# Section 3 Bayes basics

#### **Outline**

#### These slides cover Chapters 1.3-1.5

- Understand Bayesian learning, i.e., updating the prior using data
- Graphically summarize a univariate posterior distribution
- Summarize a multivariate posterior distribution
- Use Monte Carlo sampling to approximate posteriors
- Compute the posterior predictive distribution

- Say you have a scratchy throat and so you go to the doctor to be tested from strep throat
- ▶ Denote your true disease status as  $\theta = 1$  if you have strep throat and  $\theta = 0$  otherwise
- An unknown quantity such as  $\theta$  that we hope to estimate is called a **parameter**
- ▶ Unless the doctor's test is perfect, we will never know  $\theta$  exactly

- Let the **data** Y be the result of the rapid strep test with Y = 1 if you test positive and Y = 0 otherwise
- The distribution of the data given the parameters is called the likelihood
- In this example the likelihood is defined by the false positive rate

$$Prob(Y = 1 | \theta = 0) = p$$

and the false negative rate

$$Prob(Y = 0|\theta = 1) = q$$

► For now, we assume that we know *p* and *q* based on previous analyses

- Say you test positive and Y = 1, how likely is it that you have strep?
- ▶ To formalize this problem statistically, we must first decide whether Y,  $\theta$  or both are random variables
- Should we treat Y as random?

▶ Should we treat  $\theta$  as random?

O is fixed but we are unrentain about 8 so we treat it as a random variable

#### Bayesian learning

- Bayesians quantify uncertainty about fixed but unknown parameters by treating them as random variables
- ▶ This requires that we set a **prior distribution**  $\pi(\theta)$  to summarize uncertainty before observing the data
- ► The distribution of the observed data given the model parameters is the **likelihood function**,  $f(Y|\theta)$
- ► The likelihood function is the most important piece of a Bayesian analysis because it links the data and parameters

#### Bayesian learning

- ▶ The **posterior distribution**  $p(\theta|Y)$  summarizes uncertainty about the parameters given the prior and data
- The reduction in uncertainty from prior to posterior represents Bayesian learning
- Bayes' Theorem (Bayes' Rule) converts the likelihood and prior to the posterior
- Bayes' Theorem:

$$p(\theta|Y) = \frac{f(Y|\theta)\pi(\theta)}{m(Y)}$$

where  $m(Y) = \int f(Y|\theta)\pi(\theta)d\theta$  is the marginal distribution of the data and can usually be ignored

#### How to select the prior?

- There is no "true" or "correct" prior
- In some cases expert opinion or similar studies can be used to specify an informative prior
- It would be a waste to discard this information
- If prior information is unavailable, then the prior should be uninformative
- The prior is best viewed as an initial value to a statistical procedure

#### How to select the prior?

- As we'll see, as Bayesian learning continues and more and more data are collected, the posterior concentrates around the true value for any reasonable prior
- However, in finite sample the prior can have some effect
- We will study several systematic ways to select priors
- However, there is inherent subjectivity to selecting the prior
- That is, different analysts may pick different priors and thus have different results

#### How to select the likelihood?

▶ The likelihood is the same as in a freqentist analysis

For example, in a linear regression analysis we might say

$$Y_i|oldsymbol{eta}, \sigma^2 \sim \mathsf{Normal}\left(\sum_{j=1}^p X_{ij}eta_j, \sigma^2\right)$$

Is there "true" or "correct" likelihood?

Is specification of the likelihood subjective like the prior?

#### How to select the likelihood?

Subjective decisions required to specify the likelihood: 6 transformers prior (expect opinion?) To which hypothesis 1 constanctions What is the Measure (8) how to sample ? (9 n threshold 1) Micinslita

## My opinions about subjectivity

- Perhaps we should aspire to objectivity, but in most real-life analyses we are forced to accept some subjectivity
- A notable exception is a tightly controlled experiment, although even this is debatable
- However, not all subjective decisions (assumptions) are equal
- If readers disagree with your assumptions they will reject your findings
- It is your job to justify your assumptions theoretically and empirically
- Determining the sensitivity to key assumptions is an important step

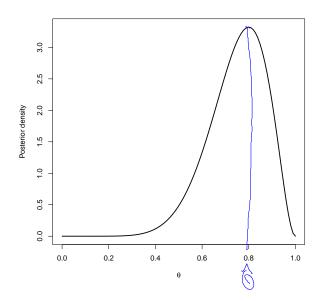
- After selecting the likelihood and prior, all that remains is to summarize the posterior
- ▶ Say there is a single parameter,  $\theta$
- For example, we say the model is

Likelihood:  $Y|\theta \sim \text{Binomial}(N, \theta)$ Prior:  $\theta \sim \text{Uniform}(0, 1)$ 

We saw that the posterior is then

$$\theta | Y \sim \text{Beta}(Y + a, N - Y + b)$$

The posterior is a distribution that can be plotted as on the next slide



In this beta/binomial example Y = 8, N = 10 and a = b = 1

- A plot of the posterior tells the whole story
- However, to be more concise we typically use a few numerical summaries of the distribution

- This is particularly important when there are many parameters
- The posterior can be summarized like any other distribution, by say the mean, variance, skewness, etc.

- A point estimator is a one number summary used to estimate the unknown parameter
- For example, we might use the posterior mean (or median) as the "best guess" of  $\theta$
- The posterior mean is

$$\hat{\theta} = \mathsf{E}(\theta|Y) = \int \theta p(\theta|Y) d\theta$$

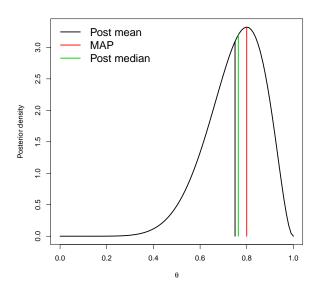
- ► For the Beta/Binomial example  $\hat{\theta} = \frac{Y+a}{n+a+b}$
- ▶ This is an alternative to the sample proportion  $\hat{\theta} = Y/n$
- Estimators usually wear hats

- ► The posterior mode is the call the maximum a posteriori
- (MAP) estimator  $\rho(\mathcal{A}|\mathcal{Y}) = \rho(\mathcal{A}|\mathcal{Y}) \rho(\mathcal{A}) \rho(\mathcal{A})$ The MAP estimator is  $\rho(\mathcal{A}|\mathcal{Y}) = \rho(\mathcal{A}|\mathcal{A}) \rho(\mathcal{A}) \rho(\mathcal{A}) \rho(\mathcal{A})$   $-\log \rho(\mathcal{A})$  $\hat{\theta} = \underset{\theta}{\operatorname{arg max}} p(\theta|Y) = \underset{\theta}{\operatorname{arg max}} \log[f(Y|\theta)] + \log[\pi(\theta)]$
- If the prior is uniform (i.e., flat) the MAP is the MLE

The MAP is easier to compute than the posterior mean

$$f(x) - \frac{\lambda}{\phi} - \frac{\lambda - \lambda}{1 - \alpha} = 0$$

$$\phi = \frac{\lambda}{\lambda}$$



In this beta/binomial example Y = 8, N = 10 and a = b = 1

Sometimes a point estimate is sufficient, but more often we need to quantify uncertainty

The posterior standard deviation is one measure of uncertainty

Give the observed data.

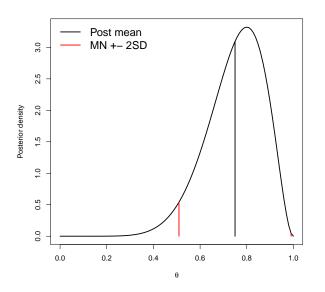
▶ If the posterior is approximately normal, then the mean plus/minus two standard deviation units captures 95% of the posterior probability

► The posterior mean is analogous to but fundamentally different than the frequentist **standard error** 

The standard error is the standard deviation of  $\hat{\theta}$ 's sampling distribution

Your repeated experiments

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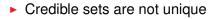


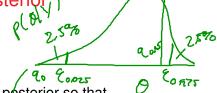
In this beta/binomial example Y = 8, N = 10 and a = b = 1

- In addition to standard error, uncertainty can be quantified using a credible interval
- ► The interval (I, u) is a  $100(1 \alpha)\%$  posterior credible interval if

$$Prob(I < \theta < u|Y) = 1 - \alpha$$

- Interpretation of a 95% credible interval: "given the data and prior, I am 95% certain that θ is between I and u"
- This is analogous but different than a confidence interval

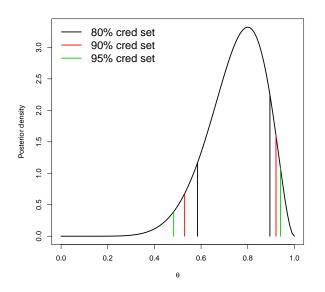




Let  $q_{\tau}$  be the  $\tau$  quantile of the posterior so that

$$\mathsf{Prob}(\theta < q / | Y) = \tau$$

- $\mathsf{Prob}(\theta < q / | Y) = \tau$  Then  $(q_{0.00}, q_{0.95}), (q_{0.01}, q_{0.96}),$  etc. are all valid 95% credible sets
- ► The **equal-tailed** interval is  $(q_{\alpha/2}, q_{1-\alpha/2})$
- The highest posterior density interval searches for the smallest interval that contains the proper probability



In this beta/binomial example Y = 8, N = 10 and a = b = 1

- Hypothesis tests are conducted by simply computing the posterior probability of each hypothesis
- Say the null hypothesis is  $\mathcal{H}_0: \theta \leq 0.5$  and the alternative is  $\mathcal{H}_1: \theta > 0.5$
- The posterior probability of the null hypothesis is

$$\mathsf{Prob}(\theta < 0.5|Y) = \int_0^{0.5} p(\theta|Y)d\theta$$

- We reject the null if its probability is small
- In a Bayesian analysis we can say "Given the data and prior the probability that the null hypothesis is true is 0.02"
- This is analogous to but different than the p-value

```
> # Data
> Y < -8; n < -10
> # The posterior is theta|Y~Beta(A,B)
> A <- Y+1; B <- n-Y+1
> # Posterior mean
> A/(A+B)
[1] 0.75
> # Posterior standard deviation
>  sqrt (A*B/((A+B)*(A+B)*(A+B+1)))
[1] 0.1200961
> # Posterior 95% credible interval
> gbeta(c(0.025,0.975),A,B)
[1] 0.4822441 0.9397823
> # Posterior probability that theta<0.5
> pbeta(0.5,A,B)
[1] 0.03271484
```

- Monte Carlo (MC) sampling is a useful tool for summarizing a posterior
- ► For univariate cases is it not particularly useful, but in harder problems is the best approach available
- ▶ In MC sampling we draw S samples from the posterior,

$$\theta^{(1)},...,\theta^{(S)} \sim p(\theta|Y)$$

and use these samples to approximate the posterior

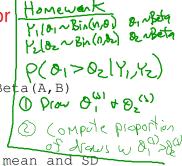
For example, the posterior mean and variance are approximated by the sample mean and variance of the  $\theta^{(s)}$ 

- MC sampling facilitates studying transformations of parameters
- ▶ For example, the odds corresponding to  $\theta$  are  $\gamma = \theta/(1-\theta)$
- ▶ How to approximate the posterior mean and variance of  $\gamma$ ?
- We simply transform each draw to the odds

$$\gamma^{(1)} = \frac{\theta^{(1)}}{1 - \theta^{(1)}}, ..., \gamma^{(S)} = \frac{\theta^{(S)}}{1 - \theta^{(S)}}$$

and use these draws to approximate  $\gamma$ 's posterior

- > # Data
- > Y <- 8; n <- 10
- > # The posterior is theta|Y~Beta(A,
- > A <- Y+1; B <- n-Y+1
- > # MC sampling
- > theta <- rbeta(100000,A,B)</pre>
- > # Approximate the posterior
- > mean(theta);sd(theta)
- [1] 0.749792
- [1] 0.1201799
- > # Transform to odds
- > gamma <- theta/(1-theta)</pre>
- > # Approximate the posterior mean and, SI
- > mean(gamma);sd(gamma)
- [1] 4.483378
- [1] 4.720541





#### Summarizing multivariate posteriors

- A univariate posterior is captured by simple plot
- When there are many parameters this is impossible
- ▶ Say  $\theta = (\theta_1, ..., \theta_p)$
- Ideally we reduce to the univariate marginal posteriors

$$p(\theta_1|Y) = \int ... \int p(\theta_1, ..., \theta_p|Y) d\theta_2, ..., d\theta_p$$

- ► The same ideas we used for univariate models then apply
- ► However, computing these integrals is often challenging

## Bayesian one-sample t-test

- In this section we will study the one-sample t-test in depth
- ▶ Likelihood:  $Y_i | \mu, \sigma \sim N(\mu, \sigma^2)$  independent over i = 1, ..., n
- ▶ Priors:  $\mu \sim N(\mu_0, \sigma_0^2)$  independent of  $\sigma^2 \sim InvGamma(a, b)$

The joint (bivariate PDF) of 
$$(\mu, \sigma^2)$$
 is proportional to 
$$\left[ \frac{\sum_{i=1}^{n} (Y_i - \mu)^2}{2\sigma^2} \right] \exp \left[ -\frac{(\mu - \mu_0)^2}{2\sigma_0^2} \right] (\sigma^2)^{a-1} \exp(-\frac{b}{\sigma^2})$$

How to summarize this complicated function?

#### Plotting the posterior on a grid

- For models with only a few parameters we could simply plot the posterior on a grid
- ► That is, we compute  $p(\mu, \sigma^2 | Y_1, ..., Y_n)$  for all combinations of m values of  $\mu$  and m values of  $\sigma^2$
- ► The number of grid points is m<sup>p</sup> where p is the number of parameters in the model
- The posterior is plotted on the next slide for

$$Y_1 = 2.68, Y_2 = 1.18, Y_3 = -0.97, Y_4 = -0.98, Y_5 = -1.03$$
  
and uniform priors over the plotting window

Bivariate posterior 10.0 7.5 b 5.0 2.5 0.0

> . μ

-4

-2

#### Summarizing the results in a table

Typically we are interested in the marginal posterior

$$f(\mu|\mathbf{Y}) = \int_0^\infty p(\mu, \sigma^2|\mathbf{Y}) d\sigma^2$$

where  $Y = (Y_1, ..., Y_n)$ 

- ▶ This accounts for our uncertainty about  $\sigma^2$
- We could also report the marginal posterior of  $\sigma^2$
- ► Results are usually given in a table with marginal mean, SD, and 95% interval for all parameters of interest
- The marginal posteriors can be computed using numerical integration

#### Summarizing the results in a table

Posterior mean Posterior SD 95% credible set
$$\frac{\rho(\mu \mid \gamma)}{\mu} = \int \rho(\mu \mid \gamma) d\tau$$
Posterior mean Posterior SD 95% credible set
$$\frac{\rho(1.10, 6.54)}{\mu} = \int \rho(\mu \mid \gamma) d\tau$$
Posterior mean Posterior SD 95% credible set
$$\frac{\rho(1.10, 6.54)}{\mu} = \int \rho(\mu \mid \gamma) d\tau$$
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Posterior mean Posterior SD 95% credible set
$$\frac{\rho(1.10, 6.54)}{\mu} = \int \rho(\mu \mid \gamma) d\tau$$

## Frequentist analysis of a normal mean

- ▶ In frequentist statistics the estimate of the mean is  $\bar{Y}$
- If  $\sigma$  is known the 95% interval is

$$ar{Y} \pm z_{0.975} rac{\sigma}{\sqrt{n}}$$

where z is the quantile of a normal distribution

• If  $\sigma$  is unknown the 95% interval is

 $ar{Y} \pm t_{0.975,n-1} rac{s}{\sqrt{n}}$  where t is the quantile of a t-distribution

- ▶ The Bayesian estimate of  $\mu$  is its marginal posterior mean
- ► The interval estimate is the 95% posterior interval
- If  $\sigma$  is known the posterior of  $\mu|\mathbf{Y}$  is Gaussian and the 95% interval is

$$\mathsf{E}(\mu|\mathbf{Y}) \pm z_{0.975} \mathsf{SD}(\mu|\mathbf{Y})$$

- If  $\sigma$  is unknown the marginal (over  $\sigma^2$ ) posterior of  $\mu$  is t with  $\nu = n + 2a$  degrees of freedom.
- Therefore the 95% interval is

$$\mathsf{E}(\mu|\mathbf{Y}) \pm t_{0.975,
u} \mathsf{SD}(\mu|\mathbf{Y})$$

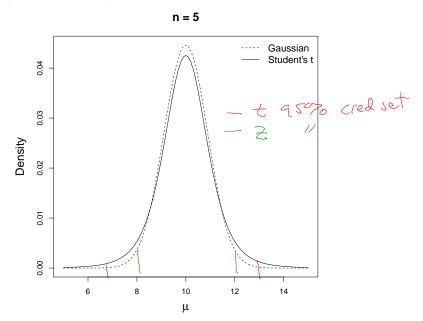
 $\blacktriangleright$  See "Marginal posterior of  $\mu$ " the online derivations

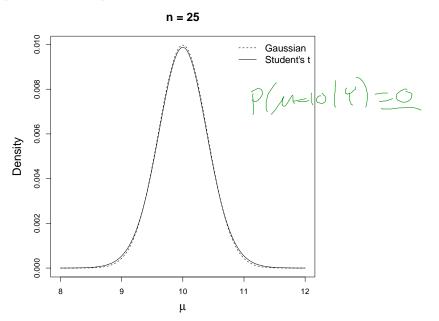
▶ The following two slides give the posterior of  $\mu$  for a data set with sample mean 10 and sample variance 4

▶ The Gaussian analysis assumes  $\sigma^2 = 4$  is known

▶ The t analysis integrates over uncertainty in  $\sigma^2$ 

As expected, the latter interval is a bit wider





#### Bayesian one sample t-test

▶ The one-sided test of  $H_1: \mu \leq 0$  versus  $H_2: \mu > 0$  is conducted by computing the posterior probability of each hypothesis

This is done with the pt function in R

point rull

- ► The two-sided test of  $H_1: \mu = 0$  versus  $H_2: \mu \neq 0$  is conducted by either
  - Determining if 0 is in the 95% posterior interval
  - Bayes factor (later)

#### Methods for dealing with multiple parameters

- ► In this case, we were able to compute the marginal posterior in closed form (a t distribution)
- We were also able to compute the posterior on a grid
- For most analyses the marginal posteriors will not be a nice distributions, and a grid is impossible if there are many parameters
- We need new tools!
- We'll spend a month on this in the computing section

- Often the objective is to predict a future event
- Example: Last spring we planted n = 10 seedlings and Y = 2 survived the winter, if we plant n again this year what is the probability at least one will survive the winter?
- Let Y\* be the predicted value and θ be the true survival probability
- If the parameters were known then we would predict

$$Y^* | heta \sim ext{Binomial}(10, heta)$$
 and thus  $ext{Prob}(Y > 0) = 1 - (1 - heta)^{10}$ 

 Of course, if we knew the parameters we would be doing probability and not statistics

- One approach for accounting for parametric uncertainty is a "plug-in" approach
- ▶ That is, if  $\hat{\theta}$  is an estimate, then  $Y^* \sim f(Y|\hat{\theta})$
- Example:  $\hat{\theta} = 2/10$  and Prob $(Y > 0) = 1 (1 0.2)^{10}$
- ▶ If  $\hat{\theta}$  has small uncertainty this is fine
- Otherwise, this underestimates uncertainty in Y\*

- For the sake of prediction, the parameters are not of interest
- They are vehicles by which the data inform about the predictive model
- ► The **Posterior Predictive Distribution** (PPD) averages over their posterior uncertainty

$$f(Y^*|Y) = \int f(Y^*|\theta)f(\theta|Y)d\theta$$

- This properly accounts for parametric uncertainty
- ▶ The input is data, the output is a prediction distribution

- Monte Carlo sampling approximates the PPD
- ▶ Say  $\theta^{(1)}, ..., \theta^{(S)}$  are samples from the posterior
- ▶ If we make a sample for  $Y^*$  for each  $\theta^{(s)}$ ,

$$Y^{*(s)} \sim f(Y|\theta^{(s)})$$

then the  $Y^{*(s)}$  are samples from the PPD

- ► The posterior predictive mean is approximated by the sample mean of the *Y*\*(*s*)
- ► The probability that  $Y^* > 0$  is approximated by the sample proportion of the  $Y^{*(s)}$  that are non-zero

```
> # Data
> Y < -2; n < -10
> # The posterior is theta|Y~Beta(A,B)
> A <- Y+1; B <- n-Y+1
>
> # Plug in estimate of P(Ystar>0)
> 1-dbinom(0,10,.2)
[1] 0.8926258
>
> # Approximate the PPD using MC sampling
> theta <- rbeta(100000,A,B)</pre>
> Ystar <- rbinom(100000,10,theta)</pre>
> mean(Ystar>0)
[1] 0.87454
```

