

# Ryan - David Reyes

2040 Stearns Rd Apt 42 – Cleveland, OH 44106

☎ (850) 559 7516 • ✉ [ryan.david.reyes@gmail.com](mailto:ryan.david.reyes@gmail.com) • 📄 [recu.rs](http://recu.rs)

## Education

### Case Western Reserve University

*M.S. Biomedical Engineering*

**Cleveland, OH**

*Fall 2016–Spring 2021*

### Florida State University

*B.S. Computer Engineering and B.S. Electrical Engineering with Honors, GPA: 3.83*

**Tallahassee, FL**

*Fall 2011–Spring 2015*

## Experience

### Graduate Student, Research Assistant

#### Case Western Reserve University

*Biomedical Engineering Department, Advanced Platform Technology Center*

**Cleveland, OH**

*August 2016–May 2021*

- **Masters Project:** [Biologically Inspired Optimal Terminal Iterative Learning Control for a Motorized Hybrid Neuroprosthesis](#)
  - a device for persons with paraplegia which combines functional electrical stimulation (FES) of their muscles with a motorized exoskeleton to restore their ability to walk using learning algorithms.
  - Designed and implemented the firmware of the exoskeleton in C across multiple Teensy 3.6's communicating over CAN.
  - Developed a web-based real-time user interface for the exoskeleton with Javascript, Node.js and Socket.IO with a Raspberry Pi.
  - Development of algorithms to control stimulated muscles and motors in tandem using terminal iterative learning control.
  - Publication: [Effect of Joint Friction Compensation on a "Muscle First" Motor-Assisted Hybrid Neuroprosthesis](#)
  - Publications as co-author:
    - [Embedded control system for stimulation-driven exoskeleton](#)
    - [Biologically Inspired Optimal Terminal Iterative Learning Control: A Modeling Study](#)
    - [Adaptation Strategies for Personalized Gait Neuroprosthetics](#)
- Worked with a mechanical engineer to create an [origami-inspired folding quadcopter](#) for the class *EMAE 488: Advanced Robotics*.
- Non-degree related:
  - Created an open source linear algebra library for the Elm programming language: [elm-numeric](#).
  - Contributed to Blender, the open source 3D modeling software. The [patch](#) concerned rewriting OpenGL 2 dependent API with an OpenGL 3 shader-based library.

### Biomedical Engineering IT Support

#### Case Western Reserve University, Louis Stokes VA

*Biomedical Engineering Department, Advanced Platform Technology Center*

**Cleveland, OH**

*Nov 2017–Dec 2019*

- General technical support for Researchers ranging from email administration to solving computer hardware issues.
- Management of MATLAB License Servers
- Management of Remote Linux (Rocks Distribution) Computing Clusters

### Research Assistant

#### Florida State University

*Mechanical Engineering Department, CISCOR Robotics Lab*

**Tallahassee, FL**

*July 2012–August 2014*

- Created drivers for Inertial Measurement Units, Gamepads, TCP/IP, and Force Sensors on Windows, Linux, and QNX in C++.
- Implemented Real-Time Linux Xenomai Framework on robots with comprehensive documentation.
- Experience writing control systems with QNX Real-Time operating system (RTOS).
- Project: [GOLIATH](#) - Gas Operated Land Intelligent All Terrain veHicle - Autonomous ATV designed for terrain classification.
  - Designed the control system that allows the user to drive the ATV via a Logitech Gamepad, communicating with the host system via TCP/IP for Windows, Linux, and QNX in C++.
- **Honors Thesis:** [Identification of the Inertial Parameters of Manipulator Payloads](#)
  - Concerned what motions a load bearing two-link manipulator can use to identify the inertial parameters of its payload.
  - Used to augment CISCOR Intelligent Planner - Sampling Based Model Predictive Optimization (SBMPO) Research.

## Qualifications and Awards

**Outstanding Master's Work Award in the CWRU Biomedical Engineering Department:**

*Spring 2021*

**Recipient of NIH T32 Training Grant:**

*Fall 2016*

**NSF Graduate Research Fellowship Program (GRFP) Honorable Mention:**

*Spring 2015*

**Eagle Scout - Boy Scouts of America:**

*Dec. 2009*