

Module 9.3: Time Series Analysis with Python

Fall Term 2023

Week 5:

Volatility Modeling

Outline in Weeks

- ➊ Introduction; Descriptive Modeling
- ➋ Returns; Autocorrelation; Stationarity
- ➌ ARMA Models
- ➍ Unit Roots; ARIMA Models
- ➎ Volatility Modeling
- ➏ Value at Risk
- ➐ Cointegration

Outline

- 1 Introduction
- 2 Historical, RiskMetrics
- 3 The ARCH and GARCH Models
- 4 Estimation of GARCH Models
- 5 Testing GARCH Models
- 6 Asymmetry and the News Impact Curve
- 7 Volatility Forecasting
- 8 Epilogue

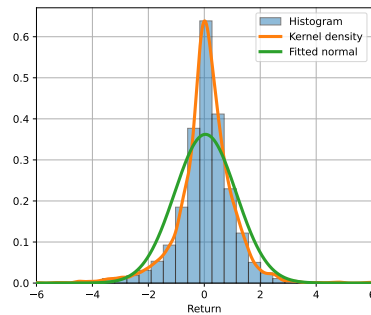
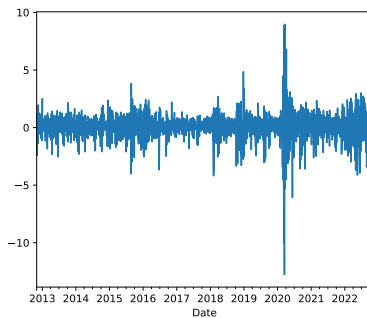
Goal

- Recall these stylized facts about asset returns:
 - 1 Lack of autocorrelation (efficient market hypothesis)
 - 2 Volatility clustering
 - 3 Distribution has heavy tails
 - 4 Leverage effects
- Goal today: model the last 3 of these, starting with the volatility clustering.

Volatility

- The *volatility* of an investment is a measure of its *risk*. Usually defined as the standard deviation of the return on the investment.
- Volatility is an important ingredient in:
 - portfolio selection;
 - risk management;
 - option pricing.
- Daily financial returns display *volatility clustering*: periods of high volatility alternate with more tranquil periods.
- In other words: large (in absolute value) returns tend to be followed by large (in absolute value) returns.
- This forms the basis for the *autoregressive-conditional heteroskedasticity* model (ARCH; Engle, 1982) and the *generalized ARCH* model (GARCH; Bollerslev, 1986).

Example: Daily Returns on the S&P 500



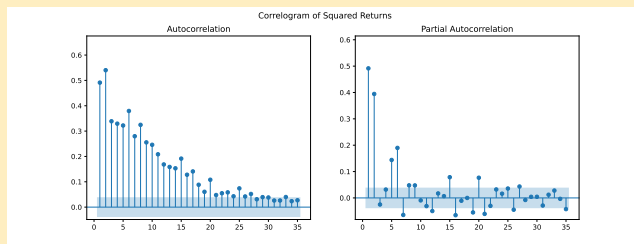
Reminder: Parameters vs. sample values

- We usually write σ for the standard deviation of, e.g., a normally distributed variable.
- σ is a *parameter* and therefore unknown.
- The best we can hope for is to *estimate* it, usually with the *sample standard deviation* s .
- With stock returns, the standard deviation (or *volatility*) changes over time, due to *volatility clustering*.
- We write σ_t for the volatility in period t .
- Note that σ_t is *unobserved*. The best we can do is *estimate* it. We'll write $\hat{\sigma}_t$ for this estimate.
- Today, we'll mostly discuss different methods of estimation.

Detecting Volatility Clustering (I)

- Since volatility clustering means that large returns tend to be followed by large returns, it is possible to detect it by inspecting the correlogram of the squared returns.

Example: correlogram of squared S&P500 returns.



- Clearly, there is a lot of predictability in squared returns (unlike returns themselves).

Detecting Volatility Clustering (II)

- Besides relying on the correlogram (or the associated Q-tests, see exercises), a formal test for volatility clustering is Engle's *ARCH-LM* test.
- The test is designed to work with regression residuals, not raw returns. Hence, we start by regressing the returns on an intercept (this is equivalent to de-meaning the returns).
- The ARCH-LM test is based on the auxiliary regression

$$\hat{u}_t^2 = \gamma_0 + \gamma_1 \hat{u}_{t-1}^2 + \dots + \gamma_m \hat{u}_{t-m}^2 + e_t.$$

- The lag length m is chosen by the user, e.g., 5 for daily data.
- The test statistic is $T \cdot R_{aux}^2$ and has a $\chi^2(m)$ distribution under $H_0 : \gamma_1 = \dots = \gamma_m = 0$ (no volatility clustering).

Example: ARCH-LM test for the S&P500 (see exercises for details)

OLS Regression Results						
=====						
Dep. Variable:	y	R-squared:		0.373		
Model:	OLS	Adj. R-squared:		0.372		
Method:	Least Squares	F-statistic:		298.0		
Date:	Wed, 04 Oct 2023	Prob (F-statistic):		8.83e-251		
Time:	17:19:09	Log-Likelihood:		-7173.1		
No. Observations:	2512	AIC:		1.436e+04		
Df Residuals:	2506	BIC:		1.439e+04		
Df Model:	5					
Covariance Type:	nonrobust					
=====						
	coef	std err	t	P> t	[0.025	0.975]

const	0.3179	0.088	3.618	0.000	0.146	0.490
x1	0.2996	0.020	15.157	0.000	0.261	0.338
x2	0.3959	0.021	19.170	0.000	0.355	0.436
x3	-0.0872	0.022	-3.955	0.000	-0.130	-0.044
x4	-0.0139	0.021	-0.671	0.502	-0.054	0.027
x5	0.1438	0.020	7.272	0.000	0.105	0.183
=====						

Here, the dependent variable y refers to \hat{u}_t^2 , the regressor x_1 refers to \hat{u}_{t-1}^2 , etc. The test statistic is $T \cdot R^2 \approx 937$, much larger than the critical value 11.07. The null of no volatility clustering is thus clearly rejected.

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Historical Volatility

- A first simple estimator is *historical volatility*, i.e., the sample standard deviation of the most recent m observations (often $m = 250$, one year).
- If $r_t = \ln P_t - \ln P_{t-1}$ denotes the daily log-return, then

$$\hat{\sigma}_{t+1, HIST}^2 = \frac{1}{m} \sum_{j=0}^{m-1} r_{t-j}^2.$$

(Typically the average return is relatively close to zero). This is an estimate of the squared volatility over day $t + 1$, made at the end of day t .

- Main disadvantages:
 - either noisy (small m), or reacts slowly to new information (large m);
 - “ghosting” feature: large shock leads to higher volatility for exactly m periods, then drops out.

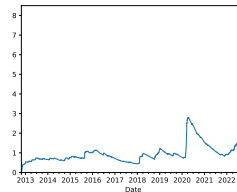
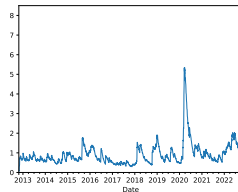
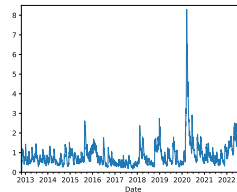
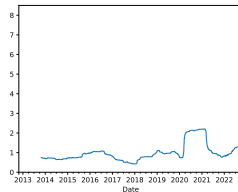
RiskMetrics

- Problems with historical volatility are addressed by replacing equally weighted moving average by an *exponentially* weighted moving average (EWMA), also used in JPMorgan's *RiskMetrics* system:

$$\begin{aligned}\hat{\sigma}_{t+1,EWMA}^2 &= (1 - \lambda) \sum_{j=0}^{\infty} \lambda^j r_{t-j}^2 \\ &= \lambda \hat{\sigma}_{t,EWMA}^2 + (1 - \lambda) r_t^2, \quad 0 < \lambda < 1.\end{aligned}$$

- This means that observations further in the past get a smaller weight.
- In practice we do not have $r_{t-\infty}$, but the second equation can be started up by an initial estimate / guess $\sigma_{0,EWMA}^2$.
- The larger λ , the stronger the persistence of shocks (large returns).
- For daily data, RiskMetrics recommends $\lambda = 0.94$.

Example: S&P500 volatility, historical and EWMA ($\lambda = 0.8, 0.94, 0.99$)



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The ARCH Model

- The first-order *autoregressive-conditional heteroskedasticity* (ARCH(1)) model, due to Engle (1982), for a return r_t with mean zero is

$$\sigma_{t+1}^2 = \omega + \alpha r_t^2.$$

- In practice, we need to allow for $\mathbb{E}[r_{t+1}] = \mu_{t+1} \neq 0$. Then $r_{t+1} = \mu_{t+1} + u_{t+1}$, and the model becomes

$$\sigma_{t+1}^2 = \omega + \alpha u_t^2.$$

The ARCH Model

- When trying to estimate ARCH models one might find that more lags are needed, leading to ARCH(q):

$$\sigma_{t+1}^2 = \omega + \alpha_1 u_t^2 + \dots + \alpha_q u_{t-q+1}^2.$$

- Note:* Variances must be positive, therefore we need to impose $\omega > 0$, $\alpha_i \geq 0$, $i = 1, \dots, q$.
- It can be shown that an ARCH(q) models corresponds to an AR(q) for the squared returns. Thus, we could determine the order from the correlogram of the squared returns: SPACF should cut off after q lags.
- In the example above, we might conclude that we need an ARCH(6) model.

The GARCH Model

- A simpler structure than ARCH(q) is an ARMA(1,1) for r_t^2 or u_t^2 , which leads to the *generalized ARCH* model of orders (1,1) (GARCH(1,1)), due to Bollerslev (1986):

$$\sigma_{t+1}^2 = \omega + \alpha u_t^2 + \beta \sigma_t^2, \quad \omega > 0, \alpha \geq 0, \beta \geq 0.$$

- *Advantage*: Flexible structure with only 3 parameters to estimate.

The GARCH Model

- The GARCH(1,1) model is stationary if the unconditional (“average”) variance $\sigma^2 = \mathbb{E}[\sigma_t^2]$ is positive, constant and finite.
- This requires

$$\begin{aligned}\sigma^2 = \mathbb{E}[\sigma_{t+1}^2] &= \omega + \alpha \mathbb{E}[u_t^2] + \beta \mathbb{E}[\sigma_t^2] \\ &= \omega + \alpha \sigma^2 + \beta \sigma^2.\end{aligned}$$

- Hence, provided that $\alpha + \beta < 1$ (the *stationarity condition*),

$$\sigma^2 = \frac{\omega}{1 - \alpha - \beta}.$$

- The nonstationary model with $\alpha + \beta = 1$ is called *integrated GARCH* (IGARCH): infinite variance, no mean-reversion in volatility.
- Notice that an IGARCH with $r_t = u_t$, $\omega = 0$, $\beta = \lambda$, and $\alpha = (1 - \lambda)$ is just the RiskMetrics model.

The GARCH Model

Some other properties:

- The ACF and PACF of r_t^2 in case of stationary GARCH(1,1) are both exponentially decaying, no cut-off point.
- The *standardized returns*

$$z_{t+1} = \frac{r_{t+1} - \mu_{t+1}}{\sigma_{t+1}}$$

satisfy $E(z_{t+1}) = 0$ and $\text{var}(z_{t+1}) = 1$. Therefore the model may be formulated as

$$\begin{aligned} r_{t+1} &= \mu_{t+1} + u_{t+1} = \mu_{t+1} + \sigma_{t+1} z_{t+1}, \\ \sigma_{t+1}^2 &= \omega + \alpha u_t^2 + \beta \sigma_t^2. \end{aligned}$$

- Often it is assumed that z_t are i.i.d. as $N(0, 1)$.
- Even if $z_t \sim N(0, 1)$, it can be shown that varying σ_t implies that r_t has non-normal distribution, with higher kurtosis.

The GARCH(p, q) Model

- The GARCH(1, 1) model can be extended to the GARCH(p, q) model

$$\sigma_{t+1}^2 = \omega + \alpha_1 u_t^2 + \cdots + \alpha_q u_{t-q+1}^2 + \beta_1 \sigma_t^2 + \cdots + \beta_p \sigma_{t-p+1}^2$$

although in practice, this is rarely necessary.

- The model is stationary if $\sum_{i=1}^p \beta_i + \sum_{i=1}^q \alpha_i < 1$, and the unconditional variance is

$$\frac{\omega}{1 - \sum_{i=1}^p \beta_i - \sum_{i=1}^q \alpha_i}.$$

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Estimation of GARCH Models

- GARCH cannot be estimated by ordinary least-squares (because σ_t^2 is not observed).
- Such models are estimated by *maximum likelihood*: the joint density of the observations $\{r_1, \dots, r_T\}$ is maximized with respect to the parameters.
- Maximization of $\log L$ can be done by numerical optimization algorithms. By default, the `arch` package for Python does this under the assumption of normality.
- If we are not sure that the z_t 's are normally distributed, then we may still use the same estimation technique. This is called *quasi-maximum likelihood estimator*.
- However, we need to construct standard errors via a more robust method (*Bollerslev-Wooldridge standard errors*). `arch` does this by default.

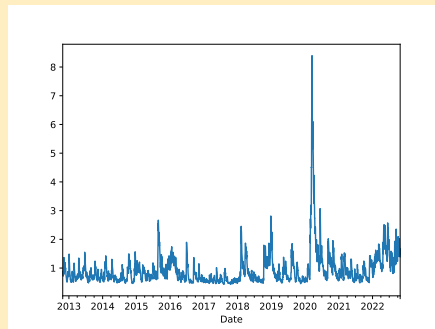
Example: arch output, estimated GARCH model for S&P500

```

                        Constant Mean - GARCH Model Results
=====
Dep. Variable:          log_return    R-squared:                0.000
Mean Model:             Constant Mean  Adj. R-squared:           0.000
Vol Model:              GARCH          Log-Likelihood:         -3119.24
Distribution:           Normal         AIC:                   6246.48
Method:                Maximum Likelihood  BIC:                   6269.80
No. Observations:      2517
Date:                  Wed, Oct 04 2023  Df Residuals:           2516
Time:                  17:23:18          Df Model:                1
Mean Model
=====
coef    std err        t    P>|t|    95.0% Conf. Int.
-----
mu              0.0803  1.410e-02    5.697  1.219e-08  [5.269e-02,  0.108]
Volatility Model
=====
                        coef    std err        t    P>|t|    95.0% Conf. Int.
-----
omega           0.0447  9.834e-03    4.551  5.346e-06  [2.548e-02,6.402e-02]
alpha[1]        0.2217  3.185e-02    6.963  3.326e-12  [ 0.159,  0.284]
beta[1]         0.7437  2.864e-02   25.970  1.094e-148  [ 0.688,  0.800]
=====
Covariance estimator: robust

```


Example: Estimated GARCH volatility of S&P500



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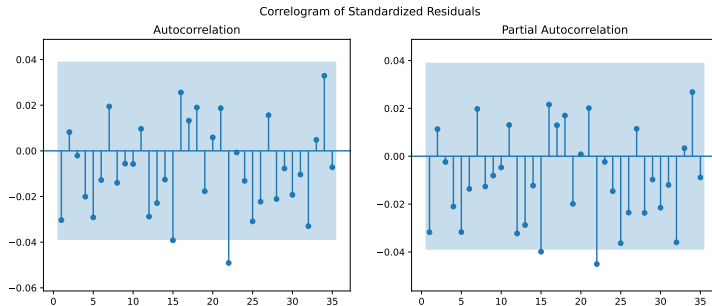
Testing GARCH Models

- Diagnostic tests are based on the *standardized residuals* $\hat{z}_t := \hat{u}_t / \hat{\sigma}_t$. If μ_t and σ_t are correctly specified, we should find no autocorrelation in \hat{z}_t and \hat{z}_t^2 .
- Therefore, the model can be tested using Q -statistics for \hat{z}_t or \hat{z}_t^2 .
- Lagrange-Multiplier (LM) test against ARCH, which is obtained by $T \cdot R^2$ in the regression

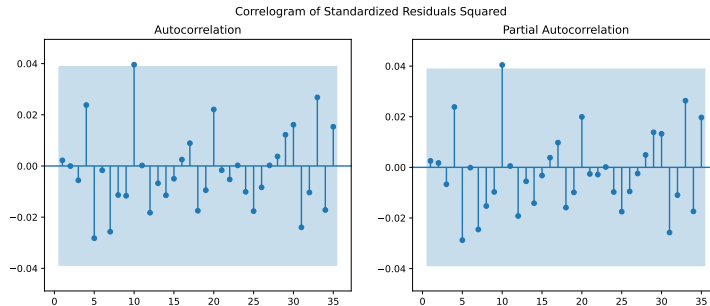
$$\hat{z}_t^2 = \gamma_0 + \gamma_1 \hat{z}_{t-1}^2 + \dots + \gamma_m \hat{z}_{t-m}^2 + \mathbf{e}_t.$$

- To test for normality of z_t , we can use the Jarque-Bera test based on the skewness and kurtosis of \hat{z}_t .

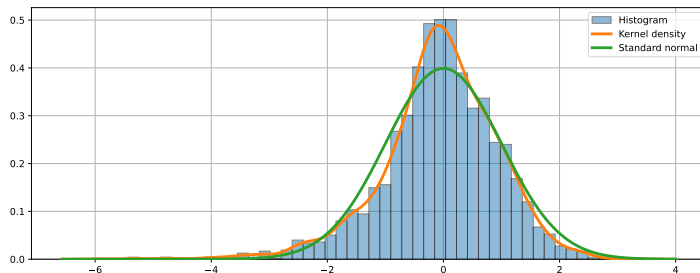
Example: Correlogram of standardized residuals for the S&P500



Example: Correlogram of squared standardized residuals for the S&P500



Example: Histogram of standardized residuals for the S&P500



The Jarque-Beta test rejects with a p -value of essentially zero, rejecting normality (see exercises).

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Asymmetry and the News Impact Curve

- The *news impact curve* (NIC) is the effect of u_t on σ_{t+1}^2 , keeping σ_t^2 and the past fixed.
- For GARCH(1,1), this is the parabola $NIC(u_t|\sigma_t^2 = \sigma^2) = A + \alpha u_t^2$, with $A = \omega + \beta\sigma^2$. This has a minimum at $u_t = 0$, and is symmetric around that minimum.
- For equity, a large negative shock is expected to increase volatility more than a large positive shock, because of *leverage effect*:
 - ↓ value of firm's stock
 - ⇒ ↓ equity value of the firm
 - ⇒ ↑ debt-to-equity ratio
 - ⇒ shareholders (as residual claimants) perceive future cashflows as more risky.
- Multiple extensions exist to deal with this issue. Here we focus on Glosten, Jagannathan and Runkle's GJR-GARCH model.

GJR-GARCH (or TARARCH, threshold GARCH)

The GJR-GARCH(1,1) model is

$$\sigma_{t+1}^2 = \omega + \alpha u_t^2 + \gamma u_t^2 I_t + \beta \sigma_t^2.$$

where

$$I_t = \begin{cases} 1 & \text{if } u_t < 0 \\ 0 & \text{if } u_t \geq 0 \end{cases},$$

and u_t/σ_t has a symmetric distribution.

Properties:

- NIC is asymmetric if and only if $\gamma \neq 0$; leverage effect if $\gamma > 0$;
- σ_t^2 is positive if $\omega > 0$, $\alpha \geq 0$, $\gamma \geq 0$, $\beta \geq 0$;
- u_t^2 is stationary if $0 \leq \alpha + \frac{1}{2}\gamma + \beta < 1$, with unconditional variance $\sigma^2 = \omega / [1 - \alpha - \frac{1}{2}\gamma - \beta]$.

Example: arch output, estimated TARCH model for S&P500

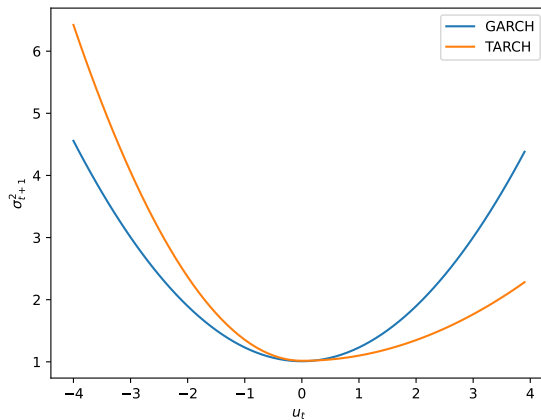
```

                        Constant Mean - GJR-GARCH Model Results
=====
Dep. Variable:          log_return      R-squared:                0.000
Mean Model:             Constant Mean   Adj. R-squared:           0.000
Vol Model:              GJR-GARCH       Log-Likelihood:        -3088.09
Distribution:           Normal          AIC:                   6186.18
Method:                Maximum Likelihood BIC:                   6215.34
No. Observations:      2517
Date:                  Wed, Oct 04 2023   Df Residuals:           2516
Time:                  18:38:45          Df Model:               1
Mean Model
=====
coef      std err        t      P>|t|      95.0% Conf. Int.
-----
mu          0.0475   1.357e-02     3.503   4.609e-04 [2.094e-02,7.415e-02]
Volatility Model
=====
                        coef      std err        t      P>|t|      95.0% Conf. Int.
-----
omega        0.0419   8.680e-03     4.832   1.352e-06 [2.493e-02,5.895e-02]
alpha[1]     0.0831   4.212e-02     1.974   4.843e-02 [5.741e-04, 0.166]
gamma[1]     0.2547   5.416e-02     4.703   2.561e-06 [ 0.149, 0.361]
beta[1]      0.7569   3.189e-02    23.736   1.541e-124 [ 0.694, 0.819]
=====

Covariance estimator: robust

```

Example: NIC of GARCH and TARCH models for S&P500



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Volatility Forecasting

- GARCH models directly provide forecasts of next day's volatility:

$$\hat{\sigma}_{t+1}^2 = \hat{\omega} + \hat{\alpha} \hat{u}_t^2 + \hat{\beta} \hat{\sigma}_t^2.$$

- Multi-period forecasts can be constructed recursively. In principle, one would use

$$\hat{\sigma}_{t+2}^2 = \hat{\omega} + \hat{\alpha} \hat{u}_{t+1}^2 + \hat{\beta} \hat{\sigma}_{t+1}^2,$$

but \hat{u}_{t+1}^2 is unobserved.

- Solution: replace \hat{u}_{t+1}^2 with its estimate, $\hat{\sigma}_{t+1}^2$.
- Result:

$$\hat{\sigma}_{t+2}^2 = \hat{\omega} + (\hat{\alpha} + \hat{\beta}) \hat{\sigma}_{t+1}^2.$$

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Learning Goals

Students

- can use appropriate tests to detect volatility clustering,
- are able to estimate, interpret, and forecast the various models (historical volatility, RiskMetrics, (G)ARCH, TARCH), and to apply diagnostic tests to the standardized residuals,
- and understand the concept of leverage, and the NIC.

Homework

- Exercise 5
- Questions 1 and 3 from Chapter 9 of Brooks (2019)