

# Ryan Tse

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## EDUCATION

### UNIVERSITY OF MARYLAND

#### FRESHMAN ELECTRICAL ENGINEERING MAJOR

2019-Present | College Park, MD

- Partial Differential Equations

### MONTGOMERY BLAIR HIGH SCHOOL

#### STEM MAGNET STUDENT

2015-2019 | Silver Spring, MD

- Intro to Complex Analysis
- Multivariable Calculus
- Differential Equations
- Linear Algebra
- Mathematical Physics
- Intro to Quantum Physics
- Analysis of Algorithms
- Intro to Computational Methods

## SKILLS

### EXPERIENCED

Python • C • Java • Git • Linux  
GNURadio • Autodesk Inventor

### FAMILIAR

C++ • Matlab • R • Tensorflow • Keras  
OpenAI Gym • OpenCV •  $\LaTeX$

### NOVICE

Slurm • ROS • JavaScript • Groovy  
AWS • GCP • AutoCAD

## LEADERSHIP

*blair3sat* President

- 19 person, 4 subteam group

*blair3sat* RF Instrument Lead

- 4 person subteam

FRC Team 449 Software and Controls  
Subteam Lead

- 5 person subteam

Troop 1449 Senior Patrol Leader

- 35 person, 4 patrol troop

## LINKS

GitHub:// [github.com/rytse](https://github.com/rytse)  
LinkedIn:// [linkedin.com/in/rytse0](https://www.linkedin.com/in/rytse0)  
Devpost:// [devpost.com/rytse](https://devpost.com/rytse)

## PERSONAL SUMMARY

Freshman electrical engineering major at the University of Maryland. Founder and former president and RF instrument engineer of an innovative high school CubeSat team. Currently pursuing advanced undergraduate research opportunities in the fields of digital signal processing, control, and machine learning. Eagle Scout for life.

## WORK EXPERIENCE

### Intelligent Automation Incorporated

Summer 2019 | Sensors, Signals and Systems Division | Intern

Assisted in the hardware implementation of a bursty space-time continuous phase modulation receiver by analyzing quantization error. Assisted in developing indoor positioning system technology by modifying tracking filters to include IMU data.

### NAVAL CENTER FOR SPACE TECHNOLOGY

Summer 2018 | Naval Research Laboratory | Intern

Developed an efficient bursty satellite ranging protocol in GNURadio. Applied control loops to correct for channel impairments and implemented packet protocols.

### LABORATORY FOR AUTONOMOUS SYSTEMS RESEARCH

Summer 2017 | Naval Research Laboratory | Intern

Researched deep learning-based approaches to vehicle trilateration, working with regression models and reinforcement learning agents. Author of Publication [1].

## EXTRACURRICULARS

### BLAIR3SAT

2017 – Present | President, Founder, and RF Payload Engineer

Developing a CubeSat to measure 3D ionospheric charge density profiles by receiving ground-based ionospheric sounders from space. Performing DSP for the instrument and leading the team in spacecraft engineering and fund seeking in an executive capacity. Secured \$6,000 of funding and two corporate partnerships in 6 months. Author of Publication [2].

### FIRST ROBOTICS CHALLENGE

2015 - 2017 | FRC Team 449 | Software and Controls Lead

Developed drivetrain control and automation software, lead the 2017 software team.

### SCOUTING

2012 - 2018 | Boy Scout Troop 1449

Eagle Scout, served as Senior Patrol Leader, Troop Quartermaster, and Patrol Leader.

## COMPETITIONS

- Bitcamp 2019, built *Open Weapon Site Finder*, won *Best Digital Forensics Hack*, runner up for *Best Machine Learning Hack*
- Kaggle's Google Cloud & NCAA 2019 ML Competition, placed 37th out of 866

## PUBLICATIONS

- [1] D. Lofaro, C. Taylor, R. Tse, and D. Sofge, "Wearable Interactive Display for the Local Positioning System (LPS)," In 19th ACM International Conference on Multimodal Interaction (ICMI 2017) Demonstration Session, ACM, 2017.
- [2] R. Tse, L. Cui, P. Kim, S. Swain, B. Cohen, and G. Das. "Space-based Ionosonde Receiver and Visible Limb-viewing Airglow Sensor (SIRVLAS): A CubeSat Instrument Suite for Enhanced Ionospheric Charge Density Measurements," Proceedings of the AIAA/USU Conference on Small Satellites, SSC19-WP2-14.