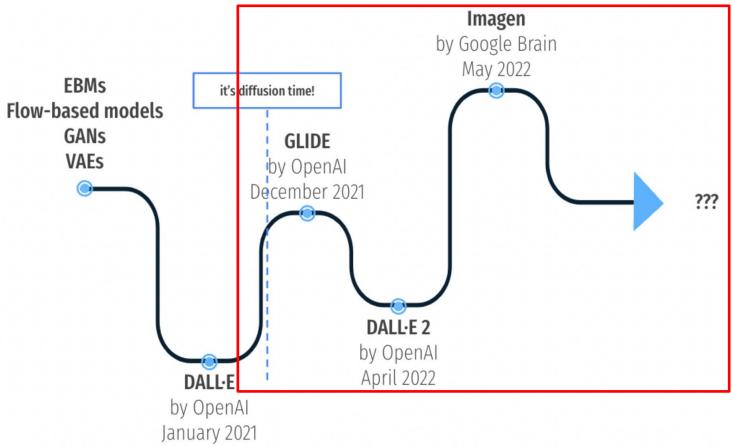
Photorealistic Text-to-Image Diffusion Models with Deep Language Understanding

Google Research, Brain Team

Xinjie Li 03/15/2023

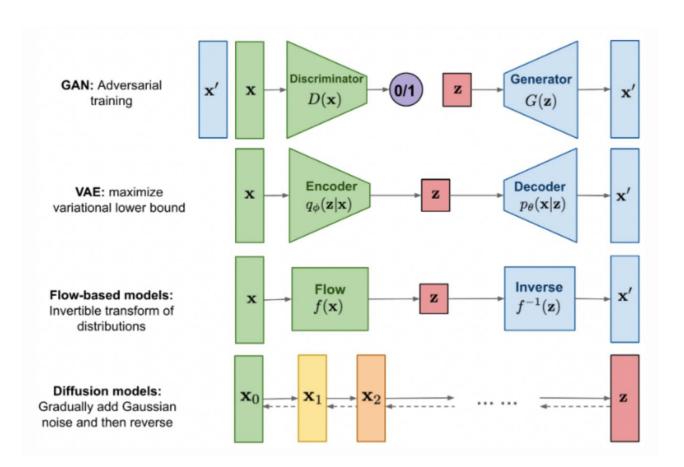
Timeline



Objective:

Generate Image **X** from latent space **Z**

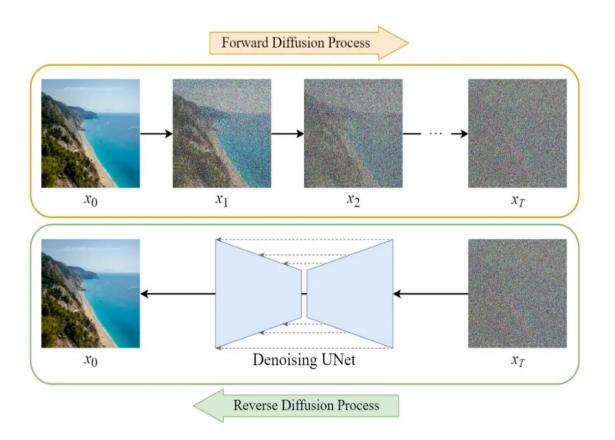
Z -> X



$$X_T == Z$$

Forward:
Get the ground truth

Backward: Z -> X (generation)



Backward:

$$X_T -> X_0$$

How?

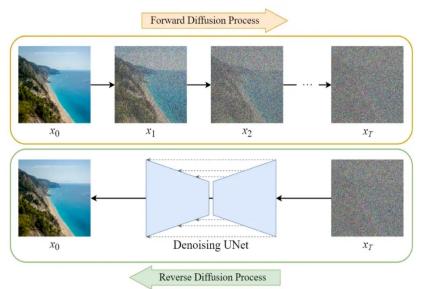
We remove some noise in X_T to get X_T-1 Step by step, we remove all the noise and get X_0

So?

We have X_T now, all we need is the noise.

So?

U-Net: input-> X_T output->noise.



Forward:

$$X_0 -> X_T$$

How?

Start distribution: $q(\mathbf{x_0})$

An image sample from $q(\mathbf{x_0})$: $\mathbf{x_0}$

Aim: $\mathbf{x_0} o \mathbf{x_1} o \ldots o \mathbf{x}_T$

Define this process: $q(\mathbf{x}_t \mid \mathbf{x}_{t-1}) = \mathcal{N}\left(\sqrt{1-\beta_t}\mathbf{x}_{t-1}, \beta_t \mathbf{I}\right)$. noising schedule $\{\beta_t\}_{t=1}^T$

Forward Diffusion Process Denoising UNet x_T Reverse Diffusion Process

we don't like step by step: re-parametrization $q(\mathbf{x}_t \mid \mathbf{x}_0) = \mathcal{N}\left(\sqrt{\overline{\alpha}_t}\mathbf{x}_0, (1-\bar{\alpha}_t)\mathbf{I}\right) = \sqrt{\overline{\alpha}_t}\mathbf{x}_0 + \sqrt{1-\bar{\alpha}_t}\cdot\epsilon$

$$\epsilon$$
 represents Gaussian noise $lpha_t:=1-eta_{t_t}\,arlpha_t:=\prod_{k=0}^tlpha_k$ and $\epsilon\sim\mathcal{N}(0,\mathbf{I})$

we don't like step by step: re-parametrization

$$q\left(\mathbf{x}_{t}\mid\mathbf{x}_{0}
ight)=\mathcal{N}\left(\sqrt{ar{lpha}_{t}}\mathbf{x}_{0},\left(1-ar{lpha}_{t}
ight)\mathbf{I}
ight)=\sqrt{ar{lpha}_{t}}\mathbf{x}_{0}+\sqrt{1-ar{lpha}_{t}}\cdot\epsilon$$

Backward:

$$X_T -> X_0$$

How to train?

How?

We remove some noise in X_T to get X_T-1 Step by step, we remove all the noise and get X_0

Output: $\epsilon_{\theta}(x_t,t)$

Ground Truth: $\epsilon \sim \mathcal{N}(0, \mathbf{I})$

So? We have X_T now, all we need is the noise.

Loss:

So?
U-Net: input-> X_T output->noise.

$$\left|\left|\epsilon-\epsilon_{ heta}(x_t,t)
ight|
ight|^2=\left|\left|\epsilon-\left|\epsilon_{ heta}(\sqrt{ar{lpha}_t}\mathbf{x}_0+\sqrt{1-ar{lpha}_t}\cdot\epsilon,t)
ight|
ight|^2$$

Training and inference

Algorithm 1 Training	Algorithm 2 Sampling
1: repeat 2: $\mathbf{x}_0 \sim q(\mathbf{x}_0)$ 3: $t \sim \text{Uniform}(\{1, \dots, T\})$ 4: $\boldsymbol{\epsilon} \sim \mathcal{N}(0, \mathbf{I})$ 5: Take gradient descent step on $\nabla_{\theta} \left\ \boldsymbol{\epsilon} - \mathbf{z}_{\theta}(\sqrt{\bar{\alpha}_t}\mathbf{x}_0 + \sqrt{1 - \bar{\alpha}_t}\boldsymbol{\epsilon}, t) \right\ ^2$ 6: until converged	1: $\mathbf{x}_T \sim \mathcal{N}(0, \mathbf{I})$ 2: $\mathbf{for} \ t = T, \dots, 1 \ \mathbf{do}$ 3: $\mathbf{z} \sim \mathcal{N}(0, \mathbf{I}) \ \text{if} \ t > 1$, else $\mathbf{z} = 0$ 4: $\mathbf{x}_{t-1} = \frac{1}{\sqrt{\alpha_t}} \left(\mathbf{x}_t - \frac{1-\alpha_t}{\sqrt{1-\tilde{\alpha}_t}} \mathbf{z}_{\theta}(\mathbf{x}_t, t) \right) + \sigma_t \mathbf{z}$ 5: $\mathbf{end} \ \mathbf{for}$ 6: $\mathbf{return} \ \mathbf{x}_0$

How to add the additional information to Diffusion? : Guided Diffusion.

Backward process of DDPM
$$p_{ heta}(x_{t-1}|x_t)$$

Classifier-quided Diffusion
$$p_{ heta,\phi}(x_{t-1}|x_t,$$

Classifier-guided Diffusion
$$p_{ heta,\phi}(x_{t-1}|x_t,$$

(more data; larger model; more GPUs)

Classifier-free Diffusion

GLIDE

Classifier-guided Diffusion
$$p_{ heta,\phi}(x_{t-1}|x_t,y) = Z \cdot p_{ heta}(x_{t-1}|x_t) \cdot p_{\phi}(y|x_{t-1})$$

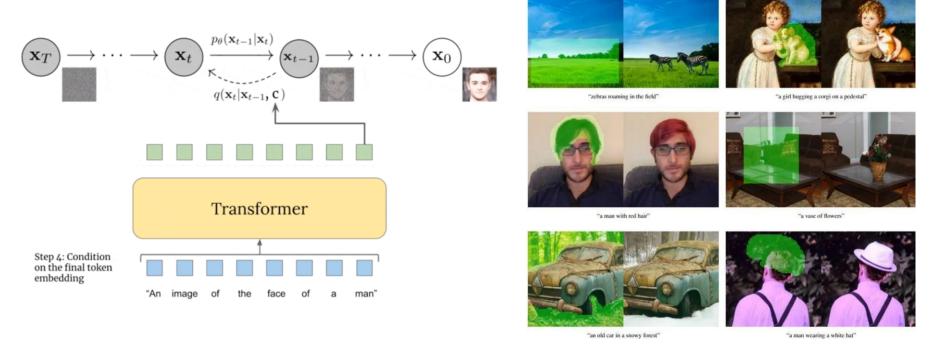
ffusion
$$p_{ heta,\phi}(x_{t-1}|x_t,$$

 $\hat{\epsilon}_{\theta}\left(\mathbf{x}_{t}, t \mid y\right) = \epsilon_{\theta}\left(\mathbf{x}_{t}, t \mid \emptyset\right) + s \cdot \left(\epsilon_{\theta}\left(\mathbf{x}_{t}, t \mid y\right) - \epsilon_{\theta}\left(\mathbf{x}_{t}, t \mid \emptyset\right)\right)$

 $\hat{\epsilon}_{\theta}(x_t|Caption) = \epsilon_{\theta}(x_t) + s \cdot (\epsilon_{\theta}(x_t, Caption) - \epsilon_{\theta}(x_t))$

Diffusion models beat gans on image synthesis. Dhariwal, P. and Nichol, A. 2021. GLIDE: Towards Photorealistic Image Generation and Editing with Text-Guided Diffusion Models. Alex Nichol et al. 2021

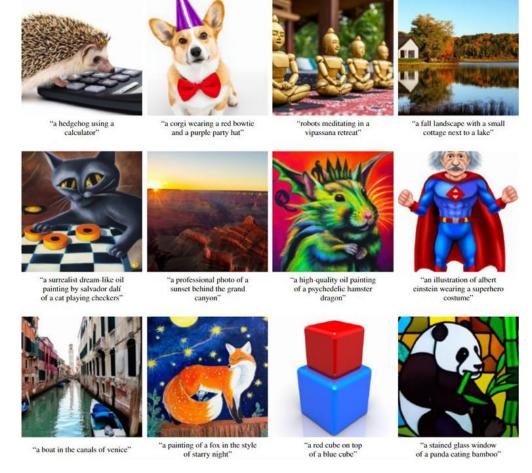
GLIDE



caption + mask area + super resolution

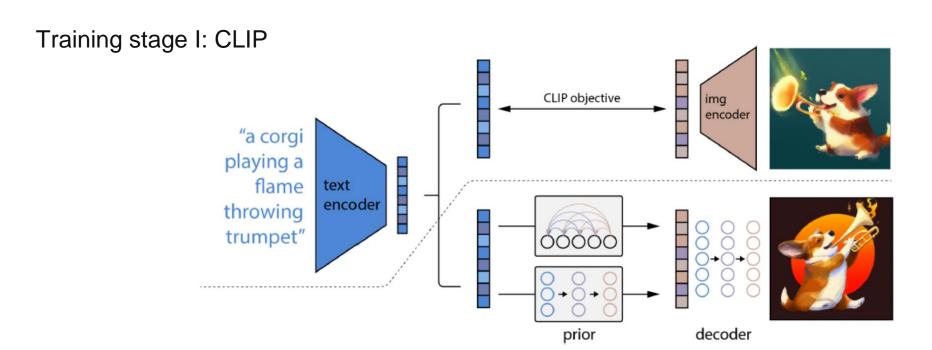
Diffusion models beat gans on image synthesis. Dhariwal, P. and Nichol, A. 2021.
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GLIDE



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CLIP + GLIDE

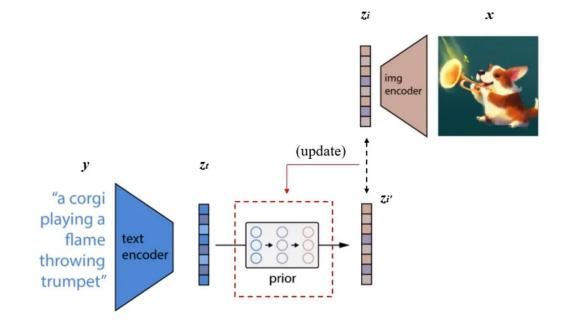


Hierarchical Text-Conditional Image Generation with CLIP Latents. Aditya Ramesh et al. 2022

CLIP + GLIDE

Training stage II:

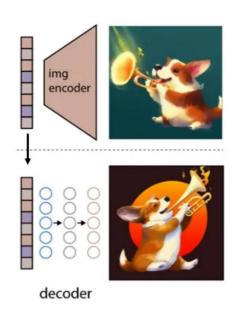
Prior (latent space)



CLIP + GLIDE

Training stage III:

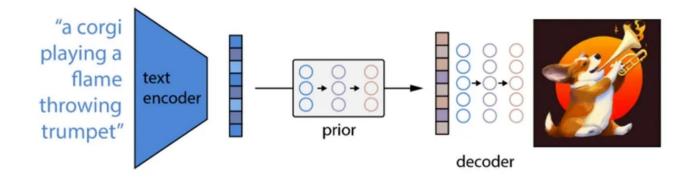
Decoder (GLIDE)





CLIP + GLIDE

Inference









a shiba inu wearing a beret and black turtleneck



a close up of a handpalm with leaves growing from it



an espresso machine that makes coffee from human souls, artstation



panda mad scientist mixing sparkling chemicals, artstation



a corgi's head depicted as an explosion of a nebula

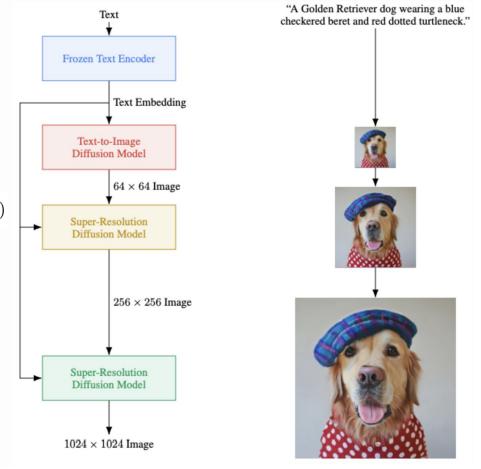
Hierarchical Text-Conditional Image Generation with CLIP Latents. Aditya Ramesh et al. 2022

A pretrained, frozen T5-XXL model

GLIDE (dynamic)

$$\hat{\epsilon}_{ heta}(x_t|Caption) = \epsilon_{ heta}(x_t) + s \cdot (\epsilon_{ heta}(x_t,Caption) - \epsilon_{ heta}(x_t))$$

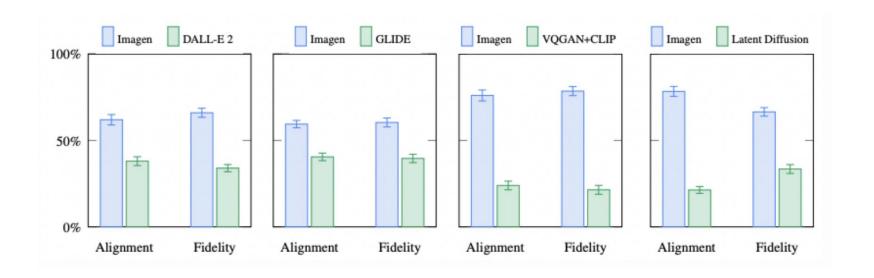
Efficient U-net

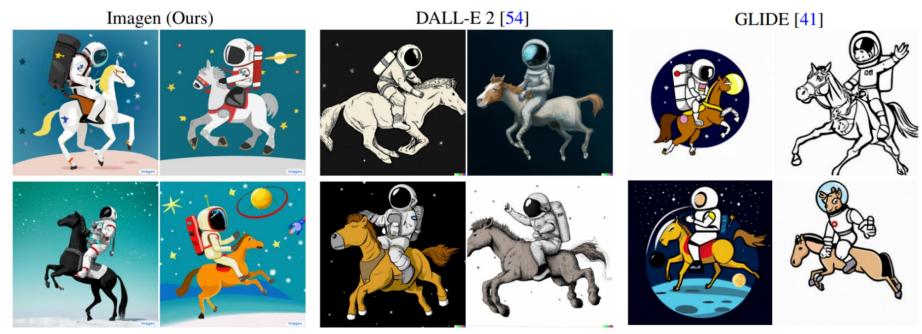


Photorealistic Text-to-Image Diffusion Models with Deep Language Understanding. Chitwan Saharia et al. 2022

Model	FID-30K	Zero-shot FID-30K
AttnGAN [76]	35.49	
DM-GAN [83]	32.64	
DF-GAN [69]	21.42	
DM- $GAN + CL [78]$	20.79	
XMC-GAN [81]	9.33	
LAFITE [82]	8.12	
Make-A-Scene [22]	7.55	
DALL-E [53]		17.89
LAFITE [82]		26.94
GLIDE [41]		12.24
DALL-E 2 [54]		10.39
Imagen (Our Work)		7.27

DrawBench





A horse riding an astronaut.

Future work

Latent Space: Stable Diffusion

Fine-grained Control: ControlNet, T2I-Adapter and Composer

Inversion: DreamBooth

Applications: Make-A-Video; Make-A-Story; Magic3D