Ryo Suzuki Curricumlum Vitae

University of Calgary iLab MS 680, 2500 University Drive NW Calgary, Alberta, Canada T2N1N4 http://ryosuzuki.org ryo.suzuki@ucalgary.ca +1 (403) 220-6015

Research Interest

I am an Assistant Professor in the Department of Computer Science at the University of Calgary. My research focus lies in the **intersection between human-computer interaction and robotics**. I have developed a novel tangible user interface made of swarm and soft robots, leveraging techniques from both robotics and HCI. The goal of my research is to *make the physical environment more adaptive and programmable with the distributed ubiquitous robots at all scales* (i.e., from mm- to m-scale).

keyword: tangible interface, swarm robots, soft robots, augmented reality

Employment

01/2021 - University of Calgary

Assistant Professor, Department of Computer Science

Human-Computer Interaction Group Director of Programmable Reality Lab

05/2020 - Microsoft Research, Redmond

08/2020 Research Intern in EPIC Group

with Mar Gonzalez-Franco, Eyal Ofek, Mike Sinclair, Andy Wilson, Ken Hinckley

08/2015 - University of Colorado Boulder

05/2020 Research Assistant in Department of Computer Science and ATLAS Institute

with Daniel Leithinger, Mark D. Gross, Tom Yeh

05/2019 - Adobe Research, Seattle

08/2019 Research Intern in Creative Intelligence Lab

with Rubaiat Habib, Li-Yi Wei, Stephen DiVerdi, Wilmot Li

12/2017 - University of Tokyo

10/2018 Research Intern in JST ERATO

with Yasuaki Kakehi, Yoshihiro Kawahara, Ryuma Niiyama

05/2016 - UC Berkeley

08/2016 Research Intern in BiD Group

with Bjoern Hartmann, Gustavo Soares, Elena Glassman

05/2015 - Stanford University

08/2015 Research Intern in HCI Group

with Michael Bernstein

09/2014 - University of Tokyo

05/2015 Research Assistant in IIS Lab with Koji Yatani

01/2015 - AIST, Tsukuba

03/2015 Research Intern in Media Interaction Group with Jun Kato, Masataka Goto

Education

08/2015 - University of Colorado Boulder

07/2020 Ph.D. candidate in Human-Computer Interaction, Department of Computer Science

PhD Dissertation: Dynamic Shape Construction and Transformation with Collective Elements Committee: Daniel Leithinger, Mark D. Gross, Hiroshi Ishii, Takeo Igarashi, Tom Yeh

04/2011 - University of Tokyo

03/2013 M.A. in Computational Game Theory, Department of Economics

Thesis: Diffusion Process and Take-off Conditions of Online Platforms

Advisor: Michihiro Kandori

04/2007 - Tokyo Institute of Technology

03/2011 B.Eng in Information and Social Science, School of Engineering

Peer-Reviewed Conference Publications

Quick summary since 2016: First Author (11), Awarded Paper (2), CHI (4), UIST (4), IROS (1), ICSE (1), ASSETS (1), and other venues (5). 570 citations and 12 h-index since 2016, based on Google Scholar (as of 08/2021) ^a

- [C16] Ryo Suzuki, Eyal Ofek, Mike Sinclar, Daniel Leithinger, Mar Gonzalez-Franco. HapticBots: Distributed Encountered-type Haptics for VR with Multiple Shape-changing Mobile Robots. In Proceedings of the Annual ACM Symposium on User Interface Software and Technology. ACM, 2021. (UIST '21, acceptance rate: 25%)
- [C15] Ryo Suzuki, Rubaiat Habib, Li-Yi Wei, Stephen Diverdi, Wilmot Li, Daniel Leithinger. RealitySketch: Embedding Responsive Graphics and Visualizations in AR through Dynamic Sketching. In Proceedings of the Annual ACM Symposium on User Interface Software and Technology. ACM, 2020. (UIST '20, acceptance rate: 21%)

Honorable Mention Paper Award (top 5%)

[C14] Hooman Hedayati, Ryo Suzuki, Daniel Leithinger, Daniel Szafir. PufferBot: Actuated Expandable Structures for Aerial Robots. In Proceedings of 2020 IEEE/RSJ International Conference on Intelligent Robots and Systems. IEEE, 2020 (IROS '20, acceptance rate: 47%)

^ahttps://scholar.google.com/citations?user=klWjaQIAAAAJ

- [C13] Ryo Suzuki, Hooman Hedayati, Clement Zheng, James Bohn, Daniel Szafir, Ellen Yi-Luen Do, Mark D. Gross, Daniel Leithinger. RoomShift: Room-scale Dynamic Haptics for VR with Furniture-moving Swarm Robots. In Proceedings of the ACM CHI Conference on Human Factors in Computing Systems. ACM, 2020. (CHI '20, acceptance rate: 24%)
- [C12] Ryo Suzuki, Ryosuke Nakayama, Dan Liu, Yasuaki Kakehi, Mark D. Gross, Daniel Leithinger. LiftTiles: Constructive Building Blocks for Prototyping Room-scale Shape-changing Interfaces. In Proceedings of the ACM International Conference on Tangible, Embedded and Embodied Interaction. ACM, 2020. (TEI '20, acceptance rate: 28%)
- [C11] Ryo Suzuki, Clement Zheng, Yasuaki Kakehi, Tom Yeh, Ellen Do, Mark D. Gross, Daniel Leithinger. ShapeBots: Shape-changing Swarm Robots. In Proceedings of the Annual ACM Symposium on User Interface Software and Technology. ACM, 2019. (UIST '19, acceptance rate: 24%)
- [C10] Ryosuke Nakayama*, Ryo Suzuki*, Satoshi Nakamaru, Ryuma Niiyama, Yoshihiro Kawahara, Yasuaki Kakehi. (* equally contributed) MorphIO: Entirely Soft Sensing and Actuation Modules for Programming Shape Changes through Tangible Interaction. In Proceedings of the ACM Conference on Designing Interactive Systems. ACM, 2019. (DIS '19, acceptance rate: 25%)

 Best Paper Award (top 1%)
- [C9] **Ryo Suzuki**, Junichi Yamaoka, Daniel Leithinger, Tom Yeh, Mark D. Gross, Yoshihiro Kawahara, Yasuaki Kakehi. Dynablock: Dynamic 3D Printing for Instant and Reconstructable Shape Formation. *In Proceedings of the Annual ACM Symposium on User Interface Software and Technology*. ACM, 2018. (**UIST '18**, acceptance rate: 20%)
- [C8] **Ryo Suzuki**, Koji Yatani, Mark D. Gross, Tom Yeh. Tabby: Explorable Design for 3D Printing Textures. *In Proceedings of the Pacific Conference on Computer Graphics and Applications*. Eurographics Association, 2018 (**PG '19**, acceptance rate: 26%)
- [C7] **Ryo Suzuki**, Jun Kato, Mark D. Gross, Tom Yeh. Reactile: Programming Swarm User Interfaces through Direct Physical Manipulation. *In Proceedings of the CHI Conference on Human Factors in Computing Systems*. ACM, 2018. (CHI '18, acceptance rate: 25%)
- [C6] Hyunjoo Oh, Tung D. Ta, Ryo Suzuki, Mark D. Gross, Yoshihiro Kawahara, Lining Yao. PEP (3D Printed Electronic Papercrafts): An Integrated Approach for 3D Sculpting Paper-based Electronic Devices. In Proceedings of the CHI Conference on Human Factors in Computing Systems. ACM, 2018. (CHI '18, acceptance rate: 25%)
- [C5] **Ryo Suzuki**, Abigale Stangl, Mark D Gross, Tom Yeh. FluxMarker: Enhancing Tactile Graphics with Dynamic Tactile Markers. *In Proceedings of the International ACM SIGACCESS Conference on Computers and Accessibility*. ACM, 2017. (ASSETS '17, acceptance rate: 26%)
- [C4] Ryo Suzuki, Gustavo Soares, Andrew Head, Elena Glassman, Ruan Reis, Melina Mongiovi, Loris D'Antoni, Bjoern Hartmann. TraceDiff: Debugging Unexpected Code Behavior Using Trace Divergences. In Proceedings of the IEEE Symposium on Visual Languages and Human-Centric Computing. IEEE, 2017. (VL/HCC '17, acceptance rate: 29%)

- [C3] Andrew Head, Elena Glassman, Gustavo Soares, Ryo Suzuki, Lucas Figueredo, Loris D'Antoni, Bjoern Hartmann. Writing Reusable Code Feedback at Scale with Mixed-Initiative Program Synthesis. In Proceedings of the ACM Conference on Learning at Scale. ACM, 2017. (L@S '17, acceptance rate: 22%)
- [C2] Reudismam Rolim, Gustavo Soares, Loris D'Antoni, Oleksandr Polozov, Sumit Gulwani, Rohit Gheyi, Ryo Suzuki, Bjoern Hartmann. Learning Syntactic Program Transformations from Examples. In Proceedings of the International Conference on Software Engineering. IEEE, 2017. (ICSE '17, acceptance rate: 19%)
- [C1] Ryo Suzuki, Niloufar Salehi, Michelle S. Lam, Juan C. Marroquin, Michael S. Bernstein. Atelier: Repurposing Expert Crowdsourcing Tasks as Micro-internships. In Proceedings of the CHI Conference on Human Factors in Computing Systems. ACM, 2016. (CHI '16, acceptance rate: 23%)

Peer-Reviewed Demo and Poster Publications

- [D13] Hiroki Kaimoto, Samin Farajian, **Ryo Suzuki**. Swarm Fabrication. In Adjunct Proceedings of the Annual ACM Symposium on User Interface Software and Technology. ACM, 2021. (**UIST '21** Student Innovation Contest)
- [D12] Martin Nisser, Leon Cheng, Yashaswini Makaram, Ryo Suzuki, Stefanie Mueller. Programmable Polarities: Actuating Interactive Prototypes withProgrammable Electromagnets. In Adjunct Proceedings of the Annual ACM Symposium on User Interface Software and Technology. ACM, 2021. (UIST '21 Demo)
- [D11] Ryo Suzuki, Eyal Ofek, Mike Sinclar, Daniel Leithinger, Mar Gonzalez-Franco. Demonstrating HapticBots: Distributed Encountered-type Haptics for VR with Multiple Shape-changing Mobile Robots. In Adjunct Proceedings of the Annual ACM Symposium on User Interface Software and Technology. ACM, 2021. (UIST '21 Demo)
- [D10] Ryo Suzuki, Rubaiat Habib, Li-Yi Wei, Stephen Diverdi, Wilmot Li, Daniel Leithinger. Demonstrating RealitySketch: Embedding Responsive Graphics and Visualizations in AR through Dynamic Sketching. In Adjunct Proceedings of the Annual ACM Symposium on User Interface Software and Technology. ACM, 2020. (UIST '20 Demo)
 - Honorable Mention Best Demo Award (top two demos)
- [D9] **Ryo Suzuki**. Collective Shape-changing Interfaces. In Adjunct Proceedings of the Annual ACM Symposium on User Interface Software and Technology. ACM, 2019. (**UIST '19** Doctoral Consortium)
- [D8] Ryo Suzuki, Ryosuke Nakayama, Dan Liu, Yasuaki Kakehi, Mark D. Gross, Daniel Leithinger. LiftTiles: Modular and Reconfigurable Room-scale Shape Displays through Retractable Inflatable Actuators. In Adjunct Proceedings of the Annual ACM Symposium on User Interface Software and Technology. ACM, 2019. (UIST '19 Poster)
- [D7] Ryo Suzuki, Clement Zheng, Yasuaki Kakehi, Tom Yeh, Ellen Do, Mark D. Gross, Daniel Leithinger. Demonstrating ShapeBots: Shape-changing Swarm Robots. In Proceedings of the Annual ACM Symposium on User Interface Software and Technology. ACM, 2019. (UIST '19 Demo)

- [D6] **Ryo Suzuki**, Junichi Yamaoka, Daniel Leithinger, Tom Yeh, Mark D. Gross, Yoshihiro Kawahara, Yasuaki Kakehi. Demonstrating Dynablock: Dynamic 3D Printing for Instant and Reconstructable Shape Formation. *In Proceedings of the Annual ACM Symposium on User Interface Software and Technology*. ACM, 2018. (**UIST '18** Demo)
- [D5] Ryo Suzuki, Gustavo Soares, Elena Glassman, Andrew Head, Loris D'Antoni, Bjoern Hartmann. Exploring the Design Space of Automatically Synthesized Hints for Introductory Programming Assignments. In Proceedings of the CHI Conference Extended Abstracts on Human Factors in Computing Systems. ACM, 2017. (CHI '17 Late-Breaking Work)
- [D4] Stanford Crowd Research Collective (For the full author list, please see the publication), Daemo: A Self-Governed Crowdsourcing Marketplace. In Adjunct Proceedings of the Annual ACM Symposium on User Interface Software and Technology. ACM, 2015. (UIST '15 Poster)
- [D₃] **Ryo Suzuki**. Toward a Community Enhanced Programming Education. In Proceedings of the CHI Conference Extended Abstracts on Human Factors in Computing Systems. ACM, 2015. (CHI '15 Workshop Paper)
- [D2] **Ryo Suzuki**, Interactive and Collaborative Source Code Annotation. *In Proceedings of the International Conference on Software Engineering*. IEEE, 2015. (**ICSE '15** Poster)
- [D1] Ryo Suzuki, Network Thresholds and Multiple Equilibria in the Diffusion of Content-based Platforms. In Proceedings of the International Conference on Web and Internet Economics. Springer, 2014. (WINE '14 Poster)

Awards and Scholarships

Awards

- 2020 UIST 2020 Honorable Mention Best Demo Award
- 2020 UIST 2020 Honorable Mention Best Paper Award
- 2020 University of Colorado Boulder Outstanding Research Award in CS
- 2019 DIS 2019 Best Paper Award
- 2018 Google PhD Fellowship Finalist
- 2013 Tech Crunch Disrupt in Tokyo 2013 Finalist
- 2012 University of Tokyo Startup Competition 1st Prize Winner

Scholarship

- 2015-2020 CU Boulder Travel Grant (\$500-\$1,200 for each conference travel)
- 2015-2020 Nakajima Foundation Scholarship (\$120,000 stipend for 5 years and 2 years tuition coverage)
- 2013-2015 JSPS Research Fellow DC1 (\$72,000 stipend for 2 years)

Funding

- **Ryo Suzuki**. Augmenting In-person Verbal Communication by Adding Interactivity to Transcribed Spoken Words in AR. *Snap, Inc,* Snap Creative Challenge Funding, \$15,000 https://www.snapcreativechallenge.com/
- 2021 Harrison Chen, **Ryo Suzuki**. Investigating Human-Drone Interaction with VR Simulation. *NSERC*, NSERC USRA, \$6,000 CAD
- 2021 Colin Au Yeoung, **Ryo Suzuki**. Situated Guidance and Visualization to Support Personal Fabrication Activities. *NSERC*, NSERC USRA, \$6,000 CAD
- 2021 Ryo Suzuki. NSERC, Discovery Grant Funding, \$145,000 CAD
- 2021 Ryo Suzuki. University of Calgary, Startup Funding, \$100,000 CAD
- 2019 Ryo Suzuki. Adaptive Physical Environments with Distributed Swarm Robots. Ministry of Internal Affairs and Communications in Japan, Innovation Research Funding, \$30,000 https://www.inno.go.jp/en/
- 2019 Ryo Suzuki. Adobe Gift Funding, \$5,000
- 2018 Ryo Suzuki. Dynamic Physical Interfaces. JST in Japan, ACT-I Funding for Young Scholars, \$30,000 and Mentorship Opportunity (my mentor was Takeo Igarashi) https://www.jst.go.jp/kisoken/act-i/en/index.html
- 2018 **Ryo Suzuki**. Programmable Architecture with Soft Inflatable Actuator. *Leave a Nest Foundation in Japan*, Emerging Research Funding for AI and Interdisciplinary Research \$5,000
- 2013-2015 **Ryo Suzuki**. Network-based Diffusion Analysis for Online Community, *JSPS*, KAKENHI Grants-in-Aid for Scientific Research, \$40,000

Teaching

Courses

- Winter 2022 CPSC 601: AR/VR and Robotics (Graduate)
 Department of Computer Science, University of Calgary
 - Fall 2021 CPSC 581: Human-Computer Interaction II (Undergradate/Graduate)
 Department of Computer Science, University of Calgary
- Winter 2021 CPSC 599/601: Design of Mixed Reality Apps (Undergradate/Graduate)
 Department of Computer Science, University of Calgary

Teaching Assistant

Fall 2019 CSCI 3002: Fundamentals of Human Computer Interaction (Undergraduate)

Instructor: Prof. Shaun Kane

Department of Computer Science, University of Colorado Boulder

Spring 2017 ATLS 6000: Soft Robotics (Graduate)

Instructor: Prof. Mark D. Gross

ATLAS Institute, University of Colorado Boulder

Fall 2012 Game and Network Theory (Graduate)

Instructor: Prof. Michihiro Kandori

Department of Economics, University of Tokyo

Fall 2012 Dynamic Programming and Optimization (Graduate)

Instructor: Prof. Kazuya Kamiya

Department of Economics, University of Tokyo

Students

Supervision

09/2020 - Neil Chulpongsatorn

present MSc student and Undergraduate research student (CPSC 502 Course)

Mixed Reality and Data Visualization

05/2021 - Adnan Karim

present MSc student

AR/VR and Robotics

09/2021 - Shivesh Jadon

present MSc student (co-supervised by Wesley Willet)

Social AR and Data Visualization

09/2021 - Marcus Friedel

present MSc student (co-supervised by Ehud Sharlin)

VR Haptics

09/2021 - Samin Farajian

present MSc student

Digital Fabrication with Swarm Robots

09/2020 - Christopher Smith

present MSc student (co-supervised by Ehud Sharlin and Sowmya Somanath)

Modular VR Haptics

05/2021 - Tian Xia

present Undergraduate research student (CPSC 502 Course, co-supervised by Ehud Sharlin)

Cross-scale Interactions with AR/VR

05/2021 - Colin Au Yeung

present Undergraduate research student (NSERC USRA, co-supervised by Wesley Willet)
Augmented Makrespace

05/2021 - Harrison Chen

present Undergraduate research student (NSERC USRA)

Human-Drone Interaction

09/2021 - Kaynen Mitchell

present Undergraduate research student (CPSC 502 Course)

09/2021 - Nathaniel Habtegergesa

present Undergraduate research student (CPSC 502 Course)

09/2021 - Manjot Khangura

present Undergraduate research student (CPSC 502 Course)

Visiting Students

05/2021 - Curtis Engerdahl

09/2021 Summer undergraduate research student (University of Alberta)

05/2021 - Gurnoor Aujla

09/2021 Summer undergraduate research student (University of Calgary)

05/2021 - Carrie Rong

08/2021 Summer undergraduate research student (McGill University)

Thesis Committee

2021 Brennan Jones

PhD Thesis Committee (supervisor: Tony Tang)

Title: Designing Remote Collaboration Technologies for Wilderness Search and Rescue

2020 Kendra Wannamaker

MSc Thesis Committee (supervisor: Wesley Willett)

Title: Situated Self-Tracking: Ideating, Designing, and Deploying Dedicated User-driven Personal Informatics Systems

Mentoring (During PhD)

2019 Chrystalina Pharr

Undergraduate student in Mechanical Engineering

University of Colorado Boulder

Project: ceiling-based swarm robots

2019 James Bohn

Undergraduate student in Computer Science

University of Colorado Boulder

Project: furniture-moving swarm robots

2018 Ryosuke Nakayama

Master student in Media Design

Keio University (Now Sony)

Project: interactive soft robots and shape-changing inflatable structure

2018 Takayuki Hirai

Undergraduate student in Media Design

Keio University (Now Nintendo)

Project: shape-changing swarm robots

2018 Takumi Murayama

Undergraduate student in Media Design

Keio University

Project: reprogrammable inflatable architectural structure

2017 Kevin Kuwata

Master student in Electrical and Computer Engineering

University of Colorado Boulder (Now Apple)

Project: mm-scale swarm robots with electromagnetic actuation

2017 Zhixian Jin

Undergraduate student in Electrical and Computer Engineering

University of Colorado Boulder

Project: tactile feedback with actuated magnetic marker

2016 Ruan Reis

Master student in Computer Science

Federal University of Campina Grande

Project: automated hint generation for programming assignment

2015 Michelle Lam

Undergraduate student in Computer Science

Stanford University

Project: micro-internship with repurposed crowdsourcing tasks

2015 Juan Marroquin

Undergraduate student in Computer Science

Stanford University (Now Microsoft)

Project: micro-internship with repurposed crowdsourcing tasks

2015 Adam Ginzberg

Undergraduate student in Computer Science

Stanford University (Now Coda.io)

Project: crowd research

Selected Press Coverage

07/2021 IEEE Computer Graphics and Applications. Cover Story of "Real Virtual Reality" (vol. 41)

- 03/2021 IT Media News. Evolution of "AR Drawing"? RealitySketch, a sketching technology that works with objects in reality
- 10/2020 ACM TechNews. Pufferfish-inspired robot could improve drone safety
- 10/2020 Interesting Engineering. Pufferfish Mimicking Drones to Improve Aerial Safety
- 10/2020 New Atlas. Drone draws on the pufferfish to protect itself and others
- 10/2020 Techable. University of Colorado researchers unveil 'RoomShift' to move props in VR space in real life
- 10/2020 Hackster.io. Putting the Reality in Virtual Reality
- 09/2020 Hackster.io. PufferBot Is an Aerial Robot That Can Change Shape In-Flight
- 09/2020 TechXplore. RoomShift: A room-scale haptic and dynamic environment for VR applications
- 09/2020 Engineering 360. Team builds drone inspired by the pufferfish
- 09/2020 TechXplore. PufferBot: A flying robot with an expandable body
- 09/2020 Yahoo News. The University of Colorado Announced "RoomShift" where Robot Rearranges Furniture to Create Virtual Spaces in a Realistic Way
- 09/2020 IT Media News. RoomShift: Reconfigurable Environments for Virtual Reality
- 02/2020 IT Media News. Giant whistle module expands the room with the University of Colorado and other "LiftTiles" developments
- 01/2020 Arduino Blog. Prototype room-scale, shape-changing interfaces with LiftTiles
- 01/2020 TechXplore. LiftTiles: Actuator-based Building Blocks for Shape-changing Interfaces
- 01/2020 ITMedia News. A Swarm of Self-transforming Robots to Assist People
- 11/2019 Hackster.io. LiftTiles Turn Walls and Floors Into Reconfigurable Structures on Demand
- 11/2019 Element 14. Engineers Develop LiftTiles, a Scale Shape-changing Interface
- 11/2019 Bouncy. Swarm Robots that can Change Shape to Visualize Data
- 10/2019 Hackster.io. Swarming Robots Can Change Their Configuration to Handle Different Tasks
- 09/2019 TechXplore. ShapeBots: A Swarm of Shape-shifting Robots that Visually Display Data
- 09/2019 Hackaday. Tiny Robots that Grow Taller and Wider
- 09/2019 Robotic Gizmo. ShapeBots: Shape Changing Swarm Robots
- 09/2019 Gadgetify. ShapeBots: Shape Changing Swarm Robots
- 10/2018 3DPrint.com. Dynablock: 3D Prints That Assemble and Disassemble in Seconds
- 10/2018 Hackster.io. The Dynamic 3D Printing That Assembles and Disassembles Objects in Seconds

- 10/2018 Arduino Blog. Create Shapes Over and Over with the Dynablock 3D Printer
- 10/2018 3DRuck.com. Dynablock: Dynamischer 3D-Drucker erstellt Objekte in Sekunden
- 10/2018 World Business Satellite (Japanese TV). Repeatable 3D Printer
- 10/2018 Nikkei Newspaper, Modeling 3D Objects with Magnet-Embedded Blocks
- 06/2016 Wired. It's Not Just Robots: Skilled Jobs Are Going to Meatware

Invited Talks

- 03/2021 From Augmented Reality to Reconfigurable Reality: Towards Seamless Interactions through Both Visually and Physically Programmable Environments

 MIT CSAIL, Boston (hosted by Arvind Satyanarayan)
- 12/2020 **Programmable Environments with Distributed Swarm Robots**Tohoku University, Tohoku, Japan (hosted by Yoshifumi Kitamura)
- 05/2020 **Programmable Environments with Distributed Swarm Robots**University of Calgary, Calgary (hosted by Ehud Sharlin)
- 03/2020 **Programmable Environments with Distributed Swarm Robots**Virginia Tech, Blacksburg (hosted by Doug Bowman)
- 03/2020 **Programmable Environments with Distributed Swarm Robots** UCSB, Santa Barbara (hosted by Misha Sra)
- 02/2020 **Programmable Environments with Distributed Swarm Robots**University of Washington, Seattle (hosted by Shyam Gollakota and Jon Froehlich)
- 02/2020 **Programmable Environments with Distributed Swarm Robots**Boston University, Boston (hosted by Emily Whiting)
- 12/2019 Adaptive Physical Environment with Distributed Swarm Robots CU Boulder ATLAS Seminar, Boulder (hosted by Ellen Do)
- 11/2019 Adaptive Physical Environment with Distributed Swarm Robots MIT CSAIL, Boston (hosted by Stefanie Mueller)
- 11/2019 Adaptive Physical Environment with Distributed Swarm Robots
 MIT Media Lab, Boston (hosted by Hiroshi Ishii)
- 10/2019 Distributed and Collective Robots as Ubiquitous Interfaces University of Tokyo, Tokyo, Japan (hosted by Takeo Igarashi)
- 10/2019 **Distributed and Collective Robots as Ubiquitous Interfaces**University of Tokyo, Tokyo, Japan (hosted by Jun Rekimoto)
- 10/2019 **Distributed and Collective Robots as Ubiquitous Interfaces**JST ERATO, Tokyo, Japan (hosted by Yoshihiro Kawahara)

10/2019 Distributed and Collective Robots as Ubiquitous Interfaces

Takram, Tokyo, Japan (hosted by Hisato Ogata)

10/2019 Distributed and Collective Robots as Ubiquitous Interfaces

ZOZO Research, Tokyo, Japan (hosted by Satoshi Nakamaru)

10/2019 Distributed and Collective Robots as Ubiquitous Interfaces

Preferred Networks, Tokyo, Japan (hosted by Hironori Yoshida)

10/2019 Distributed and Collective Robots as Ubiquitous Interfaces

Omron ScinicX Research Lab, Tokyo, Japan (hosted by Yoshitaka Ushiku)

06/2019 Real-time Binding between Physical and Digital Worlds

Adobe Research, Seattle (hosted by Wilmot Li)

10/2018 Dynamic Physical Media

CU Boulder ATLAS Seminar, Boulder (hosted by Mark Gross)

06/2016 Programming Environment for Physical Computing and Mixed Reality Era

UC Berkeley BiD Seminar, Berkeley (hosted by Bjoern Hartmann)

Service

2020 – present Program Committee

CHI 2022

UIST 2021

THRI 2021

ISMAR 2021

VRST 2021

TEI 2021, 2022

GI 2020

2016 – present Organizing Committee

UIST '21 Student Innovation Contest Chair

CHI '21 Social Media Chair

UIST '16 Web and Social Media Chair

2016 – present Reviewer

CHI 2016 - 2021

UIST 2016 - 2021

ISS 2021

ISMAR 2020

SCF 2019

SIGGRAPH ETech 2019

IEEE VR 2020

GI 2020

2016 – 2017 Student Volunteer

CHI 2017

UIST 2016

References

Daniel Leithinger

Assistant Professor ATLAS Institute, University of Colorado Boulder daniel.leithinger@colorado.edu

Mark D. Gross

Director ATLAS Institute, University of Colorado Boulder

Hiroshi Ishii

Professor and Associate Director Media Lab, MIT ishii@media.mit.edu

mdgross@colorado.edu

Takeo Igarashi

Professor

Department of Computer Science, University of Tokyo takeo@acm.org

Tom Yeh

Assistant Professor Department of Computer Science, University of Colorado Boulder tom.yeh@colorado.edu

Bjoern Hartmann

Associate Professor Department of Electrical Engineering and Computer Science, UC Berkeley bjoern@eecs.berkeley.edu

Rubaiat Habib

Senior Research Scientist Adobe Research rhabib@adobe.com