

Метод на най-малките квадрати (МНМК)

Генериране на данни

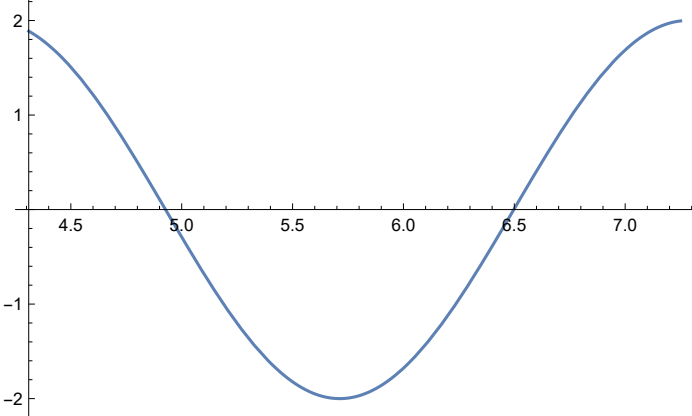
```
In[17]:= xt = Table[5 + t * 0.13, {t, -3, 15}]
Out[17]=
{4.61, 4.74, 4.87, 5., 5.13, 5.26, 5.39, 5.52, 5.65,
 5.78, 5.91, 6.04, 6.17, 6.3, 6.43, 6.56, 6.69, 6.82, 6.95}

In[18]:= f[x_] := 2 Cos[2 x - 2]
yt = f[xt]
Out[19]=
{1.18471, 0.730649, 0.22747, -0.291, -0.789909, -1.23572,
-1.59847, -1.85376, -1.98445, -1.98174, -1.84582, -1.58583,
-1.21923, -0.770676, -0.270319, 0.24821, 0.750054, 1.20148, 1.57214}

In[20]:= P = Length[xt]
Out[20]=
19
```

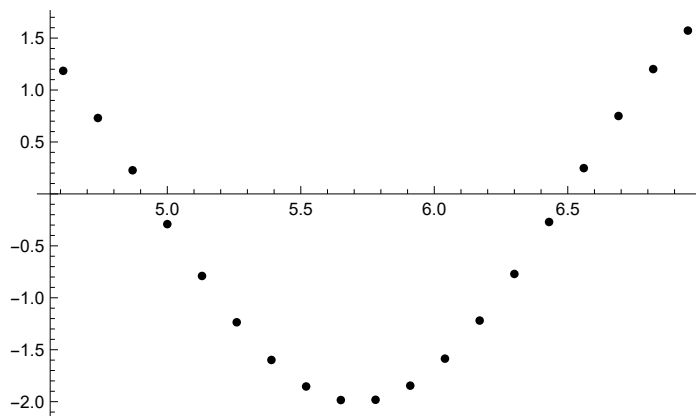
Визуализация

```
In[21]:= grf = Plot[f[x], {x, xt[[1]] - 0.3, xt[[P]] + 0.3}]
Out[21]=
```



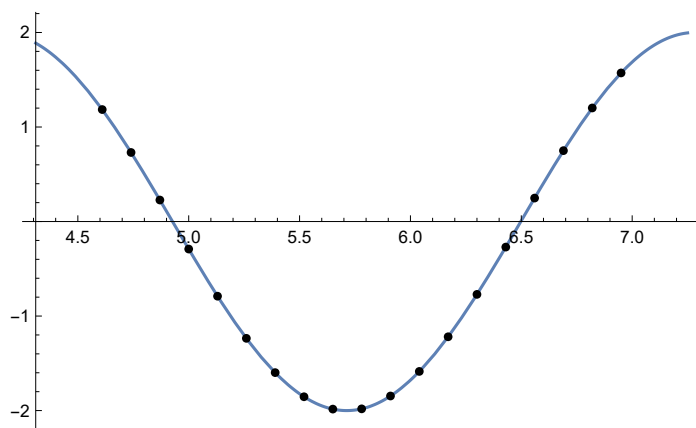
```
In[22]:= points = Table[{xt[[i]], yt[[i]]}, {i, 1, P}];
grp = ListPlot[points, PlotStyle -> Black]
```

Out[23]=



```
In[24]:= Show[grf, grp]
```

Out[24]=



Линейна регресия

Попълваме таблицата

```
In[25]:= xt2
```

Out[25]=

```
{ 21.2521, 22.4676, 23.7169, 25., 26.3169, 27.6676, 29.0521, 30.4704, 31.9225, 33.4084,
  34.9281, 36.4816, 38.0689, 39.69, 41.3449, 43.0336, 44.7561, 46.5124, 48.3025 }
```

```
In[26]:= yt * xt
```

Out[26]=

```
{ 5.46153, 3.46328, 1.10778, -1.455, -4.05223, -6.49989,
  -8.61573, -10.2328, -11.2121, -11.4545, -10.9088, -9.57838,
  -7.52264, -4.85526, -1.73815, 1.62826, 5.01786, 8.19409, 10.9264 }
```

Намиране на сумите

$$\text{In[27]:= } \sum_{i=1}^p x_t[i]$$

Out[27]=
109.82

$$\text{In[28]:= } \sum_{i=1}^p y_t[i]$$

Out[28]=
-9.51221

$$\text{In[29]:= } \sum_{i=1}^p x_t[i]^2$$

Out[29]=
644.393

$$\text{In[30]:= } \sum_{i=1}^p y_t[i] * x_t[i]$$

Out[30]=
-52.3263

Решаваме системата

$$\text{In[31]:= } A = \begin{pmatrix} 19 & 109.82 \\ 109.82 & 644.393 \end{pmatrix}; \quad b = \{-9.512, -52.326\};$$

$$\text{LinearSolve}[A, b]$$

Out[32]=
{-2.09264, 0.275433}

Съставяме полинома

$$\text{In[33]:= } P1[x_] := -2.093 + 0.275 x$$

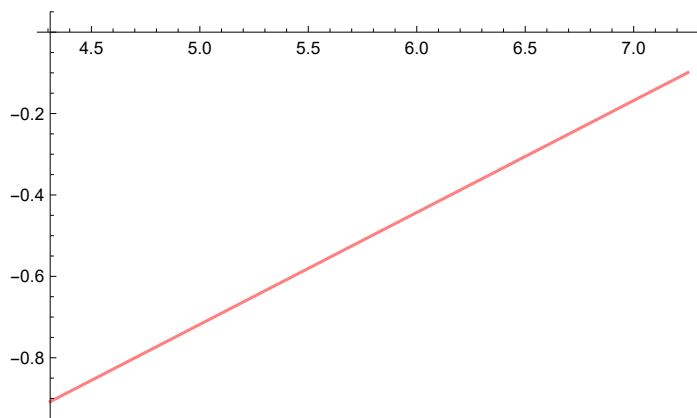
таен коз (възможност за самопроверка)

$$\text{In[40]:= } \text{Fit}[points, \{1, x\}, x]$$

Out[40]=
-2.09324 + 0.275535 x

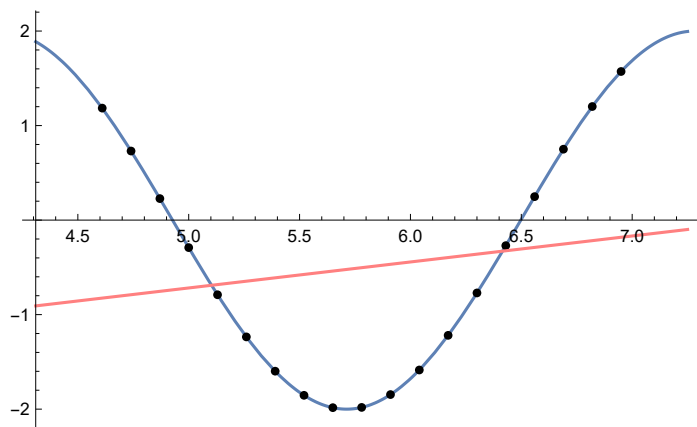
```
In[34]:= grP1 = Plot[P1[x], {x, xt[[1]] - 0.3, xt[[P]] + 0.3}, PlotStyle -> Pink]
```

```
Out[34]=
```



```
In[35]:= Show[grf, grp, grP1]
```

```
Out[35]=
```



Намиране на приближена стойност (апроксимация)

```
In[36]:= P1[4]
```

```
Out[36]=
```

-0.993

за сравнение истинската стойност

```
In[37]:= f[4.]
```

```
Out[37]=
```

1.92034

Оценка на грешката

Теоретична грешка (средноквадратична)

$$\text{In[38]:= } \sqrt{\sum_{i=1}^P (yt[[i]] - P1[xt[[i]]])^2}$$

```
Out[38]=
```

5.02027

Истинска грешка

```
In[39]:= Abs[f[4.] - P1[4]]
Out[39]=
2.91334
```

Квадратична регресия

Попълваме таблицата

```
In[*]:= xt^2
Out[*]=
{21.2521, 22.4676, 23.7169, 25., 26.3169, 27.6676, 29.0521, 30.4704, 31.9225, 33.4084,
34.9281, 36.4816, 38.0689, 39.69, 41.3449, 43.0336, 44.7561, 46.5124, 48.3025}
```

```
In[*]:= yt * xt
Out[*]=
{5.46153, 3.46328, 1.10778, -1.455, -4.05223, -6.49989,
-8.61573, -10.2328, -11.2121, -11.4545, -10.9088, -9.57838,
-7.52264, -4.85526, -1.73815, 1.62826, 5.01786, 8.19409, 10.9264}
```

```
In[41]:= xt^3
Out[41]=
{97.9722, 106.496, 115.501, 125., 135.006, 145.532, 156.591, 168.197, 180.362, 193.101,
206.425, 220.349, 234.885, 250.047, 265.848, 282.3, 299.418, 317.215, 335.702}
```

```
In[42]:= xt^4
Out[42]=
{451.652, 504.793, 562.491, 625., 692.579, 765.496, 844.025, 928.445, 1019.05, 1116.12,
1219.97, 1330.91, 1449.24, 1575.3, 1709.4, 1851.89, 2003.11, 2163.4, 2333.13}
```

```
In[43]:= yt * xt^2
Out[43]=
{25.1777, 16.4159, 5.39488, -7.275, -20.788, -34.1894,
-46.4388, -56.4849, -63.3486, -66.2069, -64.4711, -57.8534,
-46.4147, -30.5881, -11.1763, 10.6814, 33.5695, 55.8837, 75.9383}
```

Намиране на сумите

```
In[*]:= Sum[xt[[i]], {i, 1, P}]
Out[*]=
109.82
```

```
In[*]:= Sum[yt[[i]], {i, 1, P}]
Out[*]=
-9.51221
```

$$\text{In}[*]:= \sum_{i=1}^P x_t[i]^2$$

Out[*]=
644.393

$$\text{In}[*]:= \sum_{i=1}^P y_t[i] * x_t[i]$$

Out[*]=
-52.3263

$$\text{In}[44]:= \sum_{i=1}^P x_t[i]^3$$

Out[44]=
3835.95

$$\text{In}[45]:= \sum_{i=1}^P x_t[i]^4$$

Out[45]=
23146.

$$\text{In}[46]:= \sum_{i=1}^P y_t[i] * x_t[i]^2$$

Out[46]=
-282.174

Решаваме системата

$$\text{In}[47]:= \mathbf{A} = \begin{pmatrix} 19 & 109.82 & 644.393 \\ 109.82 & 644.393 & 3835.95 \\ 644.393 & 3835.95 & 23146 \end{pmatrix}; \mathbf{b} = \{-9.512, -52.326, -282.174\};$$

LinearSolve[A, b]

Out[48]=
{80.6781, -28.8073, 2.51589}

записваме в общ вид

$$\text{In}[61]:= \mathbf{A} = \begin{pmatrix} P & \sum_{i=1}^P x_t[i] & \sum_{i=1}^P x_t[i]^2 \\ \sum_{i=1}^P x_t[i] & \sum_{i=1}^P x_t[i]^2 & \sum_{i=1}^P x_t[i]^3 \\ \sum_{i=1}^P x_t[i]^2 & \sum_{i=1}^P x_t[i]^3 & \sum_{i=1}^P x_t[i]^4 \end{pmatrix};$$

$$\mathbf{b} = \left\{ \sum_{i=1}^P y_t[i], \sum_{i=1}^P y_t[i] * x_t[i], \sum_{i=1}^P y_t[i] * x_t[i]^2 \right\};$$

$$\mathbf{a} = \text{LinearSolve}[\mathbf{A}, \mathbf{b}]$$

Out[62]=
{80.7295, -28.8245, 2.5173}

Съставяме полинома

$$\text{In}[50]:= \text{P2}[x_]:= 80.678 + -28.807 x + 2.516 x^2$$

```
In[65]:= P2[x_] := a[[1]] + a[[2]] x + a[[3]] x^2
P2[x]
```

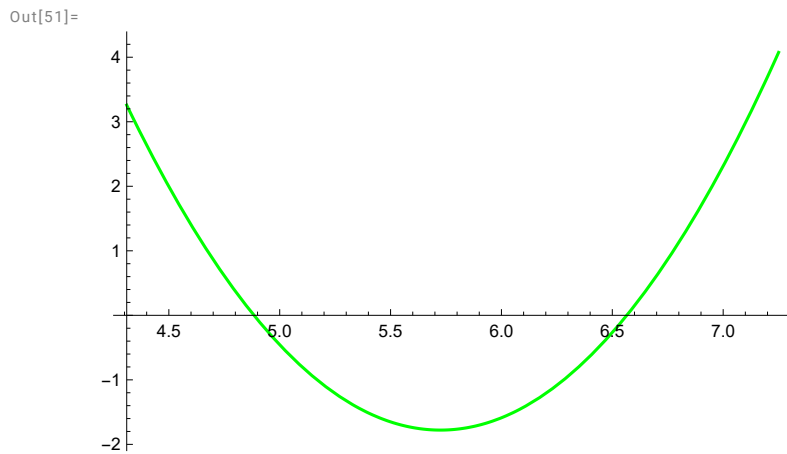
```
Out[66]= 80.7295 - 28.8245 x + 2.5173 x^2
```

таен код (възможност за самопроверка)

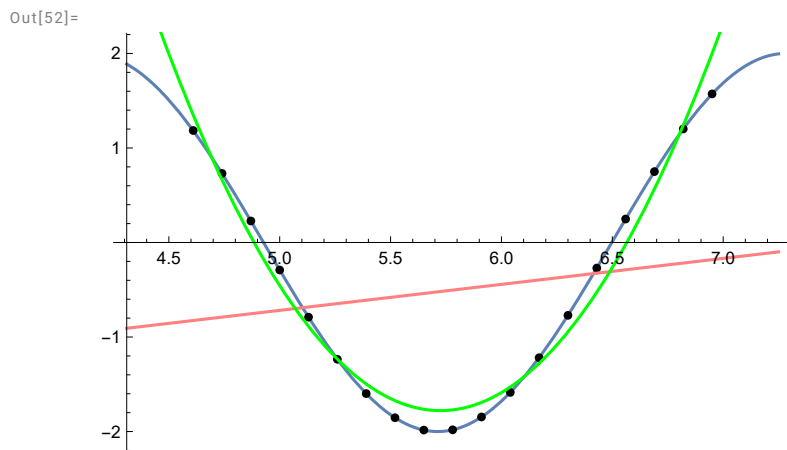
```
In[49]:= Fit[points, {1, x, x^2}, x]
```

```
Out[49]= 80.7295 - 28.8245 x + 2.5173 x^2
```

```
In[51]:= grP2 = Plot[P2[x], {x, xt[[1]] - 0.3, xt[[P]] + 0.3}, PlotStyle -> Green]
```



```
In[52]:= Show[grf, grp, grP1, grP2]
```



Намиране на приближена стойност (апроксимация)

стойност извън разглеждания интервал

```
In[53]:= P2[4]
```

```
Out[53]= 5.706
```

за сравнение истинската стойност

```
In[54]:= f[4.]
Out[54]= 1.92034
```

стойност вътре в разглеждания интервал

```
In[55]:= P2[5.3]
Out[55]= -1.32466
```

за сравнение истинската стойност

```
In[56]:= f[5.3]
Out[56]= -1.35744
```

Оценка на грешката

Теоретична грешка (средноквадратична)

```
In[57]:= 
$$\sqrt{\sum_{i=1}^p (yt[[i]] - P2[xt[[i]])^2}$$

Out[57]= 0.806867
```

Истинска грешка

```
In[59]:= Abs[f[4.] - P2[4]]
Out[59]= 3.78566
```

```
In[60]:= Abs[f[5.3] - P2[5.3]]
Out[60]= 0.0327801
```

Кубична регресия

Попълваме таблицата

```
In[*]:= xt^2
Out[*]= {21.2521, 22.4676, 23.7169, 25., 26.3169, 27.6676, 29.0521, 30.4704, 31.9225, 33.4084,
34.9281, 36.4816, 38.0689, 39.69, 41.3449, 43.0336, 44.7561, 46.5124, 48.3025}
```



```
In[ ]:= yt * xt
```

```
Out[ ]:=
{5.46153, 3.46328, 1.10778, -1.455, -4.05223, -6.49989,
-8.61573, -10.2328, -11.2121, -11.4545, -10.9088, -9.57838,
-7.52264, -4.85526, -1.73815, 1.62826, 5.01786, 8.19409, 10.9264}
```

```
In[ ]:= xt3
```

```
Out[ ]:=
{97.9722, 106.496, 115.501, 125., 135.006, 145.532, 156.591, 168.197, 180.362, 193.101,
206.425, 220.349, 234.885, 250.047, 265.848, 282.3, 299.418, 317.215, 335.702}
```

```
In[ ]:= xt4
```

```
Out[ ]:=
{451.652, 504.793, 562.491, 625., 692.579, 765.496, 844.025, 928.445, 1019.05, 1116.12,
1219.97, 1330.91, 1449.24, 1575.3, 1709.4, 1851.89, 2003.11, 2163.4, 2333.13}
```

```
In[ ]:= yt * xt2
```

```
Out[ ]:=
{25.1777, 16.4159, 5.39488, -7.275, -20.788, -34.1894,
-46.4388, -56.4849, -63.3486, -66.2069, -64.4711, -57.8534,
-46.4147, -30.5881, -11.1763, 10.6814, 33.5695, 55.8837, 75.9383}
```

допълваме необходимото

Намиране на сумите

```
In[ ]:=  $\sum_{i=1}^p xt[i]$ 
```

```
Out[ ]:=
109.82
```

```
In[ ]:=  $\sum_{i=1}^p yt[i]$ 
```

```
Out[ ]:=
-9.51221
```

```
In[ ]:=  $\sum_{i=1}^p xt[i]^2$ 
```

```
Out[ ]:=
644.393
```

```
In[ ]:=  $\sum_{i=1}^p yt[i] * xt[i]$ 
```

```
Out[ ]:=
-52.3263
```

```
In[ ]:=  $\sum_{i=1}^p xt[i]^3$ 
```

```
Out[ ]:=
3835.95
```

$$\text{In}[6]:= \sum_{i=1}^P x_t[i]^4$$

Out[6]=
23 146.

$$\text{In}[7]:= \sum_{i=1}^P y_t[i] * x_t[i]^2$$

Out[7]=
- 282.174

допълваме необходимото

Решаваме системата

записваме в общ вид

$$\text{In}[67]:= \mathbf{A} = \begin{pmatrix} P & \sum_{i=1}^P x_t[i] & \sum_{i=1}^P x_t[i]^2 & \sum_{i=1}^P x_t[i]^3 \\ \sum_{i=1}^P x_t[i] & \sum_{i=1}^P x_t[i]^2 & \sum_{i=1}^P x_t[i]^3 & \sum_{i=1}^P x_t[i]^4 \\ \sum_{i=1}^P x_t[i]^2 & \sum_{i=1}^P x_t[i]^3 & \sum_{i=1}^P x_t[i]^4 & \sum_{i=1}^P x_t[i]^5 \\ \sum_{i=1}^P x_t[i]^3 & \sum_{i=1}^P x_t[i]^4 & \sum_{i=1}^P x_t[i]^5 & \sum_{i=1}^P x_t[i]^6 \end{pmatrix};$$

$$\mathbf{b} = \left\{ \sum_{i=1}^P y_t[i], \sum_{i=1}^P y_t[i] * x_t[i], \sum_{i=1}^P y_t[i] * x_t[i]^2, \sum_{i=1}^P y_t[i] * x_t[i]^3 \right\};$$

$$\mathbf{a} = \text{LinearSolve}[\mathbf{A}, \mathbf{b}]$$

 **LinearSolve:** Result for LinearSolve of badly conditioned matrix

{{19., 109.82, 644.393, 3835.95}, {109.82, 644.393, 3835.95, 23146.}, {<<1>>}, {3835.95, 23146., 141427., 874141.}} may contain significant numerical errors.

Out[68]=
{128.634, - 54.1524, 6.93941, - 0.255023}

Съставяме полинома

$$\text{In}[70]:= \text{P3}[x_] := a[1] + a[2] x + a[3] x^2 + a[4] x^3$$

$$\text{P3}[x]$$

Out[71]=
128.634 - 54.1524 x + 6.93941 x² - 0.255023 x³

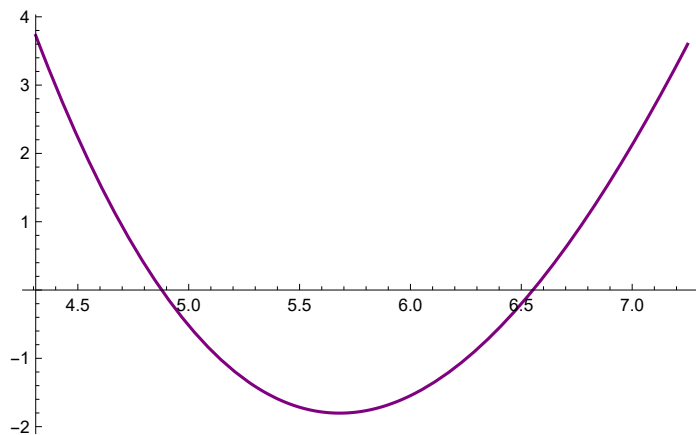
таен коз (възможност за самопроверка)

$$\text{In}[69]:= \text{Fit}[\text{points}, \{1, x, x^2, x^3\}, x]$$

Out[69]=
128.634 - 54.1524 x + 6.93941 x² - 0.255023 x³

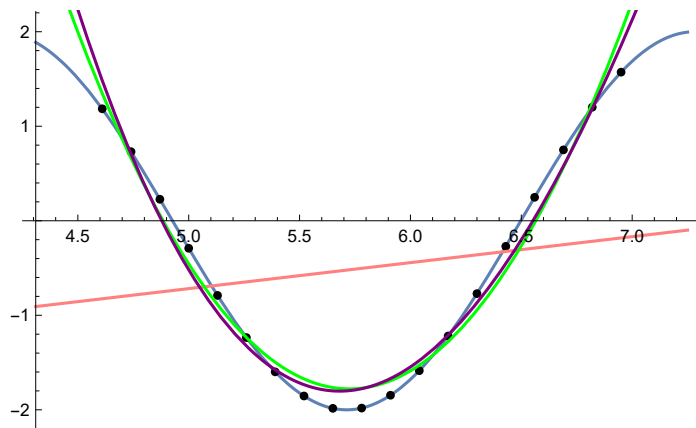
```
In[72]:= grP3 = Plot[P3[x], {x, xt[[1]] - 0.3, xt[[P]] + 0.3}, PlotStyle -> Purple]
```

```
Out[72]=
```



```
In[73]:= Show[grf, grp, grP1, grP2, grP3]
```

```
Out[73]=
```



Намиране на приближена стойност (апроксимация)

стойност извън разглеждания интервал

```
In[74]:= P3[4]
```

```
Out[74]=
```

6.73399

за сравнение истинската стойност

```
In[*]:= f[4.]
```

```
Out[*]=
```

1.92034

стойност вътре в разглеждания интервал

```
In[75]:= P3[5.3]
```

```
Out[75]=
```

-1.41228

за сравнение истинската стойност

```
In[*]:= f[5.3]
Out[*]=
-1.35744
```

Оценка на грешката

Теоретична грешка (средноквадратична)

```
In[76]:= 
$$\sqrt{\sum_{i=1}^P (yt[i] - P3[xt[i]])^2}$$

Out[76]=
0.744355
```

Истинска грешка

```
In[77]:= Abs[f[4.] - P3[4]]
Out[77]=
4.81364

In[78]:= Abs[f[5.3] - P3[5.3]]
Out[78]=
0.0548399
```