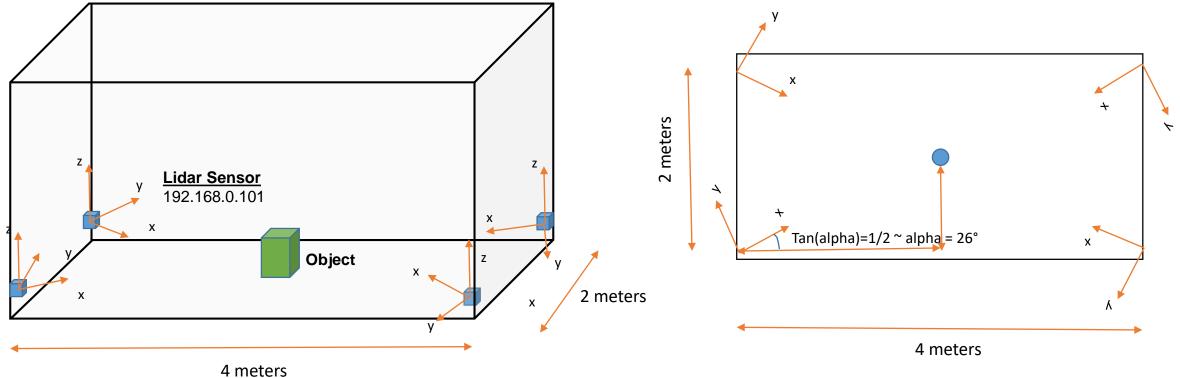
Overview of test bench for LIDAR Sensors



<u>Idea:</u> Improve the convergence to global optimum of the algorithm by translating and rotating points clouds before applying the algorithm

