ThorBScope /ThorMCM5000:

Port = 31, baudrate = 9600

ThorBCM:

Port = 33, 34, 35, baudrate = 115200

ThorMCM3000:

Port = 32, baudrate = 115200

Device File Setting:

State.Init.MicroscopeSystem = "Thor"; %if you want to use Thorlab system.

State.Init.THorPMTModule = “ThorECU” or “ThorBScope”

State.Init.ThorFlipper = “ThorBCA” or “ThorBScope”

State.Init.MotorHWName = "ThorMCM3000" or “ThorMCM5000” or “ThorBScope”