1. AIM: To print the name via pub/sub
2. METHOD:

* Create catkin workspace: mkdir -p catkin\_ws/src
* Create catkin package: catkin\_create\_pkg exp0\_postlab rospy roscpp std\_msgs
* Create scripts: cd src/exp0\_postlab/src && mkdir scripts && cd scripts && touch publisher.py && touch subscriber.py
* Add the scripts in this directory
* Catkin Make: catkin\_make

## 3. RESULT: Successfully published and received messages via ROS’s pubsub transport