Department I - C Plus Plus

Modern and Lucid C++ Advanced for Professional Programmers

Week 4 - Heap Memory Management

Thomas Corbat / Felix Morgner Rapperswil, 21.03.2023 FS2023

```
mInBounds(element_index
      ndex
                    Ostschweizer
                    Fachhochschule
      cess
     size_type element_index:
     dBuffer(size_type capacill
      argument{"Must not create
      other) : capacity{std:
     other.capacity = 0; other
        copy = other; swap(copy
     dex())) T{element}; ++nu
             { return number_of
      front() const { throw i
     back_index()); } void popul
       turn number_of_elements:
    ; std::swap(number_of_ele
      () const { return const
    erator end() const
     visize type index
```

## • Topics:

- Recap Week 3
- Pointers
- Reading Declarations Correctly
- Heap Memory (De)Allocation

- You understand how raw pointers work in C++
- You can read declarations correctly
- You can use basic heap memory management when necessary

# Recap Week 3



#### ParamType is a value/pointer type

- <expr> is a reference type: ignore the reference
- Ignore const of <expr> type (outermost)
- Pattern match <expr>'s type against ParamType to figure out T

#### ParamType is a reference

- <expr> is a reference type: ignore the reference
- Pattern match <expr>'s type against ParamType to figure out T

### ParamType is a forwarding reference (T&& / auto&&)

- <expr> is an Ivalue: T and ParamType become Ivalue references!
- Otherwise (if <expr> is an rvalue): Rules for pointer/references apply

template <typename T>
auto f(ParamType param) -> void;

- We need something that is aware of the actual template parameter type
- Recap from Forwarding References: We know whether param was an Ivalue or an rvalue

```
log_and_do(x)
log_and_do(cx)
log_and_do(crx)
log_and_do(27)
log_and_do(std::move(x))
-> T = int const&
-> T = int const&
-> T = int
-> T = int
-> T = int
| rvalues
```

- If T is of reference type we need to pass an Ivalue otherwise we need to pass an rvalue
- How can we do it?
  - std::forward

```
template <typename T>
auto log_and_do(T&& param) -> void {
   //log
   do_something(std::forward<T>(param));
}
```

- What does std::forward do?
  - It's a "conditional" cast to an rvalue reference...
  - This allows arguments to be treated as what they originally were (Ivalue or rvalue references)
- Implementation is similar to the following (there is also an overload for rvalue references):

```
template<typename T>
decltype(auto) forward(std::remove_reference_t<T>& param) {
   return static_cast<T&&>(param);
}
```

- If T is of value type, T && is an rvalue reference in the return expression
- If T is of Ivalue reference type, the resulting type is an rvalue reference to an Ivalue reference
  - Example: if T = int & then T && would mean int & &&
- What is <Type> & && supposed to mean?
  - As you know from reference collapsing: <Type> &

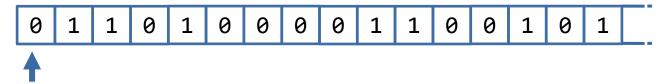
# Pointers

The pointers, memory locations and sizes in this lecture are freely invented!

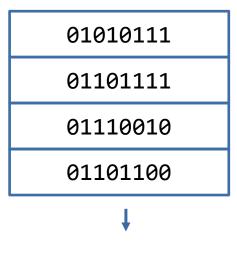


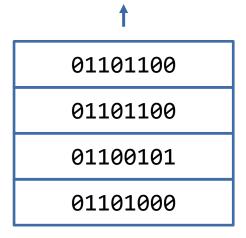
# Turing Machine (Model)

Unlimited Space



- Stack / Heap (Reality)
  - Limited Space





Deterministic

Local variables get deleted automatically upon leaving their scope

```
auto foo() -> void {
  int i{5};
   double d = 23.0;
auto main() -> int {
 foo();
```

Stack

- Deterministic
- Local variables get deleted automatically upon leaving their scope

```
auto foo() -> void {
  int i{5};
    double d = 23.0;
auto main() -> int {
  foo();
```

```
0x73fe10
    d: ???
    8 bytes¹

0x73fe1c
    i: ???
    4 bytes¹
```

Stack

<sup>&</sup>lt;sup>1</sup> Sizes depend on the platform

Deterministic

• Local variables get deleted automatically upon leaving their scope

```
auto foo() -> void {
   int i{5};
   {
      double d = 23.0;
   }
}
auto main() -> int {
   ...
   foo();
   ...
}
```

0x73fe10
 d: ???
 8 bytes¹

0x73fe1c
 i: 5
 4 bytes¹

Stack

<sup>&</sup>lt;sup>1</sup> Sizes depend on the platform

Deterministic

• Local variables get deleted automatically upon leaving their scope

```
auto foo() -> void {
  int i{5};
   double d = 23.0;
auto main() -> int {
  foo();
```

0x73fe10

d: 23.0
8 bytes¹

Stack

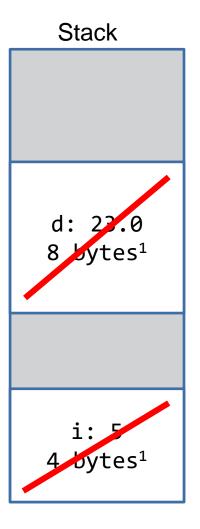
0x73fe1c

i: 5
4 bytes¹

<sup>&</sup>lt;sup>1</sup> Sizes depend on the platform

- Deterministic
- Local variables get deleted automatically upon leaving their scope

```
auto foo() -> void {
  int i{5};
   double d = 23.0;
auto main() -> int {
 foo();
```



<sup>&</sup>lt;sup>1</sup> Sizes depend on the platform

- Deterministic (too)
- Creation and deletion happens explicitly

```
auto foo() -> void {
   auto ip = new int{5};
   ...
   delete ip;
}
```

0x73fe08

ip: <unknown> 8 bytes¹

Stack

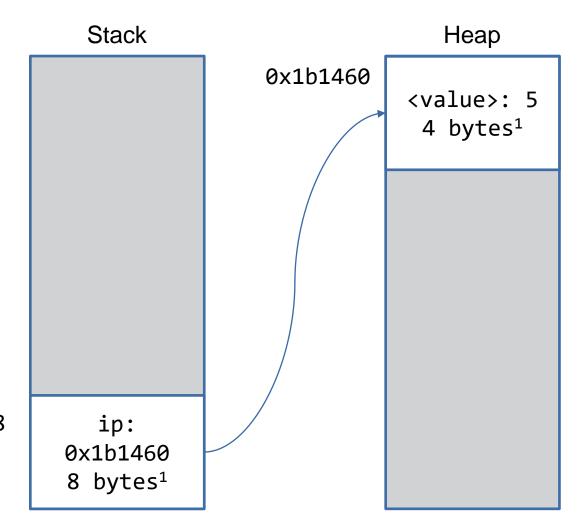
Heap

<sup>&</sup>lt;sup>1</sup> Sizes depend on the platform

- Deterministic (too)
- Creation and deletion happens explicitly

```
auto foo() -> void {
  auto ip = new int{5};
  ...
  delete ip;
}
```

```
0x73fe08
```

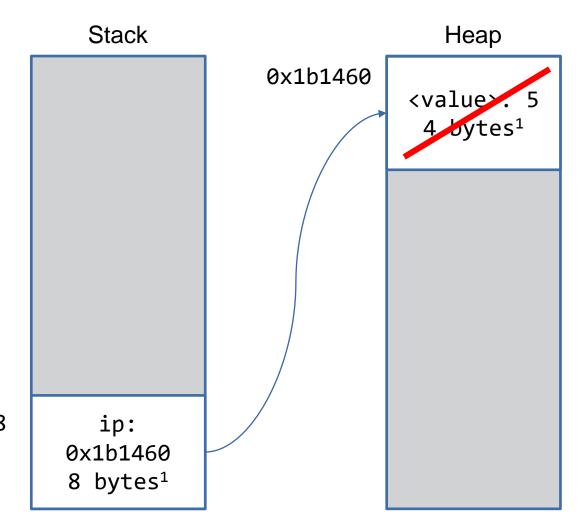


<sup>&</sup>lt;sup>1</sup> Sizes depend on the platform

- Deterministic (too)
- Creation and deletion happens explicitly

```
auto foo() -> void {
  auto ip = new int{5};
  ...
  delete ip;
}
```

0x73fe08



<sup>&</sup>lt;sup>1</sup> Sizes depend on the platform

- Deterministic (too)
- Creation and deletion happens explicitly

```
auto foo() -> void {
  auto ip = new int{5};
  ...
  delete ip;
}
```

```
0x73fe08
```



Stack

0xd11460 Heap

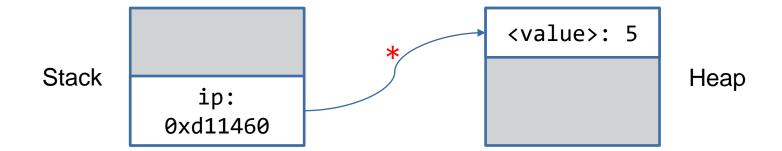
<sup>1</sup> Sizes depend on the platform

• What is the type of ip in the example?

Explicit declaration

Accessing the value at a pointer

int 
$$v = * ip; //v == 5$$



• What is the type of arr in the example?

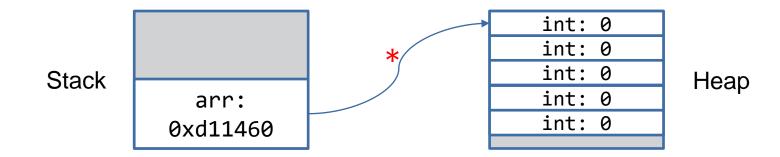
```
auto arr = new int[5]{};
```

Explicit declaration

```
int * arr = new int[5]{};
```

Accessing elements with index operator []

```
int v = arr[4];
```



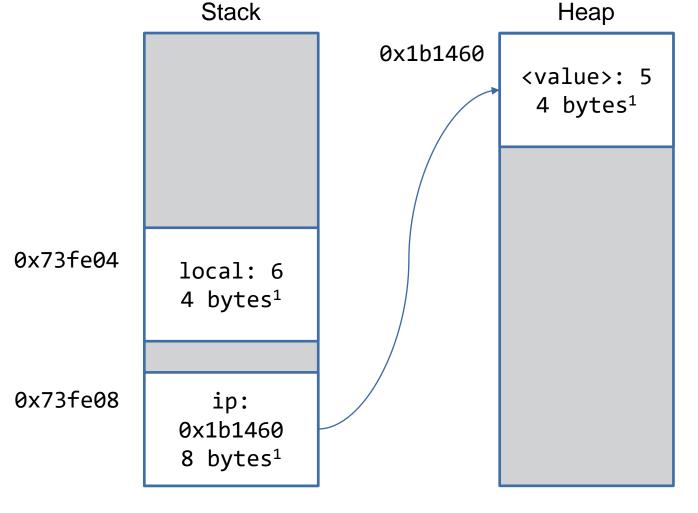
- Direct Member Access (->)
- this is a pointer

```
struct S {
  auto member() -> void {
    this->value = ...;
  int value;
auto foo() -> void {
  S* sp = new S{};
  sp->member();
  //same as
  (*sp).member();
```

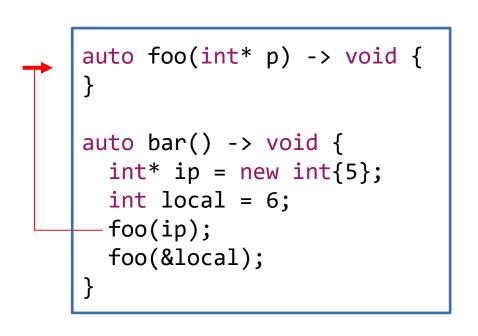
- Pointers can be used as parameters
- Addresses can be taken with (&)
  - Or std::addressof()

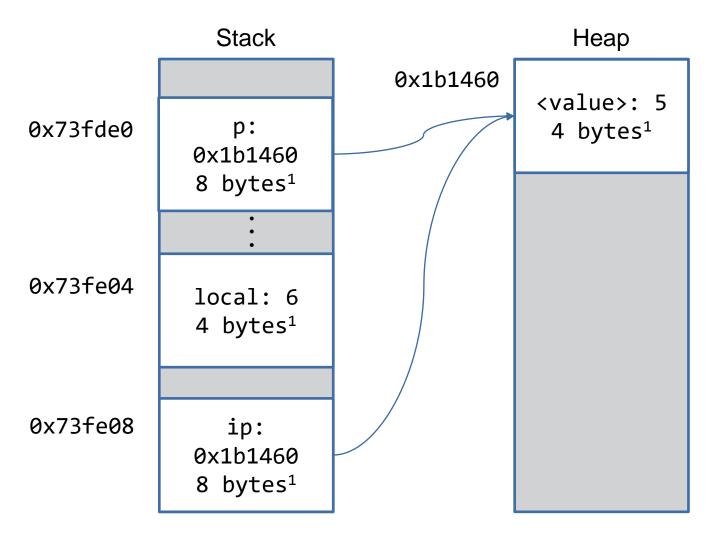
```
auto foo(int* p) -> void {
}

auto bar() -> void {
  int* ip = new int{5};
  int local = 6;
  foo(ip);
  foo(&local);
}
```

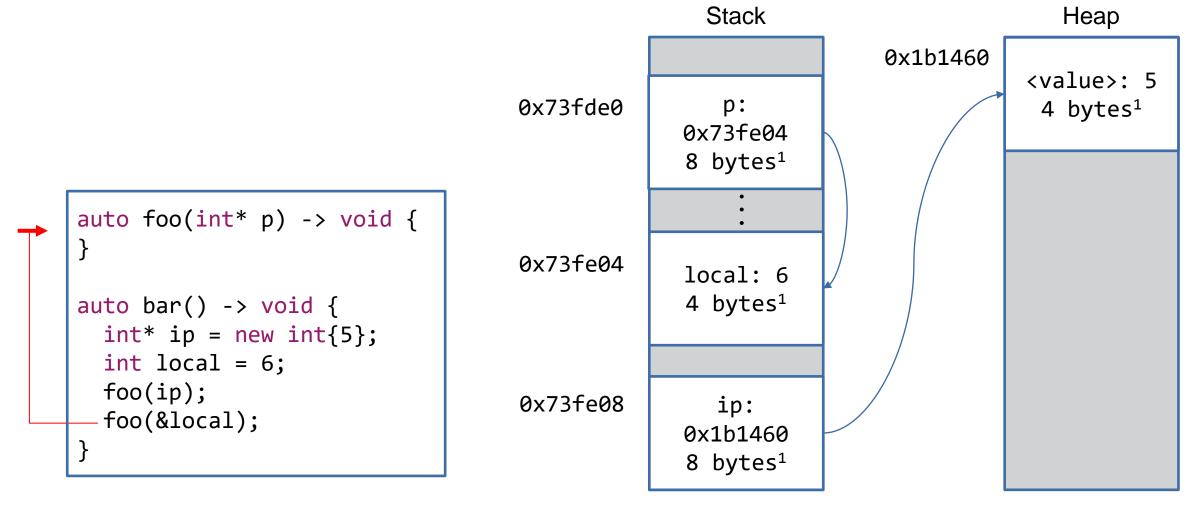


<sup>&</sup>lt;sup>1</sup> Sizes depend on the platform

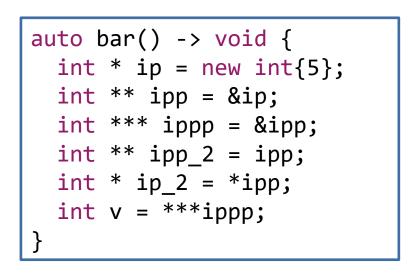


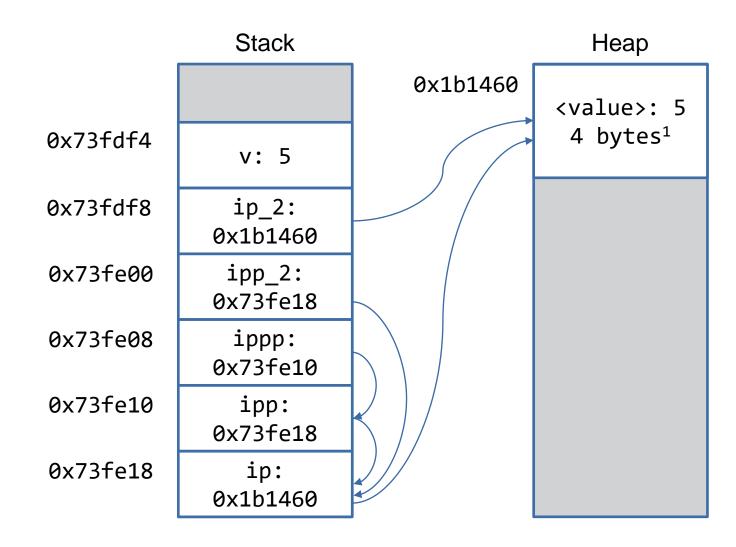


<sup>&</sup>lt;sup>1</sup> Sizes depend on the platform



<sup>&</sup>lt;sup>1</sup> Sizes depend on the platform





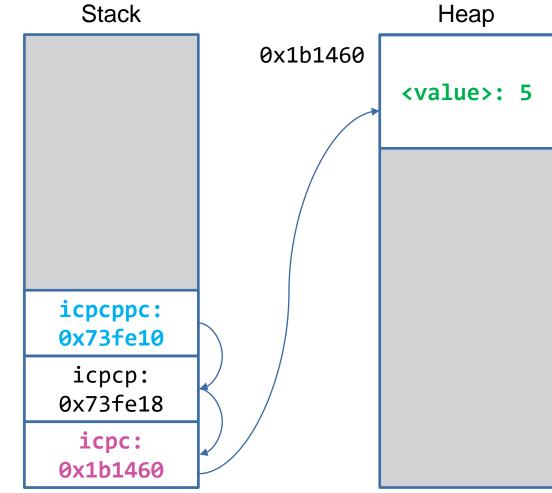
- Pointers can be const
  - const is on the RIGHT side of the \*

int const \* const \* \* const icpcppc = &icpcp;

0x73fe08

0x73fe10

0x73fe18



- Represents a null-Pointer
- Literal (prvalue)
- Type: nullptr\_t
- Implicit conversion to any pointer type: T \*
- Prefer nullptr over 0 and NULL
  - No implicit conversion to integral type
  - No ambiguity on overload with integral type (discouraged)
  - Significant for template type deduction

```
auto bar(int i) -> void;
auto bar(S* ps) -> void;

//calls
bar(0); //bar(int)
bar(NULL); //surprising
bar(nullptr); //bar(S*)
```

# Reading Declarations



### Declarations are read starting by the declarator

First read to the right until a closing parenthesis is encountered

**)** 

Second read to the left until an opening parenthesis is encountered

Third jump out of the parentheses and start over



int const	* const	*	* const	icpcppc;
(5)	(4)	(3)	(2)	(1)

## icpcppc is the declarator (name)

- there is nothing to the right
- to the left: const pointer to a pointer to a const pointer to a const int

## Reading the example

- icpcppc is a const pointer to a pointer to a const pointer to a const int
  - (1)

(2)

(3)

(4)

(5)

- Modifiers right to the declarator
  - Array Declarator: []
  - **Function Parameter List: (<parameter declarations>)**
- Modifiers left to the declarator
  - References: &&, &
  - Pointers: \*
  - Type: e.g. int

```
void (* f)(int &, double)
  (4)   (2)(1)   (3)
```

```
(1) f is)
```

- (a pointer to
- a function, taking a reference to int and a double, returning
- (4) void

Array example

f is an array of 2 elements of arrays of 3 elements of pointers to arrays of 5 elements of pointers to const int

In extremis

```
int (*f(int(*)(int))) (int);
```

```
int (*f(int(*)(int))) (int);
```

f is a function this function takes a pointer to a function as argument (1) and returns a pointer to a function (2)

- (1) this function takes an int and returns an int
- (2) this function takes an int and returns an int

Never do something like this without proper type aliases!

```
using alias = int(*)(int);
alias f(alias);
```

const might be written to the left of the type it qualifies

```
int const i; //both declarations
const int i; //are the same
```

const applies to its left neighbor; only if there is no left neighbor it applies to its right neighbor



const might be written to the left of the type it qualifies

```
int const i; //both declarations
const int i; //are the same
```

Let's add an alias

```
using alias = int;
alias const i; //both declarations
const alias i; //are the same
```

What about more complex types

```
int const * const icpc; //both declarations
const int * const cipc; //are the same
```

Aliasas worked well before

```
//Extract the int const * part
using alias = int const *;
alias const icpc; //works well
```

```
//Extract the int * const part
using alias = int * const;
const alias cipc; //not good
```

The type is int \* const const now

- Always write const to the right of the type
  - It's consistent with every other placement of const (e.g. pointers)
  - It avoids surprises with type aliases

- The mutable specifier refers to the declared name
- What does the following mean?

```
mutable const int * mutable_const_int_pointer;
```

- const makes the pointee int immutable
- mutable makes the pointer mutable
- When does this make sense? Shouldn't the non-const mutable\_const\_int\_pointer always be mutable?

# HEAP Memory (De)Allocation





- Explicit heap memory allocation
  - new expression
- Syntax

```
new <type> <initializer>
```

- Allocates memory for an instance of <type>
- Returns a pointer to the object or array created (on the heap)
  - of type <type> \*
- The arguments in the <initializer> are passed to the constructor of <type>

```
struct Point {
  Point(int x, int y) :
       x \{x\}, y \{y\}\{\}
 int x, y;
auto createPoint(int x, int y) -> Point* {
 return new Point{x, y}; //constructor
auto createCorners(int x, int y) -> Point* {
 return new Point[2]{{0, 0}, {x, y}};
```

- Explicit heap memory deallocation
  - delete expression
- Syntax

```
delete <pointer>
```

- Deallocates the memory (of a single object) pointed to by the <pointer>
- Calls the Destructor of the destroyed type
- delete nullptr is well defined
  - it does nothing
- Deleting the same object twice is Undefined Behavior!

```
struct Point {
 Point(int x, int y) :
       x \{x\}, y \{y\} \{\}
 int x, y;
auto funWithPoint(int x, int y) -> void {
 Point * pp = new Point{x, y};
 //pp member access with pp->
 //pp is the pointer value
 delete pp; //destructor
```



- Explicit heap memory deallocation
  - delete[] expression
- Syntax

```
delete[] <pointer-to-array>
```

- Deallocates the memory (of an array) pointed to by the <pointer-to-array>
- Calls the Destructor of the destroyed objects
- Also deletes multidimensional arrays

```
struct Point {
  Point(int x, int y) :
       x \{x\}, y \{y\}\{\}
  int x, y;
auto funWithPoint(int x, int y) -> void {
  Point * arr = new Point[2]{\{0, 0\},
                              {x, y}};
  //element access with [], e.g. arr[1]
  //arr points to the first element
  delete[] arr; //destructors
```

- Construction of an object at an already allocated memory location
- Syntax

```
new (<location>) <type> <initializer>
```

- Does NOT allocate new memory
  - You need to make sure that the memory at <location> is suitable for construction of a new object and any element there must be destroyed properly before (or be uninitialized)
- Calls the Constructor for creating the object at the given location (<location>)
- Returns the given memory location

```
struct Point {
   Point(int x, int y) :
        x {x}, y {y}{}
   int x, y;
};

auto funWithPoint() -> void {
   auto ptr = new Point{9, 8};
   //must release Point{9, 8}
   new (ptr) Point{7, 6};
   delete ptr;
}
```

- Does not exist, but a destructor can be called explicitly
- Syntax
  - Call like any other member function

```
S * ptr = ...;
ptr->~S();
```

- Destroys the object, but does not free its memory
- You cannot destroy an array in this way as a whole
  - You need to create your own infrastructure, which keeps track of arrays to achieve this
- Better use std::destroy\_at(ptr);

```
struct Resource {
  Resource() {
    /*allocate resource*/
 ~Resource() {
    /*deallocate resource*/
auto funWithPoint() -> void {
  auto ptr = new Resource{};
  ptr->~Resource();
  new (ptr) Resource{};
  delete ptr;
```

- Point is not default constructible
  - We cannot allocate arrays of default-constructed Points

```
new Point[2];
```

```
struct Point {
   Point(int x, int y);
   ~Point();
   int x, y;
};
```

• We can allocate the plain memory (std::byte[])

```
auto memory = std::make_unique<std::byte[]>(sizeof(Point) * 2);
```

And initialize it later

```
new (memory.get()) Point{1, 2};
```

Accessing the elements is tedious. Let's add a helper function

```
auto elementAt(std::byte * memory, size_t index) -> Point& {
   return reinterpret_cast<Point *>(memory)[index];
}
```

We must not use the Point if it is uninitialized

```
auto memory = std::make_unique<std::byte[]>(sizeof(Point * 2));
Point * first = &elementAt(memory.get(), 0);
new (first) Point{1, 2};
Point * second = &elementAt(memory.get(), 1);
new (second) Point{4, 5};
```

- Before our memory is deallocated, we have to destroy the elements
  - Call the destructor explicitly or use std::destroy\_at

```
Point * first = &elementAt(memory.get(), 0);
new (first) Point{1, 2};
first->~Pointer();
```

```
auto memory = std::make_unique<std::byte[]>(sizeof(Point) * 2));
Point * first = &elementAt(memory.get(), 0);
new (first) Point{1, 2};
Point * second = &elementAt(memory.get(), 1);
new (second) Point{4, 5};
std::destroy_at(second);
std::destroy_at(first);
```

Overloading new and delete operators for a class can inhibit heap allocation

```
struct not on heap {
    static auto operator new(std::size_t sz) -> void * {
      throw std::bad_alloc{};
    static auto operator new[](std::size_t sz) -> void * {
      throw std::bad alloc{};
    static auto operator delete(void *ptr) -> void noexcept {
      // do nothing, never called, but should come in pairs
    static auto operator delete[](void *ptr) -> void noexcept {
       // do nothing, never called, but should come in pairs
};
```

Experiment in exercises

- Overloading new and delete operators for a class can be used to provide efficient allocation
  - useful with a memory pool for small instances
  - useful if thread-local pools are used
    - heap-memory is a shared resource
  - can log or limit number of heap-allocated instances
    - for testing purposes, figuring bottlenecks
- But in general, not advisable
  - if used in standard-containers you need to adjust their Allocator template argument instead

```
struct not_on_heap {
//...
};

struct small_but_many {
//...
};

std::vector<X, PoolAllocator> vp;
```



## Simple rules

- Delete every object you allocated
- Do not delete an object twice
- Do not access a deleted object

### Just don't do the following

```
auto foo() -> void {
  int * ip = new int{5};
  //exit without deleting
  //location ip points to
```

```
auto foo() -> void {
  int * ip = new int{5};
  delete ip;
  delete ip;
```

```
auto foo() -> void {
  int * ip = new int{5};
  delete ip;
  int dead = *ip;
```







#### More cases

```
auto bar() -> void;

auto foo() -> void {
  int * ip = new int{5};
  bar(); //exception?!
  delete ip;
}
```

```
auto foo(int * p) -> void {
   //is it up to me to
   //delete p? likely not
}
```

```
auto create() -> int * {
  int * ip = new int{5};
  return ip;
}
auto foo() -> void {
  int * ip = create();
  //My turn to delete?
  //Probably yes
}
```

It gets even more tricky when pointers are used for shared members

```
auto createTree() -> Node * {
  Node * root = new Node{};
  new Node{root}; new Node{root};
  return root;
}
auto find_child_X() -> Node * {
  Node * root = createTree();
  Node * child_X = ...; //find child X
  delete root;
  return child_X;
}
```

 The mistakes here can be discovered with reasonable effort, but it is a much bigger issue in a large code base

- Getting familiar with the syntax of pointers is important
  - You will come across them in most real world C++ (legacy) applications
- Use pointers only if necessary and only in confined code areas
  - Reasoning about the life-time of the heap-allocated objects must be easy
- Prefer smart pointers to make reasoning about object life-time easier
- You can use emplace to directly create objects into standard containers

Resource Management with RAII Container's emplace() Overloading new/delete

Self-Study



- Alternative to allocating and deallocating a resource explicitly
  - Wrap allocation and deallocation in a class
  - Constructor for allocation
  - Destructor for deallocation
- The automatic destruction at the end of a scope will take care of the resource deallocation
- Works with exceptions
  - No finally required
- STL classes for heap memory
  - std::unique\_ptr/std::shared\_ptr

```
struct Resource {
  Resource() {
    //Allocate Resource
 ~Resource() {
    //Deallocate Resource
  //API for accessing the resource
  //Don't leak the resource!
private:
  WrappedResource * wrappedResource;
```

```
auto workWithResource() -> void {
  Resource item{};
  functionThatMightThrow();
  //Resource is released automatically
}
```

```
std::unique_ptr<char> cPtr = std::make_unique<char>('*');
```

- std::unique\_ptr<T>
  - Wraps a plain pointer
  - unique\_ptr have zero runtime overhead
  - A custom deleter could be supplied if required that is called instead of the destructor

```
std::unique_ptr<char> cPtr = std::make_unique<char>('*');
```

- std::make\_unique<T>
  - Always use make\_unique if possible

- You can create unbound arrays
- You cannot create arrays of fixed size

```
template<typename T, typename...Args>
std::unique_ptr<T>
make_unique(Args&&...args) {
   return std::unique_ptr<T> {
    new T(std::forward<Args>(args)...)};
}
```

```
std::make_unique<char[]>(42)
```

```
std::make_unique<char[42]>(...)
```

- Putting elements into a container...
  - Copying big objects into standard containers might be inefficient
  - Moving big objects into standard containers might be more efficient
  - Creating big objects into the space already allocated for a standard container might be even better
- Syntax for emplace, example for std::stack

```
template<typename... Args>
auto emplace(Args&&... args) -> void;
```

- Constructs an element of type T from the forwarded arguments in-place
  - Can put objects into a container that can neither be copied nor moved
- Not available for std::array
  - Has fixed size

It is possible to overload the new and delete operators

```
//Global new
auto operator new (std::size_t) -> void *
auto operator new[] (std::size_t) -> void *
//Placement new
auto operator new (std::size_t, void * ptr) -> void *
auto operator new[] (std::size_t, void * ptr) -> void *
//For specific type T
auto T::operator new (std::size t) -> void *
auto T::operator new[] (std::size t) -> void *
//more new operators & delete operators
```

See <a href="http://en.cppreference.com/w/cpp/memory/new">http://en.cppreference.com/w/cpp/memory/new</a> for more details

- A type is non-default-constructible when...
  - ... there is no explicit default constructor and ...
  - ... there is no implicit default constructor!
- Why can't we use new T[capacity] for allocating a T array?
  - If T is of class type it must be default-constructible to allow this call.
  - That is not the case for fundamental types!

#### Alternative

Allocate a std::byte array and manage the objects "manually"

#### Static

- Local
- Size known at compile-time (no\_of\_bytes)

```
std::array<std::byte, no_of_bytes> values_memory;
```

## Dynamic

- On heap
- Size known at run-time

```
std::unique_ptr<std::byte[]> values_memory;
```

#### • Given:

- An array of elements of type T is accessible through a pointer to std::byte.
- Declaration of data: std::byte \* data;
- How to correctly access the fifth element in this array?
- a) data[4]
- b) reinterpret\_cast<T\*>(data)[4]
- c) \*reinterpret\_cast<T\*>(data + 4)
- d) \*reinterpret\_cast<T\*>(data) + 4

• Note you can access the raw memory behind an std::array with .data() or for std::unique\_ptr<T[]> with .get()