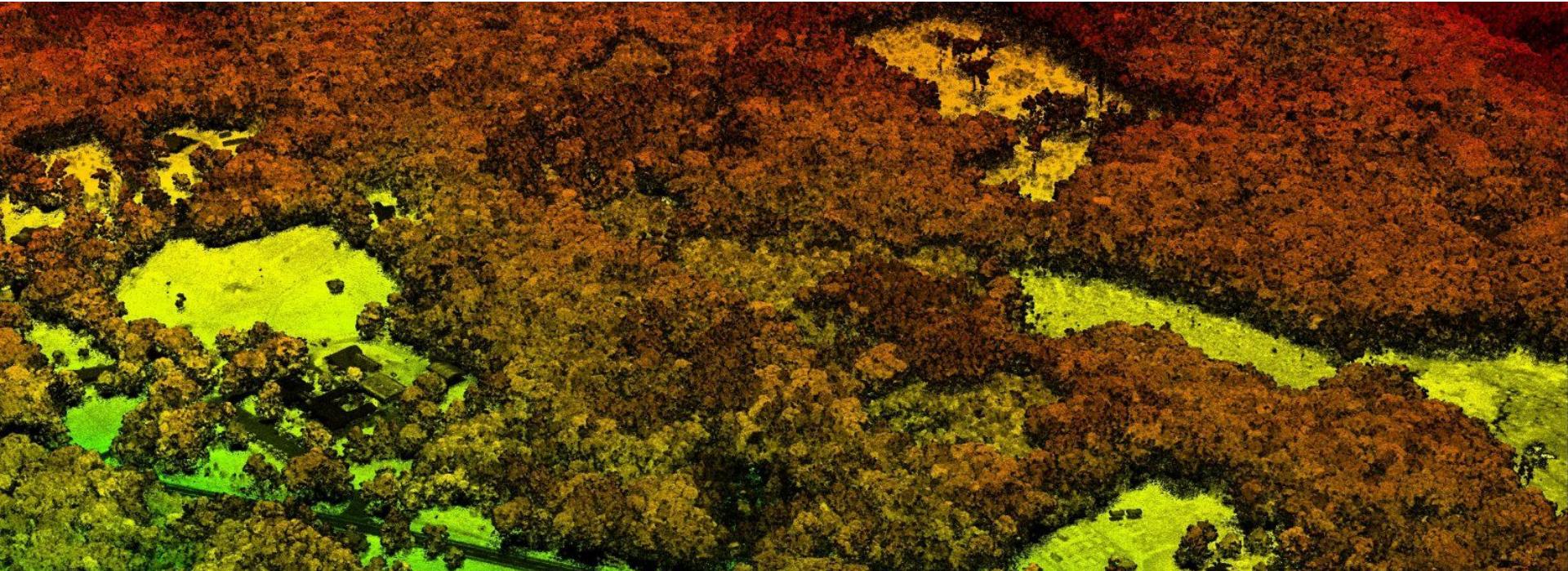


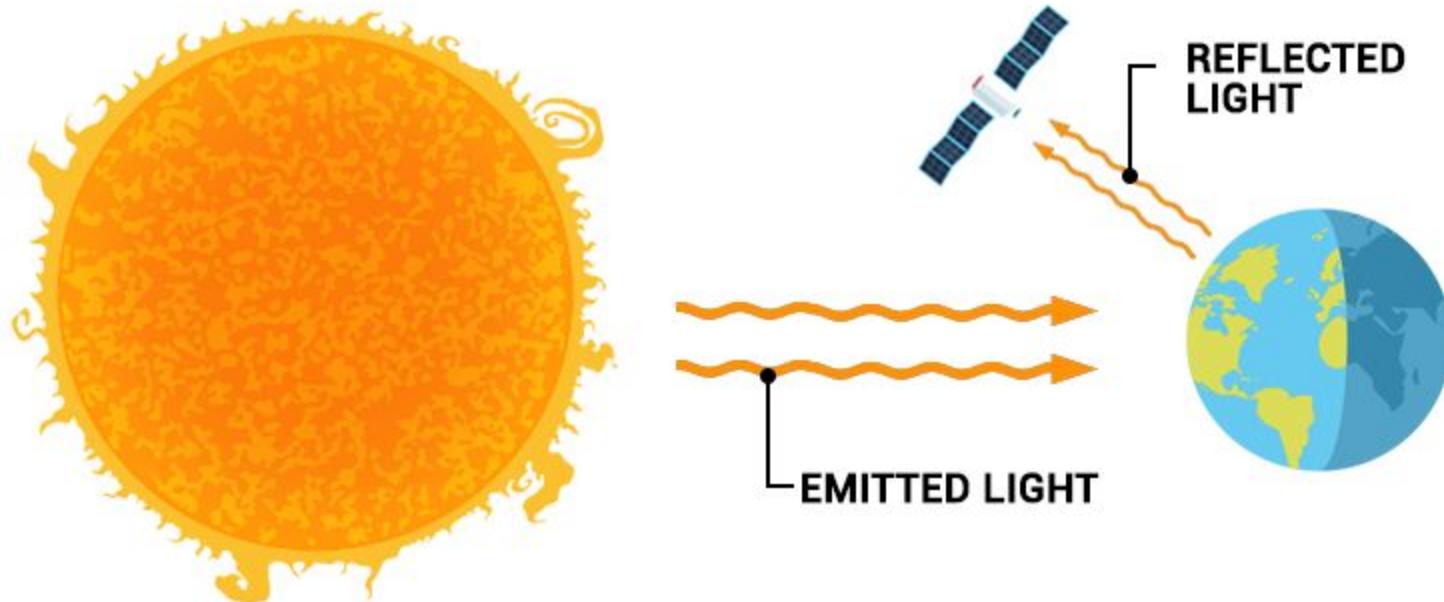
EDS 223: Geospatial Analysis & Remote Sensing

Week 10

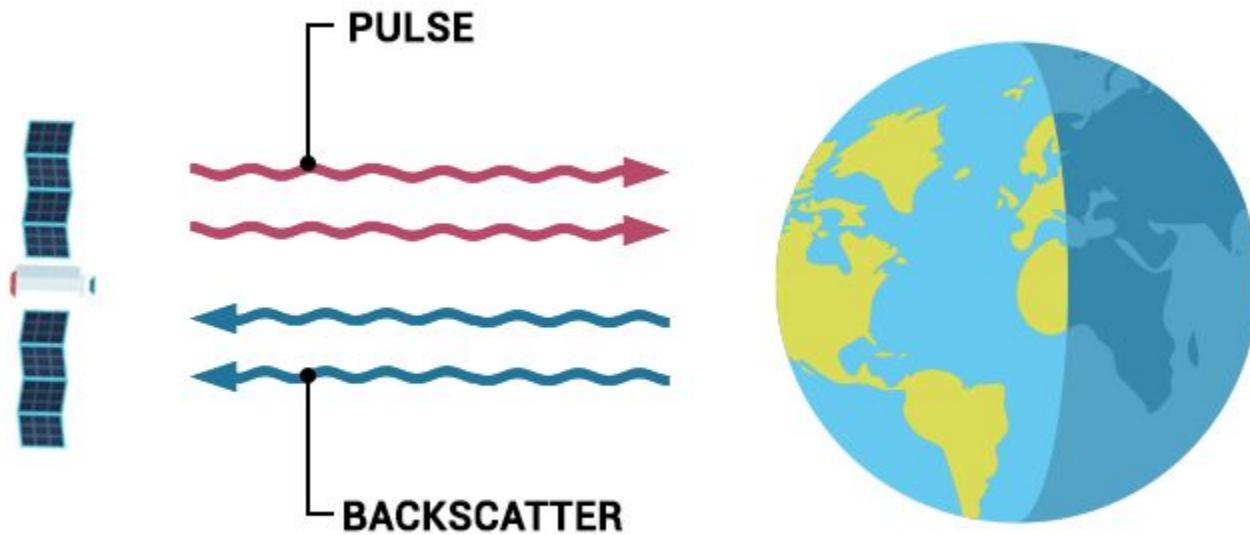


NEON

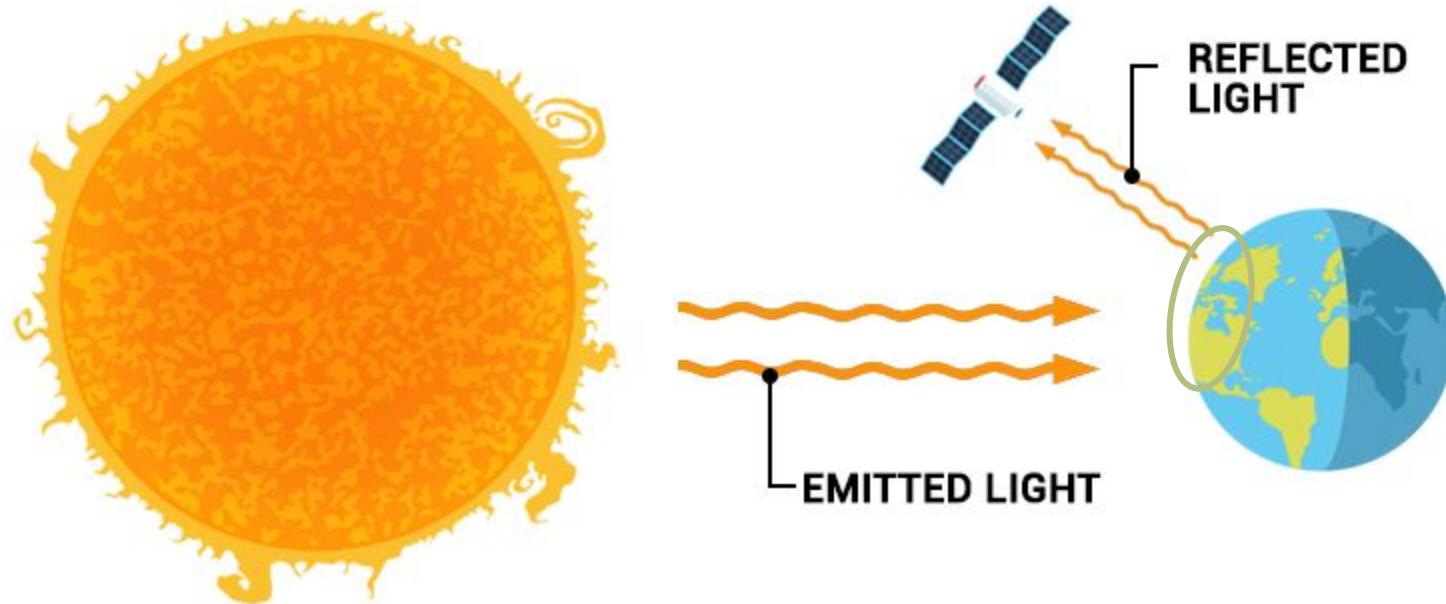
Passive remote sensing



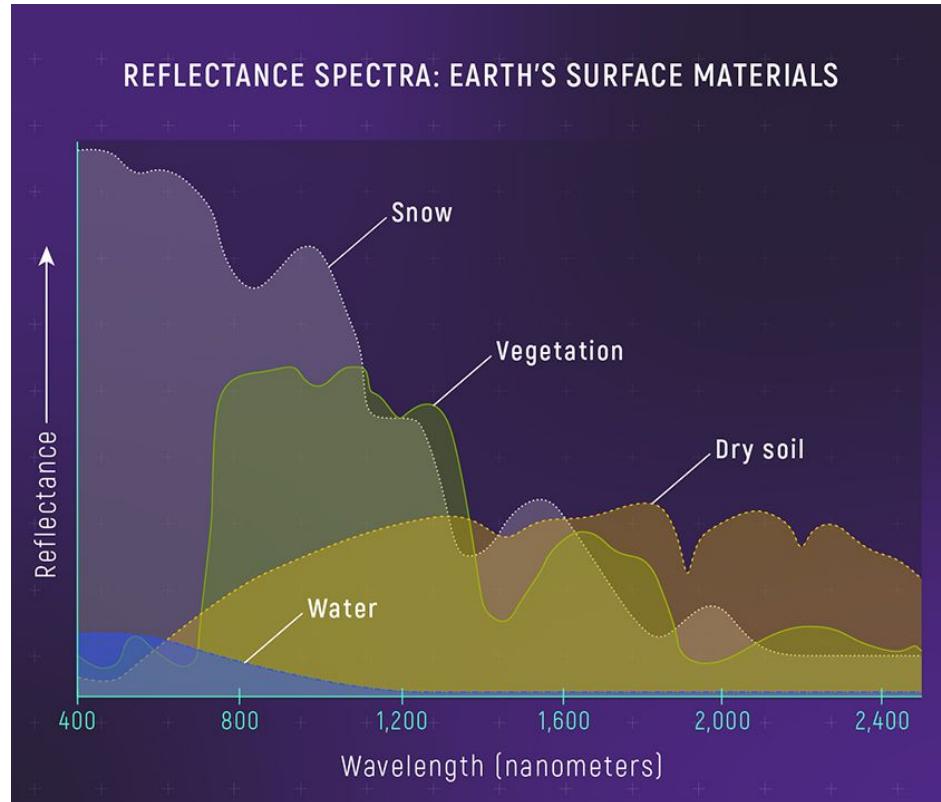
Active remote sensing



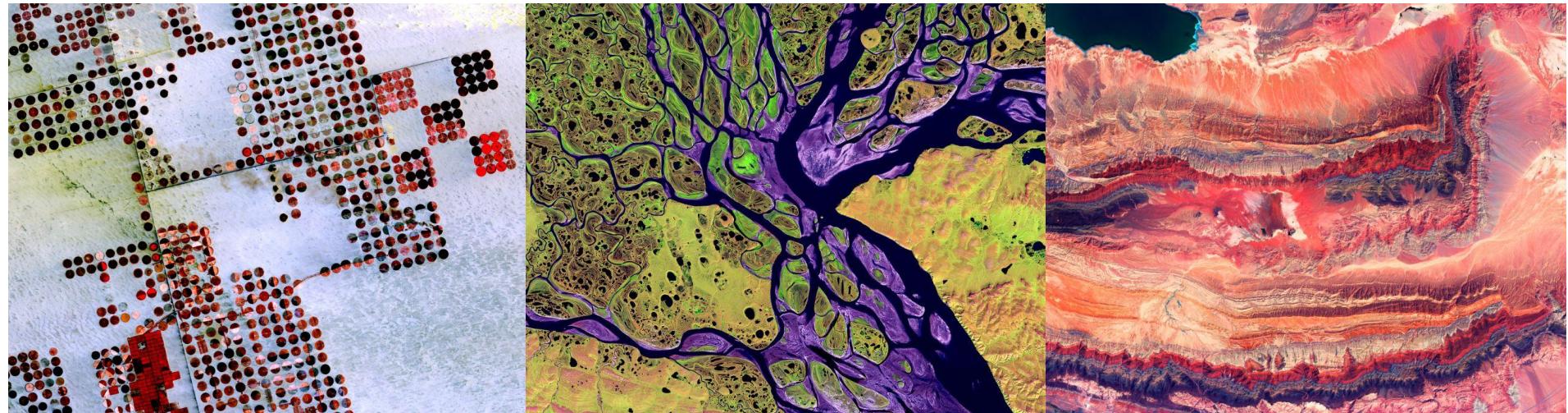
Passive remote sensing



Reflectance spectra

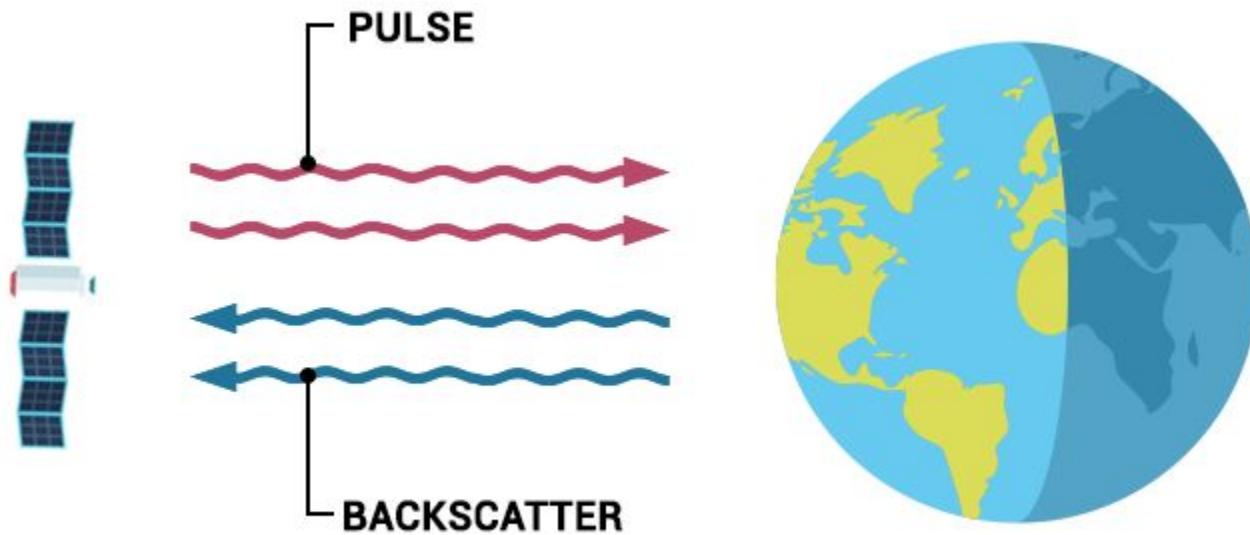


Passive remote sensing



USGS via Unsplash

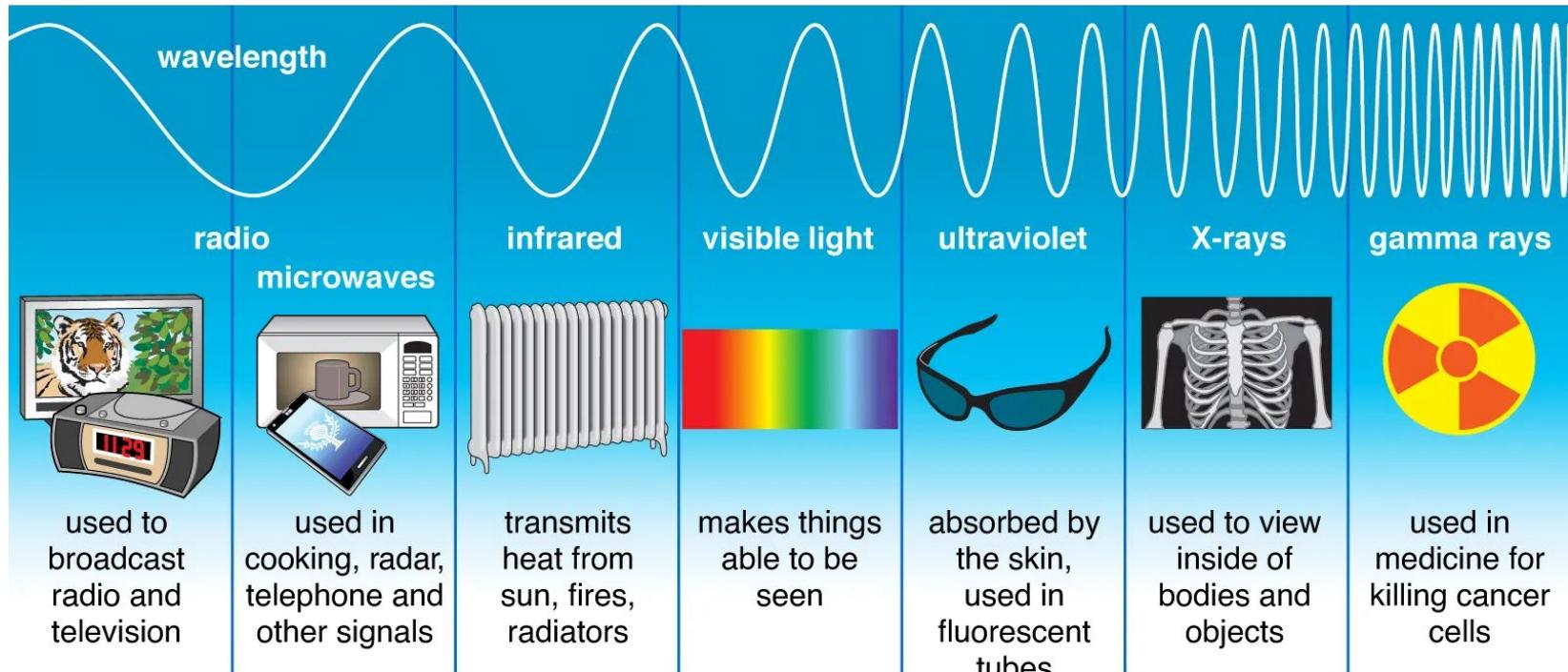
Active remote sensing



What is remote sensing?

“**the art, science, and technology** of obtaining reliable information about physical objects and the environment, through the process of recording, measuring, and interpreting imagery and digital representations of **energy** patterns derived from **non-contact sensor systems.**”
(Colwell, 1997)

Electromagnetic spectrum



Active remote sensing

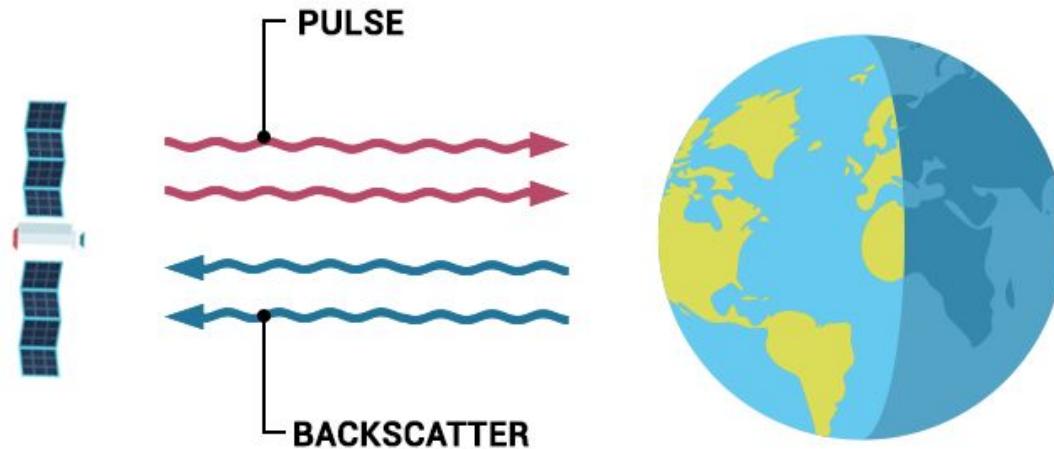
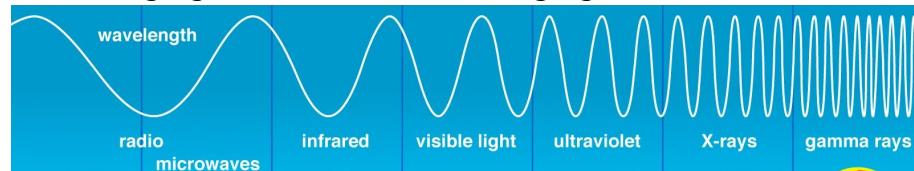
What type of energy are we working with?

RADAR

Radio Detection
and Ranging

LiDAR

Light Detection
and Ranging



Active remote sensing

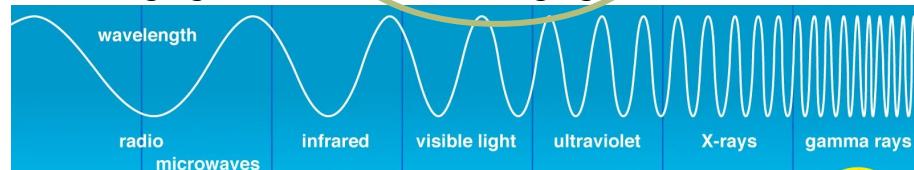
What type of energy are we working with?

RADAR

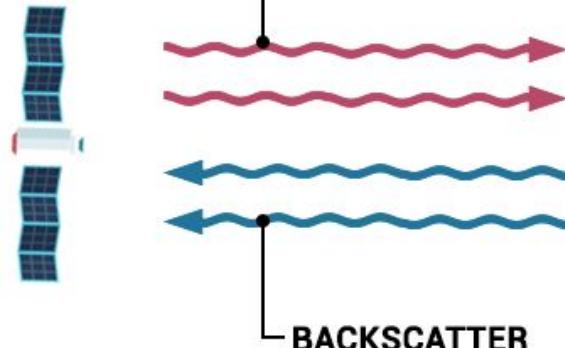
Radio Detection
and Ranging

LiDAR

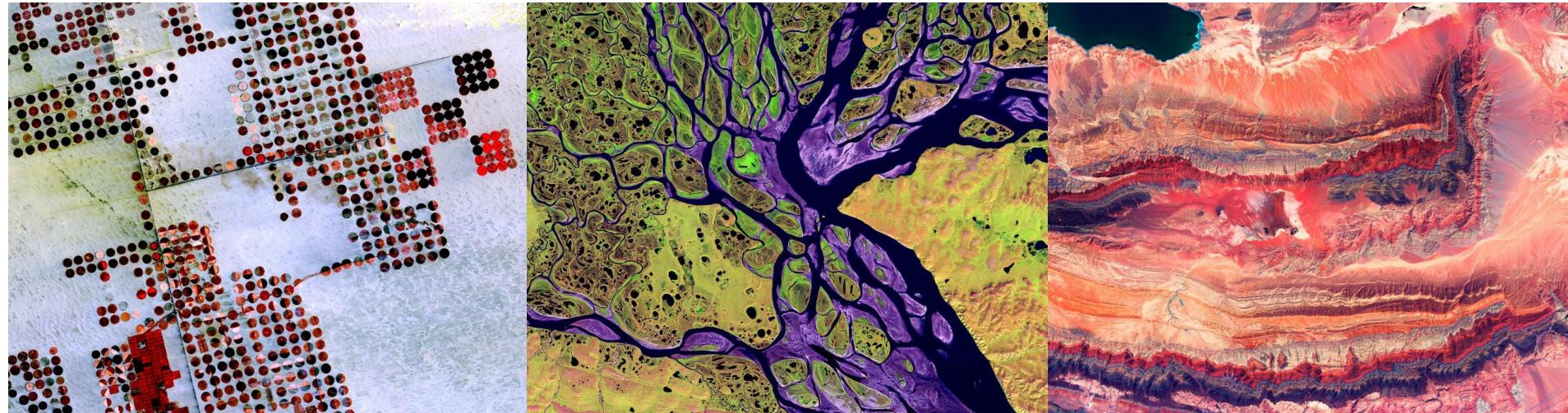
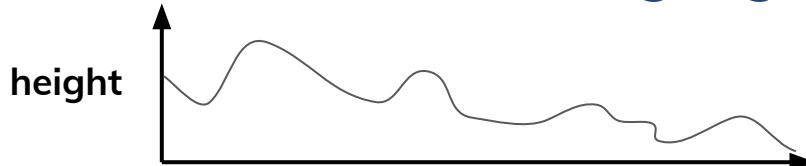
Light Detection
and Ranging



PULSE

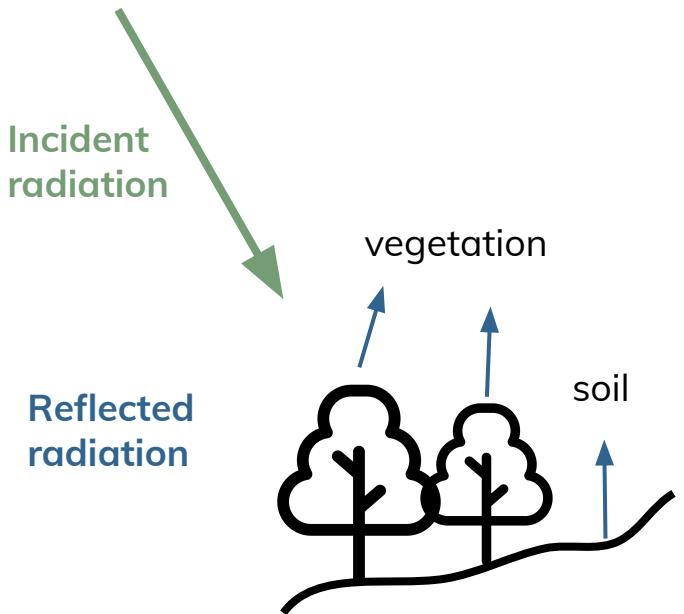


LiDAR: Light Detection and Ranging

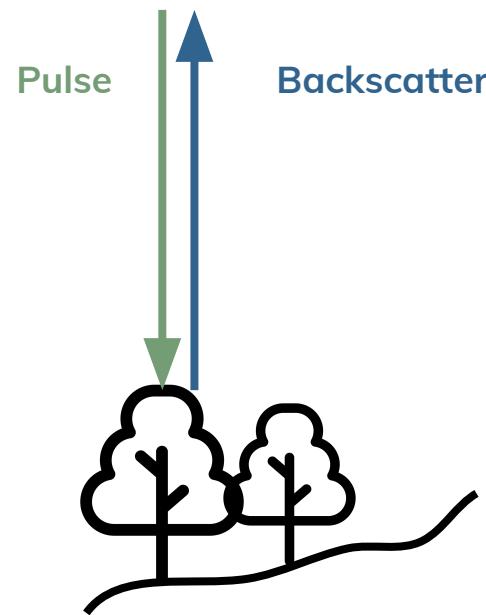
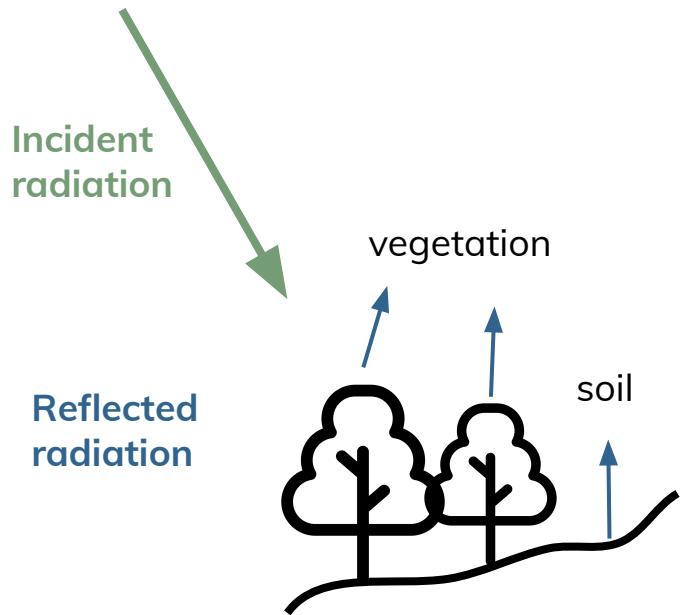


USGS via Unsplash

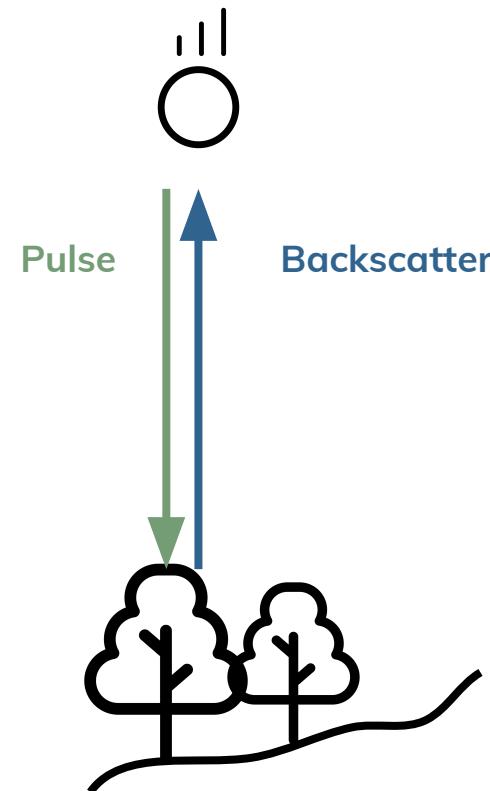
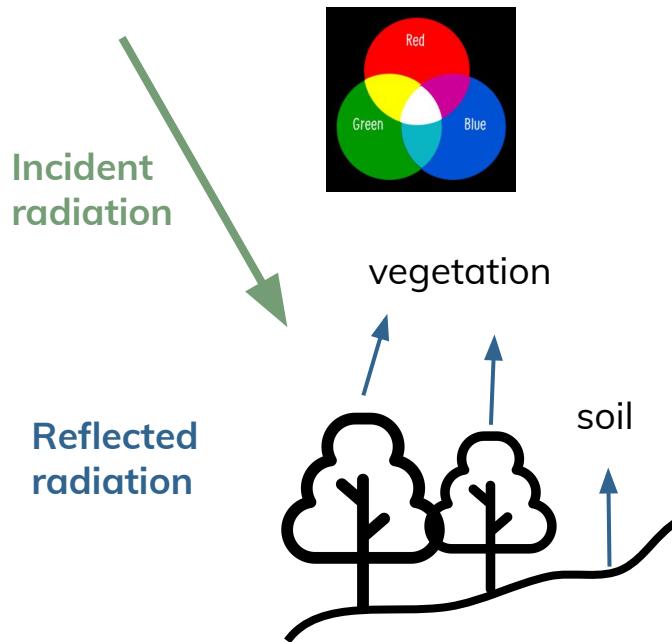
Using light to measure height



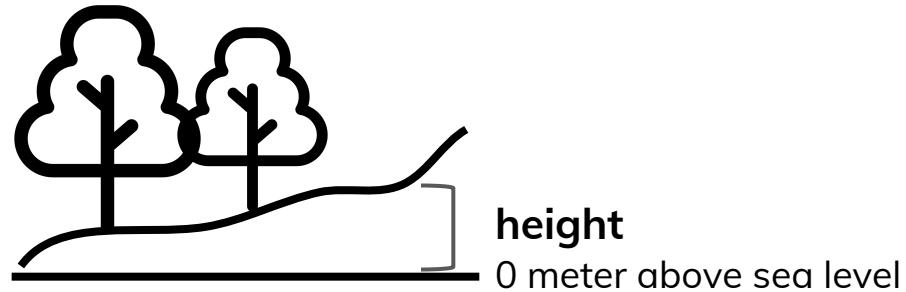
Using light to measure height



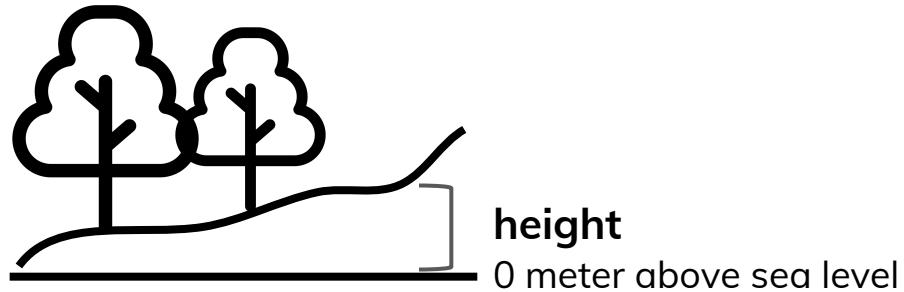
Using light to measure height



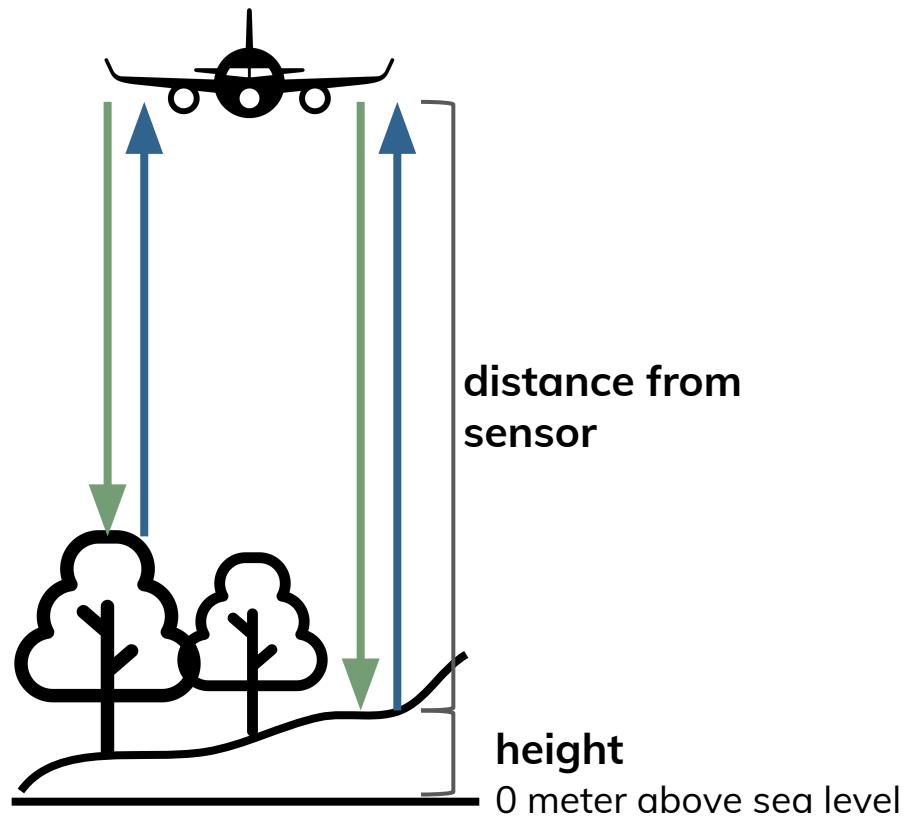
Using light to measure height



Using light to measure height

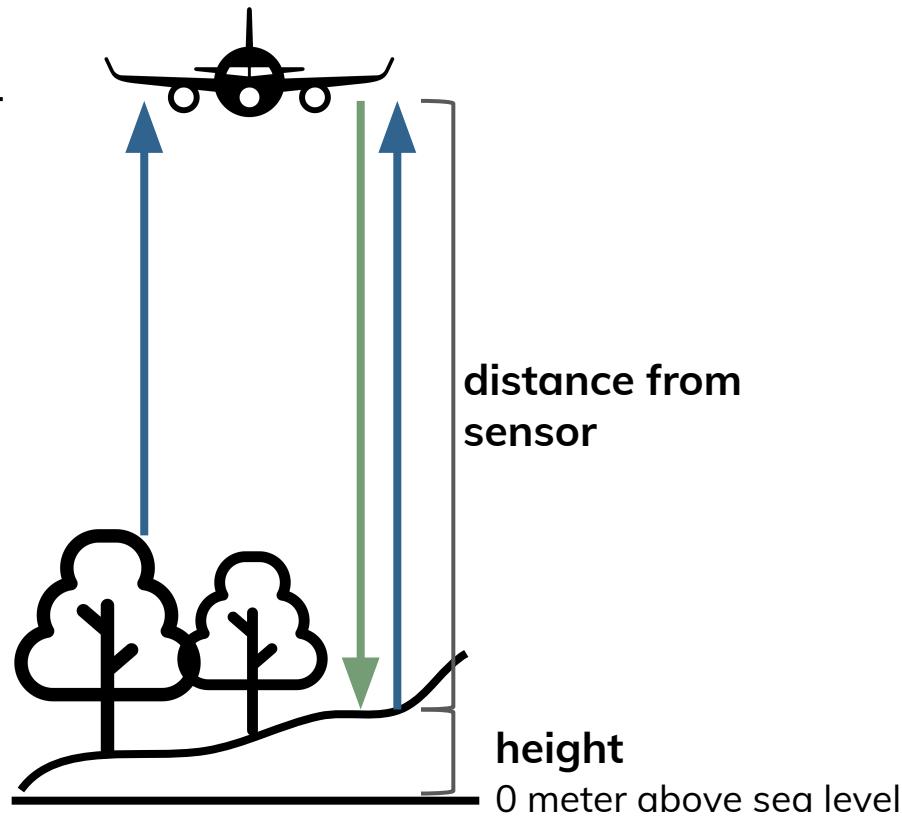


Using light to measure height



Using light to measure height

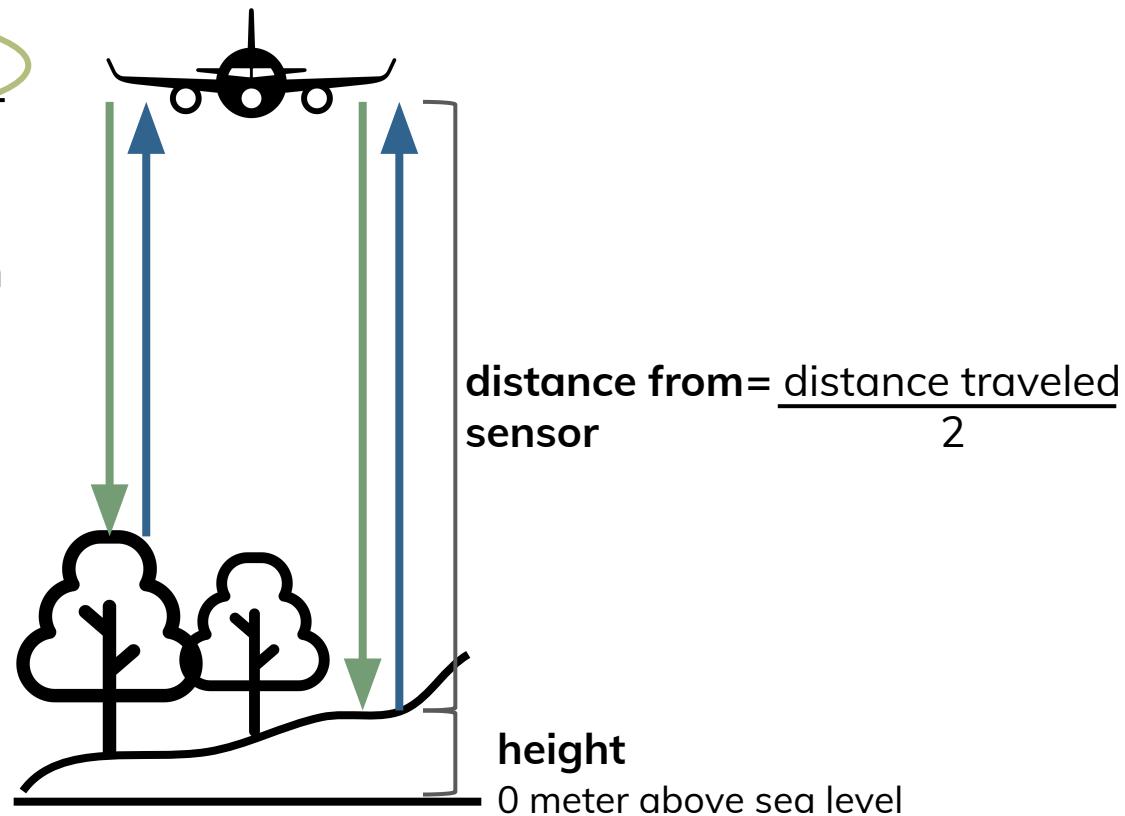
$$\text{Velocity} = \frac{\Delta x}{\Delta t} = \frac{\text{distance traveled}}{\text{duration}}$$



Using light to measure height

$$\text{Velocity} = \frac{\Delta x}{\Delta t} = \frac{\text{distance traveled}}{\text{duration}}$$

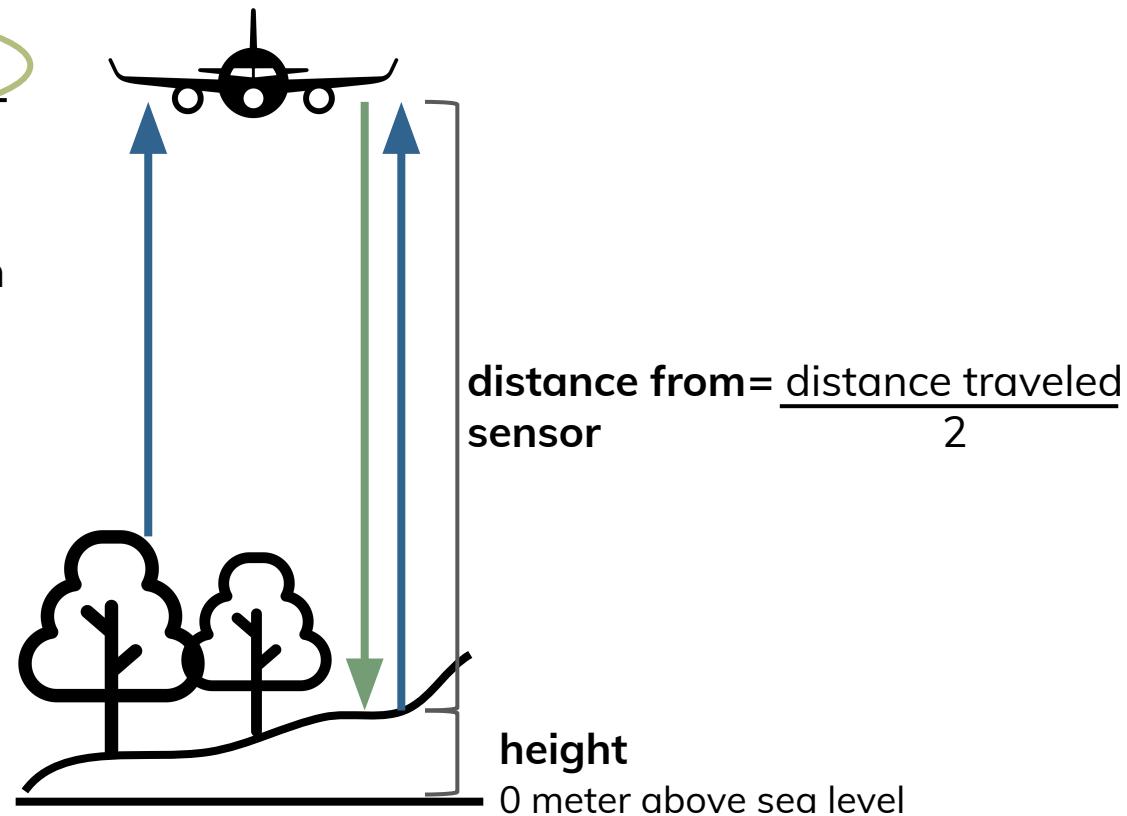
$$\text{distance traveled} = \text{velocity} \times \text{duration}$$



Using light to measure height

$$\text{Velocity} = \frac{\Delta x}{\Delta t} = \frac{\text{distance traveled}}{\text{duration}}$$

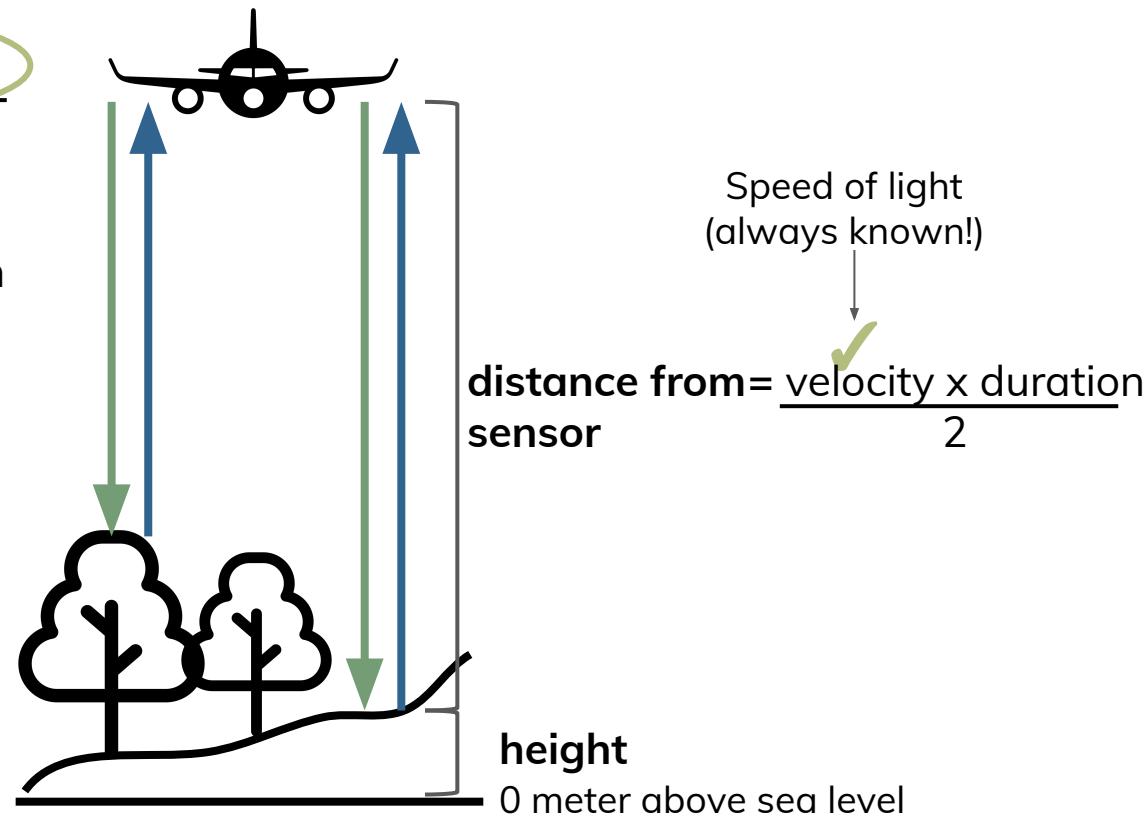
distance traveled = velocity x duration



Using light to measure height

$$\text{Velocity} = \frac{\Delta x}{\Delta t} = \frac{\text{distance traveled}}{\text{duration}}$$

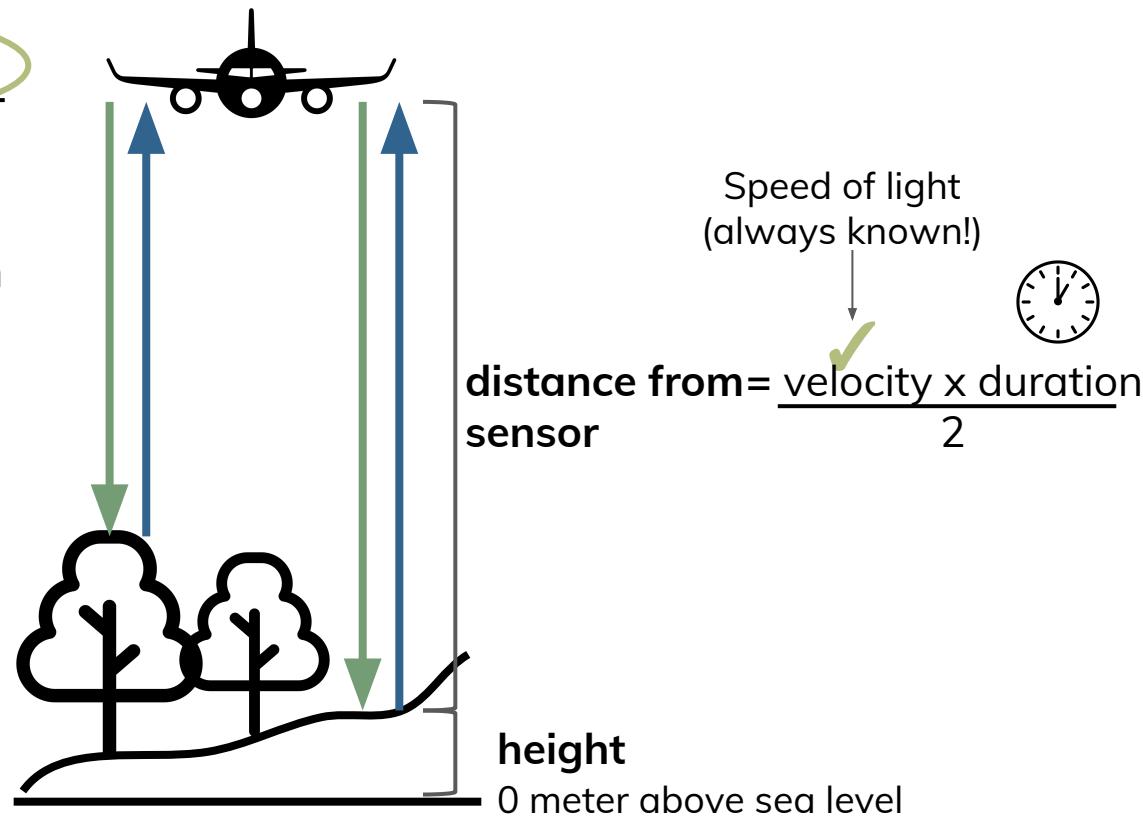
$$\text{distance traveled} = \text{velocity} \times \text{duration}$$



Using light to measure height

$$\text{Velocity} = \frac{\Delta x}{\Delta t} = \frac{\text{distance traveled}}{\text{duration}}$$

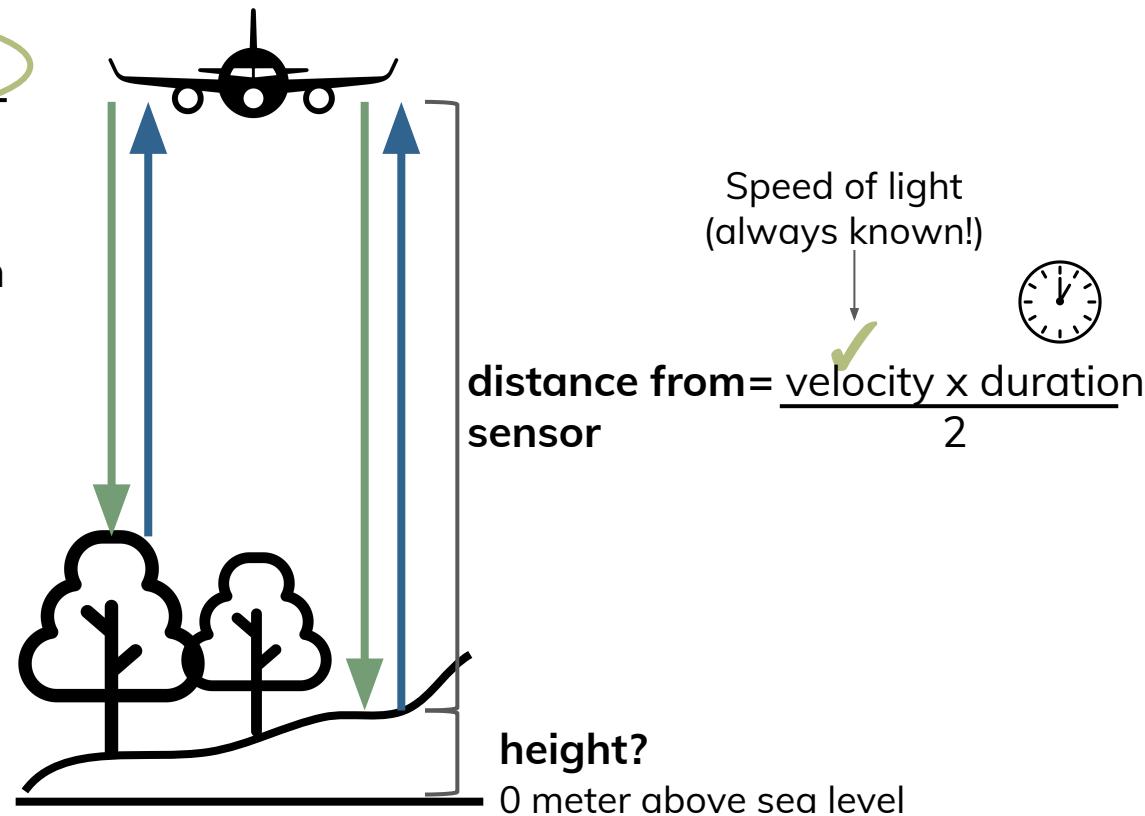
$$\text{distance traveled} = \text{velocity} \times \text{duration}$$



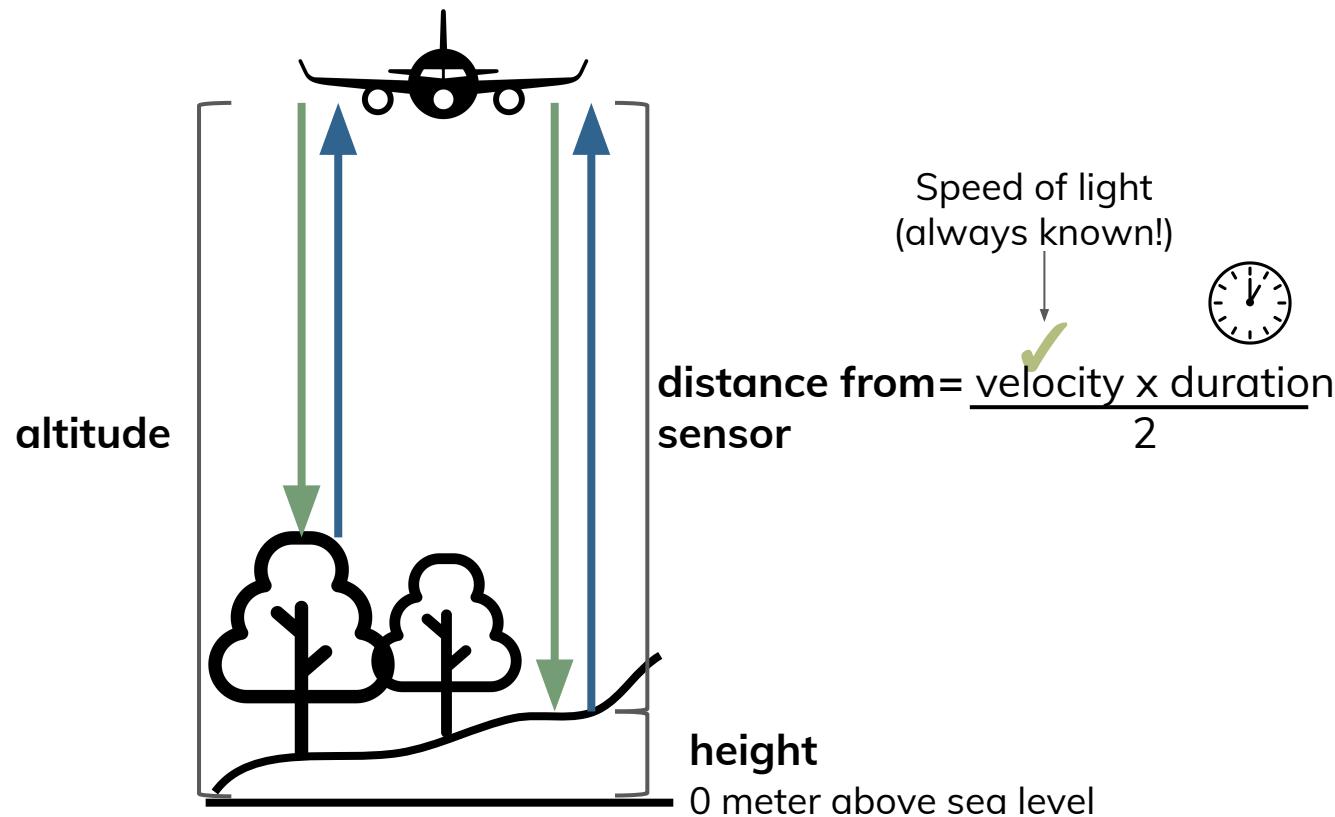
Using light to measure height

$$\text{Velocity} = \frac{\Delta x}{\Delta t} = \frac{\text{distance traveled}}{\text{duration}}$$

$$\text{distance traveled} = \text{velocity} \times \text{duration}$$



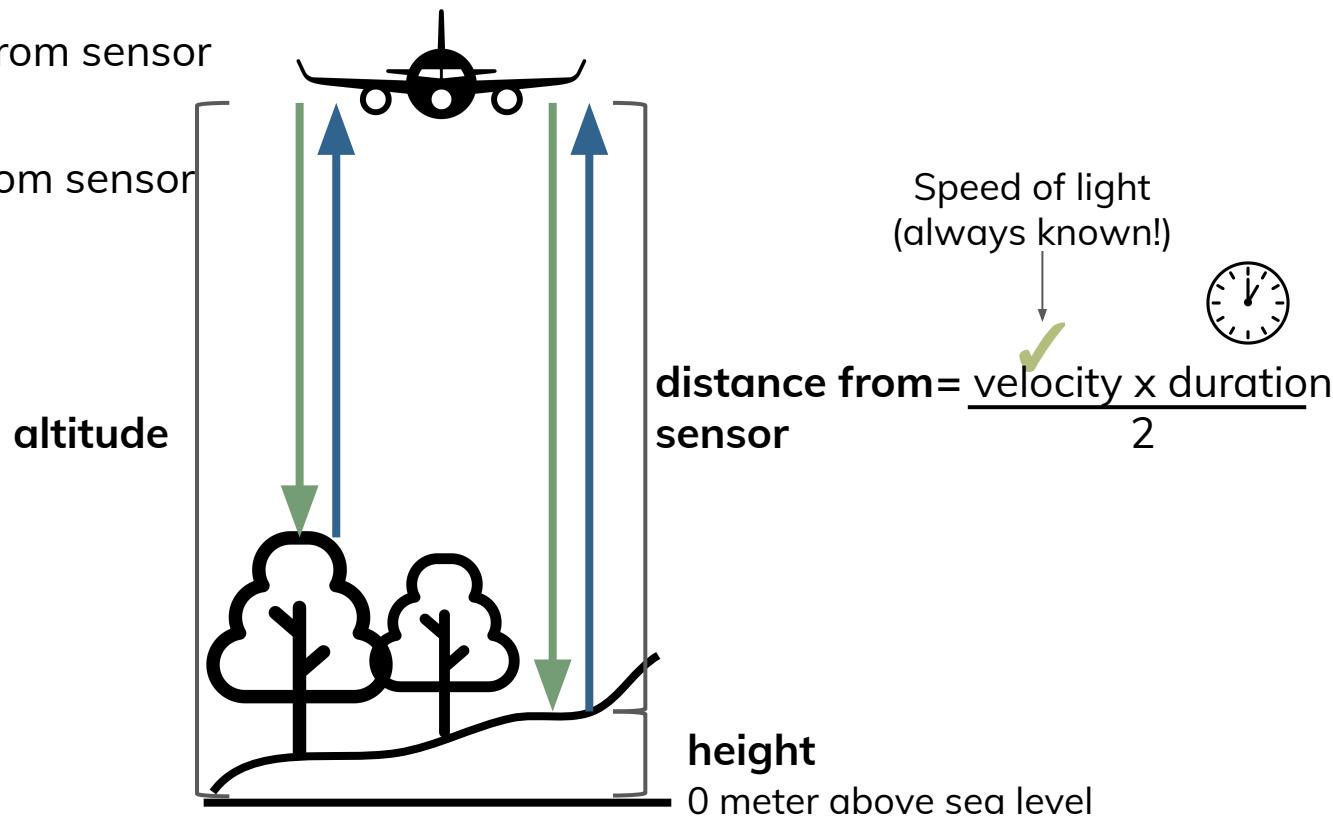
Using light to measure height



Using light to measure height

altitude = height + distance from sensor

height = altitude - distance from sensor

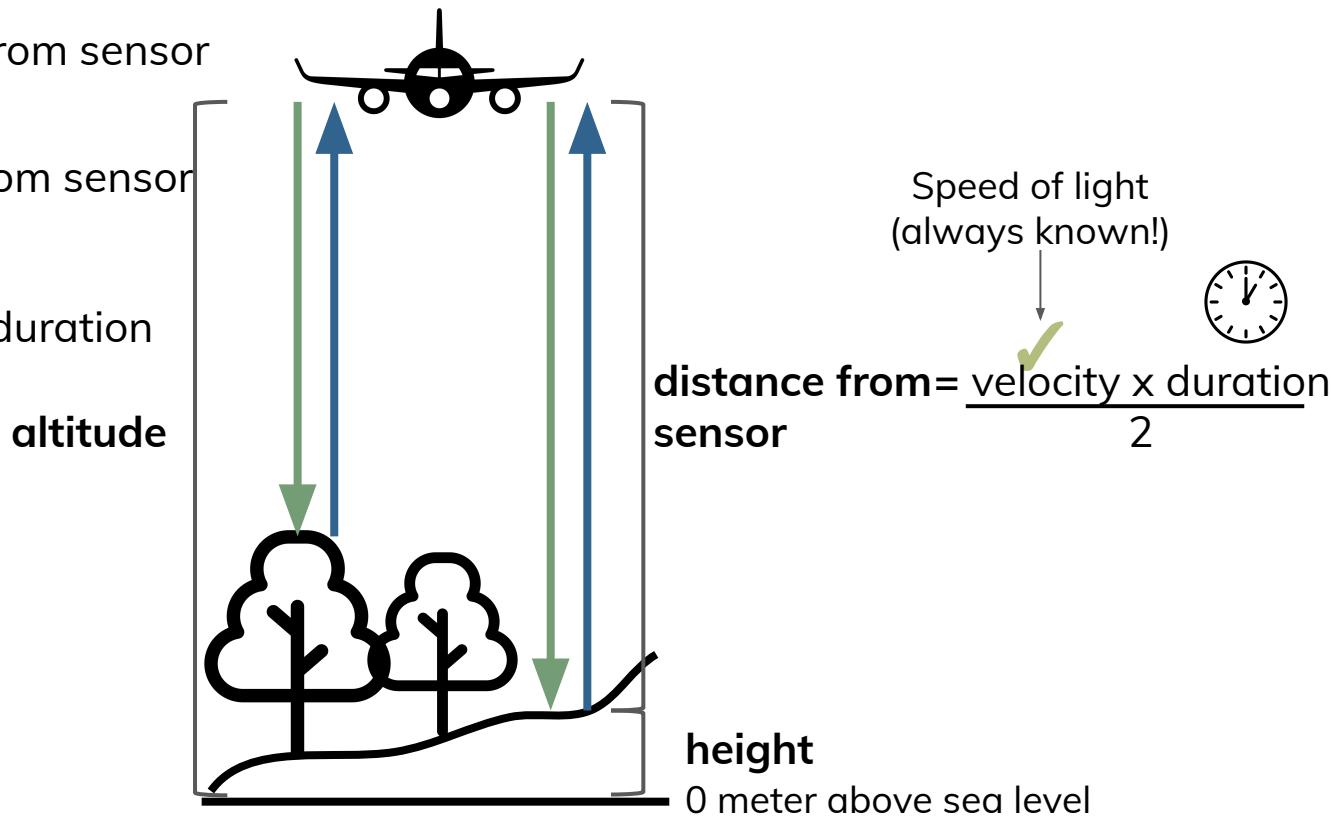


Using light to measure height

altitude = height + distance from sensor

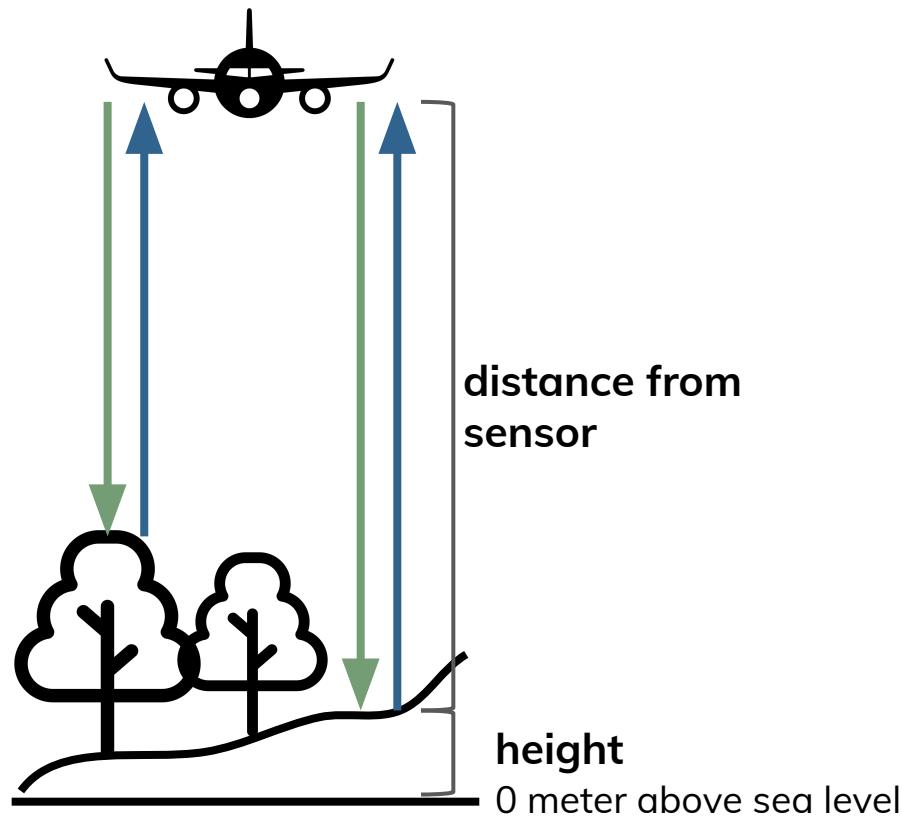
height = altitude - distance from sensor

height is inversely related to duration



Using light to measure height

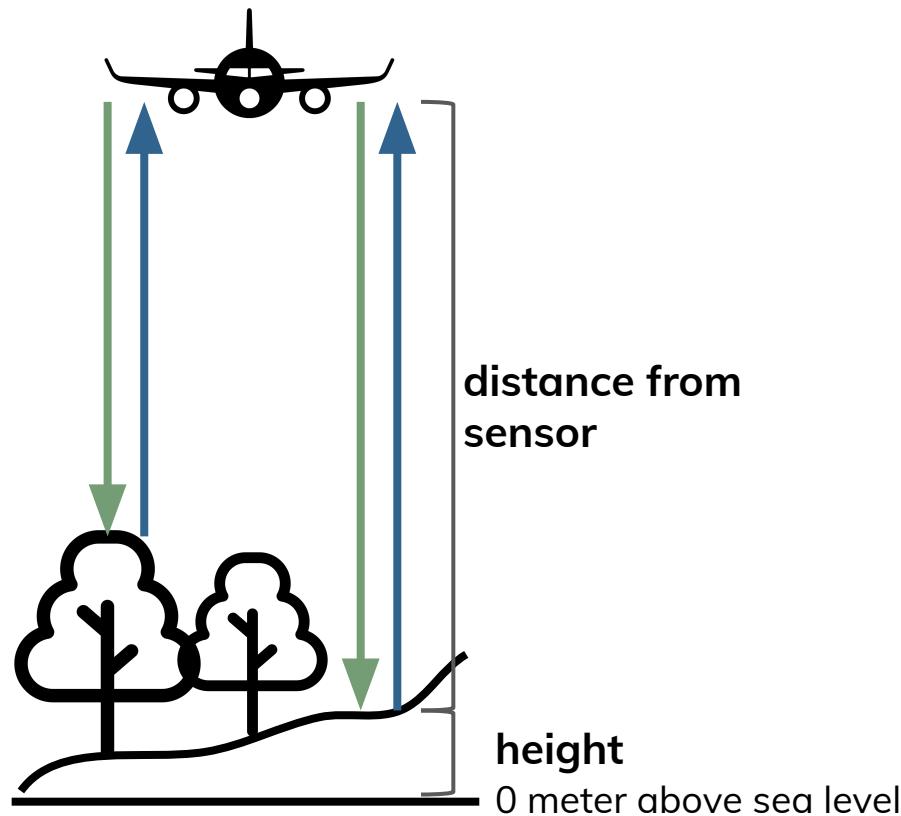
What components do we need?



Using light to measure height

What components do we need?

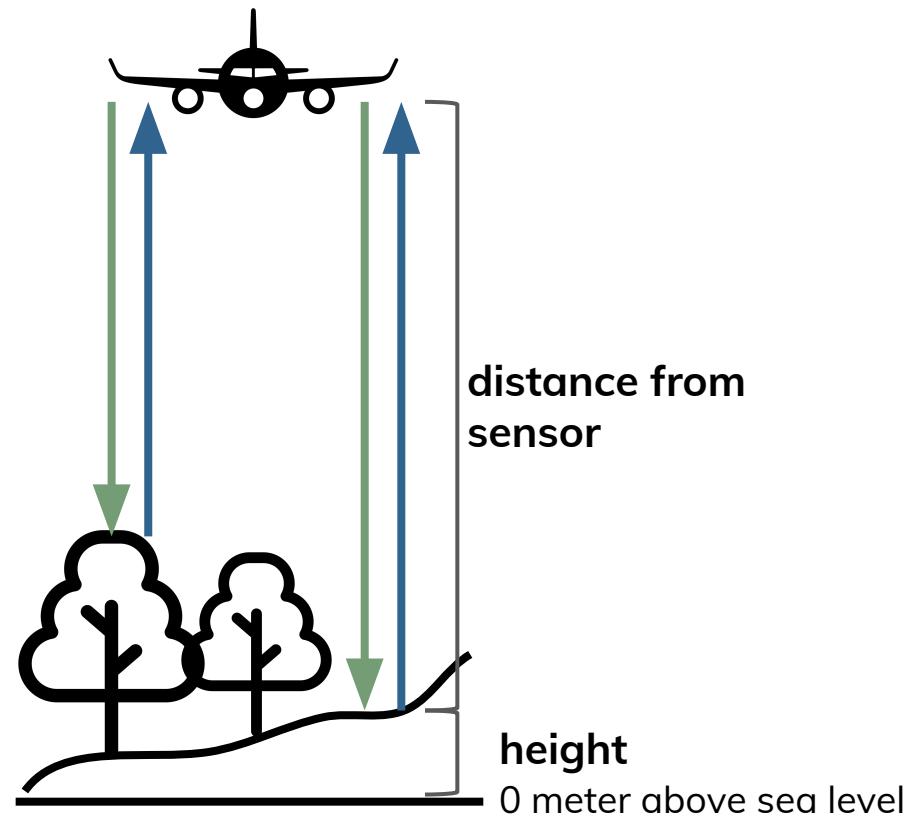
- emit/receive radiation
- know location
- know orientation
- keep track of everything



Using light to measure height

What components do we need?

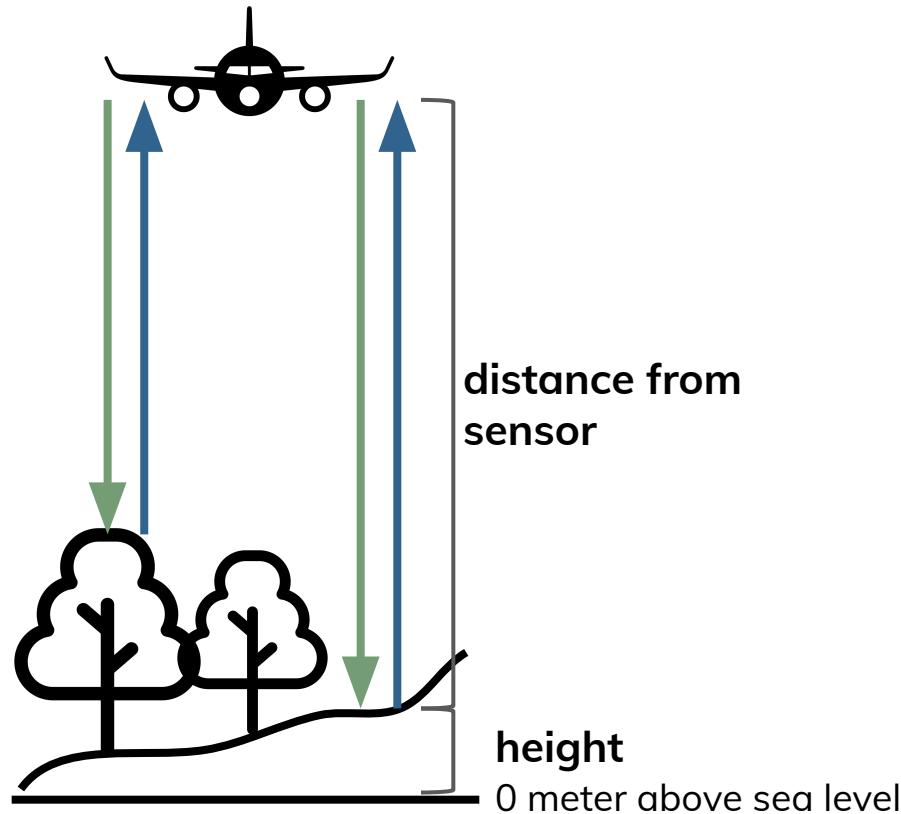
- emit/receive radiation
- know location
- know orientation
- keep track of everything



Using light to measure height

What components do we need?

- **emit/receive radiation**
 - Laser
- know location
- know orientation
- keep track of everything



Lasers

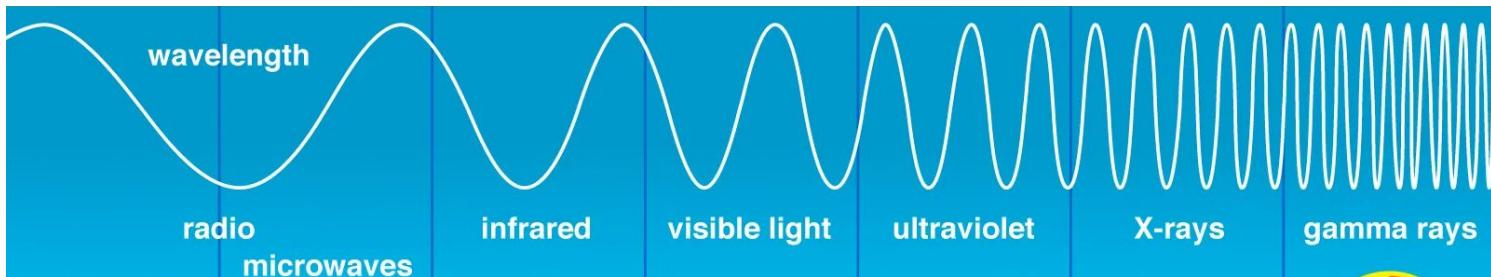


Source: Google Image search for "laser cats"

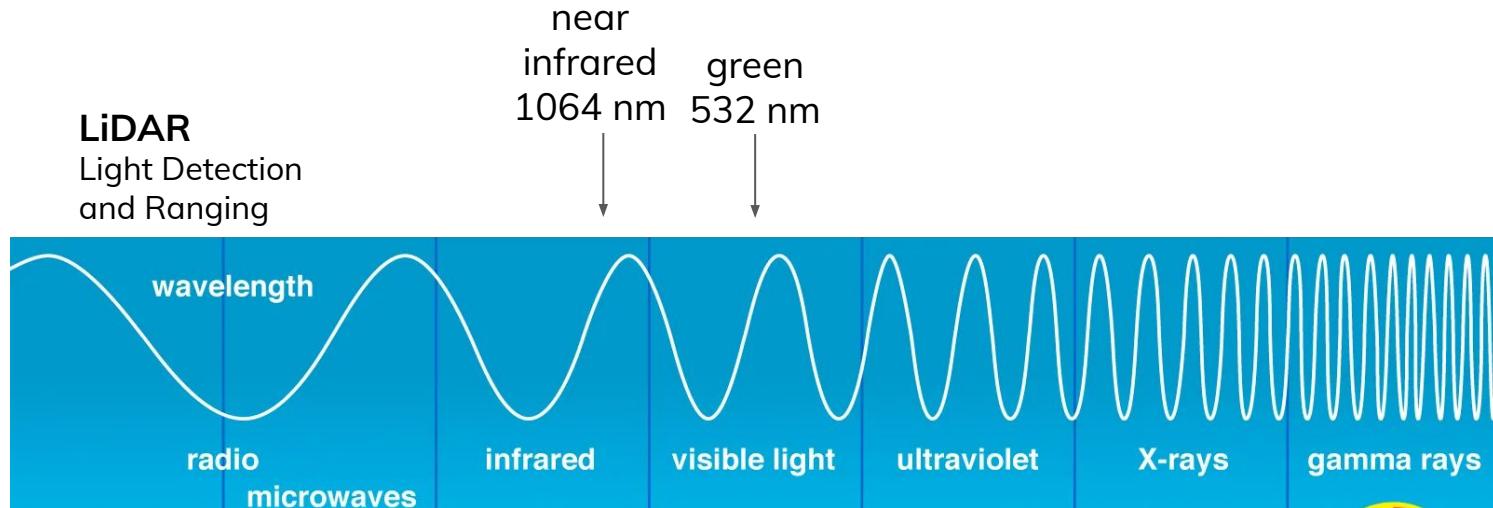
Lasers

LiDAR
Light Detection
and Ranging

near
infrared
1064 nm green
532 nm



Lasers

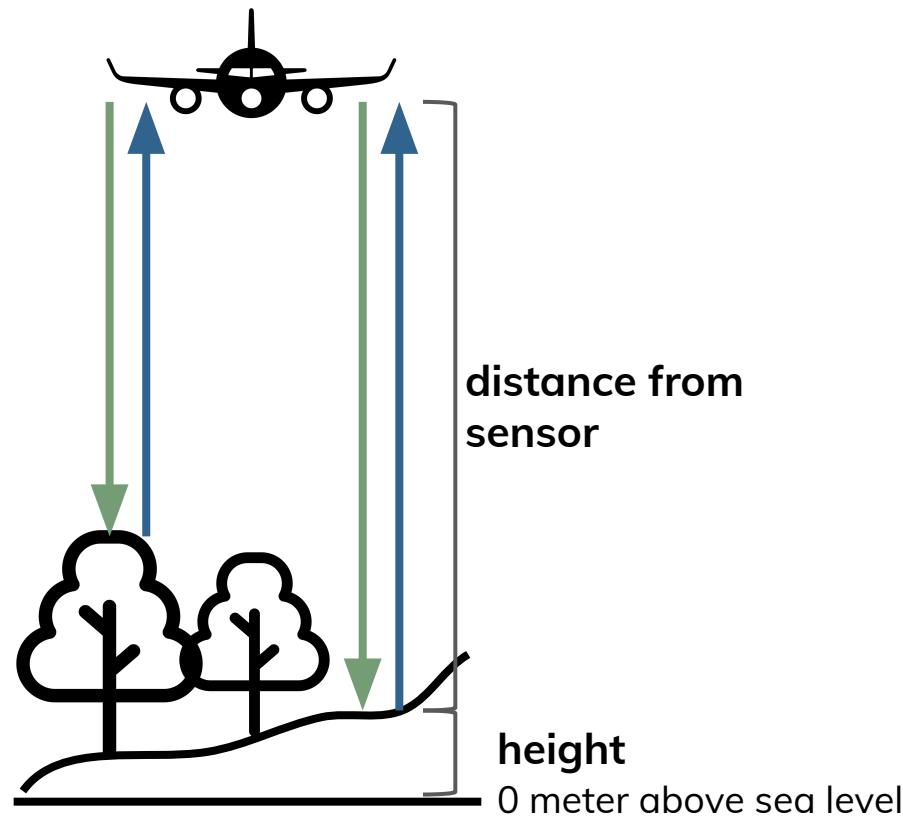


- Highly reflected off of vegetation
- Monochromatic
 - spectrally narrow - know what to expect from its interactions
 - spatially narrow - stays concentrated over long distances

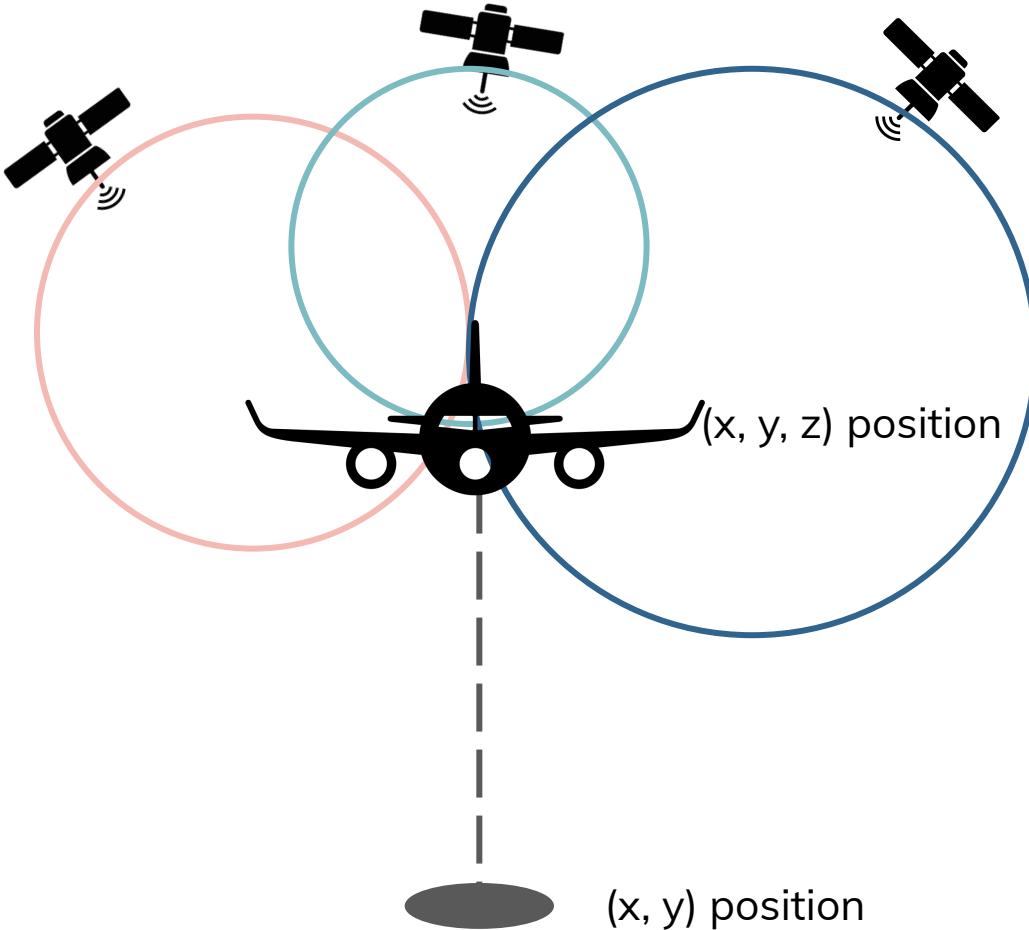
Using energy to measure height

What components do we need?

- **emit/receive radiation**
 - Laser
- **know location**
 - GPS
- know orientation
- keep track of everything



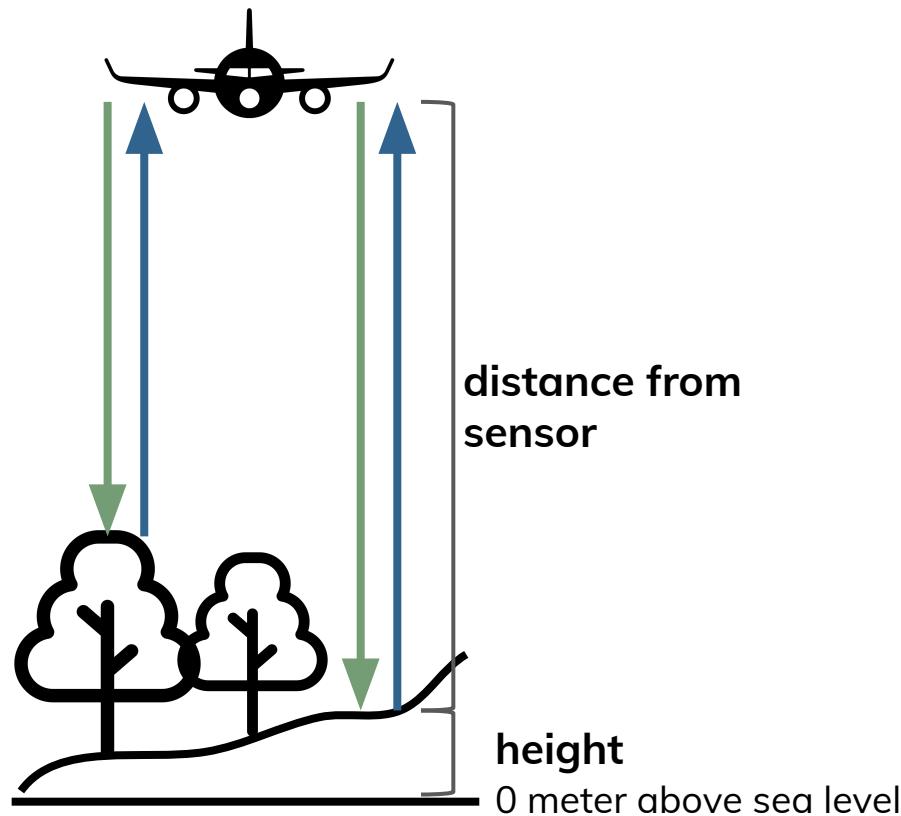
Positioning



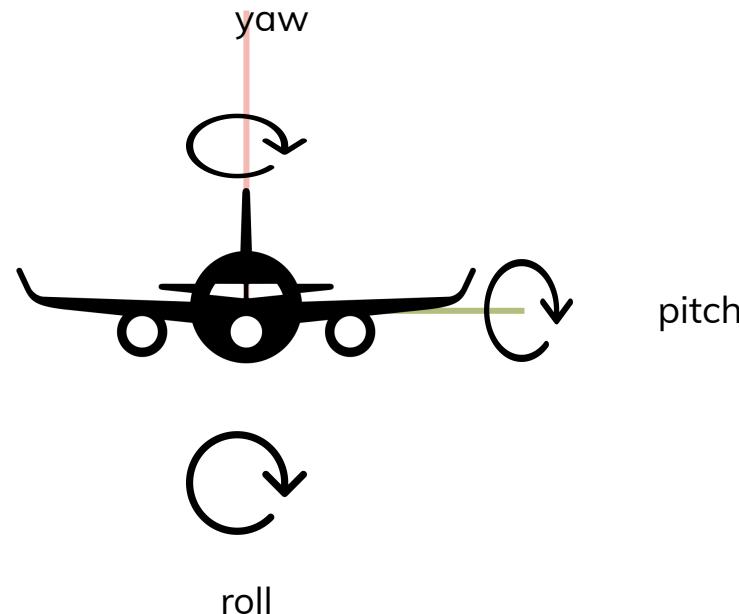
Using energy to measure height

What components do we need?

- **emit/receive radiation**
 - Laser
- **know location**
 - GPS
- **know orientation**
 - Inertial Measurement Unit
- keep track of everything



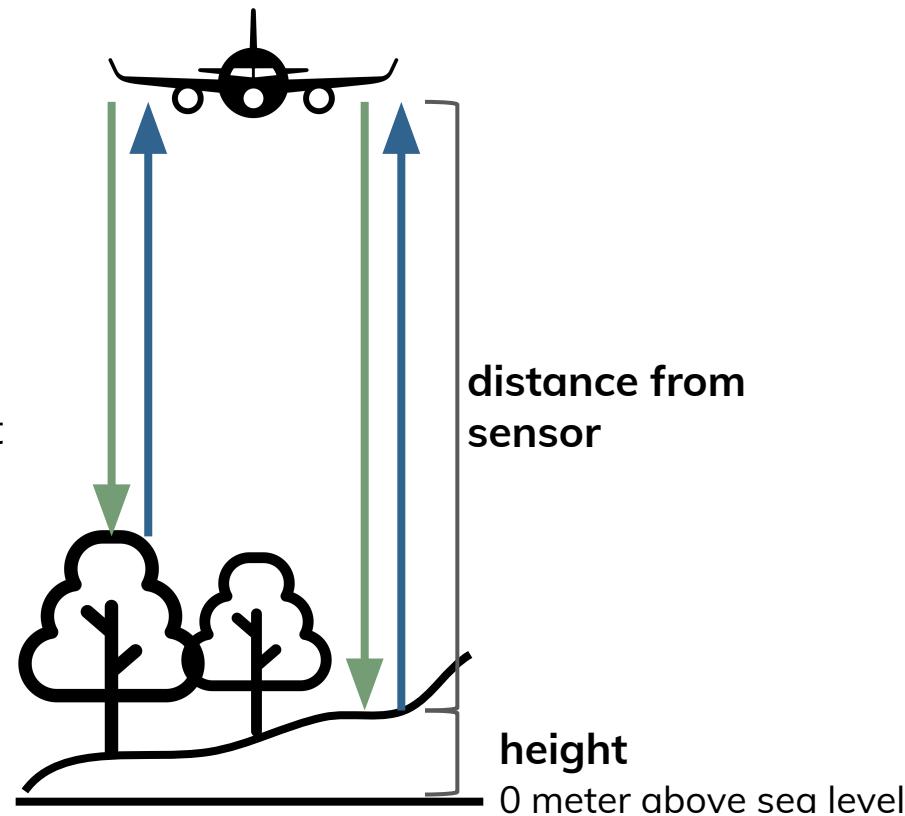
Orientation



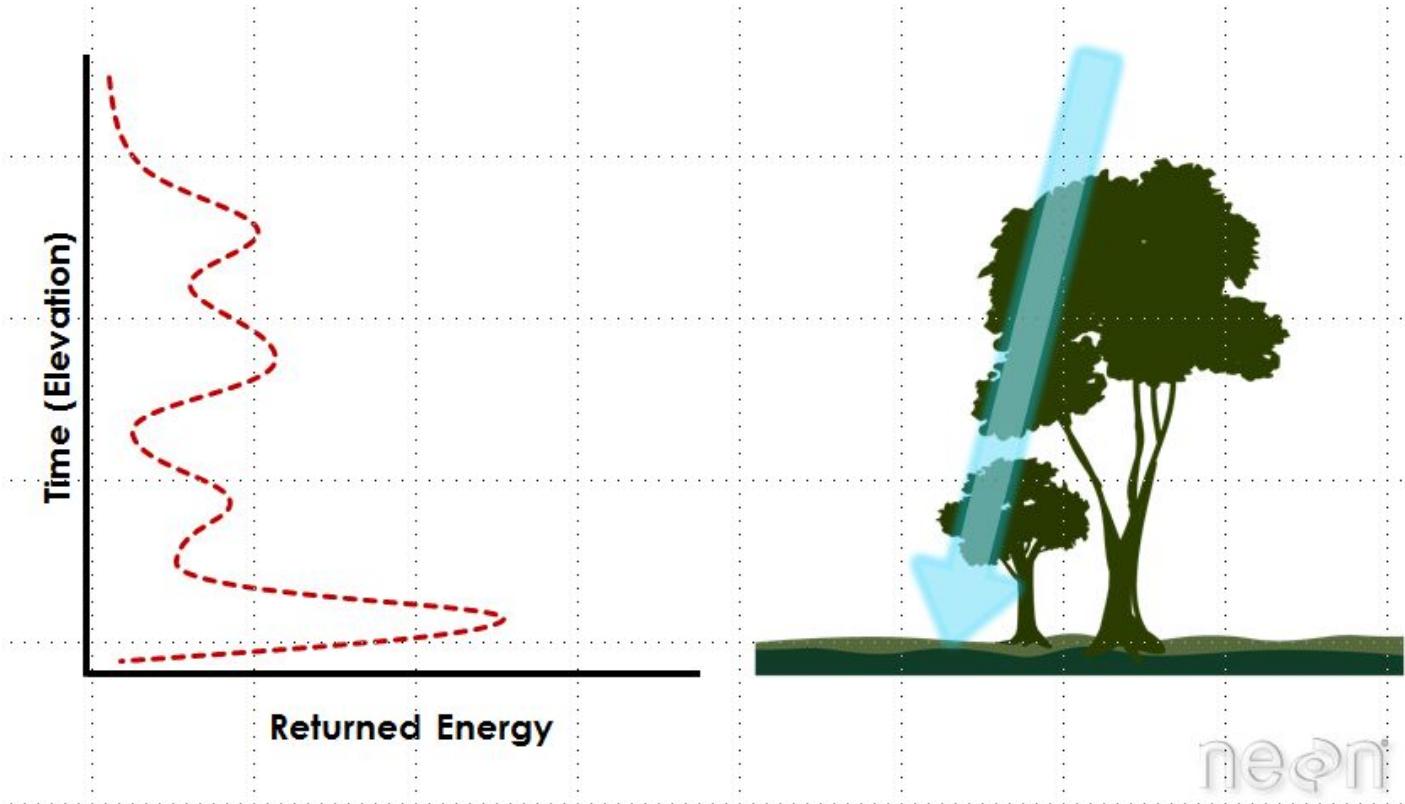
Using energy to measure height

What components do we need?

- **emit/receive radiation**
 - Laser
- **know location**
 - GPS
- **know orientation**
 - Inertial Measurement Unit
- **keep track of everything**
 - On-board computer

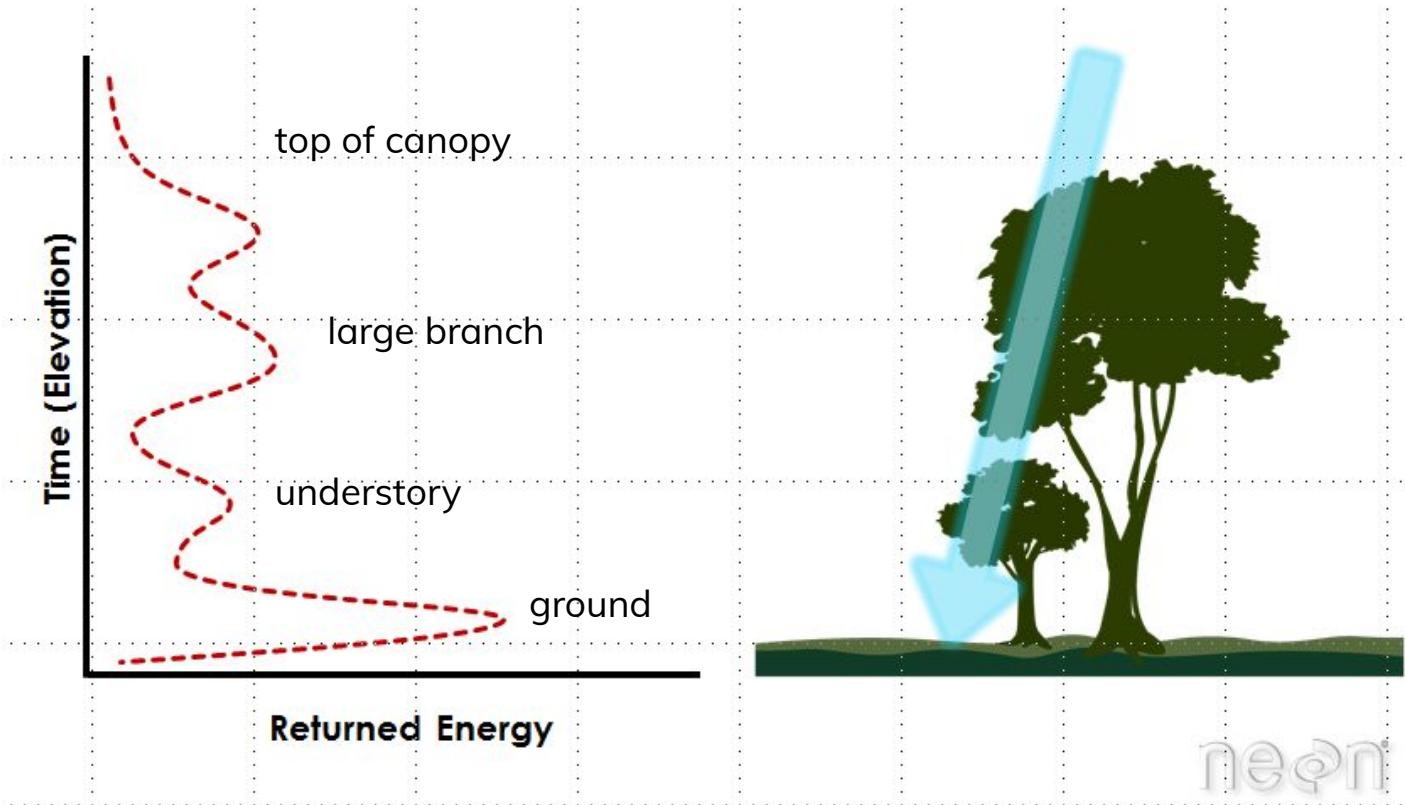


LiDAR energy returns



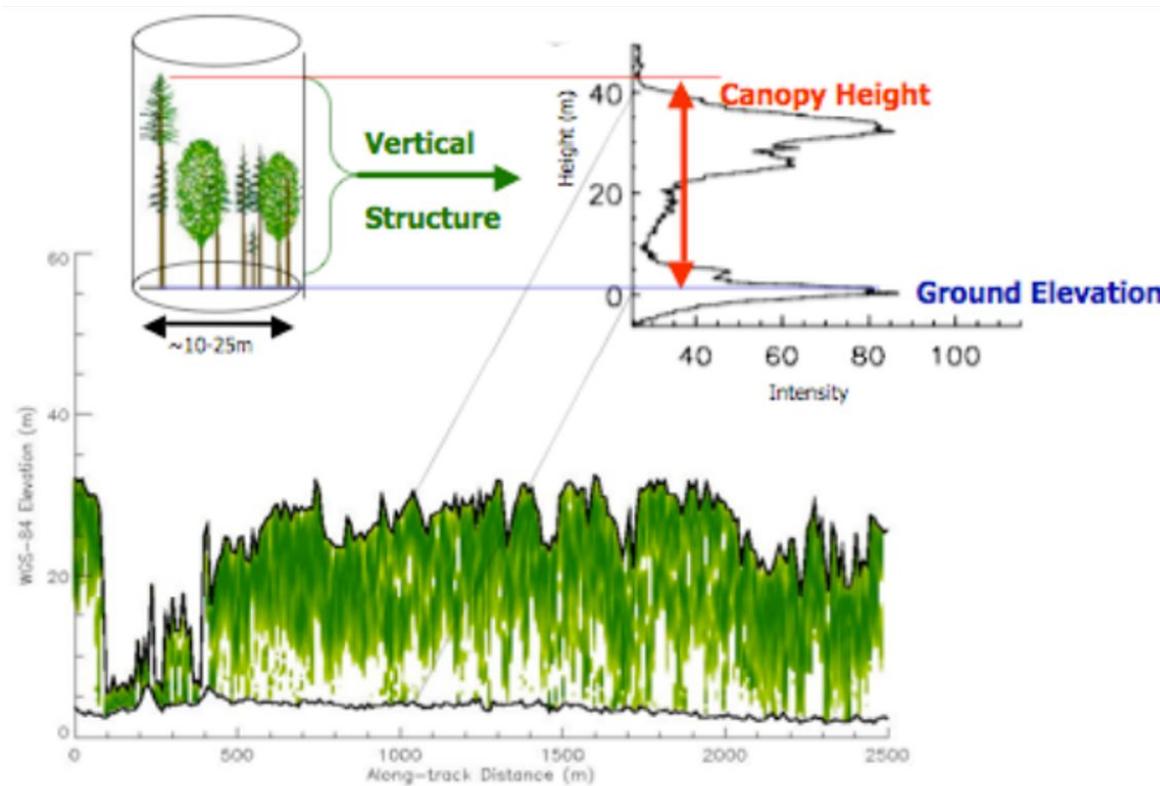
neon

LiDAR energy returns

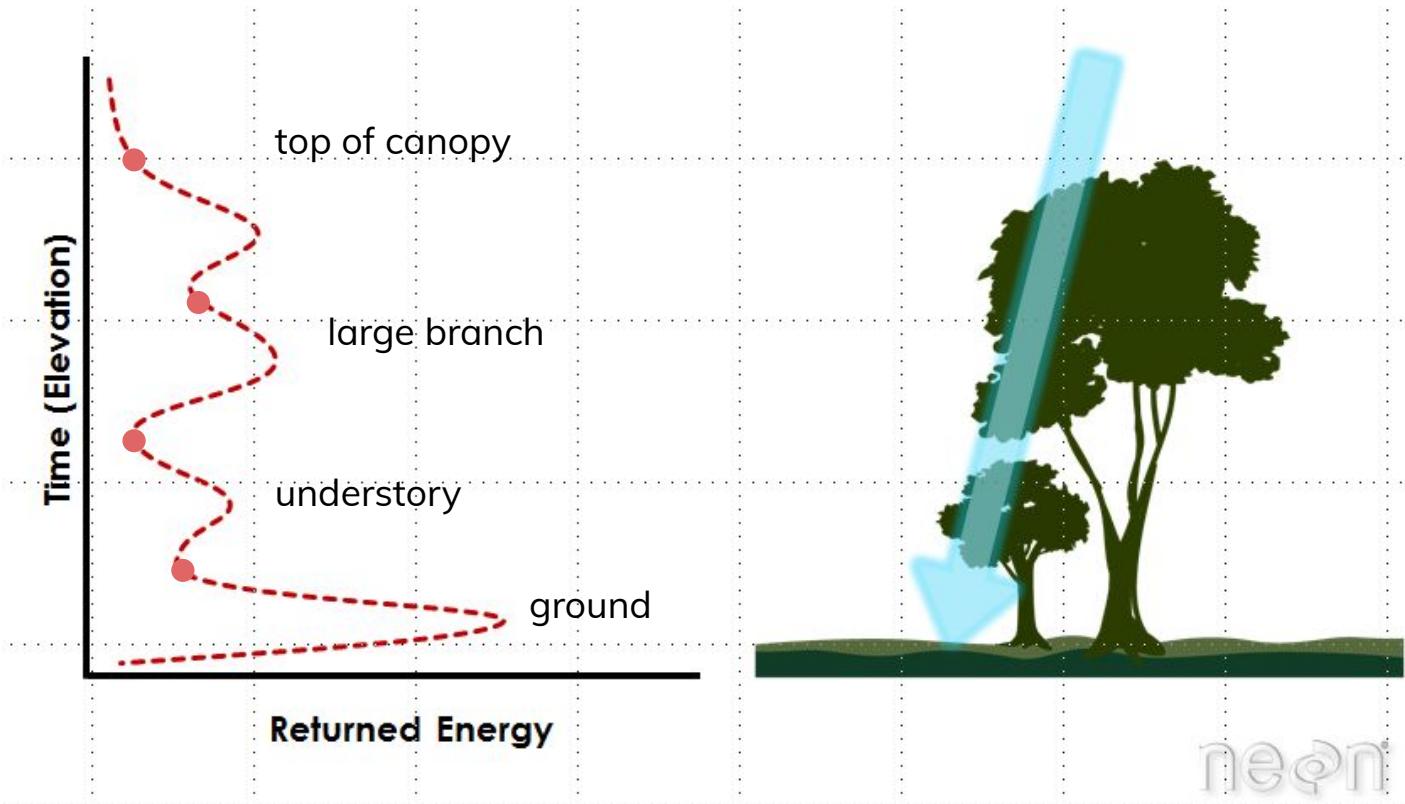


neon

LiDAR energy returns

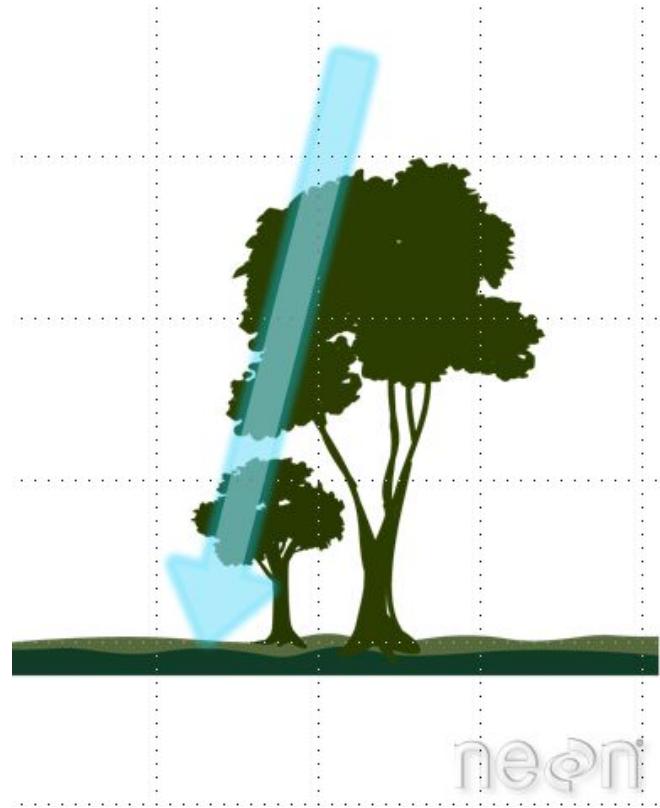
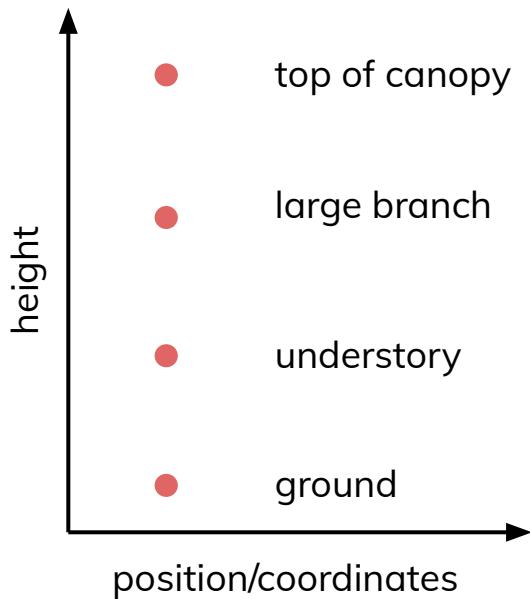


LiDAR energy returns



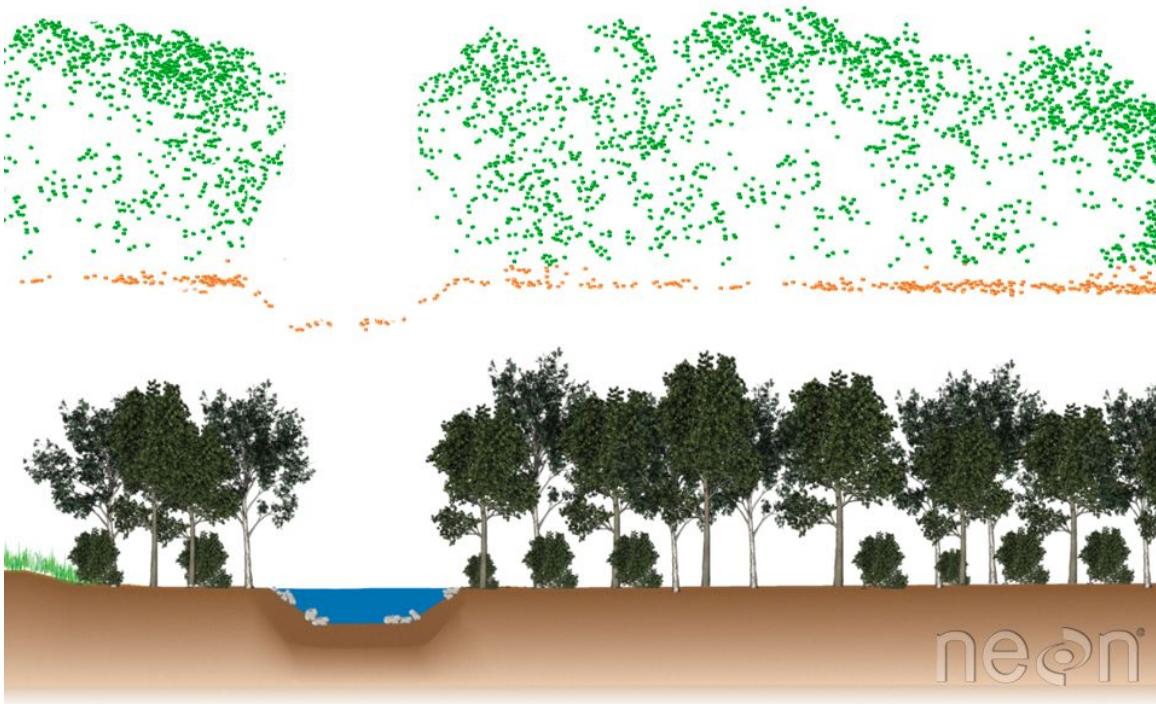
neon

LiDAR energy returns



neon

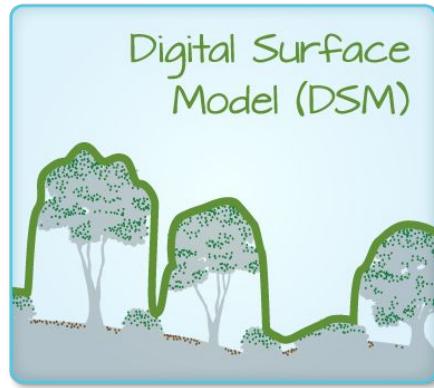
LiDAR energy returns



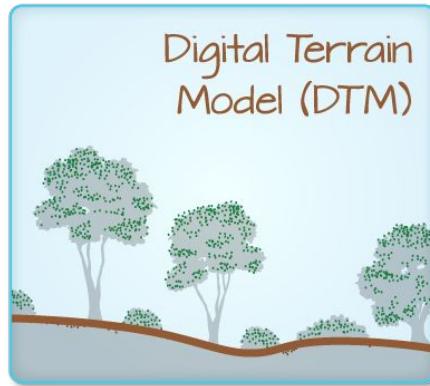


https://www.youtube.com/watch?v=mi0w3OhpswM&t=3s&ab_channel=LiDARit

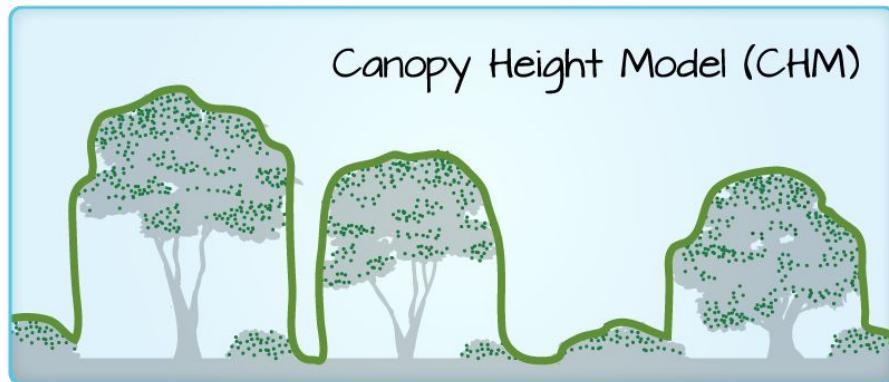
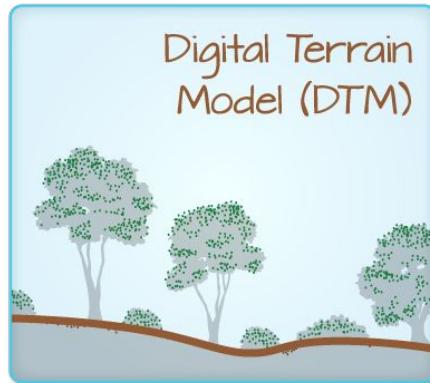
Point clouds to surface models



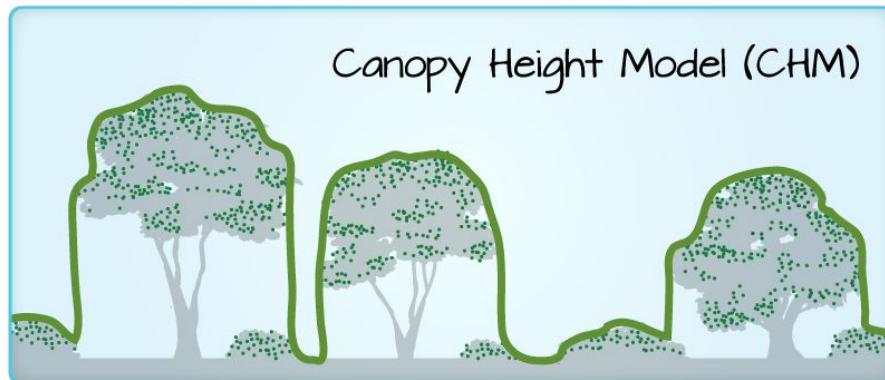
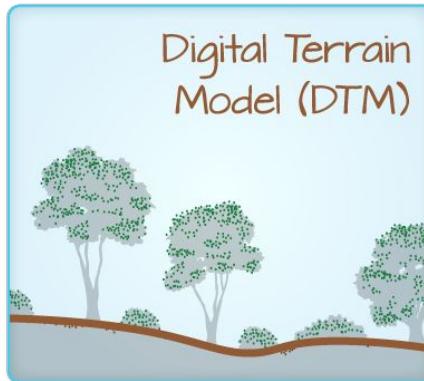
Point clouds to surface models



Point clouds to surface models



Point clouds to surface models

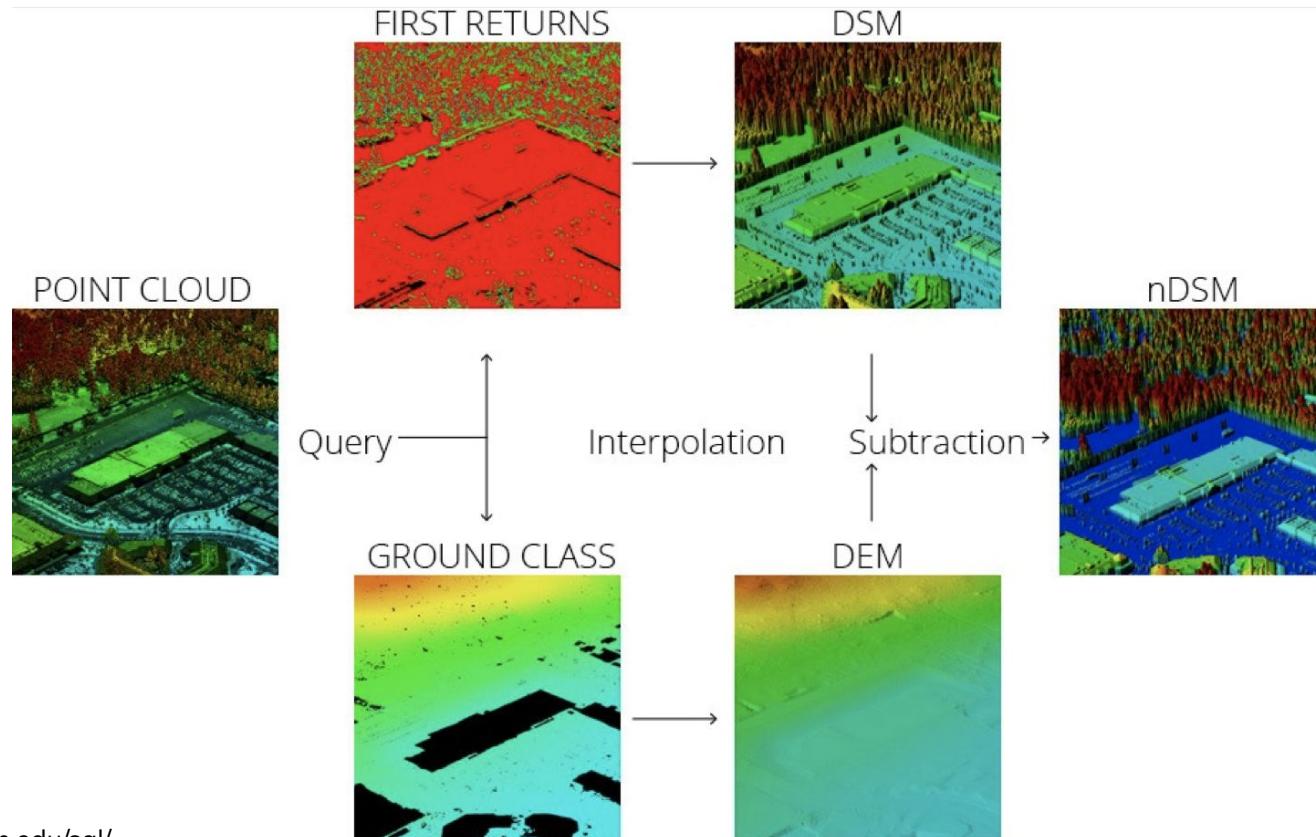


$$\frac{\text{DSM} - \text{DTM}}{\text{CHM}}$$

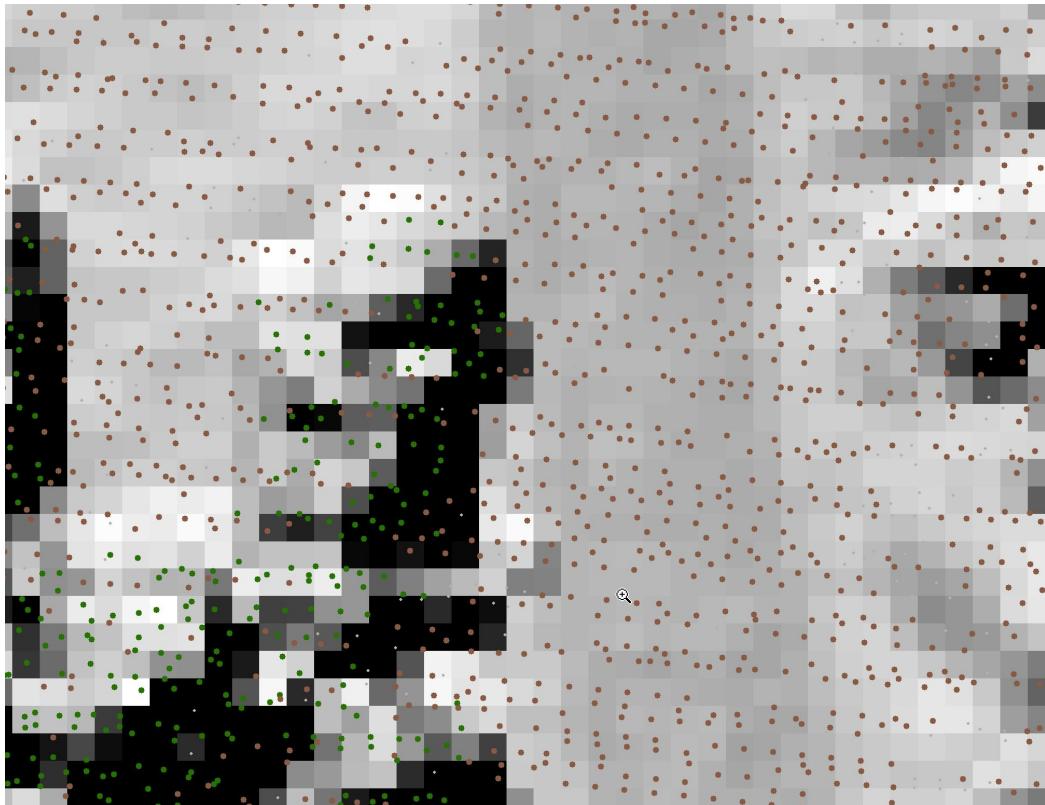
(Digital Surface Model)
(Digital Terrain Model)
(Canopy Height Model)

neon

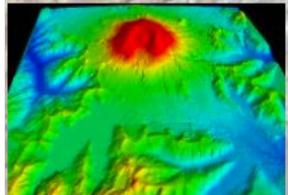
Point clouds to surface models



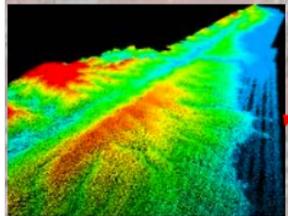
Point clouds to raster



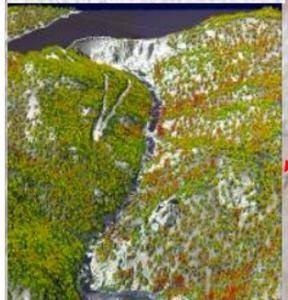
A wealth of information derived from lidar



Volcano monitoring



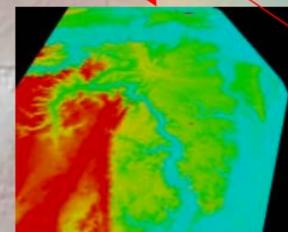
Earthquake faults



Hydrologic / Hydraulic



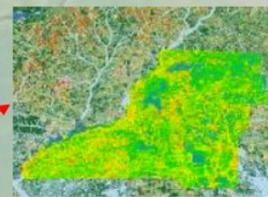
Urban / Suburban Response



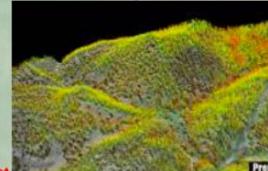
Coastal Studies



Vegetation / Biomass



Land Cover



Carbon studies

LiDAR systems



terrestrial



air-borne



space-borne

LiDAR systems



terrestrial



air-borne



space-borne

- Best resolution
 - Worst coverage
- Worst resolution
 - Best coverage

LiDAR systems



terrestrial

- Best resolution
- Worst coverage



air-borne

- Most common
- Still rare!



space-borne

- Worst resolution
- Best coverage

LiDAR systems



terrestrial

- Best resolution
- Worst coverage



air-borne

- Most common
- Still rare!

NEON

National Ecological Observatory Network

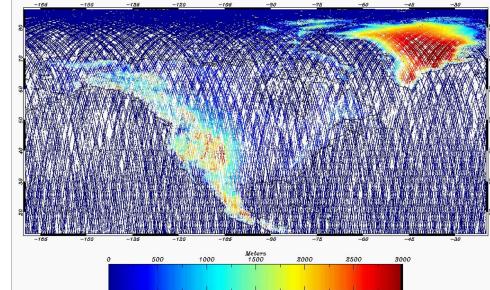


space-borne

- Worst resolution
- Best coverage

ICESat

Ice, Cloud, and land Elevation Satellite



LiDAR systems



terrestrial

- Best resolution
- Worst coverage



air-borne

- Most common
- Still rare!

NEON

National Ecological Observatory Network

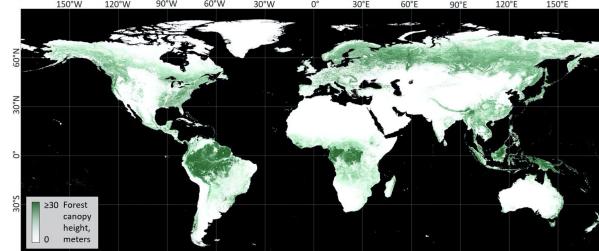


space-borne

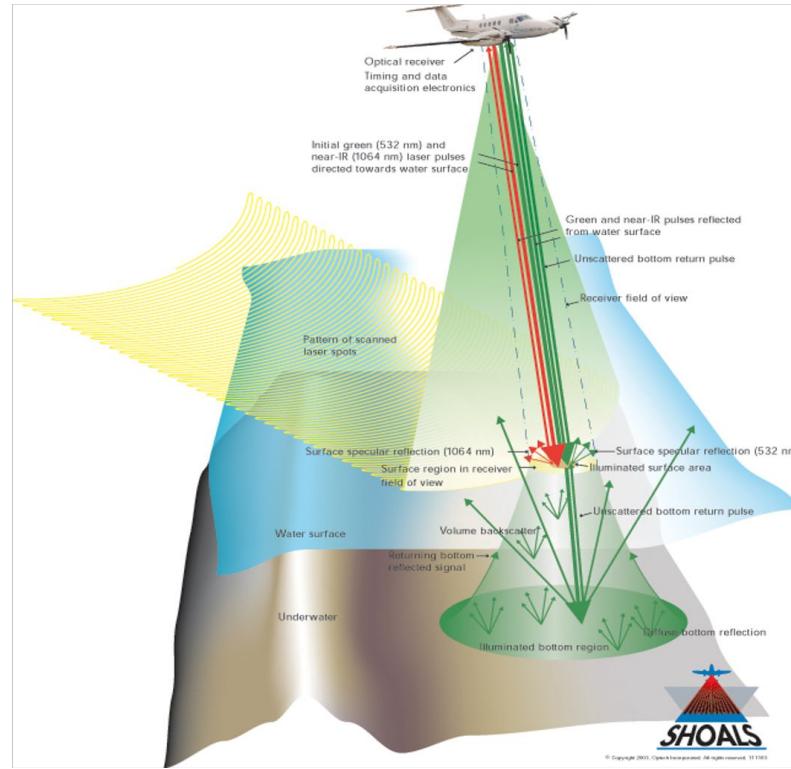
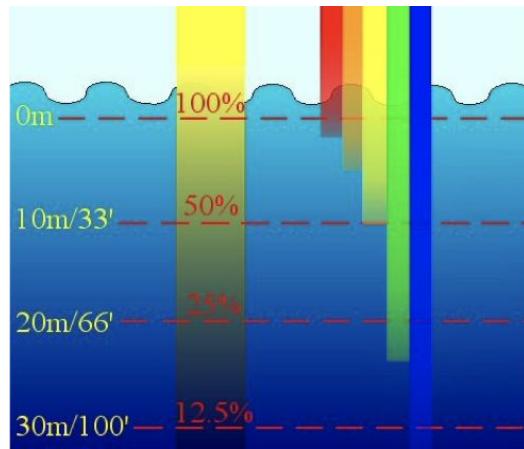
- Worst resolution
- Best coverage

GEDI

Global Ecosystem Dynamics Investigation



Aquatic LiDAR





Active remote sensing

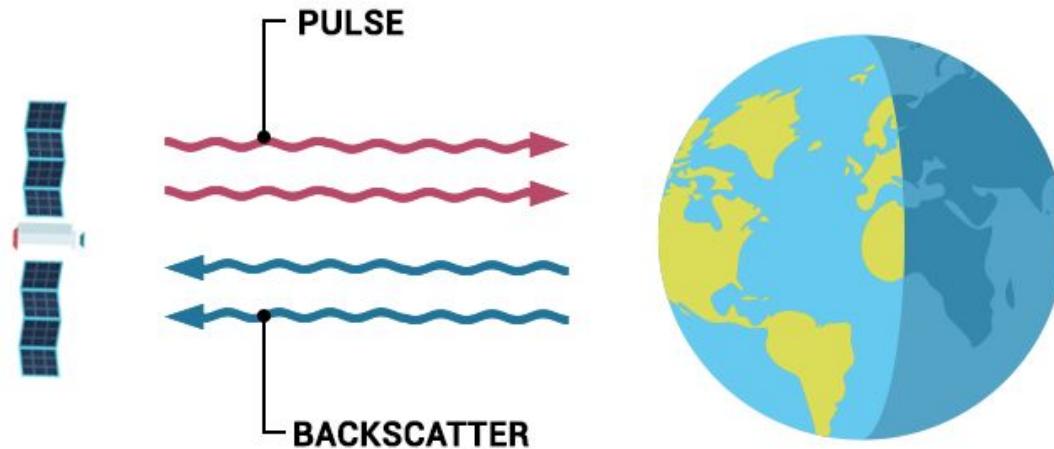
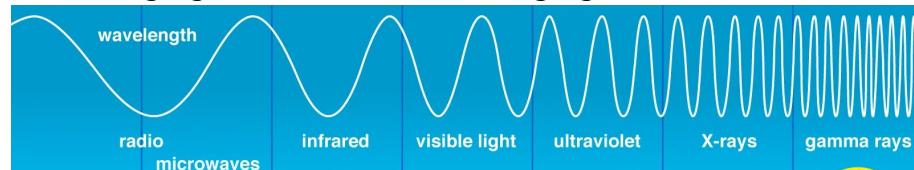
What type of energy are we working with?

RADAR

Radio Detection
and Ranging

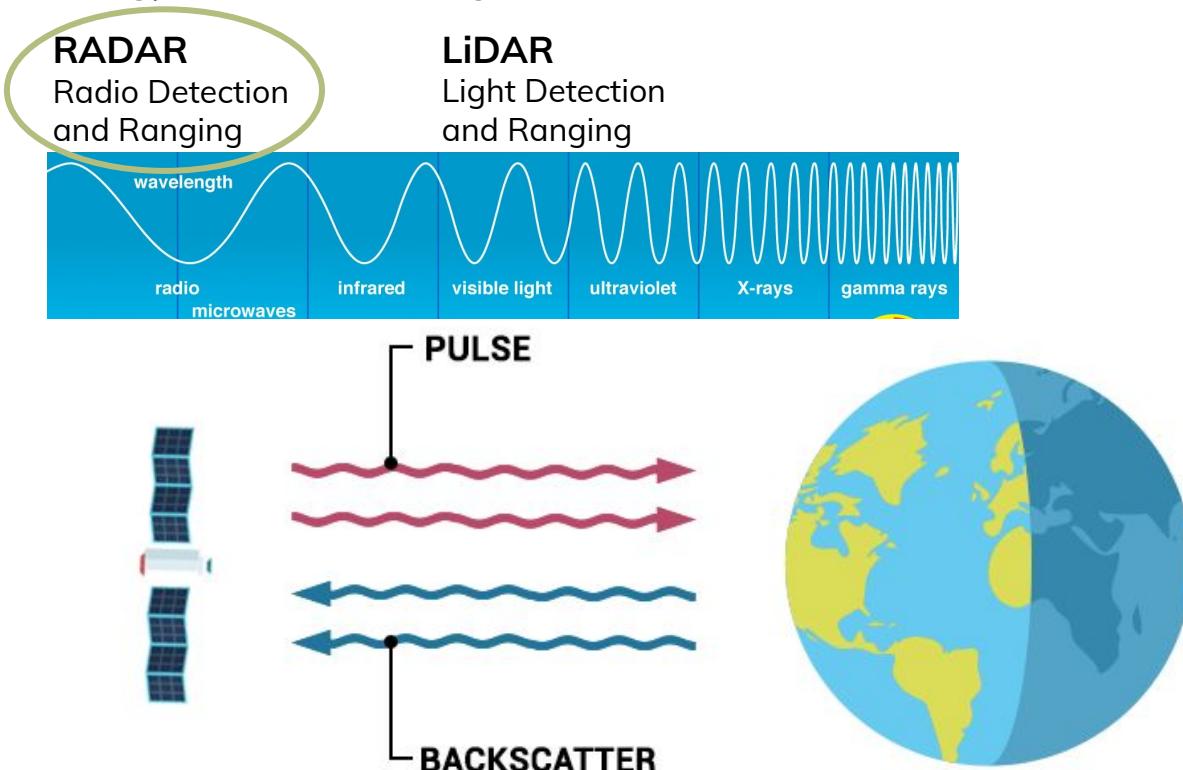
LiDAR

Light Detection
and Ranging



Active remote sensing

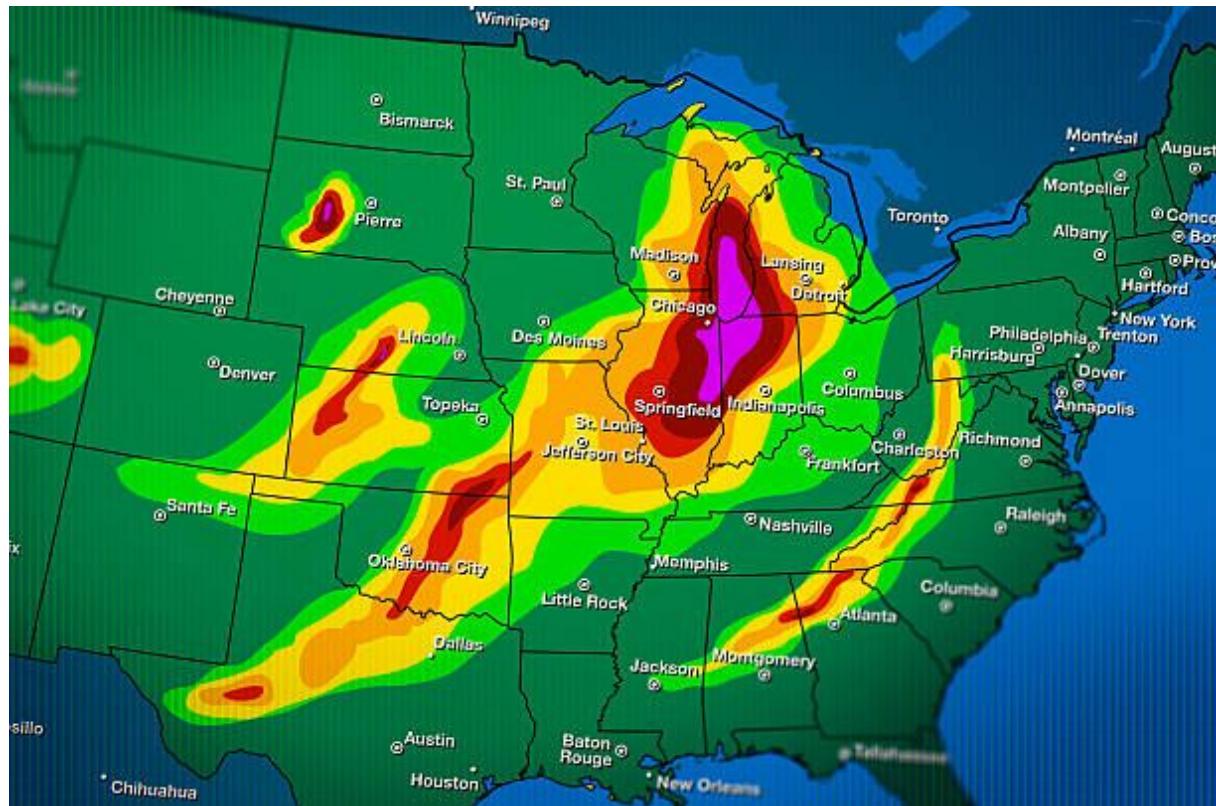
What type of energy are we working with?

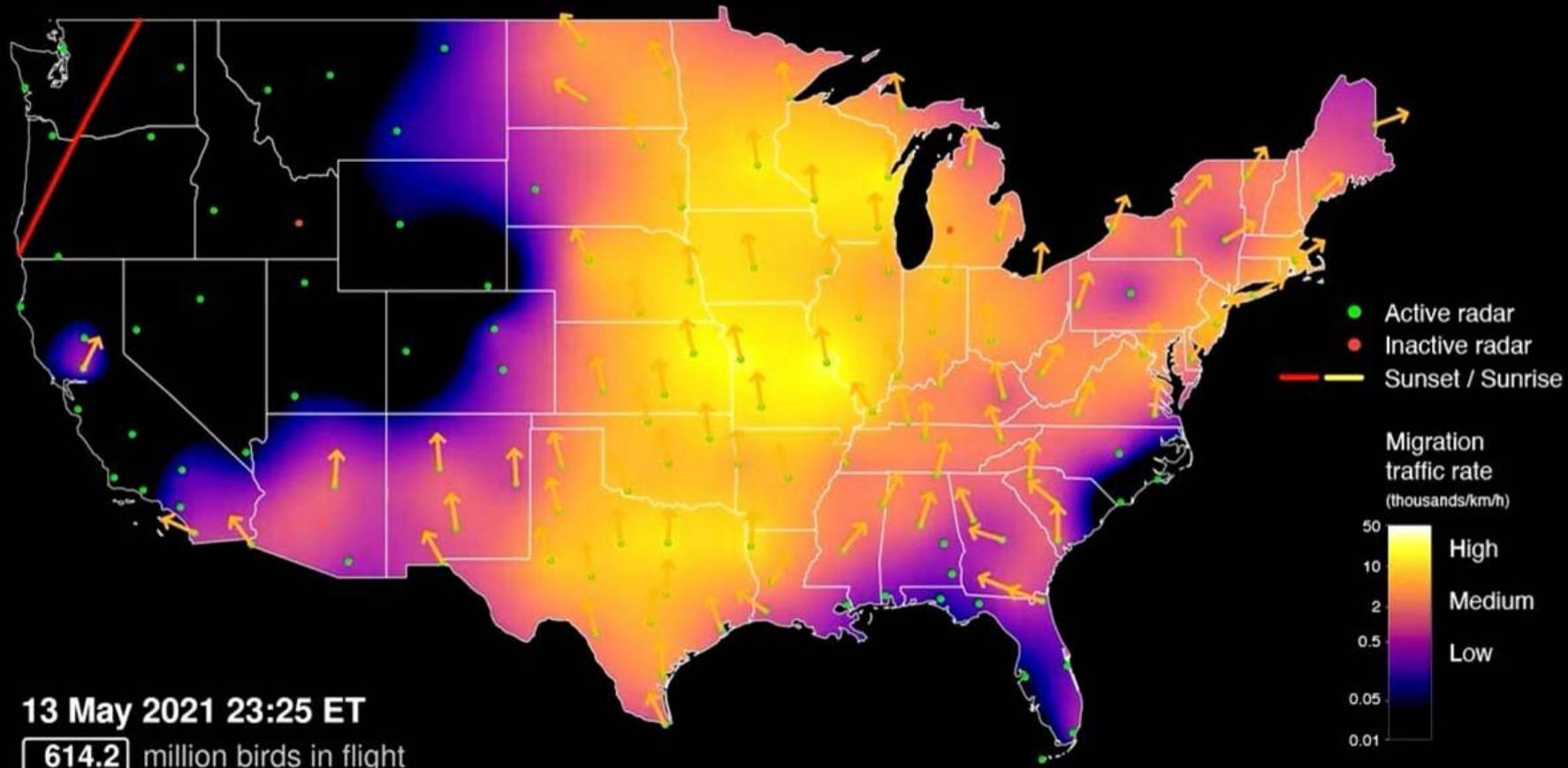


A note on context...



https://www.youtube.com/watch?v=xpIRqdxqDyY&ab_channel=CanadaAviationandSpaceMuseum





13 May 2021 23:25 ET

614.2 million birds in flight

Live bird migration maps

Dokter 2021

BirdCast

RADAR systems



terrestrial



air-borne



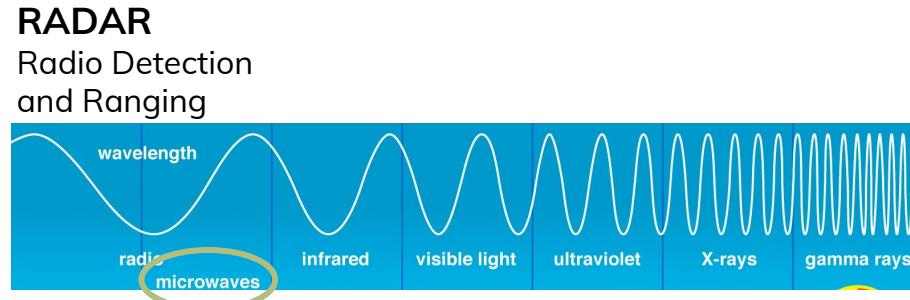
space-borne



“remote sensing”

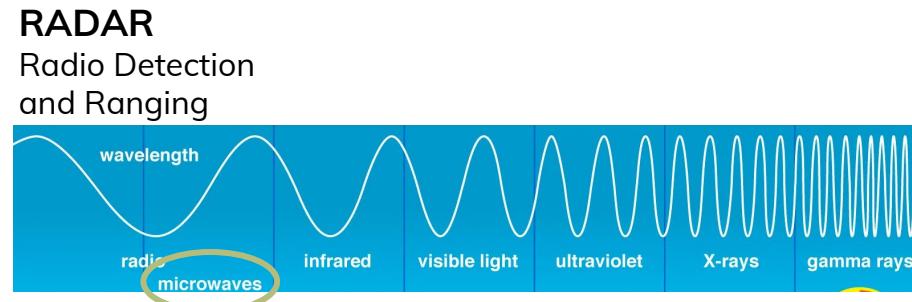
RADAR electromagnetic

What type of energy are we working with?



RADAR electromagnetic wavelengths

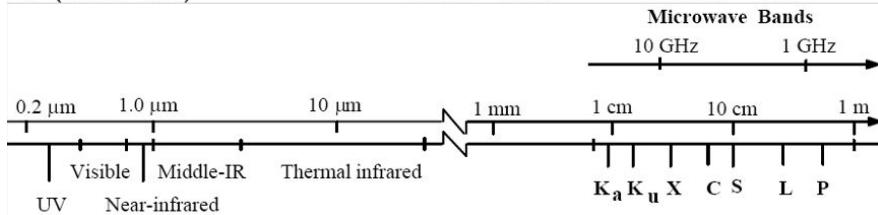
What type of energy are we working with?



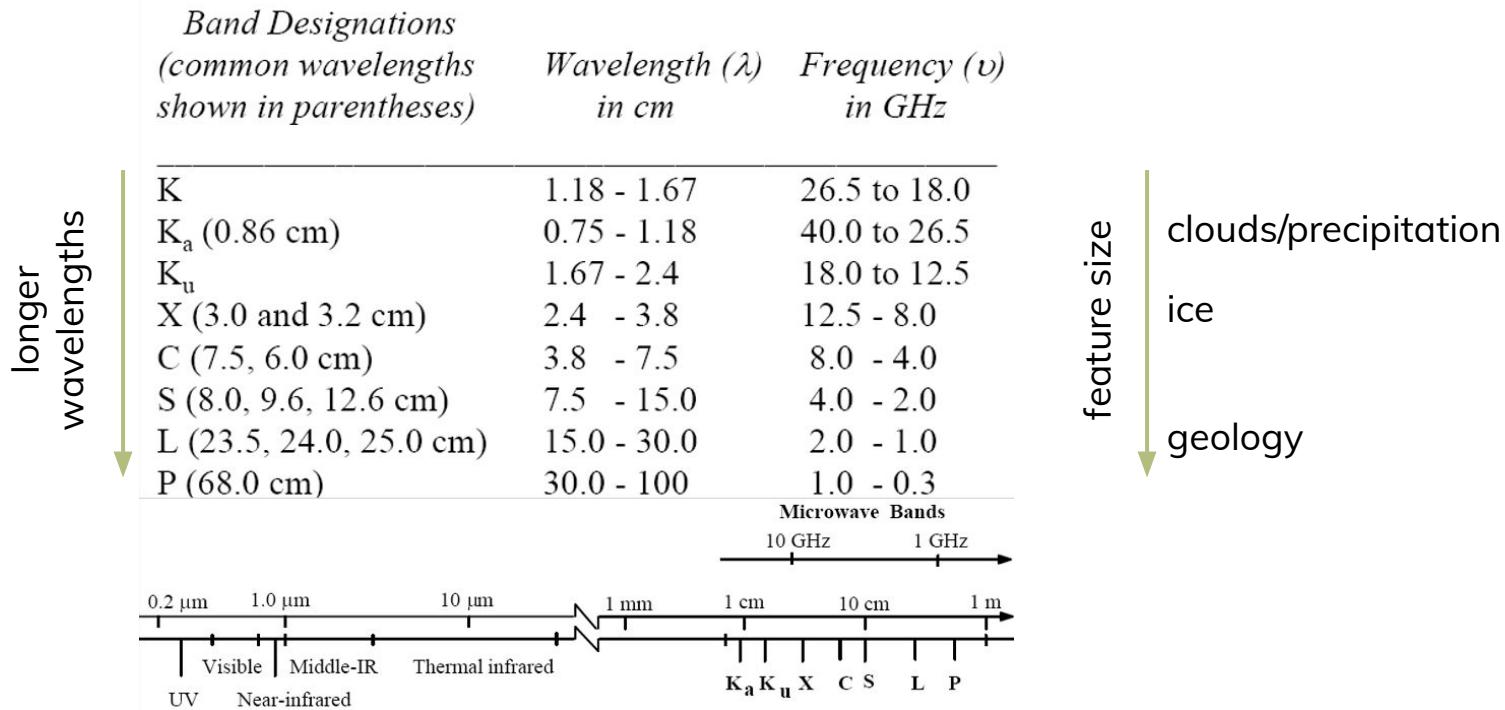
RADAR electromagnetic wavelengths

longer
wavelengths

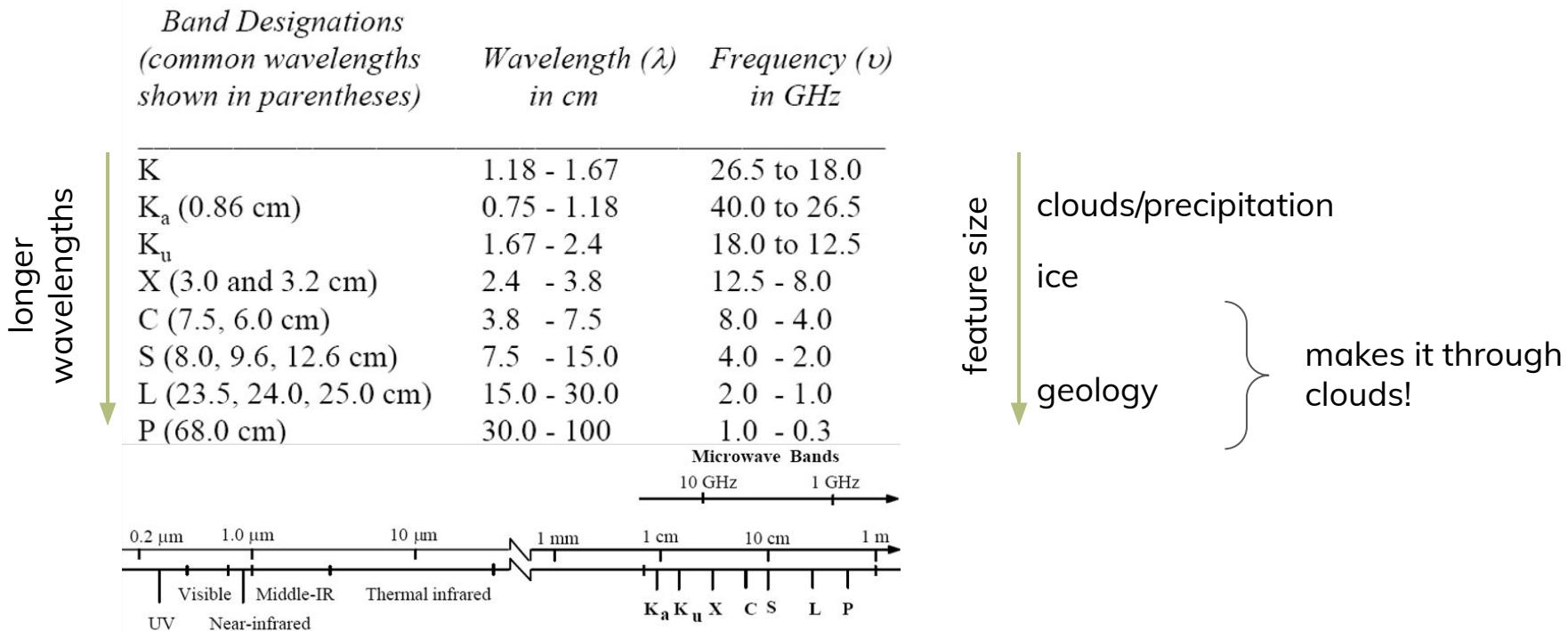
<i>Band Designations (common wavelengths shown in parentheses)</i>	<i>Wavelength (λ) in cm</i>	<i>Frequency (ν) in GHz</i>
K	1.18 - 1.67	26.5 to 18.0
K _a (0.86 cm)	0.75 - 1.18	40.0 to 26.5
K _u	1.67 - 2.4	18.0 to 12.5
X (3.0 and 3.2 cm)	2.4 - 3.8	12.5 - 8.0
C (7.5, 6.0 cm)	3.8 - 7.5	8.0 - 4.0
S (8.0, 9.6, 12.6 cm)	7.5 - 15.0	4.0 - 2.0
L (23.5, 24.0, 25.0 cm)	15.0 - 30.0	2.0 - 1.0
P (68.0 cm)	30.0 - 100	1.0 - 0.3



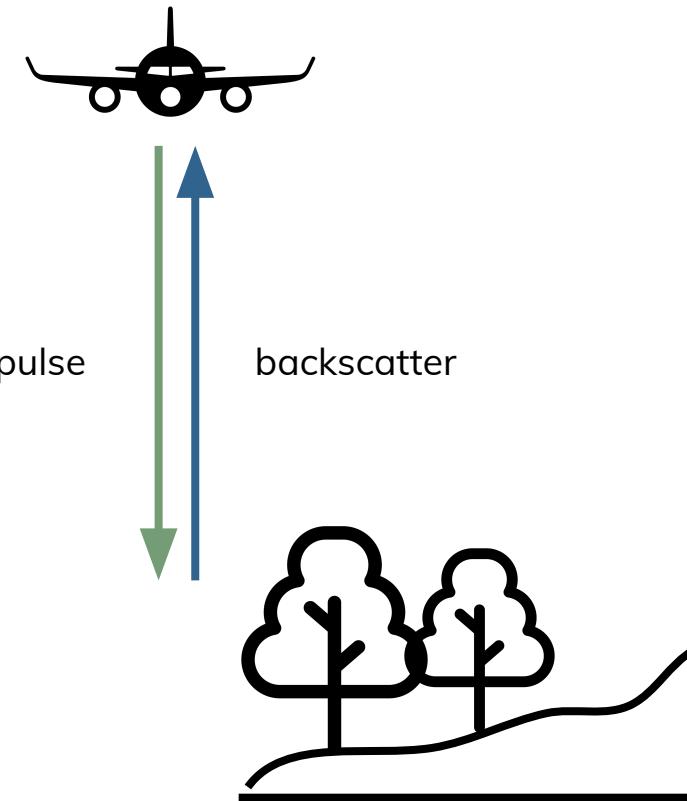
RADAR electromagnetic wavelengths



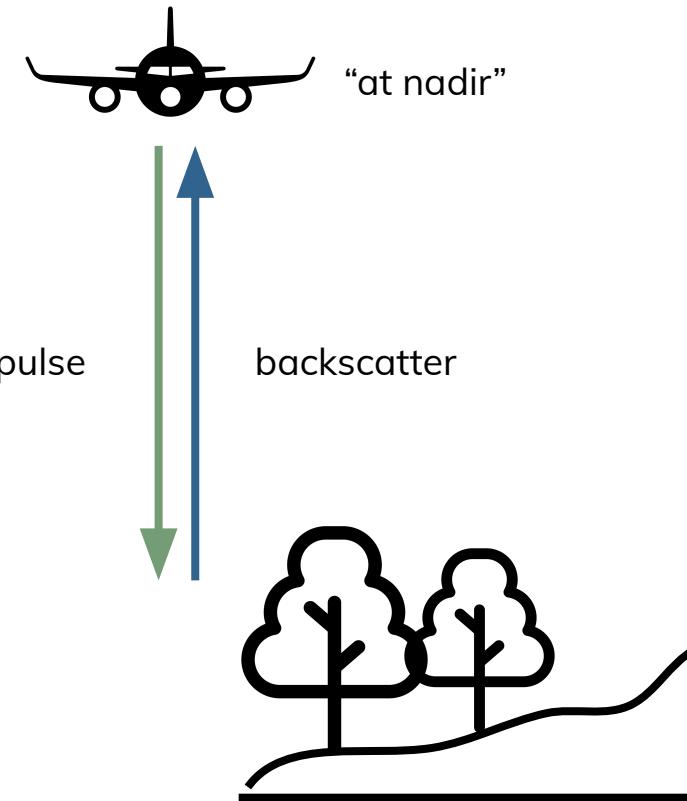
RADAR electromagnetic wavelengths



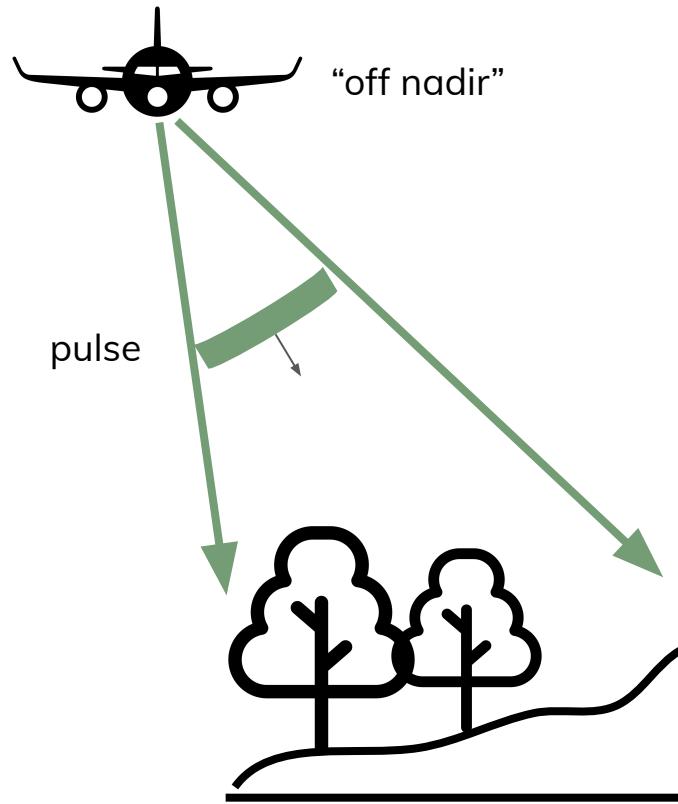
RADAR viewing geometry



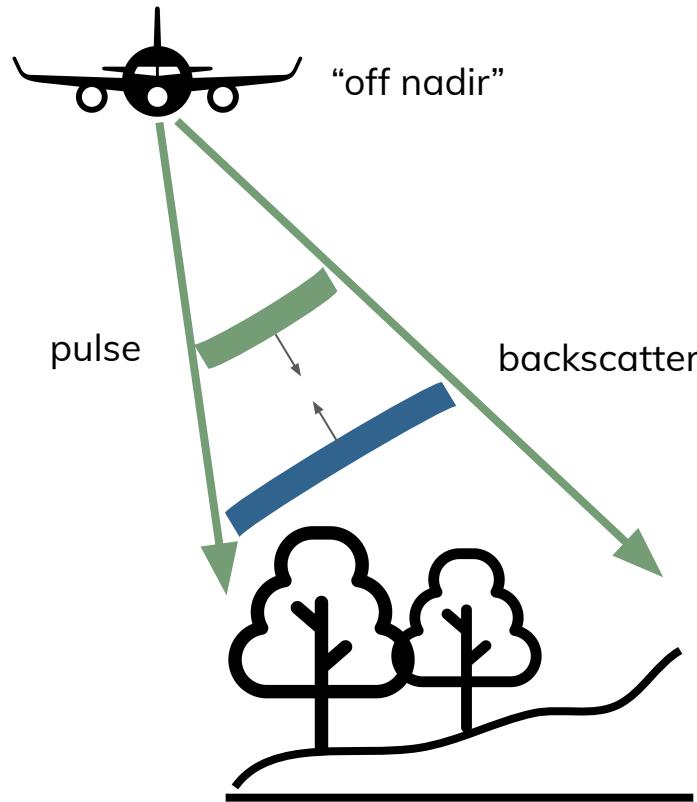
RADAR viewing geometry



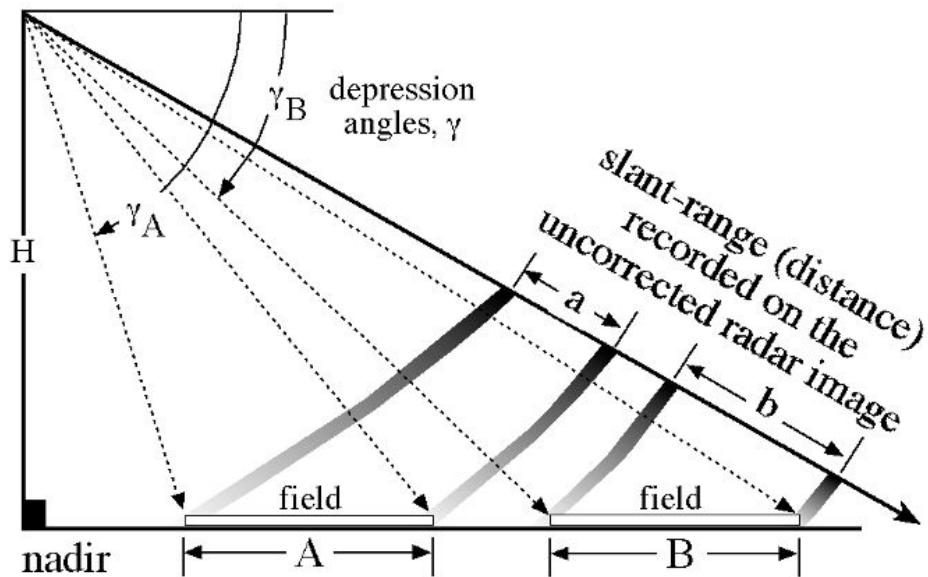
RADAR viewing geometry



RADAR viewing geometry



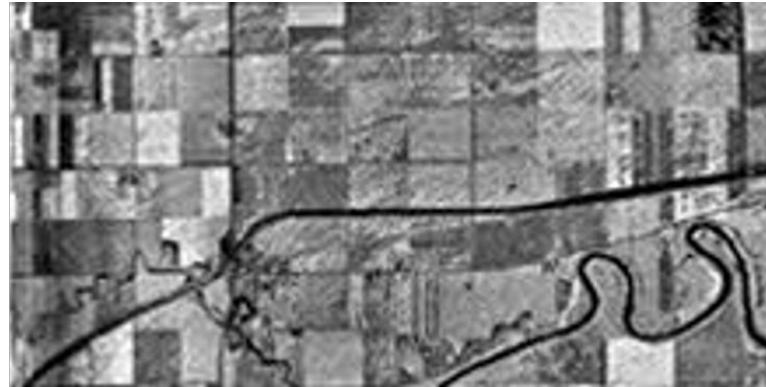
RADAR viewing geometry



True Ground-range (distance) Display Plane

RADAR viewing geometry

uncorrected
slant-range geometry

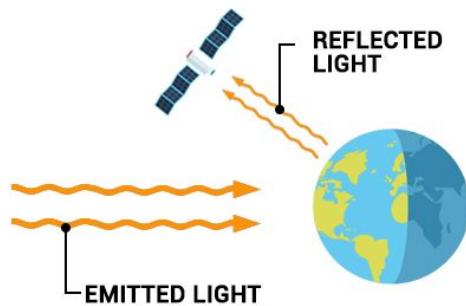
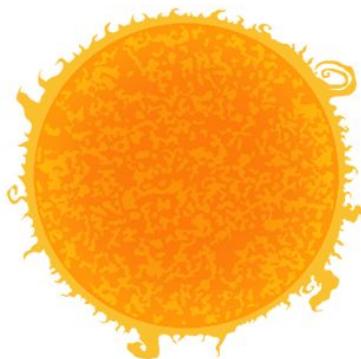


corrected
ground-range geometry

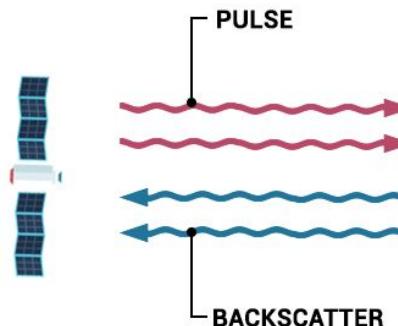


Microwave interactions with matter

Passive systems:

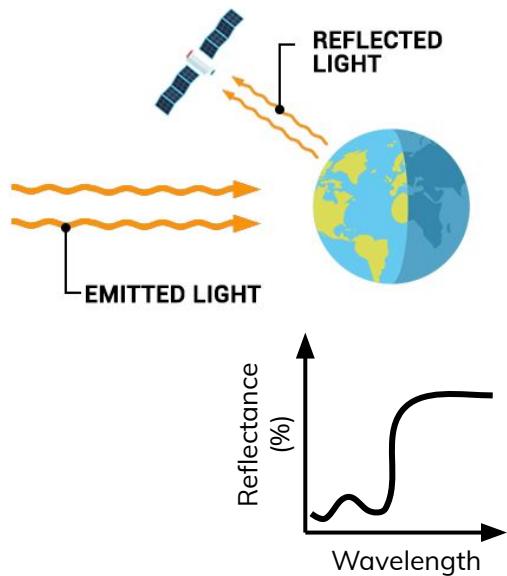
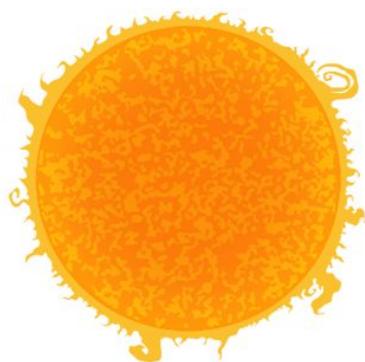


Active systems:

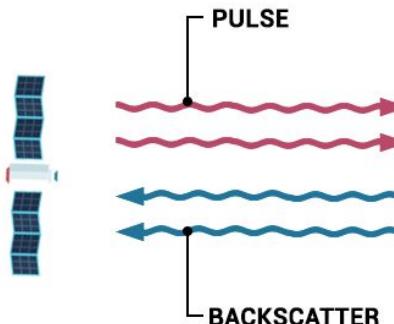


Microwave interactions with matter

Passive systems:

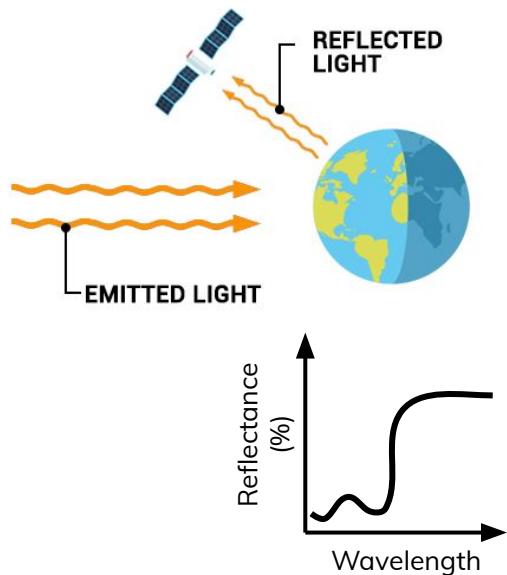
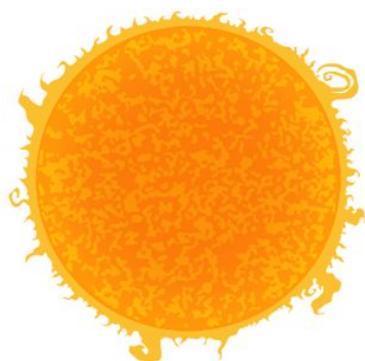


Active systems:

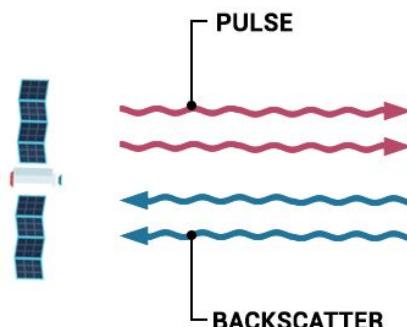


Microwave interactions with matter

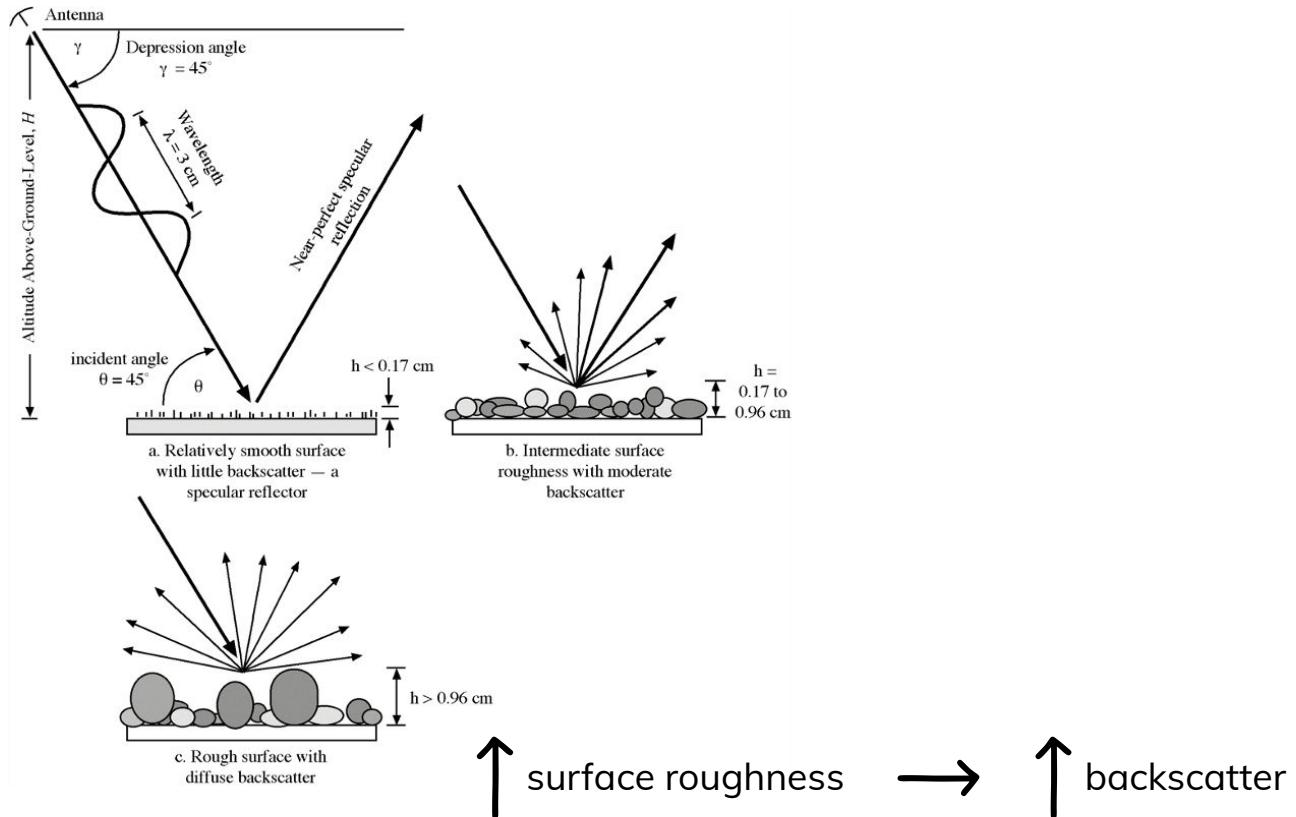
Passive systems:



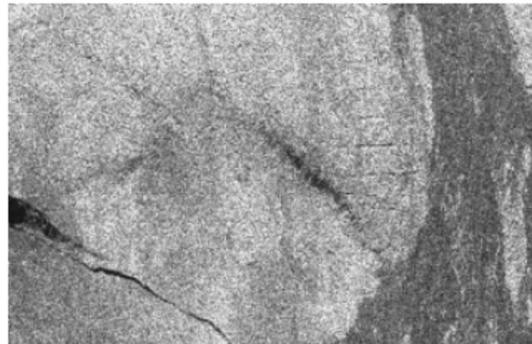
Active systems:



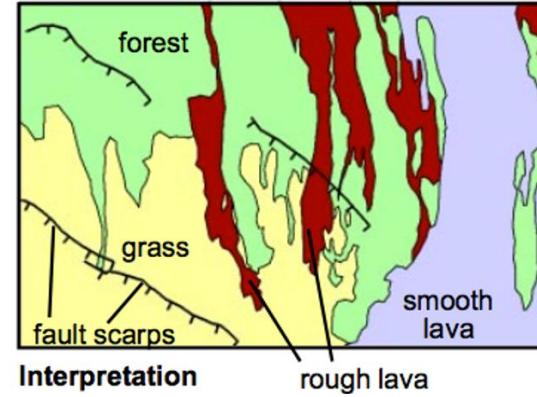
Microwave interactions with matter



Microwave interactions with matter

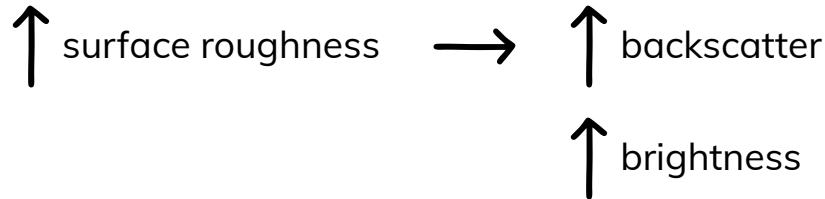


C-Band VV (wavelength = 6 cm)

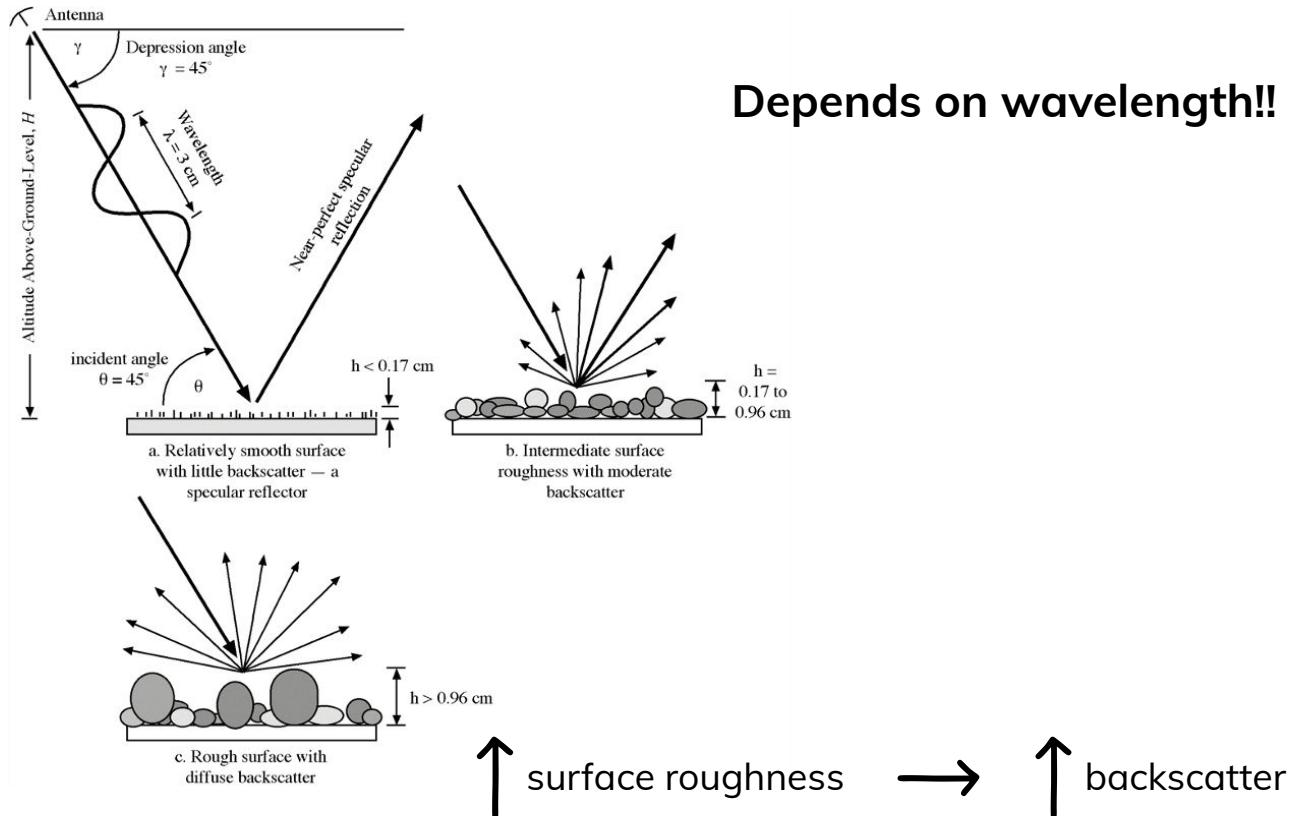


Interpretation

rough lava



Microwave interactions with matter



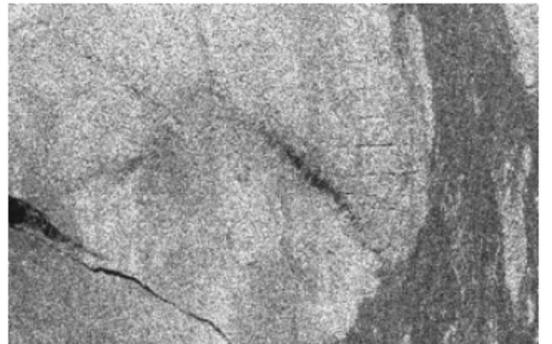
Microwave interactions with matter



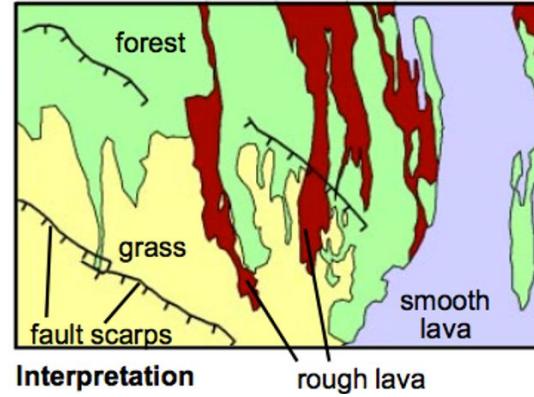
Microwave interactions with matter



Microwave interactions with matter

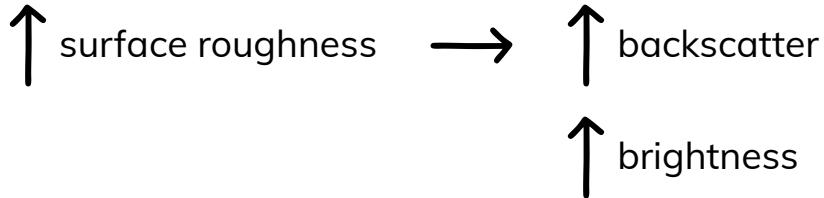


C-Band VV (wavelength = 6 cm)



Interpretation

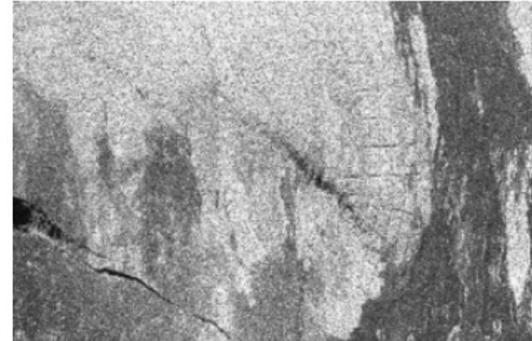
rough lava



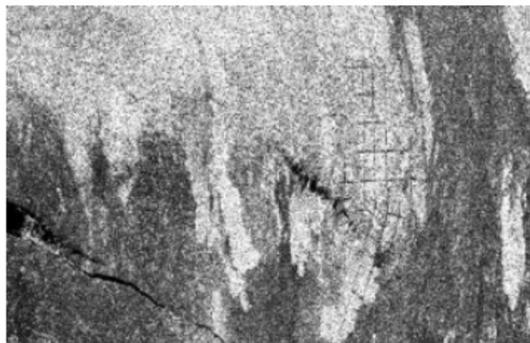
Microwave interactions with matter



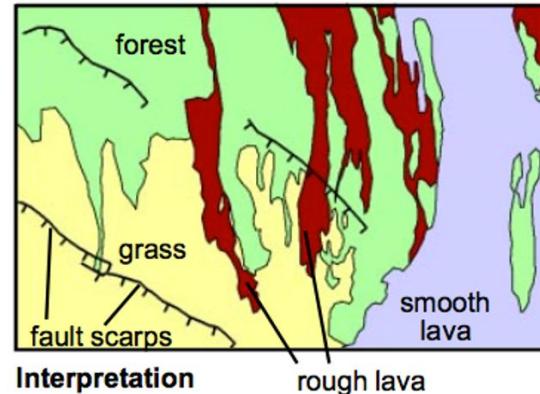
C-Band VV (wavelength = 6 cm)



L-Band VV (wavelength = 23.5 cm)



P-Band VV (wavelength = 68 cm)



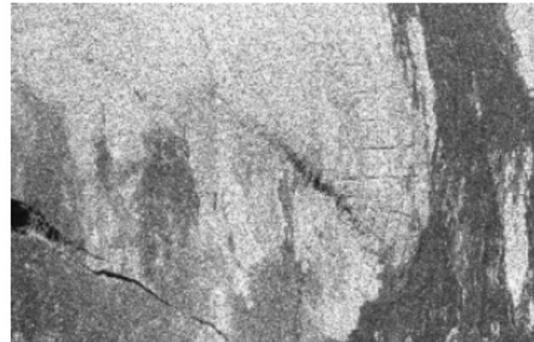
Interpretation

rough lava

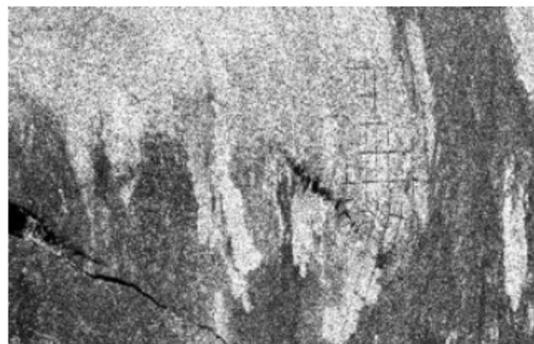
Microwave interactions with matter



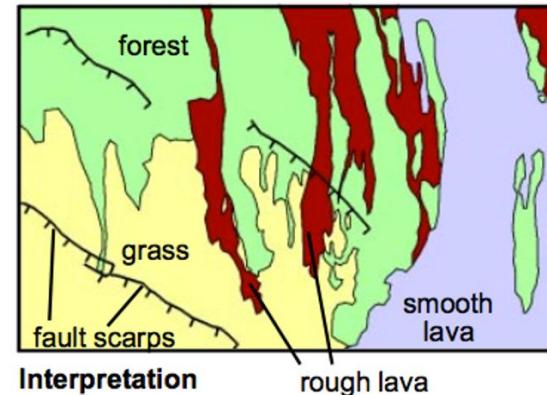
C-Band VV (wavelength = 6 cm)



L-Band VV (wavelength = 23.5 cm)



P-Band VV (wavelength = 68 cm)



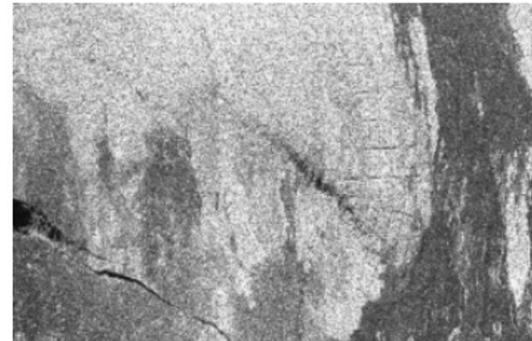
Interpretation

↑ wavelength
↓
↑ materials appear smooth

Microwave interactions with matter



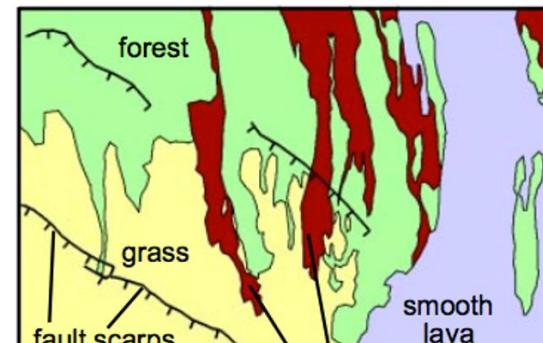
C-Band VV (wavelength = 6 cm)



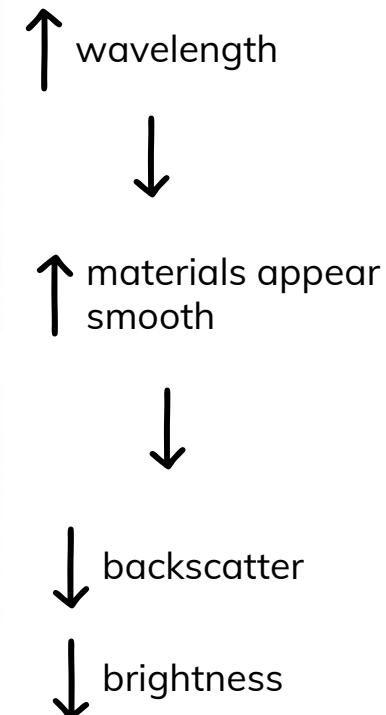
L-Band VV (wavelength = 23.5 cm)



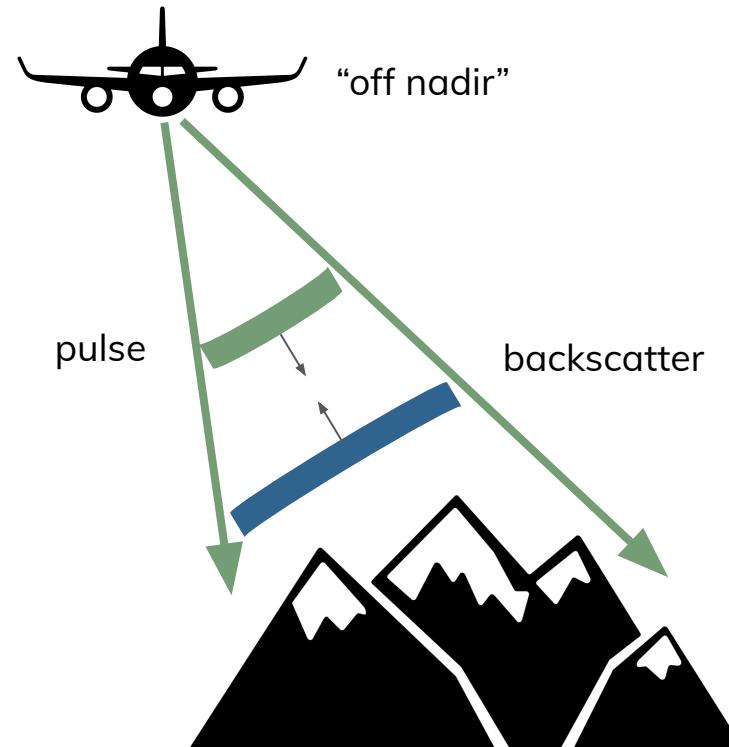
P-Band VV (wavelength = 68 cm)



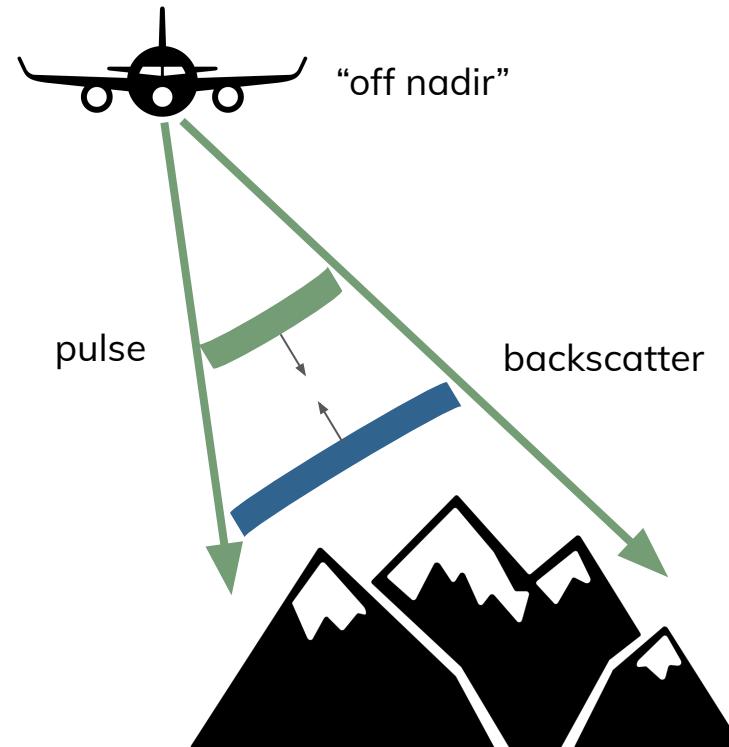
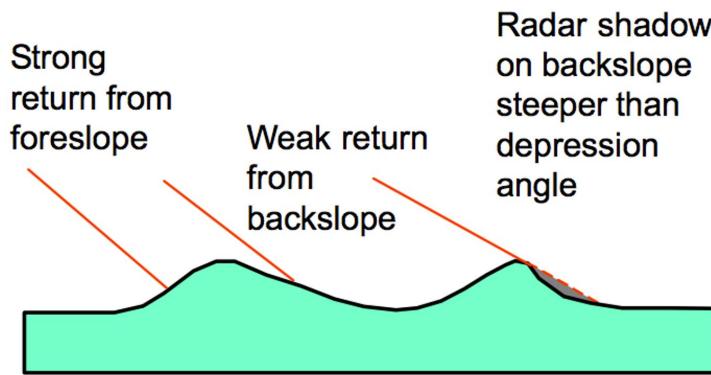
Interpretation



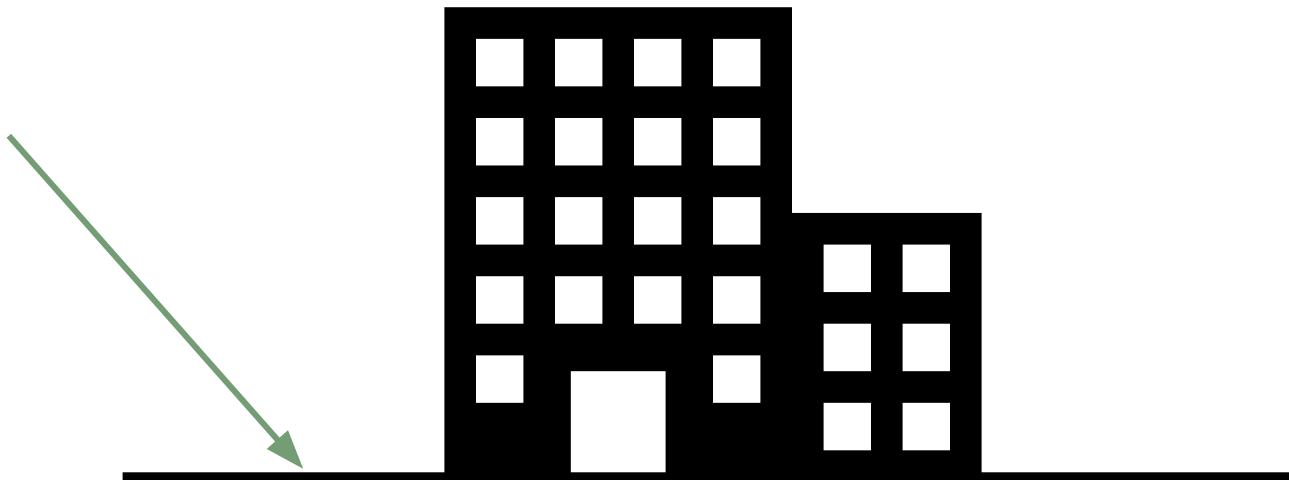
Microwave interactions with matter



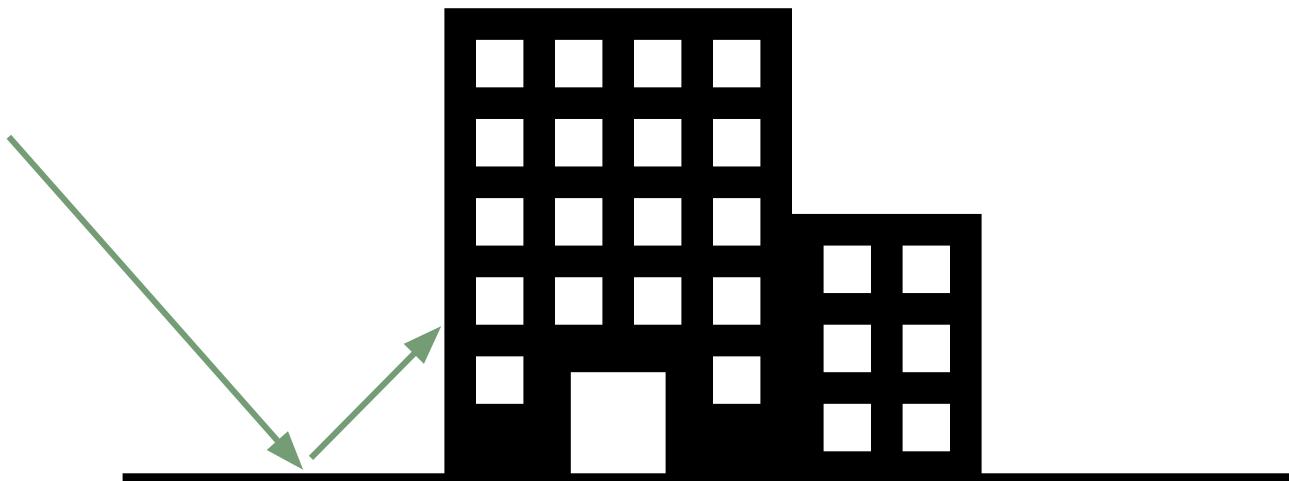
Microwave interactions with matter



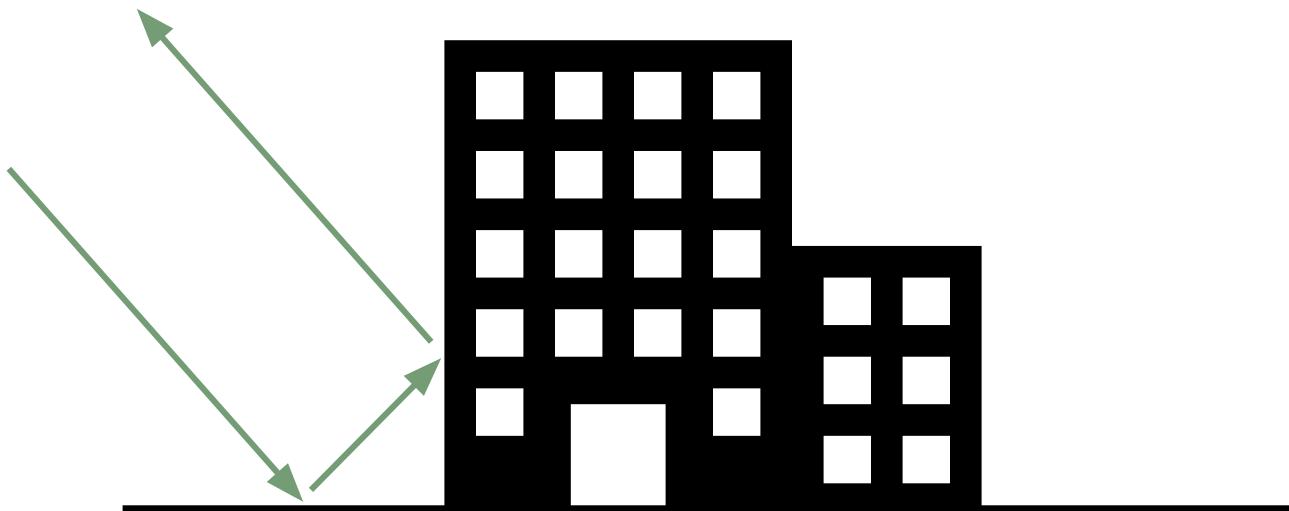
Microwave interactions with terrain



Microwave interactions with terrain

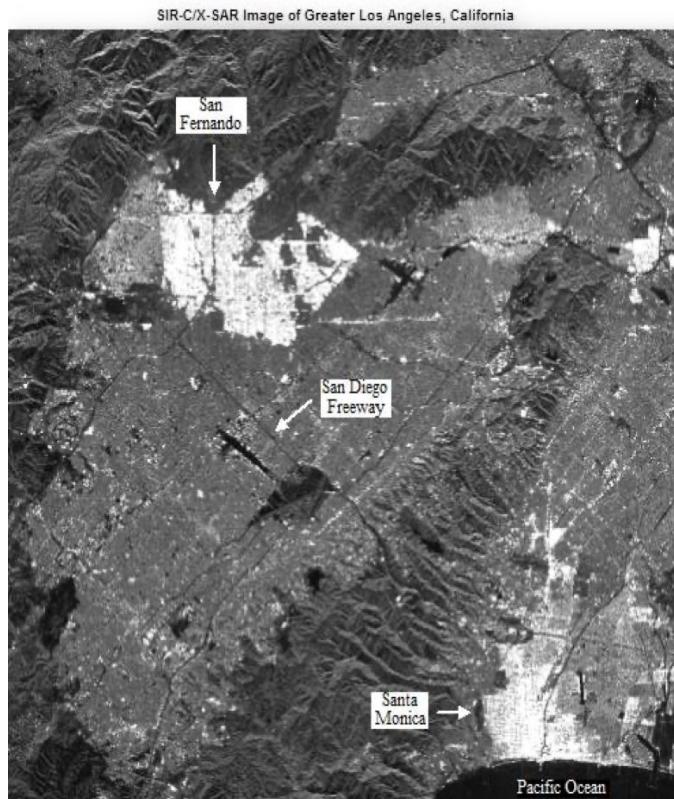


Microwave interactions with terrain

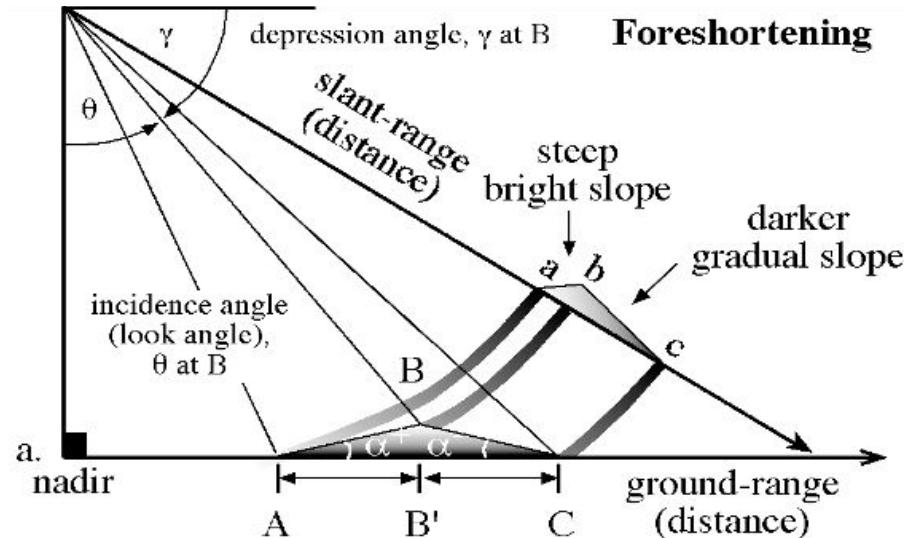


Microwave interactions with terrain

“corner reflector”



Microwave interactions with terrain



front of slope imaged faster
than back of slope



front of slope appears compressed

Microwave interactions with terrain



a.

C-band ERS-1
depression angle = 67°
look angle = 23°



b.

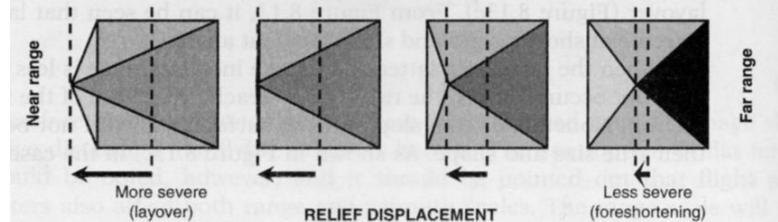
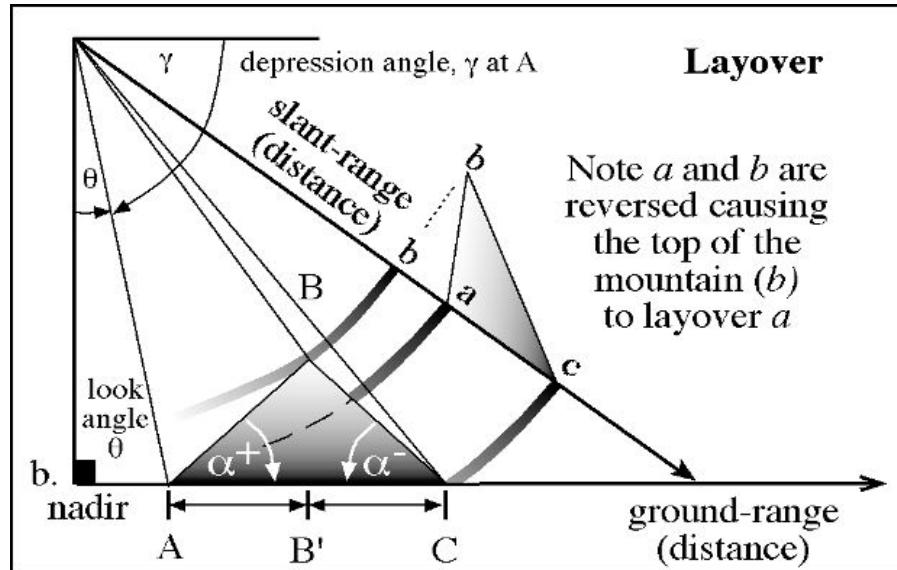
L-band JERS-1
depression angle = 54°
look angle = 36°
look direction ↓

front of slope imaged faster
than back of slope

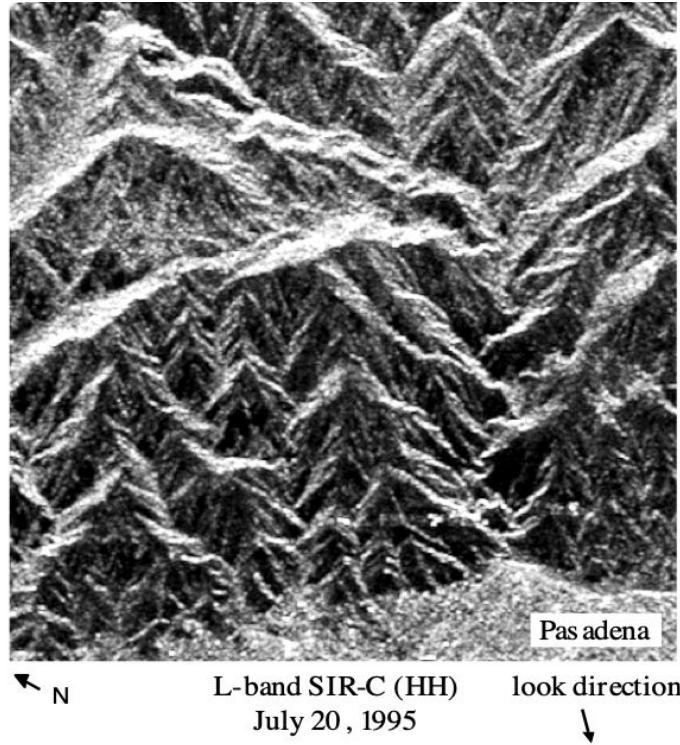


front of slope appears compressed

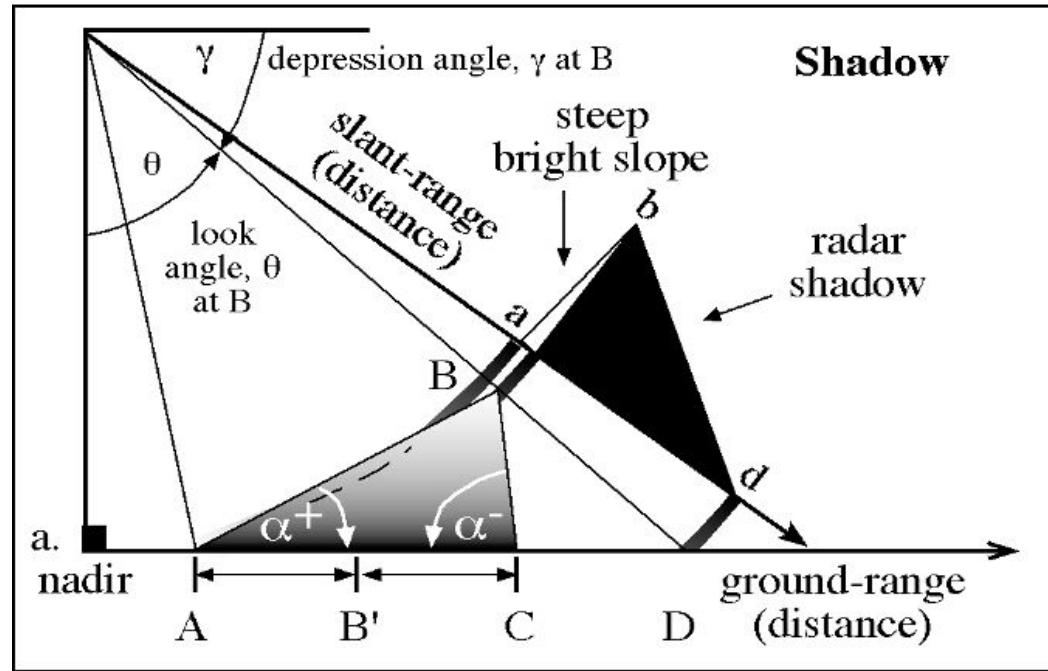
Microwave interactions with terrain



Microwave interactions with terrain



Microwave interactions with terrain

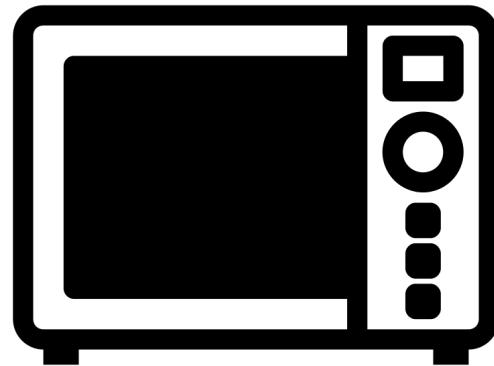


Microwave interactions with terrain

“radar shadow”



Microwave interactions with matter



Interpreting RADAR images

tone	terrain feature	cause of signature
bright	steep slopes facing antenna	lots of energy reflected back
very dark	steep slopes facing away	no energy reaches terrain, no return
very dark	calm water, dark pavement	smooth surfaces reflect energy away
very bright	man-made structure	intersecting surfaces reflect strongly
medium	vegetation	scatter in many directions

Advantages of RADAR

- **Works in all weather**
- **Works at night**
- **Provides information outside of the visible and infrared**
 - E.g. surface roughness, dielectric properties, moisture content
- **Can penetrate certain objects**
 - E.g. vegetation, sand, surface layers of snow
- **Spatial resolution independent of distance to object**