Name - Rahul Keshwani Netld - ryk248

Name - Arun Kodnani Netld - ak6384

### **Setup**

```
In [0]: # http://pytorch.org/
from os import path
from wheel.pep425tags import get_abbr_impl, get_impl_ver, get_abi_tag
platform = '{}{}-{}'.format(get_abbr_impl(), get_impl_ver(), get_abi_tag())

accelerator = 'cu80' if path.exists('/opt/bin/nvidia-smi') else 'cpu'
!pip install -q http://download.pytorch.org/whl/{accelerator}/torch-0.3.0.pc
```

### **Imports**

```
In [0]: import torch
import torchvision.transforms as transforms
import torchvision.transforms as transforms
import matplotlib.pyplot as plt
import numpy as np
import sys
import random
from sklearn.metrics import accuracy_score
import pandas as pd
import matplotlib.pyplot as plt
from google.colab import files
plt.style.use('fivethirtyeight')
```

# Utility class for fetching data

```
In [0]: class Data():
          def __init__(self):
            self.transform = transforms.Compose([transforms.ToTensor(),transforms.No
            self.trainset = torchvision.datasets.CIFAR10(root='./data', train=True,
            self.Xtrain, self.ytrain = self.splitXandY(self.trainset)
            self.testset = torchvision.datasets.CIFAR10(root='./data', train=False,
            self.Xtest, self.ytest = self.splitXandY(self.testset)
          def splitXandY(self, data):
            x = []
            y = []
            for image in data:
              x.append(image[0].numpy().flatten())
              y.append(image[1])
            x = np.array(x)
            y = np.array(y)
            return x,y
          def get_xtrain(self):
            return self.Xtrain
          def get ytrain(self):
            return self.ytrain
          def get xtest(self):
            return self.Xtest
          def get ytest(self):
            return self.ytest
          def load data(self):
            Xtrain = self.get_xtrain()
            ytrain = self.get ytrain()
            Xtest = self.get xtest()
            ytest = self.get ytest()
            return (Xtrain, ytrain, Xtest, ytest)
```

### **Neural Network Class**

```
In [0]: # Block for functions and classes.
        def save predictions(filename, y):
          Dumps y into .npy file
          np.save(filename, y)
        class NeuralNetwork(object):
          def init__(self, layer_dimensions, drop_prob=0.0, reg_lambda=0.0):
            np.random.seed(1)
            self.parameters = {}
            for i in range(1,len(layer_dimensions)):
              self.parameters[i] = [np.random.randn(layer dimensions[i], layer dimensions[i])
            self.num_layers = len(layer_dimensions)
            self.drop prob = drop prob
            self.reg_lambda = reg_lambda
          def generateClassVector(self, y):
            result = np.zeros(shape=(10,y.shape[0]))
            result[y, range(y.shape[0])] = 1
            return result
          def affineForward(self, A, W, b):
            Z = np.dot(W,A) + b
            cache = (A, W, b, Z)
            return Z, cache
          def activationForward(self, A, activation):
            if activation == 'relu':
              return np.maximum(0, A)
            if activation == 'softmax':
              y = np.exp(A - np.max(A))
              return y/y.sum(axis=0)
          def forwardPropagation(self, X):
            allCache = []
            for layer in range(1,self.num layers-1):
              Z, cache = self.affineForward(A, self.parameters[layer][0], self.param
              A = self.activationForward(Z, 'relu')
              allCache.append(cache)
            ZL, last cache = self.affineForward(A, self.parameters[self.num layers-]
            AL = self.activationForward(ZL, 'softmax')
            allCache.append(last cache)
            return AL, allCache
          def costFunctions(self, AL, y):
            correct prob = AL[y, range(y.shape[0])]
            cost = -np.sum(np.log(correct prob))/y.shape[0]
            cost = np.squeeze(cost)
```

```
dAL = AL - self.generateClassVector(y)
  return cost, dAL
def affineBackward(self, dA prev, cache):
  A, W, b, Z = cache
  dW = np.dot(dA prev, A.T)/A.shape[1]
  dB = np.sum(dA prev, axis=1, keepdims=True)/A.shape[1]
  dA = np.dot(W.T, dA prev )
  gradients = [dW, dB]
  return dA, gradients
def activationBackward(self, dA, cache, activation="relu"):
  A, W, b, Z = cache
  return self.relu derivative(dA, Z)
def relu derivative(self, dx, cached x):
  dx[cached_x < 0] = 0
  return dx;
def backPropagation(self, dAL, Y, cache):
  gradients = {}
  cacheLength = len(cache)
  dAL_prev, gradients[self.num_layers - 1] = self.affineBackward(dAL, cack
  for layer in range(self.num layers-2, 0, -1):
    dZ prev = self.activationBackward(dAL prev, cache[layer-1])
    dAL prev, gradients[layer] = self.affineBackward(dZ prev, cache[layer-
  return gradients
def updateParameters(self, gradients, alpha):
  for layer in range(1,self.num layers):
    dW, dB = gradients[layer]
    W, b = self.parameters[layer]
    W = W - alpha*dW
    b = b - alpha*dB
    self.parameters[layer][0] = W
    self.parameters[layer][1] = b
def train(self, X, y, iters, alpha, batch size, print every):
  randomizer = np.array(range(X.shape[0]))
  random.shuffle(randomizer)
  self.iterationCost = pd.DataFrame(columns=['cost'])
  for i in range(iters):
    for k in range((int)(X.shape[0]/batch size)):
      inputX = [X[x] for x in randomizer[(k*batch size): (k*batch size + k
      inputY = [y[x] for x in randomizer[(k*batch_size): (k*batch_size + k
      inputX = np.array(inputX)
      inputY = np.array(inputY)
      AL, allCache = self.forwardPropagation(inputX.T)
      cost, dAL = self.costFunctions(AL, inputY)
```

```
gradients = self.backPropagation(dAL, inputY, allCache)
      self.updateParameters(gradients, alpha)
    self.iterationCost.loc[i] = cost
    if i % print_every == print_every-1:
      print("Last cost after iteration", i, ":", cost)
def predict(self, X):
  predicted, cache = self.forwardPropagation(X)
  predicted = self.activationForward(predicted, 'softmax')
  predicted_label = []
  for i in range(predicted.shape[1]):
   max prob = max(predicted[:,i])
    predicted label.append(list(predicted[:,i]).index(max prob))
  return predicted_label
def summary(self):
  print("Layer\tShape\tParameters")
  for layer in self.parameters:
    shapes = str(self.parameters[layer][1].shape[0])
   parameters = self.parameters[layer][0].shape[0]*self.parameters[layer]
    print(layer,"\t", shapes,"\t", parameters)
  self.iterationCost.plot(title='Loss Vs Iterations')
```

## Loading the data

```
In [5]: obj = Data()
Xtrain, ytrain, Xtest, ytest = obj.load_data()
```

Downloading https://www.cs.toronto.edu/~kriz/cifar-10-python.tar.gz (https://www.cs.toronto.edu/~kriz/cifar-10-python.tar.gz) to ./data/cifar-10-python.tar.gz

Files already downloaded and verified

```
Last cost after iteration 9 : 2.2796301717421397
Last cost after iteration 19 : 2.114793067567329
Last cost after iteration 29: 1.9599712922880863
Last cost after iteration 39 : 1.875005220840953
Last cost after iteration 49: 1.7658571131993086
Last cost after iteration 59 : 1.680011513648965
Last cost after iteration 69 : 1.6199667813535832
Last cost after iteration 79 : 1.5732004946478326
Last cost after iteration 89 : 1.5382875144151456
Last cost after iteration 99 : 1.5056067924757324
Last cost after iteration 109 : 1.4746092793802947
Last cost after iteration 119 : 1.4447315014164857
Last cost after iteration 129 : 1.4165190391591722
Last cost after iteration 139 : 1.3920144069507112
Last cost after iteration 149: 1.3701252086535007
Last cost after iteration 159 : 1.3494698437095127
Last cost after iteration 169 : 1.3282786263406243
Last cost after iteration 179 : 1.3072009394084687
Last cost after iteration 189 : 1.2877188429681843
Last cost after iteration 199 : 1.2682611815811744
Laver
        Shape
                Parameters
1
         512
                 1573376
2
         256
                 131328
3
         10
                 2570
```



```
In [0]: pLabels = nn.predict(Xtest.T)
    save_predictions('ans1-ryk248.npy', pLabels)
    save_predictions('ans1-ak6384.npy', pLabels)
```