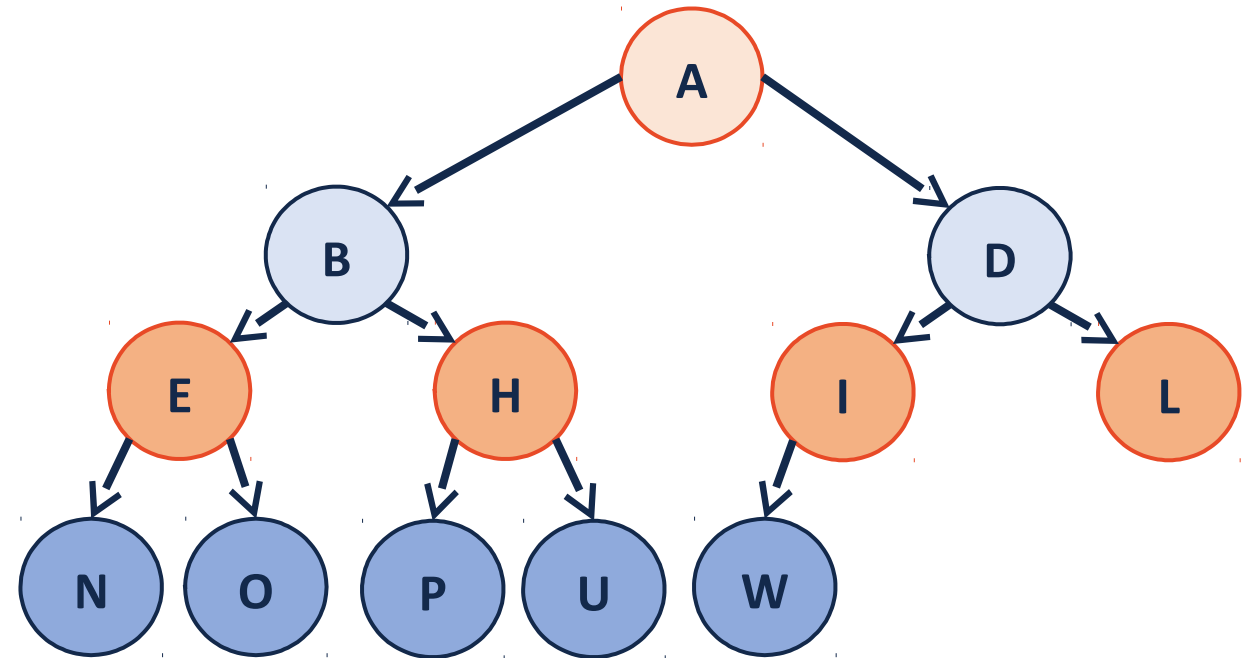
**ID: 10-03**

# buildHeap

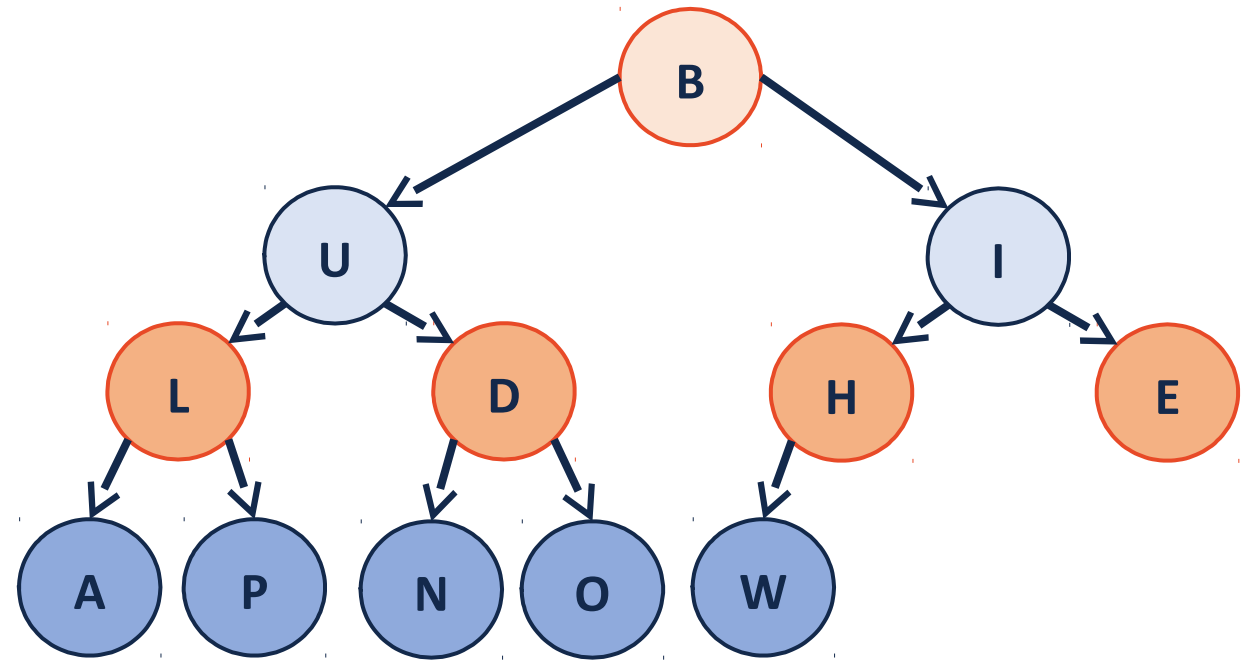




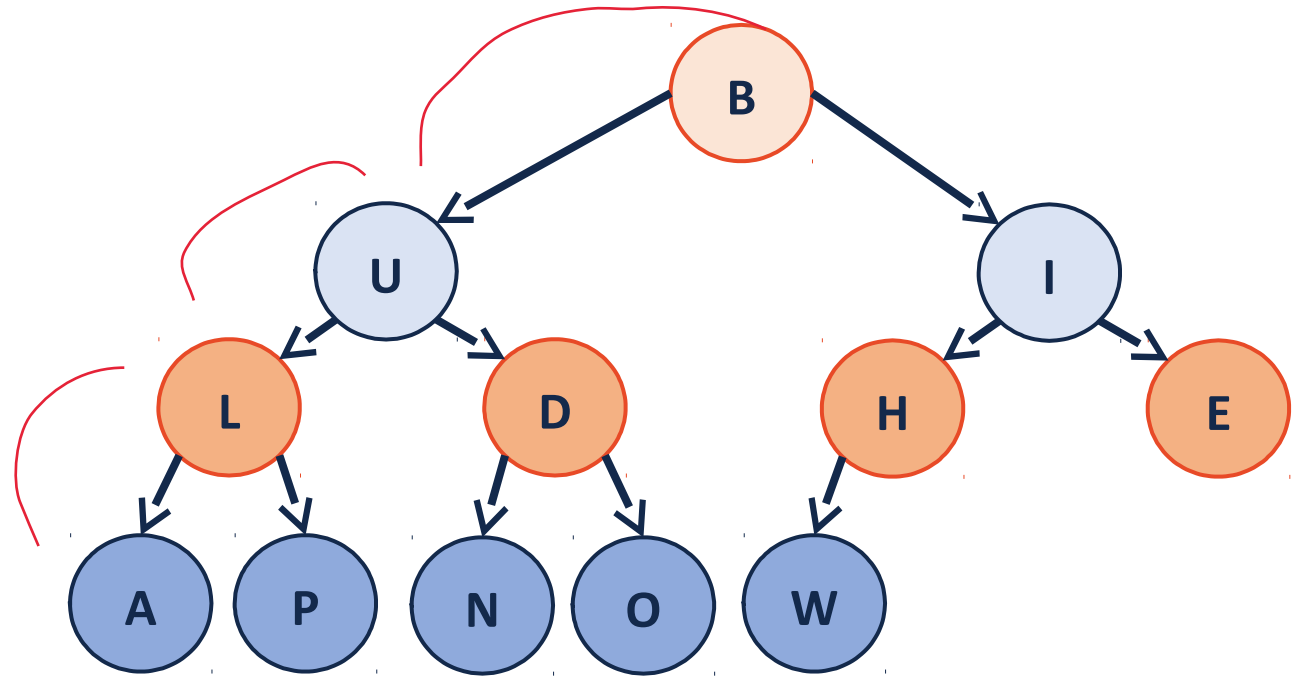
# buildHeap – sorted array



# buildHeap - heapifyUp



# buildHeap - heapifyDown



# buildHeap

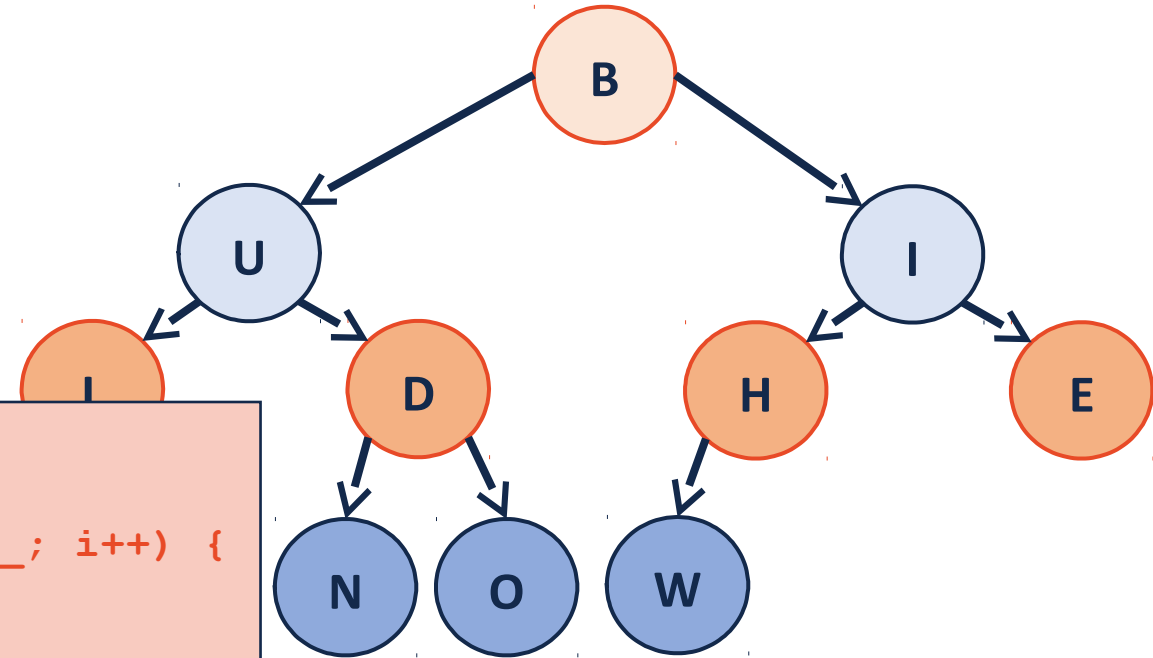
1. Sort the array – it's a heap!

2.

```
1 template <class T>
2 void Heap<T>::buildHeap() {
3     for (unsigned i = 2; i <= size_; i++) {
4         heapifyUp(i);
5     }
6 }
```

3.

```
1 template <class T>
2 void Heap<T>::buildHeap() {
3     for (unsigned i = parent(size); i > 0; i--) {
4         heapifyDown(i);
5     }
6 }
```



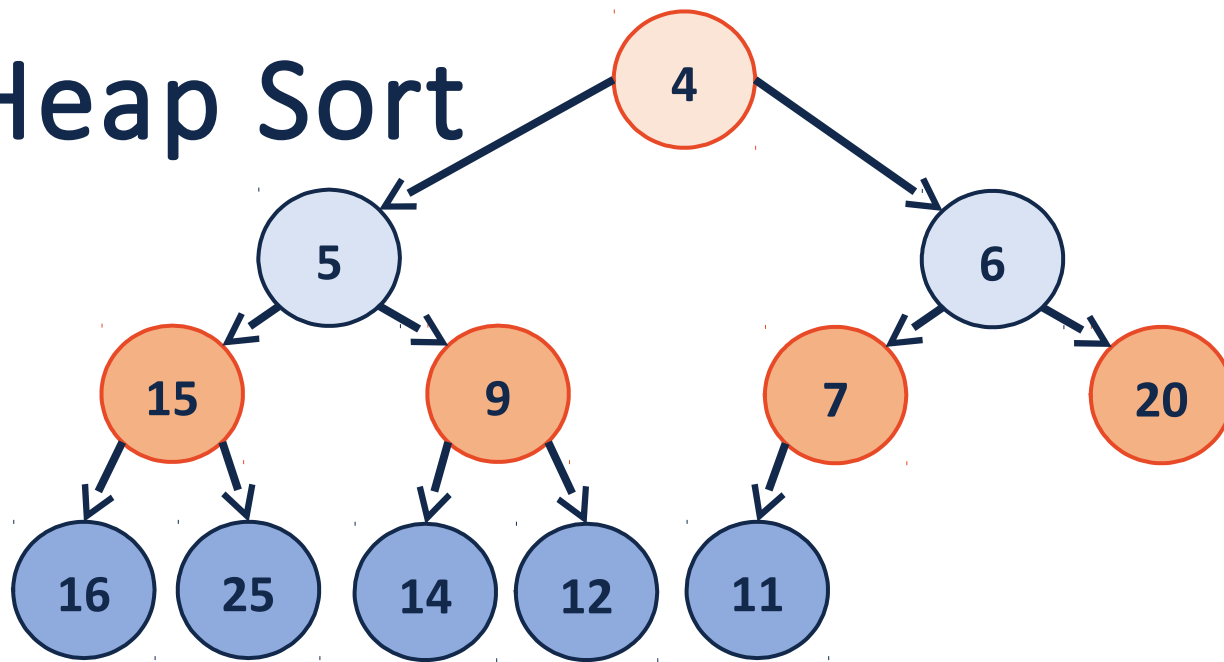


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## **Heap – Runtime Analysis**

**ID: 10-04**

# Heap Sort



1. Build Heap  $O(n)$
2.  $n$  \* removeMin  $O(\log(n))$
3. Swap element to main property



Running Time?

$n * \log(n)$  for worst case

Why do we care about another sort?