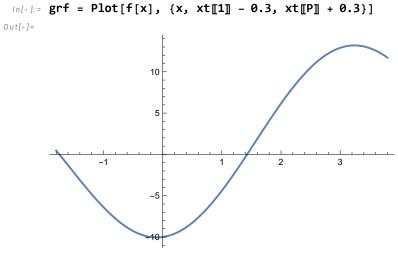
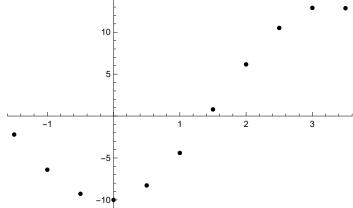
Изпит-Георги Г.-2001261019

Генериране на данни

```
In[*]:= xt = Table[1+i*0.5, {i, -5, 5}]
Out[0]=
        \{-1.5, -1., -0.5, 0., 0.5, 1., 1.5, 2., 2.5, 3., 3.5\}
 In[*]:= f[x_] := x - 10 Cos[x]
 In[*]:= yt = f[xt]
Out[0]=
        \{-2.20737, -6.40302, -9.27583, -10., -8.27583,
         -4.40302, 0.792628, 6.16147, 10.5114, 12.8999, 12.8646<sub>}</sub>
 In[•]:= xt<sup>2</sup>
Out[0]=
        \{2.25, 1., 0.25, 0., 0.25, 1., 2.25, 4., 6.25, 9., 12.25\}
 In[ • ]:= yt * xt
Out[0]=
        \{3.31106, 6.40302, 4.63791, 0., -4.13791, \}
         -4.40302, 1.18894, 12.3229, 26.2786, 38.6998, 45.026}
 In[•]:= xt<sup>3</sup>
Out[0]=
        \{-3.375, -1., -0.125, 0., 0.125, 1., 3.375, 8., 15.625, 27., 42.875\}
 In[*]:= xt4
Out[0]=
        {5.0625, 1., 0.0625, 0., 0.0625, 1., 5.0625, 16., 39.0625, 81., 150.063}
 In[*]:= Vt * xt<sup>2</sup>
Out[0]=
        \{-4.96659, -6.40302, -2.31896, 0., -2.06896,
         -4.40302, 1.78341, 24.6459, 65.6965, 116.099, 157.591}
 In[*]:= P = Length[xt]
Out[0]=
        11
```



In[@]:= points = Table[{xt[i], yt[i]}, {i, 1, P}]; In[*]:= grp = ListPlot[points, PlotStyle → Black] Out[0]=



Линейна регресия

Попълваме таблицата

```
In[*]:= xt<sup>2</sup>
Out[0]=
        \{2.25, 1., 0.25, 0., 0.25, 1., 2.25, 4., 6.25, 9., 12.25\}
 In[*]:= yt * xt
Out[0]=
        \{3.31106, 6.40302, 4.63791, 0., -4.13791,
         -4.40302, 1.18894, 12.3229, 26.2786, 38.6998, 45.026}
```

Решаваме системата

```
In[*]:= A = \begin{pmatrix} P & \sum_{i=1}^{p} xt[i] \\ \sum_{i=1}^{p} xt[i] & \sum_{i=1}^{p} xt[i]^{2} \end{pmatrix}; b = \left\{ \sum_{i=1}^{p} yt[i], \sum_{i=1}^{p} yt[i] * xt[i] \right\};
  In[*]:= LinearSolve[A, b]
Out[0]=
              {0.49398, 0.0365801}
```

Съставяме полинома

```
In[*]:= P1[x_] := 0.49398 + 0.0365801x
       Таен коз (възможност за самопроверка)
 In[*]:= Fit[points, {1, x}, x]
Out[0]=
       0.49398 + 0.0365801 x
 In[*]:= P1[-8.25]
Out[@]=
       0.192194
       За сравнение истинската стойност
 In[@]:= f[-8.25]
Out[@]=
       0.19205
```

Квадратична регресия

Попълваме таблицата

```
In[*]:= xt<sup>2</sup>
Out[0]=
        \{2.25, 1., 0.25, 0., 0.25, 1., 2.25, 4., 6.25, 9., 12.25\}
 In[0]:= yt * xt
Out[0]=
        \{3.31106, 6.40302, 4.63791, 0., -4.13791, \}
         -4.40302, 1.18894, 12.3229, 26.2786, 38.6998, 45.026}
 In[•]:= xt3
Out[0]=
        \{-3.375, -1., -0.125, 0., 0.125, 1., 3.375, 8., 15.625, 27., 42.875\}
```

Намиране на сумите

$$ln[*]:=\sum_{i=1}^{p}xt[[i]]$$

Out[0]=

11.

In[*]:=
$$\sum_{i=1}^{P} yt[i]$$

Out[0]=

2.66495

$$ln[*]:=\sum_{i=1}^{p}xt[i]^{2}$$

Out[0]=

38.5

Out[0]=

129.327

$$In[*]:=\sum_{i=1}^{P}xt[[i]]^{3}$$

Out[0]=

93.5

$$ln[a]:=\sum_{i=1}^{p}xt[i]^4$$

Out[•]=

298.375

Out[0]=

345.655

Решаваме системата

$$In[*] := A = \begin{pmatrix} P & \sum_{d=1}^{p} xt[i] & \sum_{d=1}^{p} xt[i]^{2} \\ \sum_{d=1}^{p} xt[i] & \sum_{d=1}^{p} xt[i]^{2} \\ \sum_{d=1}^{p} xt[i]^{2} & \sum_{d=1}^{p} xt[i]^{3} \\ \sum_{d=1}^{p} xt[i]^{2} & \sum_{d=1}^{p} xt[i]^{3} \end{pmatrix}; b = \left\{ \sum_{i=1}^{p} yt[i], \sum_{i=1}^{p} yt[i] * xt[i], \sum_{i=1}^{p} yt[i] * xt[i]^{2} \right\};$$

$$In[*] := LinearSolve[A, b]$$

$$Out[*] = \begin{cases} -6.68541, 1.5102, 1.54785 \end{cases}$$

$$Taeh KO3 (Bъзможност за самопроверка)$$

$$In[*] := Clear[x]$$

$$In[*] := Fit[points, \{1, x, x^{2}\}, x]$$

$$Out[*] = \begin{cases} -6.68541 + 1.5102 \times + 1.54785 \times^{2} \end{cases}$$

Съставяме полинома

$$In[a] := P2[x_] := -6.68541 + 1.5102 x + 1.54785 x^2$$

Оценка на грешката

Теоретична грешка (средноквадратична)

Намиране на приближена стойност