

# Exact bounds for distributed graph colouring

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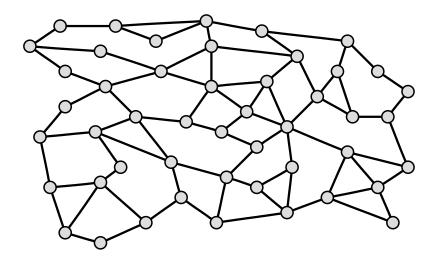
Department of Computer Science, University of Helsinki

Federated Computer Science Event, Helsinki

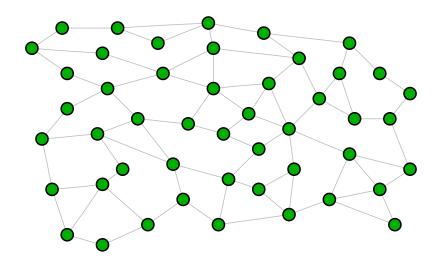
#### **Outline**

- 1. What is distributed computing?
- 2. The graph colouring problem
- 3. The model of distributed computing
- 4. Attaining exact bounds: Techniques and results

# The distributed setting

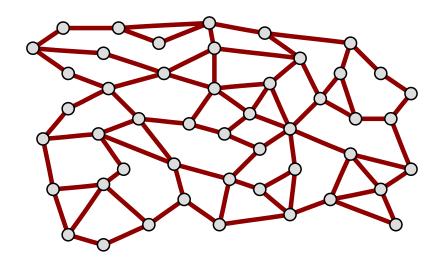


### The distributed setting



Nodes = processors

### The distributed setting

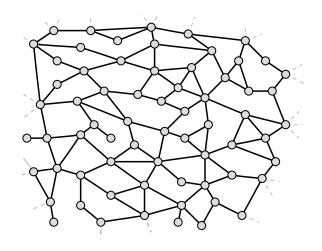


Nodes = processors, **edges = communication links** 

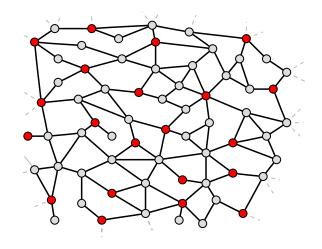
#### Theory of distributed computing

Theory of distributed computing studies algorithmic problems in large networks.

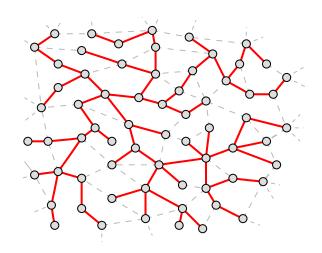
- All processors run the same algorithm
- The network itself is the input
- Each node outputs its own part in the solution



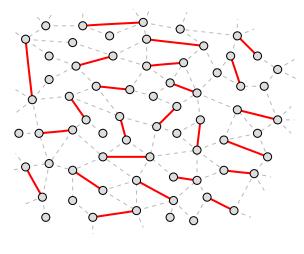
Focus on graph problems



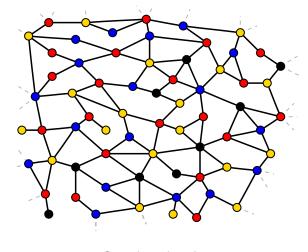
Dominating sets



Spanning trees



Matchings

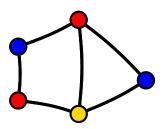


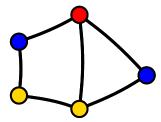
Graph colouring

#### Graph colouring

The task is to give each node a colour such that

- colours = numerical labels
- adjacent nodes have different colours
- the total number of colours is small

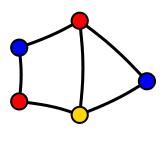


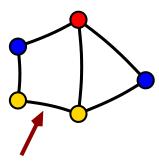


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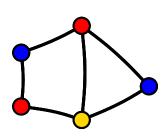


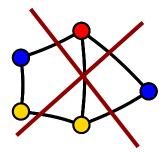


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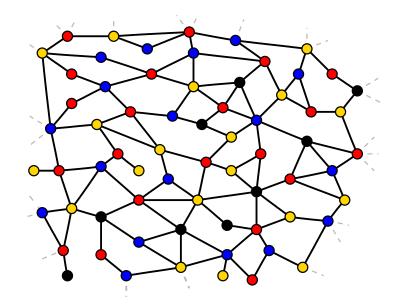
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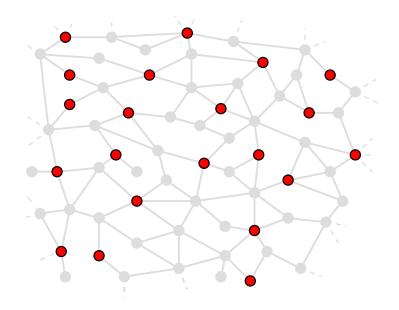


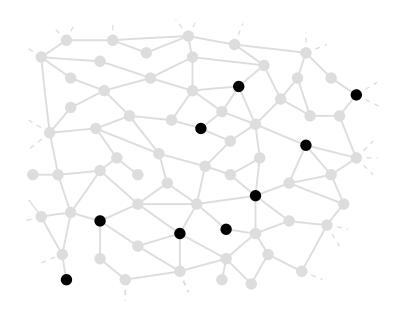


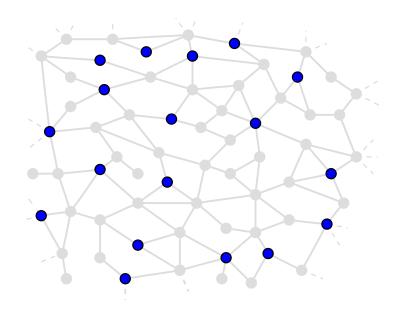
Suppose we have a wireless sensor network..

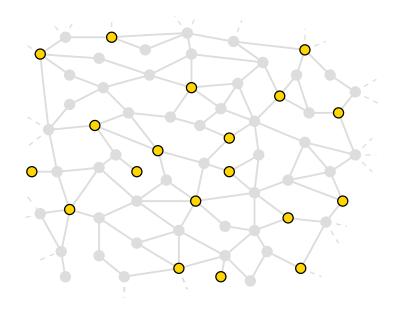
- all nodes are equipped with radio transmitters
- near-by nodes cannot transmit simultaneously due to interference





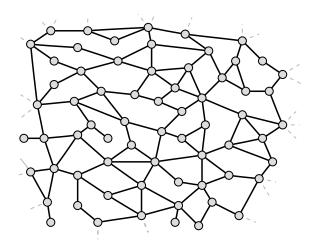




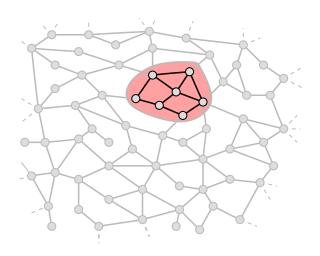


Locality is an important theme in distributed computing:

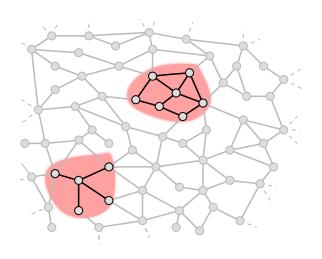
- Many problems are global in nature (e.g., optimal colouring)
- But an efficient distributed algorithm cannot depend on global knowledge.



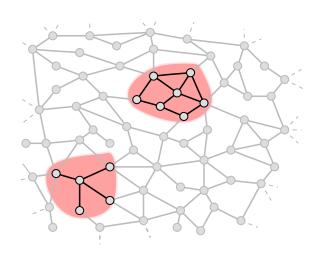
The aim is to find **global** solutions using **local** information.



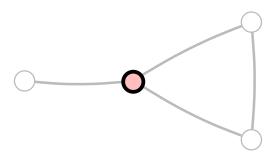
The aim is to find **global** solutions using **local** information.



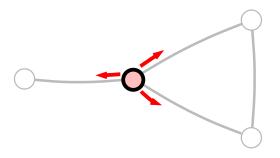
Minimal dependence with others



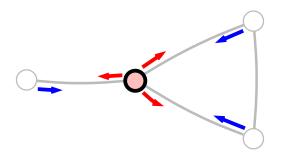
Think global, act local



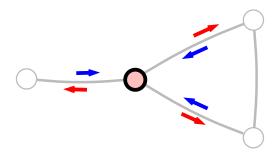
The system proceeds in discrete synchronous communication rounds.



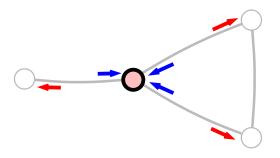
#### 1. Send messages



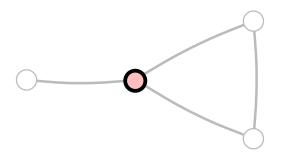
#### 1. Send messages



2. Wait for the messages to propagate



#### 3. Receive messages



4. Perform local computation. Continue or declare output.

During a single communication round each node

- 1. sends messages to neighbours
- 2. waits for the messages to propagate
- 3. receives messages from neighbours
- 4. performs local computation

Repeat until all nodes have declared their output.

Time complexity = Number of communication rounds

During a single communication round each node

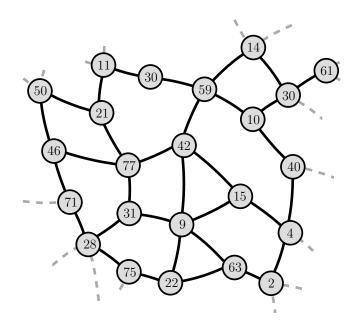
- 1. sends messages to neighbours
- 2. waits for the messages to propagate
- 3. receives messages from neighbours
- 4. performs local computation

Repeat until all nodes have declared their output.

Time complexity = Number of communication rounds

Space complexity = Size of sent messages

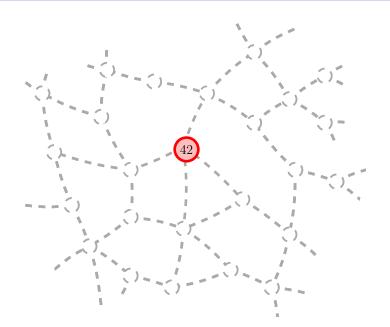
### Unique identifiers



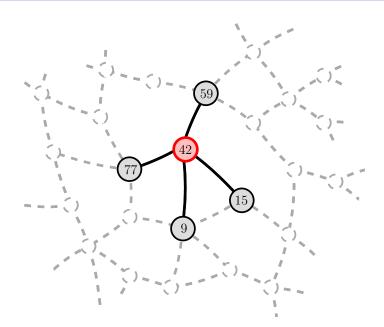
#### Local views

We can use so-called local views to reason about distributed algorithms.

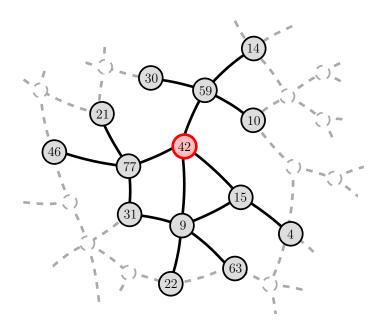
# Local views (0 rounds)



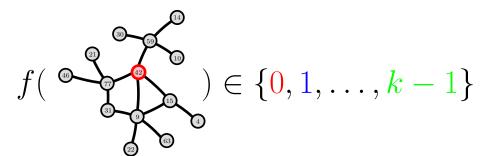
# Local views (1 round)



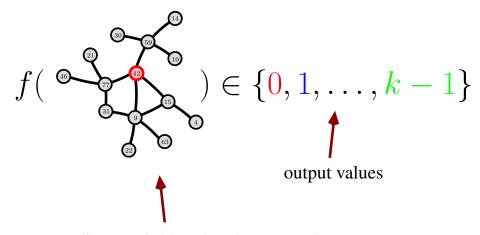
# Local views (2 rounds)



## Algorithms as mappings



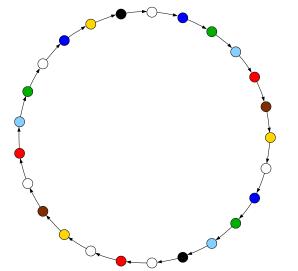
## Algorithms as mappings



radius-2 neighbourhood = 2 rounds

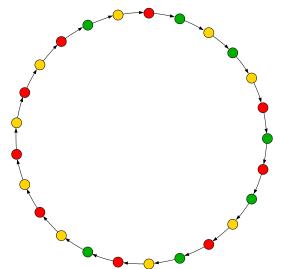
## Colour reduction in directed cycles

**Input:** a *k*-coloured directed cycle (UIDs = colouring)



## Colour reduction in directed cycles

**Output:** a 3-colouring



#### Log-star

The  $\log^*$  function appears often in distributed computing.

Definition: 
$$\log^* k = \min\{i : \overbrace{\log\left(\cdots \log(k)\right)}^{i \text{ times}} \le 1\}$$

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$$\log^* k = \min\{i : \overbrace{\log\left(\cdots \log(k)\right)}^{i \text{ times}} \le 1\}$$

The  $\log^*$  function grows *very* slowly:

- $\log^* 2 = 1$
- $\log^* 4 = 2$
- $\log^* 16 = 3$
- $\log^* 2^{16} = 4$
- $\log^* 2^{65536} = 5$

### Colouring directed cycles

The work focuses on 3-colouring directed cycles:

- A fundamental problem in distributed computing
- ► Always possible in O(log\* k) rounds (Cole and Vishkin 1986)
- ▶ Cannot be done in  $o(\log^* k)$  rounds (Linial 1987)

What is the exact complexity of the problem?

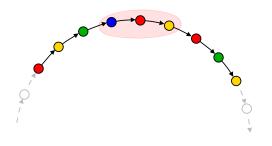
#### The key idea: neighbourhood graphs

Colourability of certain graphs  $\iff$  existence of distributed colouring algorithms:

finding optimal colourings gives optimal algorithms

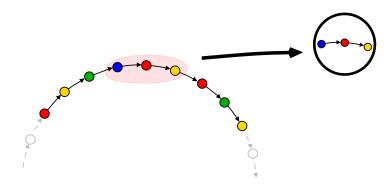
Solving finite combinatorial problems tells us how fast distributed algorithms exist!

### The neighbourhood graph construction

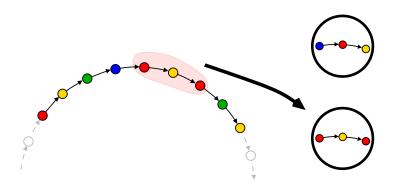


Example: Consider a k-coloured cycle and radius-1 neighbourhoods.

## Neighbourhood graphs construction

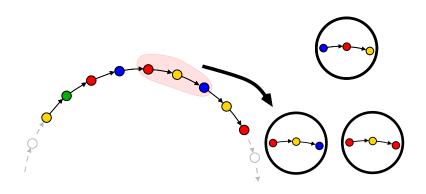


## Neighbourhood graphs: nodes



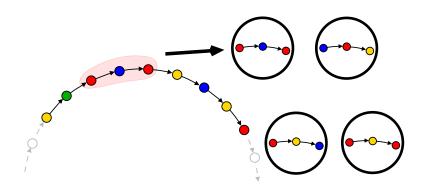
Make a node of each neighbourhood in a coloured cycle.

## Neighbourhood graphs: nodes



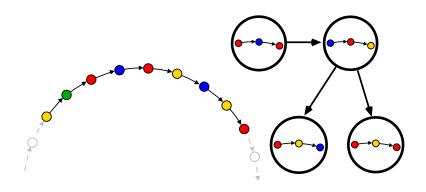
There are many possible neighbourhoods that could occur ("different worlds").

## Neighbourhood graphs: nodes



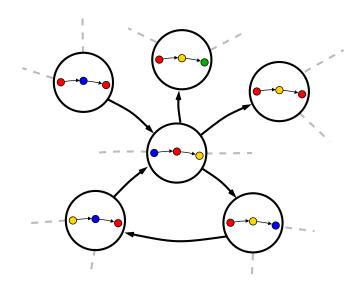
Keep adding all the neighbourhoods.

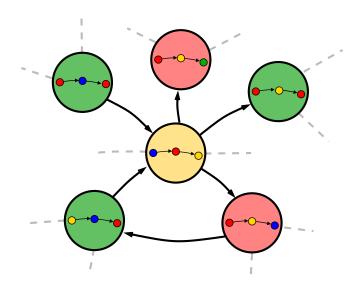
## Neighbourhood graphs: edges

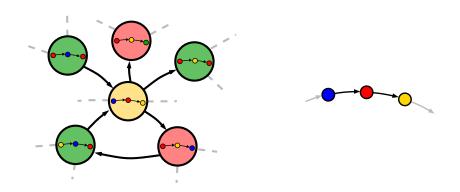


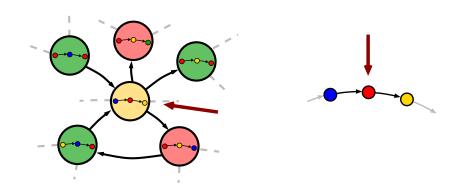
Finally, connect neighbourhoods that can be adjacent.

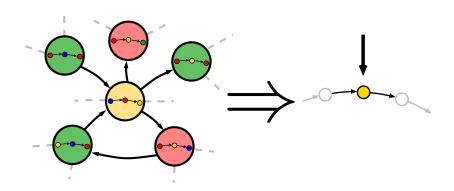
# Neighbourhood graphs

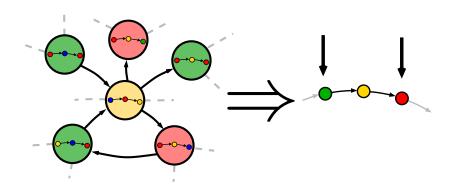












#### **Exact bounds**

#### Complexity of 3-colouring *k*-coloured cycles:

	Before	Now
Positive:	$\frac{1}{2}(\log^* k + 7)$	$\frac{1}{2}(\log^* k + 3)$

#### **Exact bounds**

#### Complexity of 3-colouring *k*-coloured cycles:

	Before	Now
Positive:	$\frac{1}{2}(\log^* k + 7)$	$\frac{1}{2}(\log^* k + 3)$
Negative:	$\frac{1}{2}(\log^* k - 3)$	$\frac{1}{2}(\log^* k + 1)$

- ► Earlier positive results follow from Cole and Vishkin (1986).
- Previous negative result due to Linial (1992).

### Summary

#### In summary:

- distributed computing studies what can be computed efficiently in large networks
- efficient algorithms are local
- graph colouring is inherently global but can be computed with little communication
- existence of distributed algorithms can posed as a combinatorial problem

